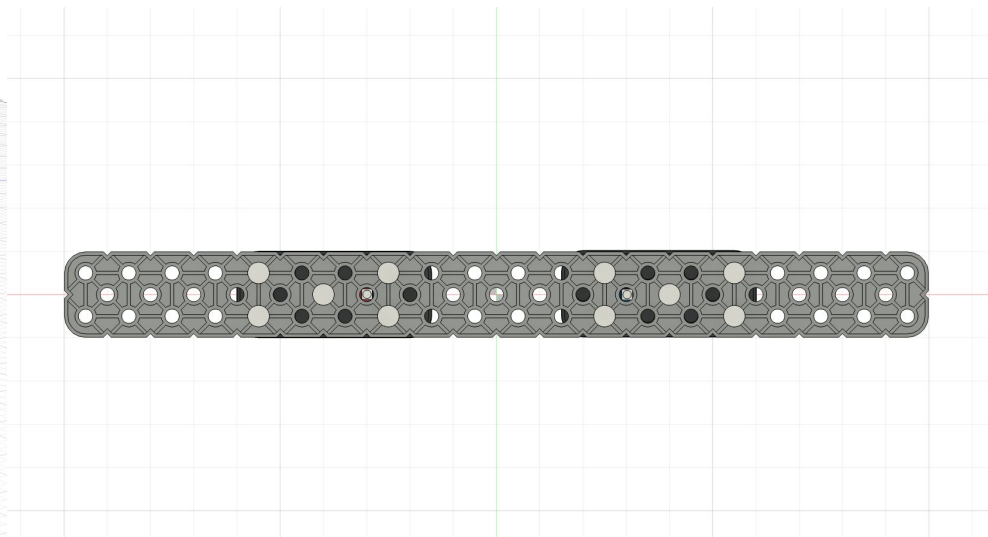
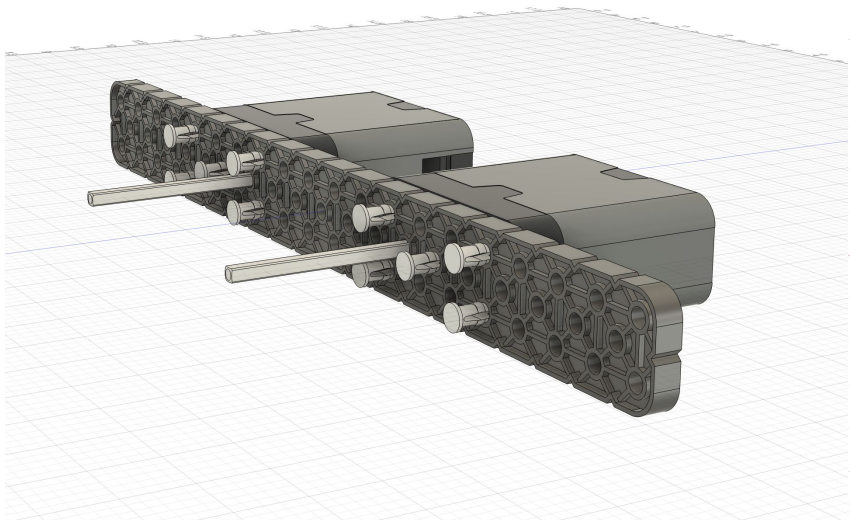
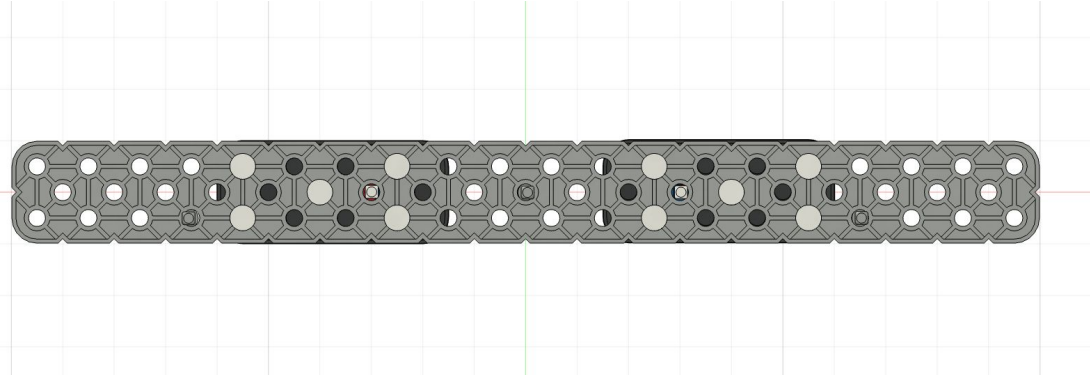
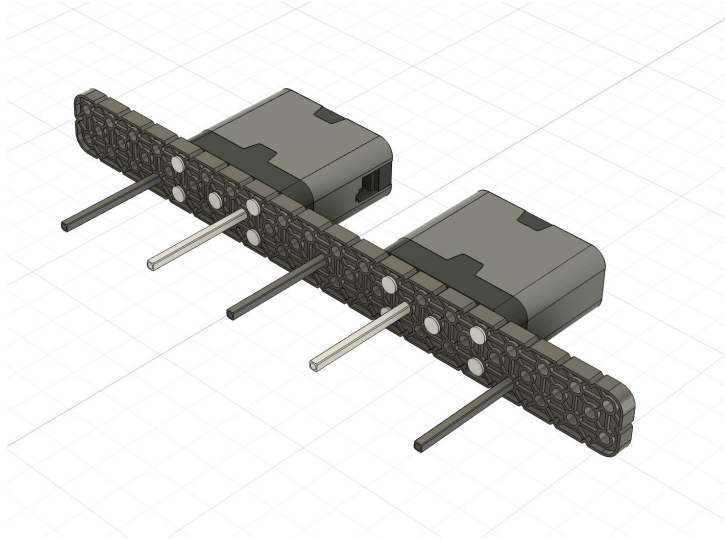


