

Outpatient Tracking to Reduce Cross Infection

Progress Report

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Outline

Introduction

Literature Review

Method

Results

Conclusion

Background

- ▶ 200,000 hospital acquired infections (HAIs) occur annually in Australia.



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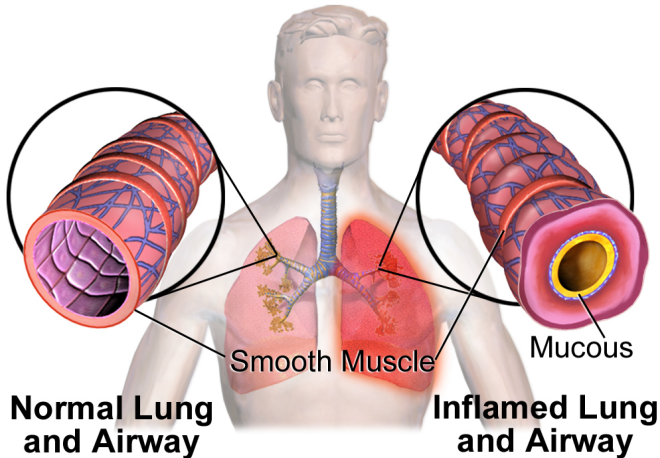
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- ▶ In-patient care vs out-patient care
- ▶ Cystic Fibrosis (CF) is a genetic condition that primarily affects the lungs.
- ▶ CF health care delivery has moved to out-patient environments.



Research Outline

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Our hypothesis is that patient encounters can be tracked using lightweight indoor localisation technologies allowing for interventions to improve patient flow, reduce patient contact, and reduce HAIs.

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Aim

Identify areas of potential cross infection in the hospital out-patient environment.

Scope

- ▶ Android smart-phone

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 - ▶ presence of low cost embedded sensors in smart-phones

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- ▶ Air-borne infection transmission among CF patients
- ▶ SNA focused on disease transmission and control

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- ▶ Development of algorithms to identify high risk areas for CF patients in the hospital out-patient environment.
- ▶ Implementation and testing of the software system to identify areas of improvement and practicality of system.

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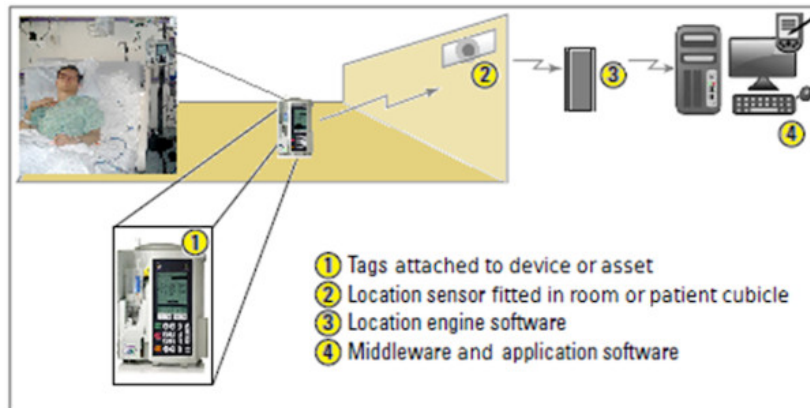
Real Time Location Systems (RTLS) in Hospitals

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- ▶ Used in monitoring and workflow improvements
- ▶ No consistent RTLS system

Indoor Localisation

- ▶ Pedestrian Dead Reckoning (PDR)

Indoor Localisation

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- ▶ Direct Sensing

Indoor Localisation

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- ▶ Direct Sensing
- ▶ **Triangulation**

Indoor Localisation

- ▶ Pedestrian Dead Reckoning (PDR)
- ▶ Direct Sensing
- ▶ Triangulation
- ▶ Pattern Recognition

Pedestrian Dead Reckoning (PDR)

- ▶ Dead reckoning systems specific to pedestrians

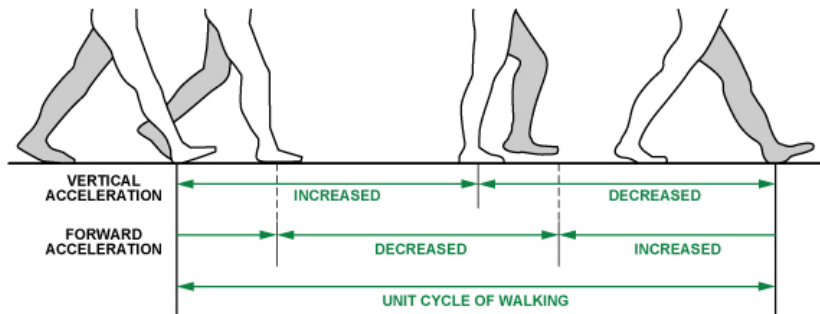
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- ▶ **Error accumulation**

