

e-Yantra Robotics Competition (eYRC-2018)

Task 0: Ant Bot

Welcome to Task-0 of Ant Bot!!

The aim of this task is to get you started with installation of required software. You need to install following software/libraries and run the provided python script to test the installation of the software/libraries.

You will find the following folders in Task 0 folder along with this Read Me file.

- First Folder is Installation_Instructions:
 - Please find the *Installation_Instructions_for-Linux.pdf* and *Installation_Instructions_for-Windows.pdf* file in this folder. As the name suggest, depending on operating system installed on your machine, you can follow the installation procedure to **install** the following softwares:
 - 1. Python
 - 2. NumPy
 - 3. OpenCV
 - 4. pySerial

Second Folder is Test_setup:

- Please find the file checkversion.py
- After installing the software/libraries, open Terminal/Command Prompt.
- From Terminal/Command Prompt change directory (using cd command) to Test_setup.
- Type *python checkversion.py* (for Windows machine) and *python3 checkversion.py* (for Linux machine).
- You should get output as shown in Figure 1.
- Note that Python, OpenCV, NumPy and pySerial installation comes OK!!
- In case of discrepancies, make sure that you make necessary corrections.





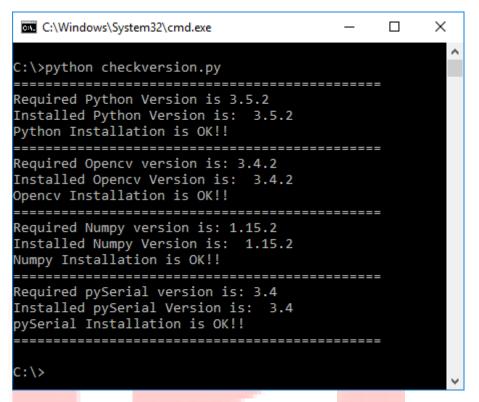


Figure 1: Output Window after running script

• Submission Instructions:

- If your checkversion.py runs with all OK!!, take the screen-shot of terminal and save it as "output.jpg". In Test_setup folder, a file named "output.csv" gets saved automatically.
- Save both the files and "checkversion.py" in a folder #Teamid_Task0. For example, if your Team ID is 1001, the folder should be named 1001_Task0.
- Compress the folder into zip format and upload the .zip file as per instructions on Portal Interface.

Note: Do not edit any line in "checkversion.py" or in "output.csv". The files submitted by you will be run through a test script for automatic grading. Teams making any changes will be disqualified.