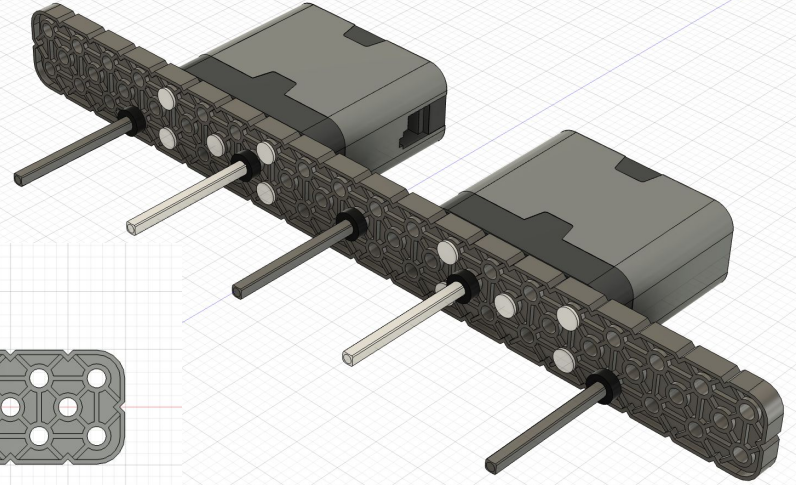
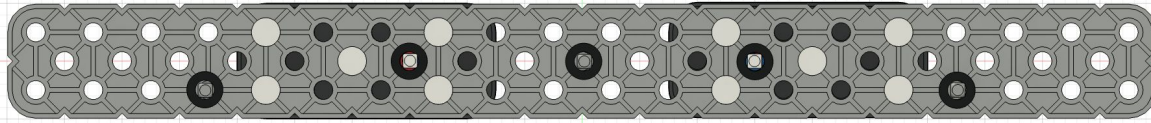
# Basebot Drivetrain Instructions