Direct Sensing Technologies

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Pedestrian Dead Reckoning

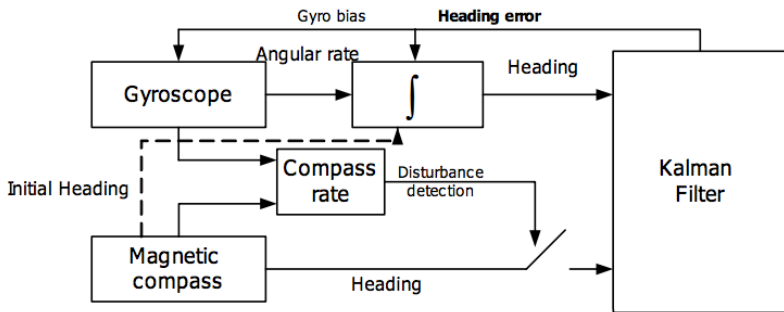
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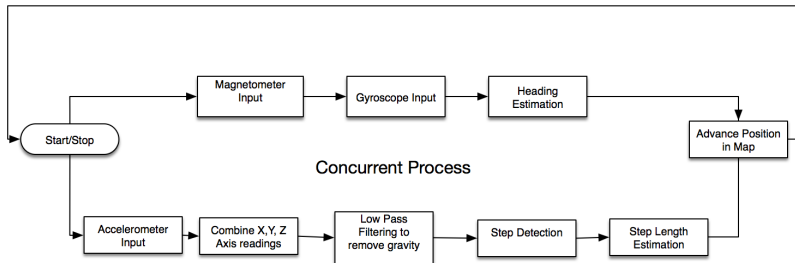
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Pedestrian Dead Reckoning



$$\omega_{compass} = \frac{\psi_{compass}(t_k + \Delta t) - \psi_{compass}(t_k)}{\Delta t}$$

Pedestrian Dead Reckoning



$$\mathbf{x} = \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x + s \sin(\theta) \\ y + s \cos(\theta) \end{bmatrix}$$

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- ▶ Error Correction with Direct Sensing Technology
 - ▶ Bluetooth Beacons with known positions scattered through the map

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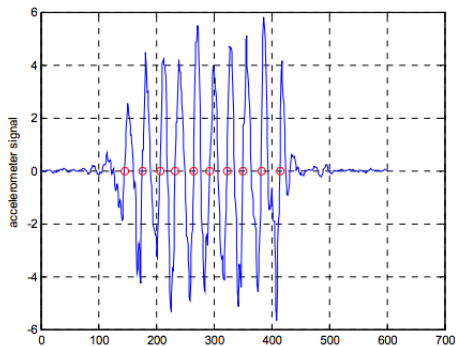
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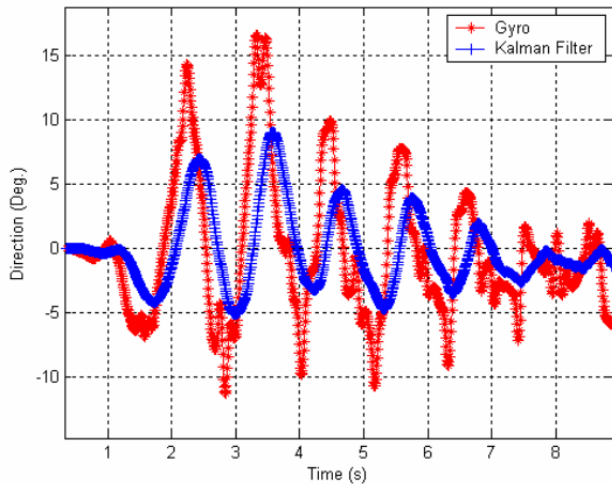
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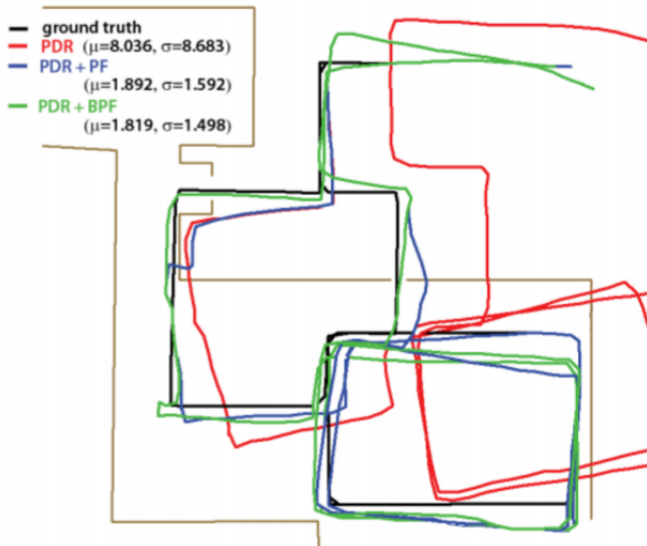
Step Detection



Heading Estimation



Map Matching



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Summary

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