Message = “cat”

binaryMessage = “010000110100000101010100”

key = “110110001001001101110100”

aliceBases = “dhhddhdhhhhddhddhdhhdhhd”

bobBases = “hhdhdddhhdhhdhddhhdhddhd”

servo max rotation speed = 400 degrees/sec

maximum rotation time = 662 ms

every 2170 ms, new rotation