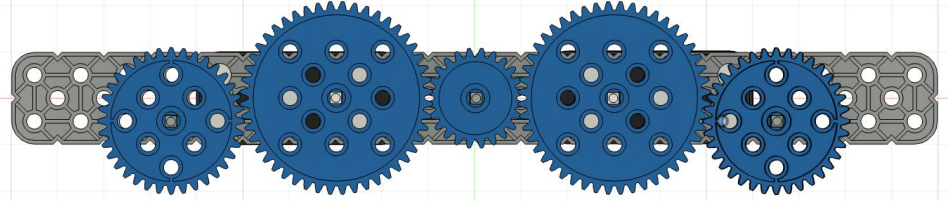
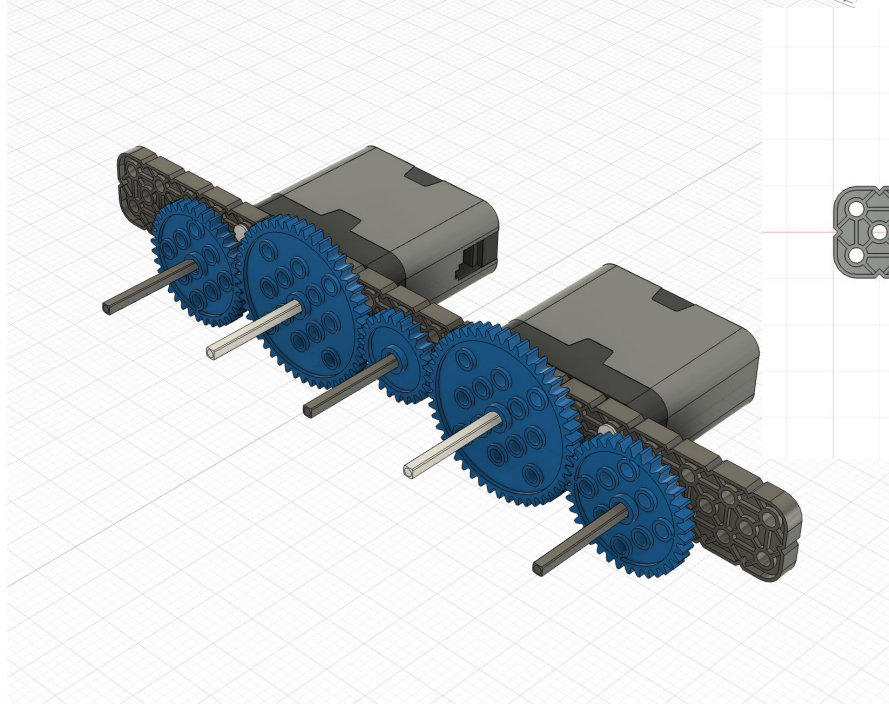
- 1 2x20 Beam
- 2 Motors
- 2 Green Cap Motor Shafts
- 10 Single Sided White Pins



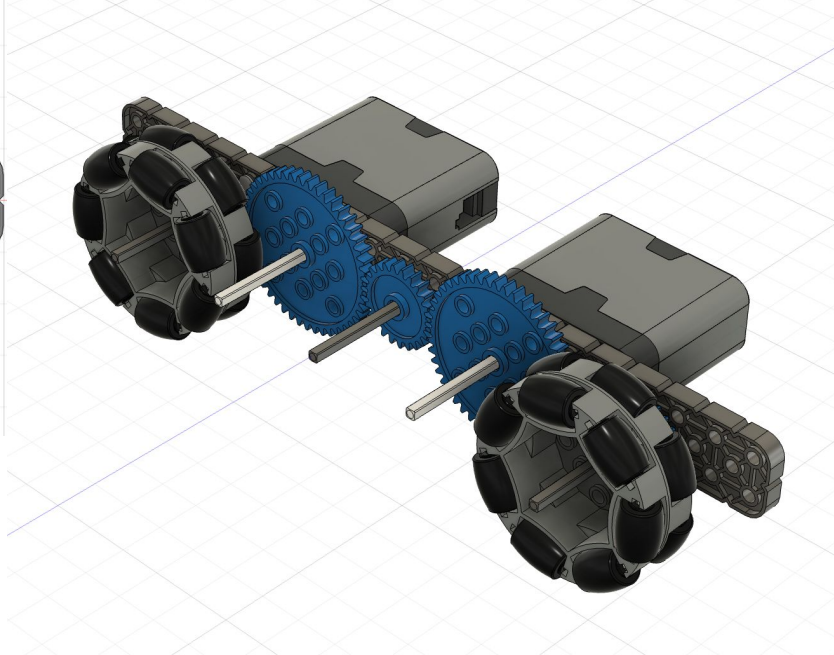
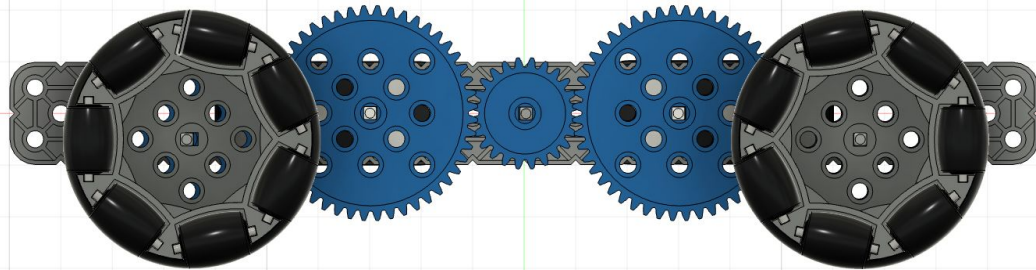
- 4 4x Pitch Capped Shafts



