

Classifications of Routing Protocols:

❖ *Proactive routing protocols:*

- ✓ These are table-driven protocols. These are extensions of the wired network routing protocols. They maintain the global topology information in the form of tables at every node.
- ✓ These tables are updated frequently in order to maintain consistent and accurate network state information.

We consider:

- ❖ Destination Sequenced Distance Vector Routing Protocol (DSDV);
- ❖ Wireless Routing Protocol (WRP);
- ❖ Cluster Head Gateway Switch Routing Protocol (CGSR).
- ❖ Source-Tree Adaptive Routing Protocol (STAR);

Common Positives:

- ✓ Low delay of route setup process: all routes are immediately available;

Common Negatives:

- ✓ High bandwidth requirements: updates due to link loss leads to high control overhead;
- ✓ Low scalability: control overhead is proportional to the number of nodes;
- ✓ High storage requirements: whole table must be in memory.

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❖ *Proactive routing protocols:*

➤ **Destination Sequenced Distance Vector Routing Protocol (DSDV):**

- ✓ Modification of the Bellman-Ford algorithm where each node maintains:
 - the shortest path to destination;
 - the first node on this shortest path.

- ✓ This protocol is characterized by the following:
 - Routes to destination are readily available at each node in the Routing Table (RT).
 - RTs are exchanged between neighbors at regular intervals.
 - RTs are also exchanged when significant changes in local topology are observed by a node.

➤ **Wireless Routing Protocol (WRP):**

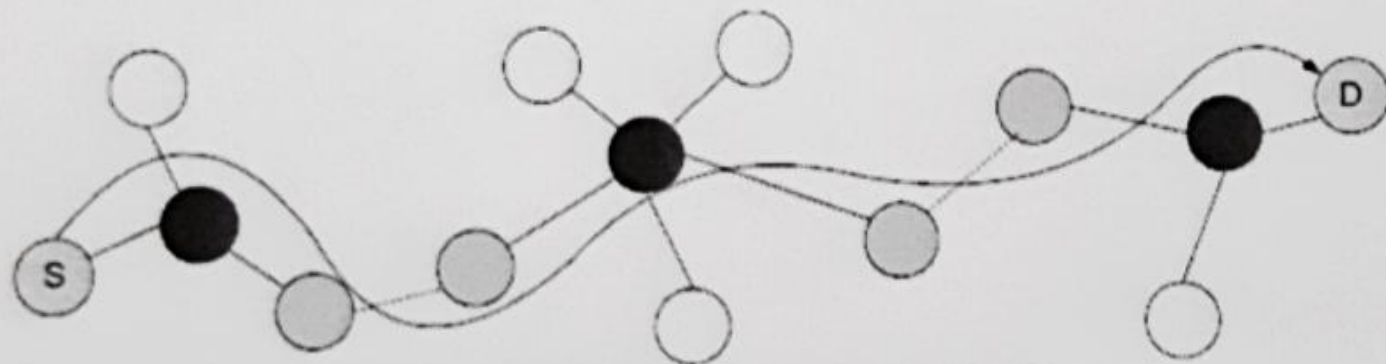
- ✓ Similar to DSDV, but it uses multiple tables for routing processes.
- ✓ Differs from table maintenance and in the update procedure.
 - Uses a set of tables to maintain more accurate information instead of single topology information
 - Not only updates distance for transmitted neighbor but also checks the other neighbors' distance.

- **Distance Table:** Contains distance and predecessor (penultimate node) node for a destination
- **Routing Table:** Contains shortest distance, predecessor node, successor node (next node to reach destination), and status of the path
- **Link Cost Table:** Cost of relaying messages through each link and number of update periods passed since the last successful update was received (for detecting link breaks)
- **Message Retransmission Table:** Update message that is to be retransmitted with a counter. The counter is decremented after every update message retransmission.

➤ **Cluster head Gateway Switch Routing protocol:**

❑ It is characterized by the following:

- ✓ Nodes are organized into clusters, each having an elected cluster-head;
- ✓ Cluster head provides a coordination within its transmission range (single hop);
- ✓ Token-based scheduling is used within a cluster for sharing bandwidth between nodes;
- ✓ All communications pass through the cluster head;
- ✓ Communication between cluster is done using the common nodes (gateways with two interfaces).



Abstract representation of routing in GCSR

➤ **Source-Tree Adaptive Routing protocol (STAR):**

- ✓ There are two protocols with different aims:
 - Least Overhead Routing Approach (LORA): Minimize control overhead irrespective of optimality.
 - Optimum Routing Approach (ORA): Provide optimal routes irrespective of the control overhead.

- ✓ The STAR protocol operates as follows:
 - Each node is required to:
 - Send an update message to its neighbors during initialization;
 - Send update messages about new destinations, chances of routing loops, costs of paths.
 - Every node broadcasts its source-tree information:
 - Wireless links used by the node in its preferred path to destinations.
 - Every node builds its partial graph of topology based on:
 - Its adjacent links with neighbors, source-tree broadcasts by neighbors.