

CS230 - Learning to Play Minichess Without Human Knowledge

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Abstract

- Implementing a self play based algorithm using neural nets has become popular after the huge success of Alpha Zero by Deep Mind.
- Replicating the results for games with larger search space like chess requires scaling.
- We develop a scaled up version of alpha-zero-general for the game of Minichess and evaluate our learning algorithm with various baselines.

Keywords: CNN, Reinforcement Learning, Distributed Computing, Monte Carlo search

Introduction

- Self play and improve without any human knowledge.
- MCTS provides provides ground truth to compare and learn.
- 5X5 chess board with Gardner layout will be used for our training.

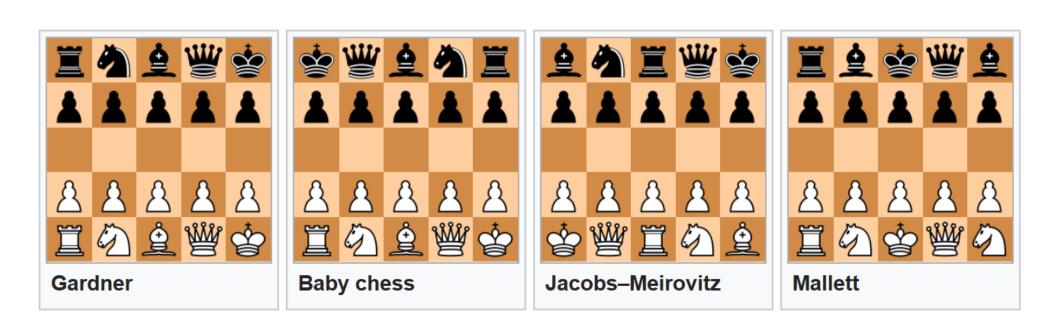


Figure 1:Popular Minichess Board Layouts

- Single Neural network used for both Policy and Value evaluation
- We will use the following Loss function

$$l = -\sum (v_{\theta}(s_t) - z_t)^2 + \vec{\pi_t} log(\vec{p_{\theta}}(s_t))$$

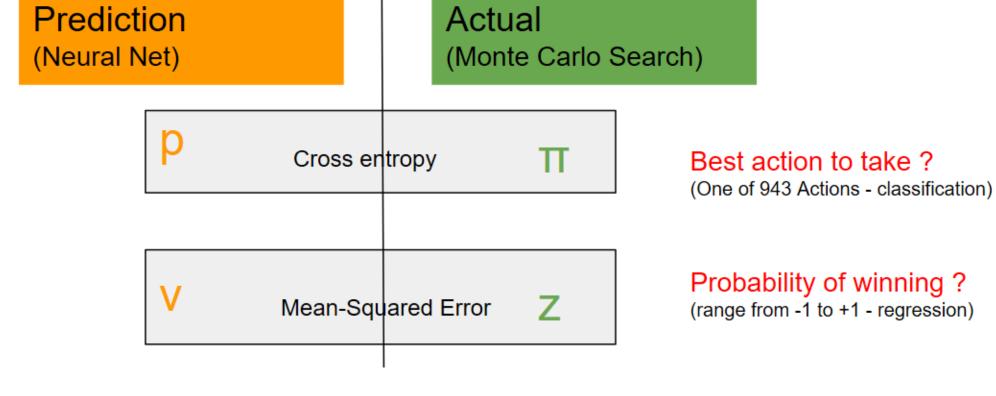


Figure 2:Parameters in network and choice of loss functions

Distributed Architecture

Three major components in self play and learn are:

- Training Data Generator Plays games and generates data for training.
- Trainer Consumes the data from Training Data Generator, compares against MCTS and learns.
- Pitter Compares two models and publishes a winner model.

