

# KARTHIK KALIDAS

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## PROFESSIONAL SUMMARY

Technical leader with 6 years of experience driving end-to-end development of autonomous vehicle platforms. Skilled in HIL infrastructure, sensor integration, and large-scale test automation, enabling faster, safer, and more scalable deployment of autonomy software across engineering and product teams.

## WORK EXPERIENCE

### Senior Systems Engineer, Test Automation

Jan 2025 – Present

*Torc Robotics, Dallas–Fort Worth, TX*

- Spearheading HIL validation roadmap across 5 autonomy teams, boosting system test coverage by **70%**
- Leading team of **7** engineers, delivering 15+ HIL features per release through efficient sprints and reviews
- Deployed fully automated robotic HIL testing via CI/CD using temporal workflows, achieving zero-touch software flash, mission validation, and mode engagement in under **20 mins**
- Improved truck HIL uptime and stability from 30% to **99%** through proactive monitoring and fault isolation

### System Integration Engineer, Autonomous Driving Kit

Nov 2021 – Jan 2025

*Torc Robotics, Albuquerque, NM*

- Led rapid integration and deployment of autonomy platform in collaboration with **Daimler Truck** for mass production
- Developed patented sensor setup station for full sensor set configuration in under **12 mins** with remote diagnostics
- Commissioned **4** vehicle generations with self-developed tooling, optimized workflows, and thorough documentation
- Spearheaded system issue troubleshooting, RCA, and resolution, resolving **100+** critical system issues

### Test Engineer, On-Road Testing

Jan 2021 – Nov 2021

*Torc Robotics, Albuquerque, NM*

- Deployed instrumentation, infrastructure, and sensor calibration as defined by vehicle test plans
- Tuned and optimized longitudinal and lateral controllers, reducing autonomous disengagements by **30%**

## PUBLICATIONS

**Karthik Kalidas**, 2025, Systems And Methods For Automatic Sensor Configuration, 139906-05801

**Karthik Kalidas**, 2025, A Cloud-Based Platform For Automatic Sensor Configuration, 139906-08501

**Kalidas, K**, Simulation Framework for Testing Autonomous Vehicles, SAE Technical Paper [2021-01-0118](#)

## EDUCATION

### The Ohio State University, Columbus, OH

Dec 2020

Master of Science, Mechanical Engineering

GPA: 4.0/4.0

### Indian Institute of Technology (IIT) Bombay, India

Aug 2019

Bachelor of Technology, Mechanical Engineering

CPI: 8.4/10.0

## SKILLS

### Languages

C/C++17, Python, Go, JavaScript

### Frameworks

ROS1/2, TensorFlow, OpenCV, Jenkins, AWS, Temporal

### Tools

Docker, Bazel, Linux, Git, MATLAB, CANape, SolidWorks

## AWARDS

2024 – **Employee of the Quarter Q2**, Torc Robotics

2021 – **Employee of the Quarter Q1**, Torc Robotics

2019 – **Formula Student Award**, IIT Bombay Racing

2018 – **Institute Technical Citation**, IIT Bombay

2015 – **All India Rank 606**, JEE Advanced