

# CS3.301 Operating Systems and Networks

## Persistence: Hard Disks

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# Acknowledgement

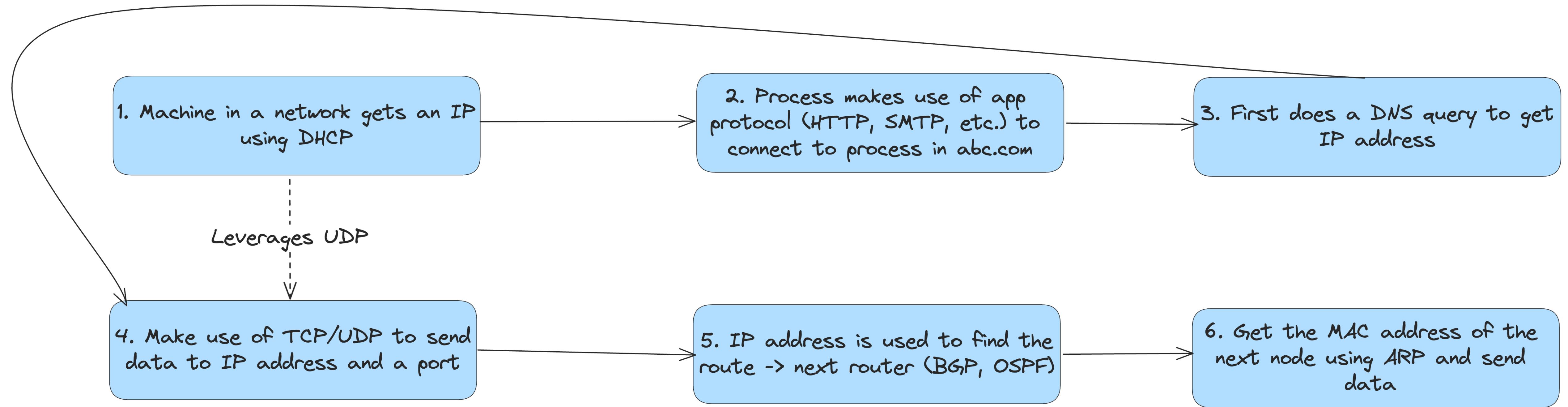
The materials used in this presentation have been gathered/adapted/generate from various sources as well as based on my own experiences and knowledge -- Karthik Vaidhyanathan

## Sources:

- Computer Networks, 6e by Tanbaum, Teamster and Wetherall
- Computer Networks: A Top Down Approach by Kurose and Ross
- Computer Networking essentials, Youtube Channel
- Other online sources which are duly cited