- 4 0.25x Pitch Spacers ( $\frac{1}{8}$ " )

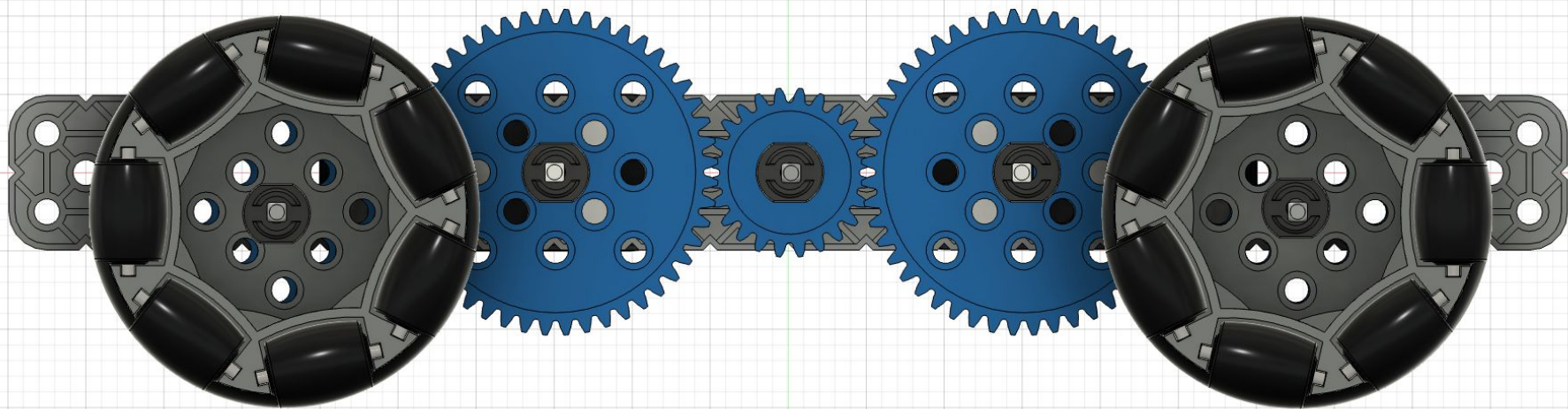


- 2 48T Gears
- 2 60T Gears
- 1 24T Gear

