#include <wiringPi.h>

#include<string.h>

#include<wiringserial.h>

include<stdio.h>

int ser;

char ch;

int j;

char temp[3];

char rfid[15];

void serialbegin(int baudrate)

{

if ((ser= serialOpen ("/dev/ttyS0",baudrate)) <0)

{

printf("unable to open serial port");

}

}

void setupwiringPi()

{

if (wiringPiSetup () == 1)

{

printf("unable to start");

printf("wiringPi");

}

serialbegin(9600);

}

void get\_card()

{

rfid[j]='';

j=0;

while(j<5);

{

while(serialDataAvailable (ser))

{

ch= serialGetchar(ser);

rfid[j]=ch;

printf("%s",rfid);

j++;

}

}

rfid[j]='0';

return 0;

}

int main()

{

setupwiringPi();

printf("rfidreading");

printf("using RPI \n");

delay(1000);

while(1)

{

printf("place your card:\n");

get\_card();

printf("%s \n",rfid);

delay(200);

}

}

#include<stdio.h>

#include<fcntl.h>

#include<termios.h>

#include<string.h>

#include<wiringPi.h>

#include<stdlib.h>

char value;

char \*Serialport ="/dev/ttyS0";

char number[] ="6476741649";

void setupgsm()

{

int f, count;

char buf[10];

serialport.begin(9600);

serialport.println("gsm module intilization through serialport");

delay(38000);

}

void gsmsms()

{

serialport.println("AT");

serialport.println("AT+CMGH=1");

serialport.print("AT+CMGS=");

serialport.print(number);

delay(500);

serialport.print("object\_status");

delay(1500);

#include <stdio.h>

#include <fnctl.h>

#include <termios.h>

#include <string.h>

char \*serialport="/dev/ttyS0";

define object\_1=0;

define object\_2=0;

char ch =" "

void read\_rfid()

{

int fd;

char \*serialport="/dev/ttyS0";

if(fd =open(portname)<0)

{

printf("unable to open serial port");

}

else

{

printf("serial port open")

}

return ch;

while(id=read\_rfid())

{

print id;

}

if(id is $0008978971 && object\_1 ==0)

{

printf("object\_1 entry")

else if

{

printf("object\_1 exit")

}

return;

if (id is $0008976142 && object\_2 ==0 )

{

printf("object\_2 entry")

else if

{

printf(object\_2 exit")

}

int main()

{

object\_1=0;

object\_2=0;

printf("(object\_1 status:......> "+str(object\_1));

printf(("object\_2 status:.......>"+str(object\_2));

f =open("data.txt","w")

f.write("object\_1 Status "+str(object\_1)+" "+"object\_2 Status "+str(ob$

f.close()

}

#include <stdio.h>

#include <stdlib.h>

#include <assert.h>

int main(void) {

FILE \*pip;

printf("sending ...\n");

assert(pip = popen("karthikr381@gmail.com", "w"));

fprintf(pip, "Subject: status\n");

fprintf(pip, "object\_1 status\n");

fprintf(pip, "object\_2 status\n");

fprintf(pip, "status\n");

fprintf(pip, ".\n");

pclose(pip);

printf("... sent\n");

exit(0);

}

}

#include<stdio.h>

#include <string.h>

#include<unistd.h>

#include<termios.h>

char str[currentDT]

int main()

{

FILE \*fp;

fp=fopen("gsm.c");

return(0);

}

while(currentDT=datetime.datetime.now())

{

printf("currentDT");

}

void setup()

{

printf(" if h == 08 and m == 00 and s == 00:

printf("data")

os.system('espeak -s40 \"{}\"'.format(data))

send(str(data));

printf(\"Send\"\n");

return 0;

}

void ()

{

printf(" if h == 16 and m == 00 and s == 00:

printf("data")

os.system('espeak -s40 \"{}\"'.format(data))

send(str(data));

printf(\"Send\"\n");

return 0;

}