# Putting it together for Networks

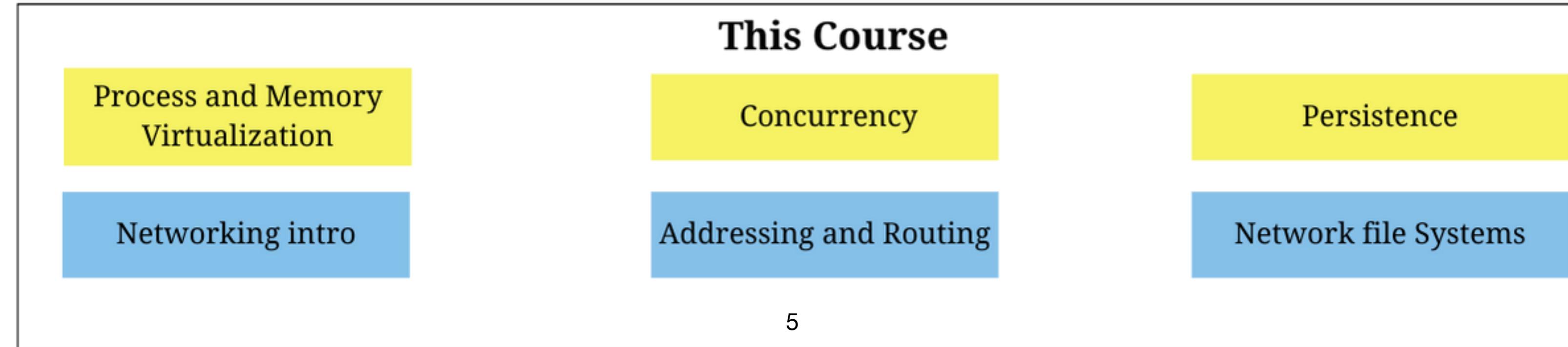
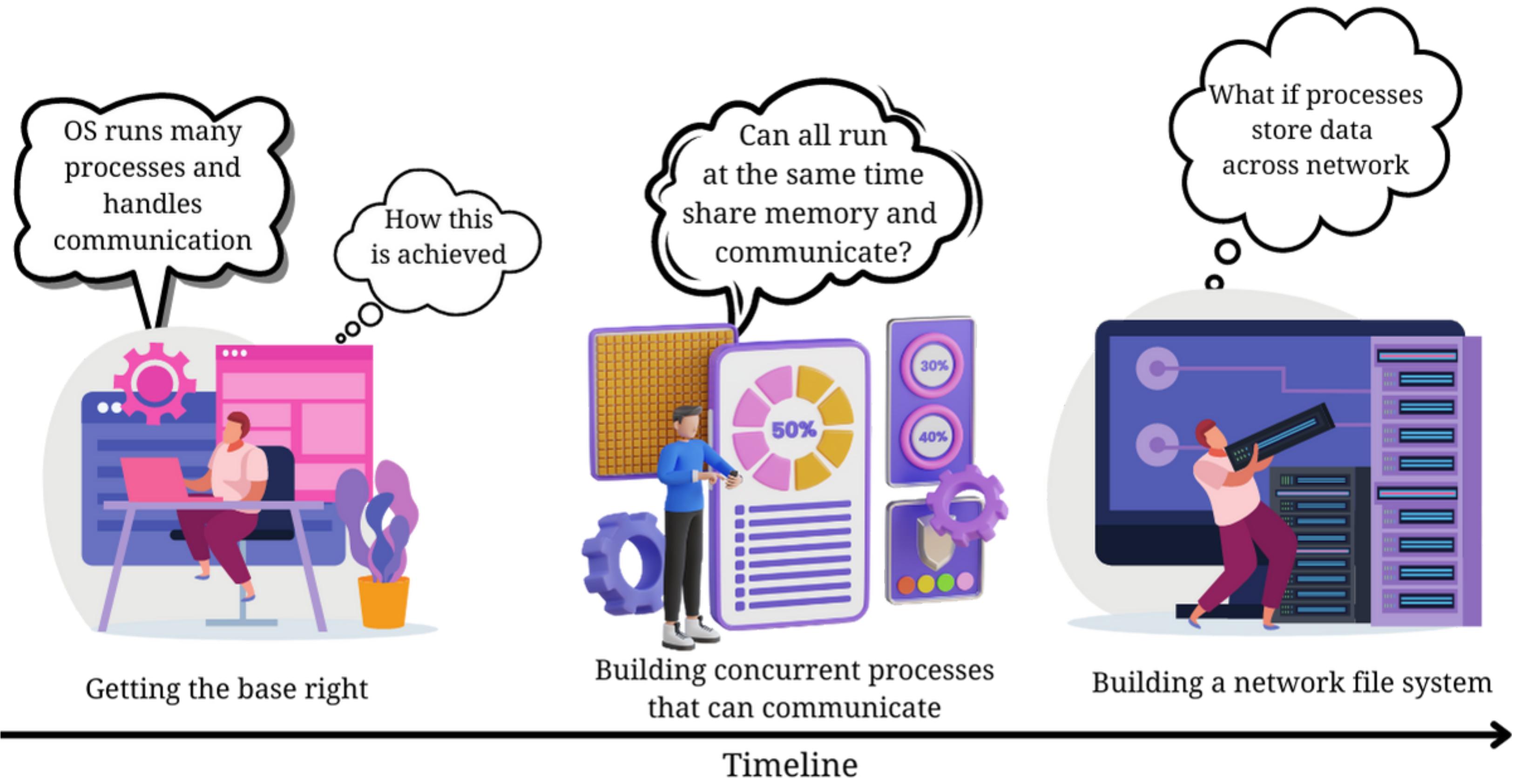