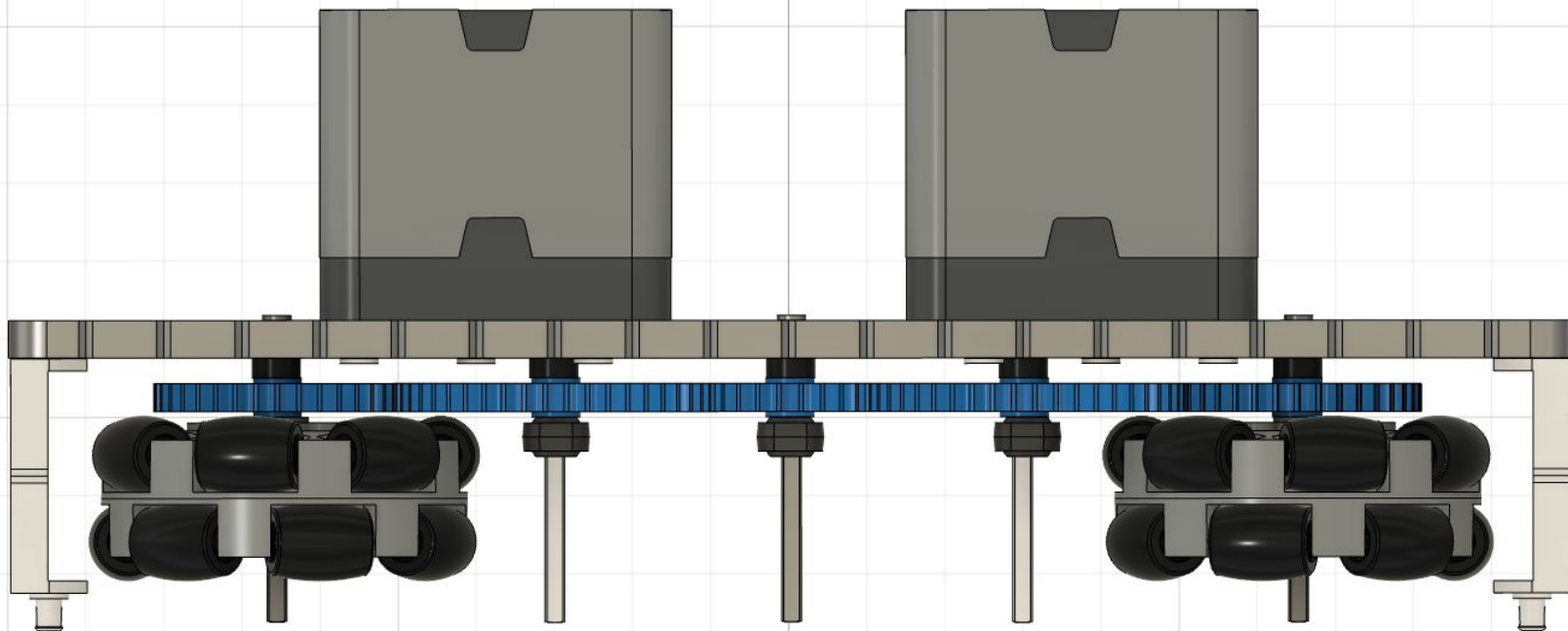


- 2 Omni-Directional Wheels



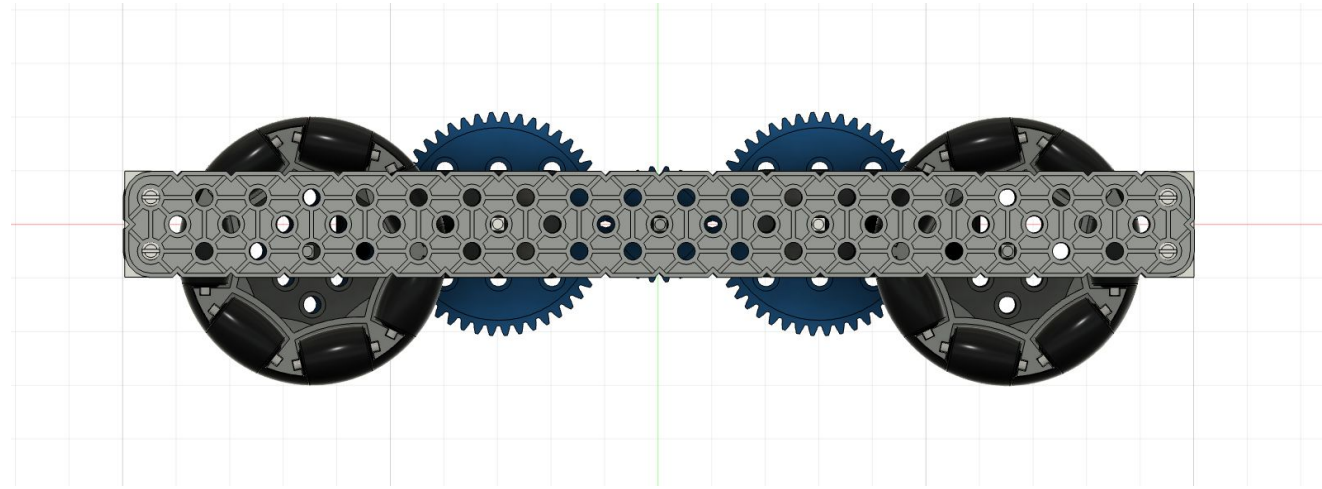
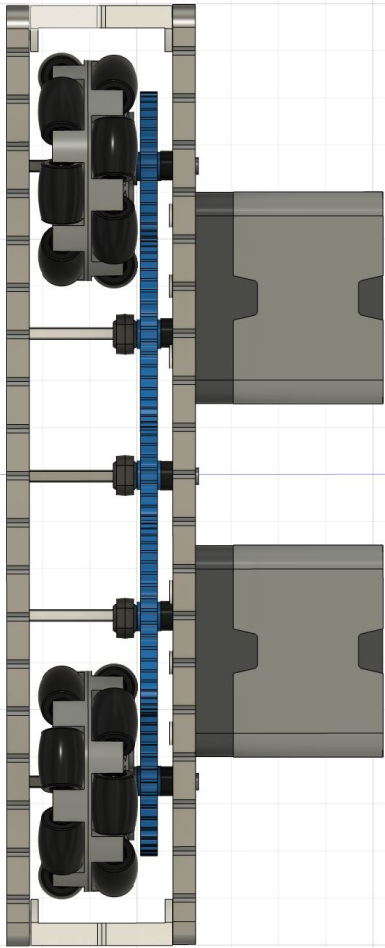