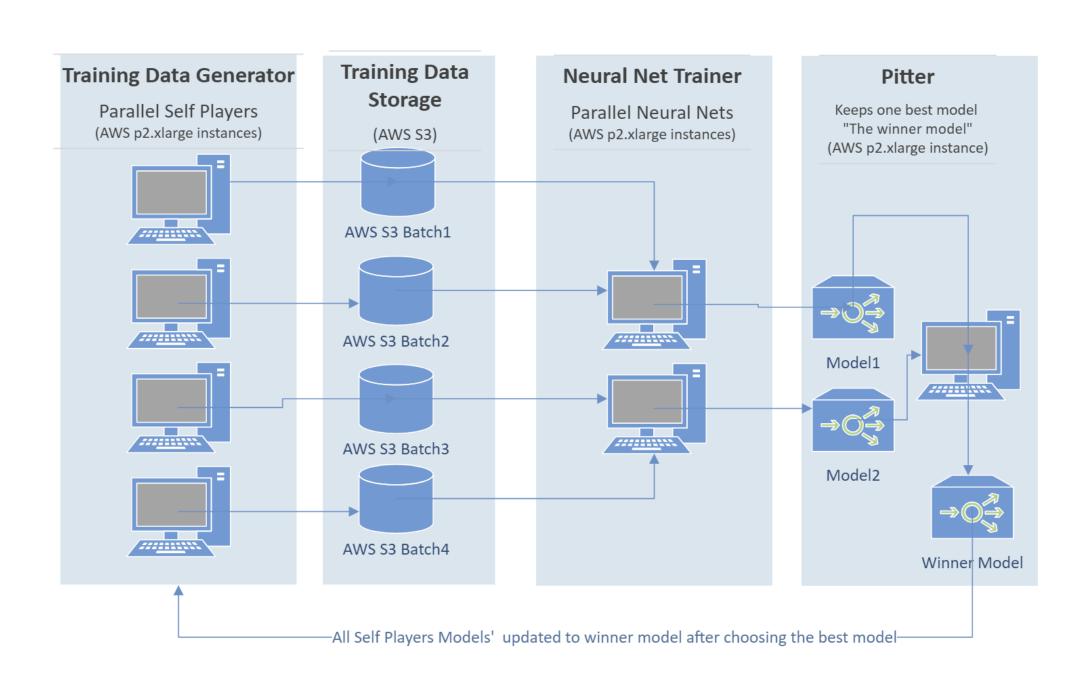


Figure 3:Scaling up the training using Distributed Architecture

Neural Network Model

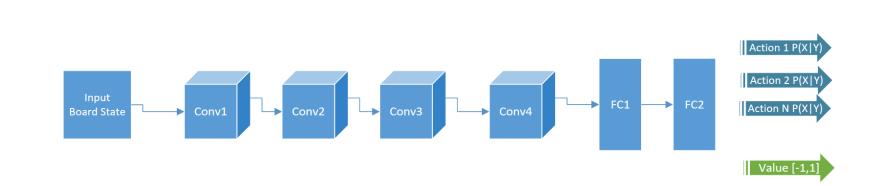


Figure 4:CNN Layers with both Policy and Value output

Туре	Value	Туре	Value	
MCTS Simulations	200			
Exploration (cpuct)	1	Value Activation	tanh	
Learning Rate	0.0005	Policy Activation	Softmax	
Update Threshold	0.5	Batch Size	128	
Arena Compare	20	Number of Layers	7 (4 CONV, 3 FC)	
Iterations	100	Regularization	Dropout (0.2)	
Episodes	100	Optimizer	Adam	
Data Augmentation	Two way Symmetry	Normalization	Batch Normalization	

Figure 5: Hyperparams used for Pre-processing and Training

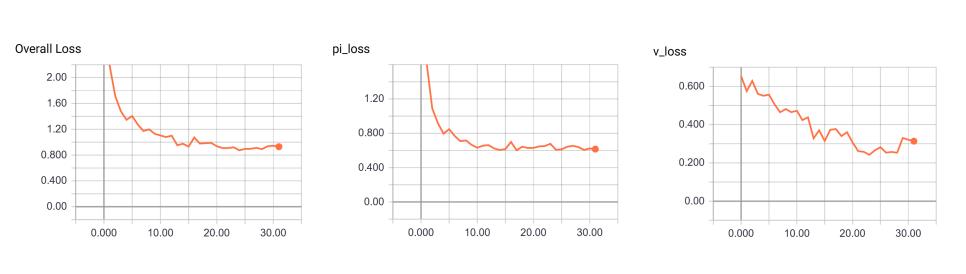


Figure 6:Loss values after each epoch

Baseline Comparison

Baseline	Color	Won	Lost	Draw
Random Player	White	10	0	0
	Black	10	0	0
Greedy Player	White	10	0	0
	Black	3	0	7
Model Version 1	White	10	0	0
	Black	7	0	3
Model Version 5	White	10	0	0
	Black	0	0	10
Model Version 15	White	0	0	10
	Black	0	0	10

Figure 7:Results of pitting Best Model (V21) with other players

Chess Layout	Baseline	Color	Won	Lost	Draw
BabyChess	Random	White	10	0	0
		Black	9	1	0
	Greedy	White	10	0	0
		Black	0	10	0
Mallot	Random	White	10	0	0
		Black	9	1	0
	Greedy	White	10	0	0
		Black	10	0	0

Figure 8:Trained on Gardner and transferred to other layouts

Performance Improvements

• 2.5 times improvement in training speed with distributed setup.