**Wait we still have one main part**

**How does OS handles the data and how is it stored?**



# Lets go to the final part

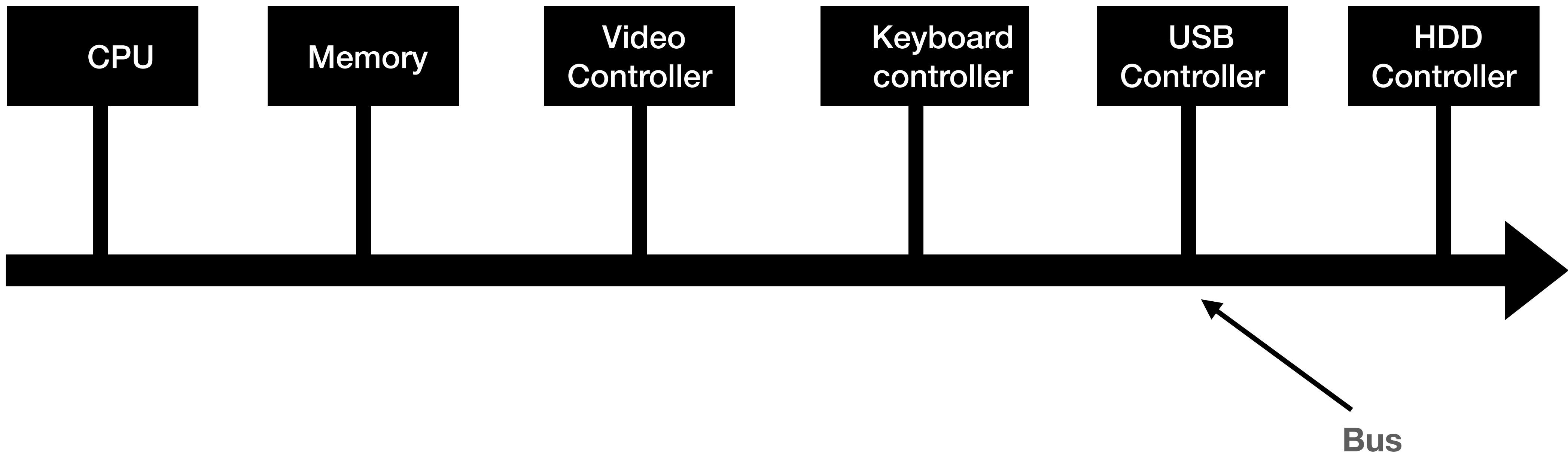


# Persistence

- RAM is Volatile - Again we need two parts here
- **Hardware and software** are needed to store data persistently
  - Hardware: I/O devices such as hard drive, SSDs, etc.
  - Software:
    - File system manages the disk
    - File system is responsible for any files that the user creates
    - Read, writes are handled by file system which interacts with low level device drivers