- 5 Rubber Shaft Collars

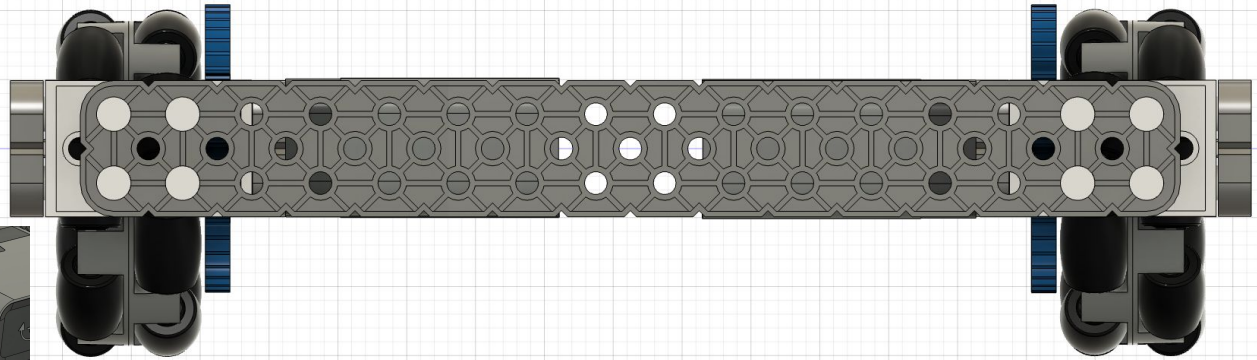
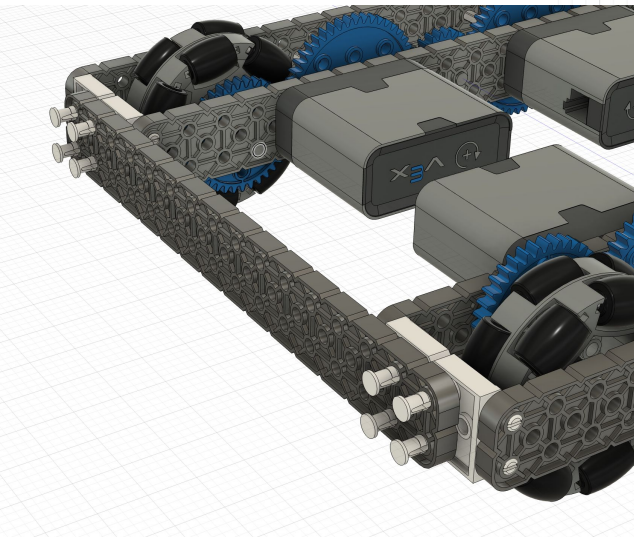