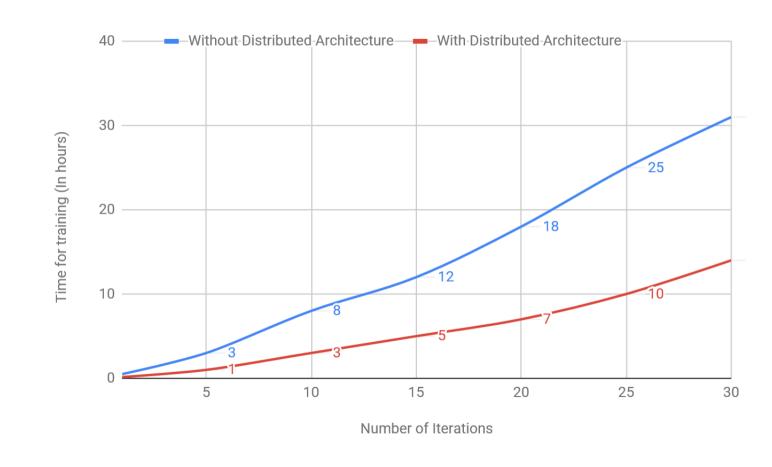


Figure 9:Single CPU vs Distributed Architecture

After 21 iterations of training, when evaluated:

- Defeats random player 100%.
- Defeats greedy player 100% when Neural Net takes first turn (White)

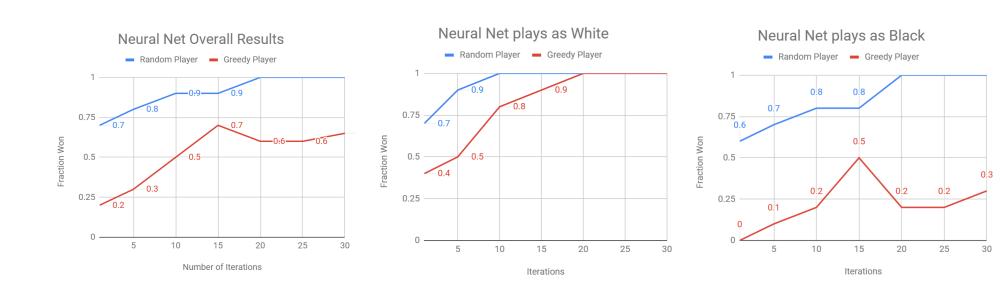
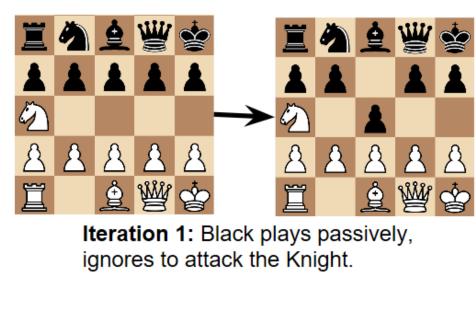
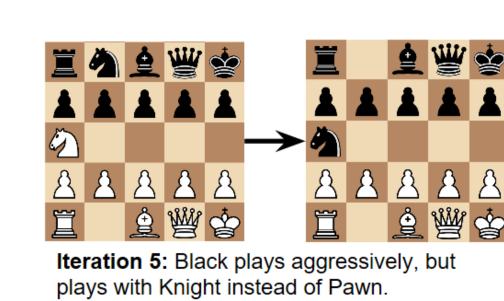
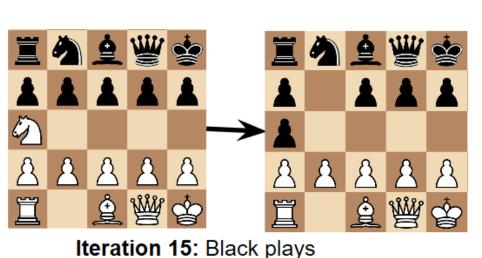


Figure 10:Performance of Neural Net over other baselines

Observations







aggressively, and uses Pawnt.

Iteration 30: During self play at higher iterations 30+, most games ends in Draw

Conclusion

- Trained model beats the random, greedy baselines and performs decently on other layouts.
- Monte Carlo Tree Search and CNN can approximate search space as large as $9 * 10^{18}$ as we seen in Minichess.
- Parallelizing self play, training and pitter by leveraging cloud services improves the performance substantially

References

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- Learning to Play Othello Without Human Knowledge Surag Nair et al
- Mastering Chess and Shogi by Self-Play with a General Reinforcement Learning Algorithm. Silver et al. 2017a

Contact Information

- Web: https://github.com/karthikselva/alpha-zero-general/tree/minichess
- Demo Video: https://youtube.com/wahch?aw3rrfdf5
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