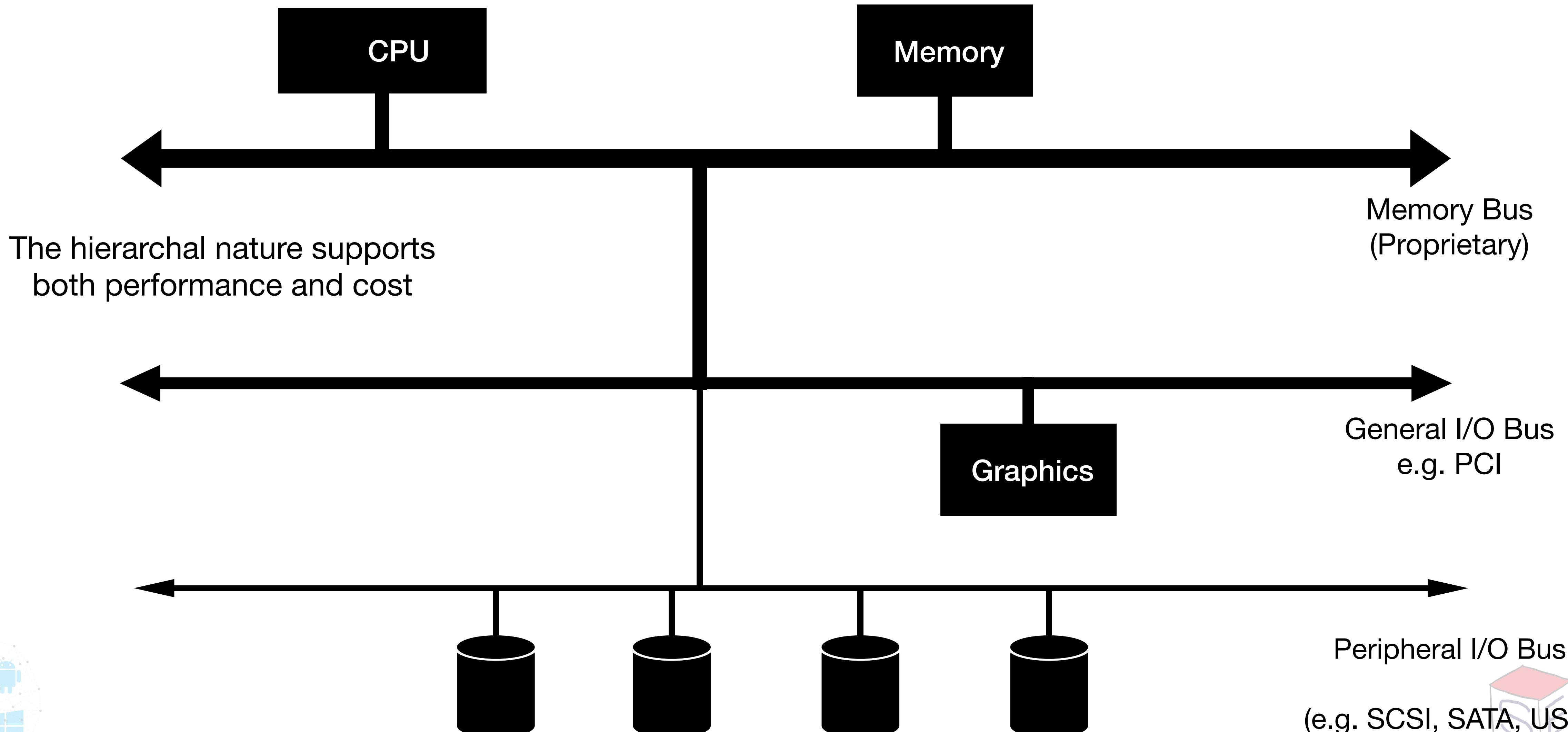
# Some Prerequisite



As we go more away from CPU, the more time it takes

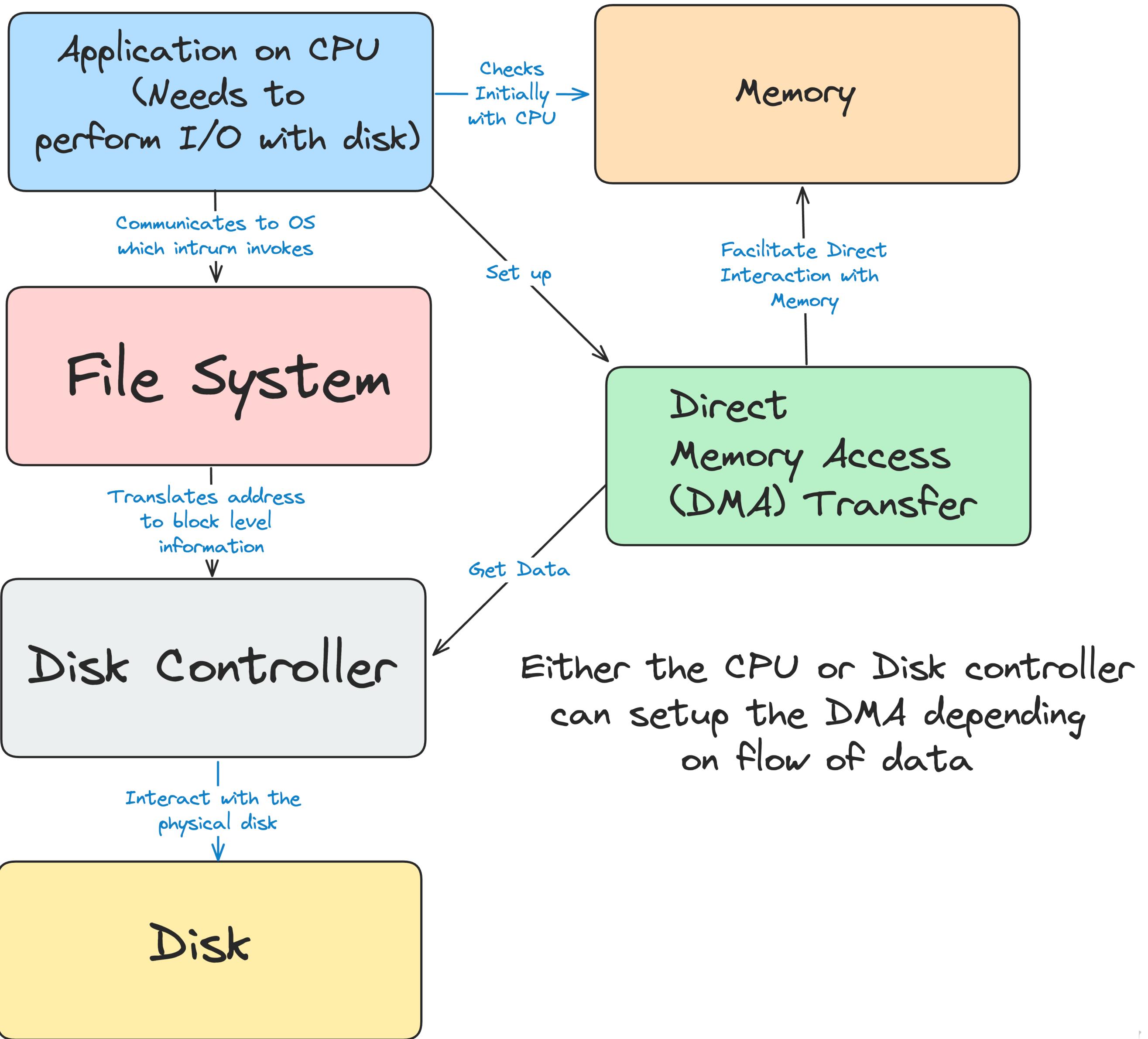


# Prototypical System Architecture



# The flow of access

- Application performs read or write to a file
- CPU communicates to OS which invokes the File System (FS)
- The OS may check in its cache if its already there
- FS prepares block level information to disk controller
- A Direct Memory Access (DMA) is set up
- Disk controller performs the physical read or write based on commands from DMA and file system
- If its read, Disk -> DMA, for writes, DMA -> Disk



# Hard Disk and How it works!

- Main form of storage in computer systems over decades
- How to store and access data?
  - How do modern hard disks store data?
  - What is the interface?
  - How is the **data laid out and accessed?**
  - How does **disk scheduling** improve performance?