- Two Double 2x Wide 2x2 Connector

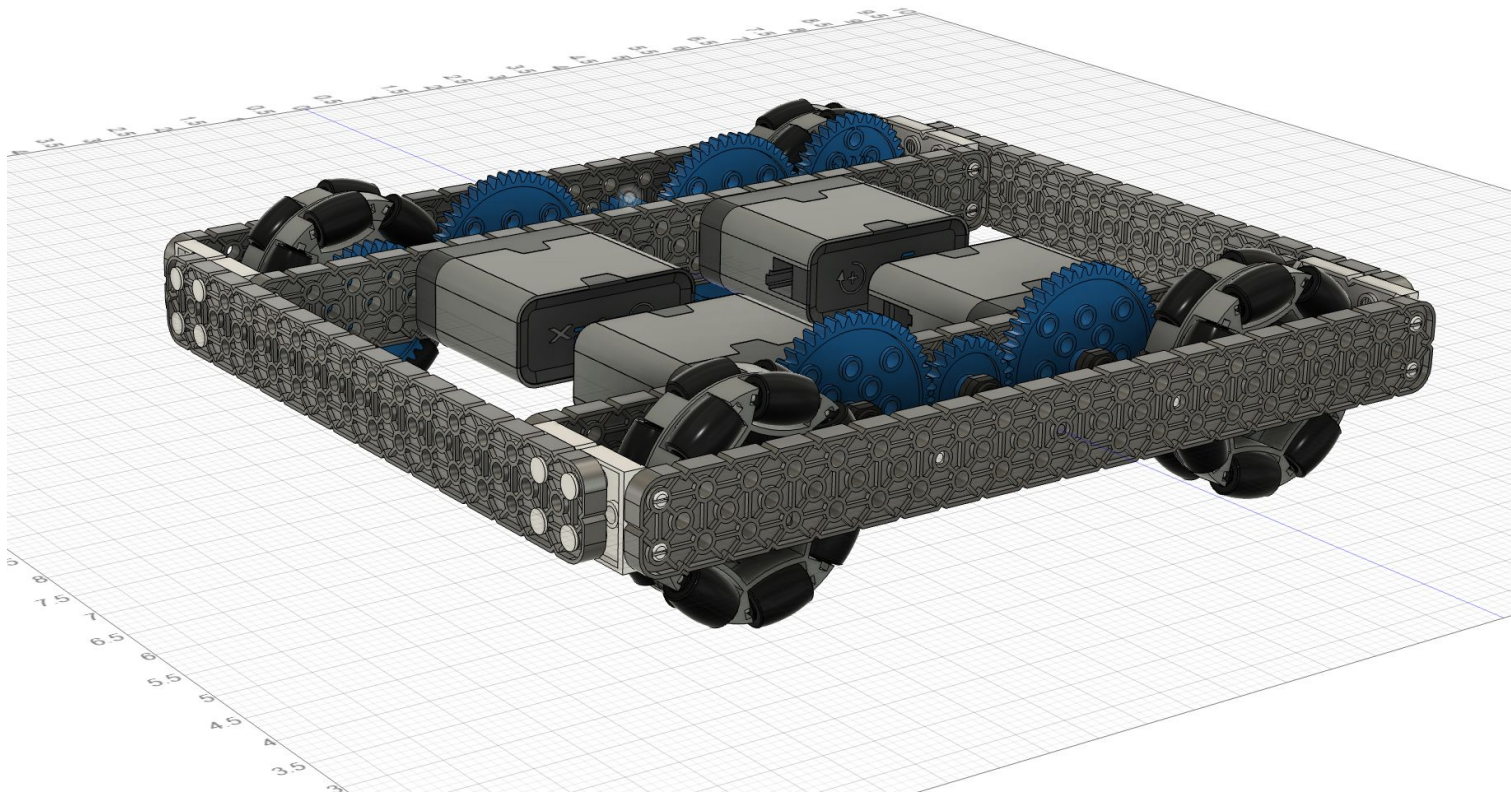




- 1 2x20 Beam



- 1 2x16 Beam
- 8 Single Sided White Pins



Same thing, other side



Figure out how to attach  
Brain onto the robot