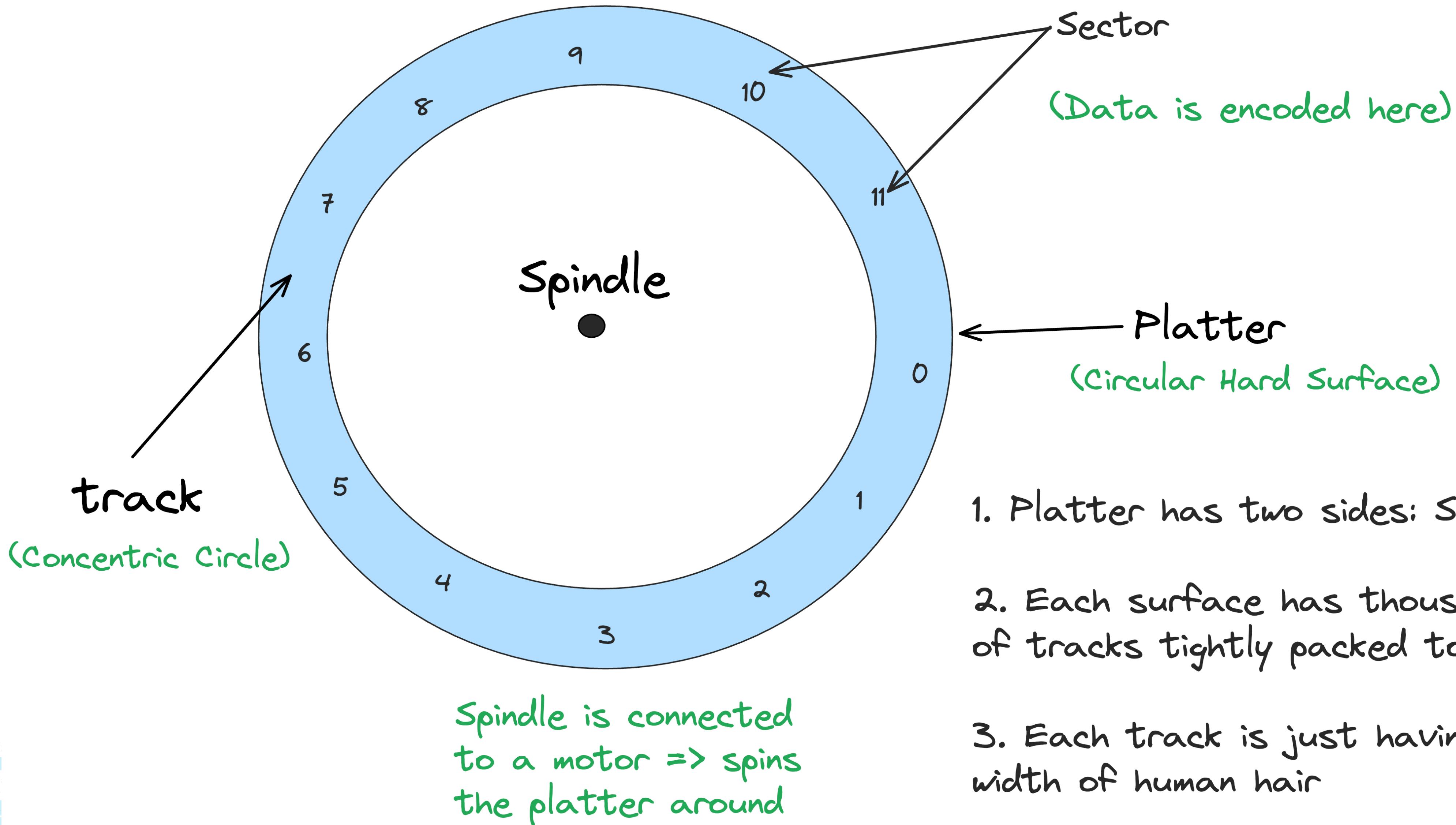


# Interface to Hard disk

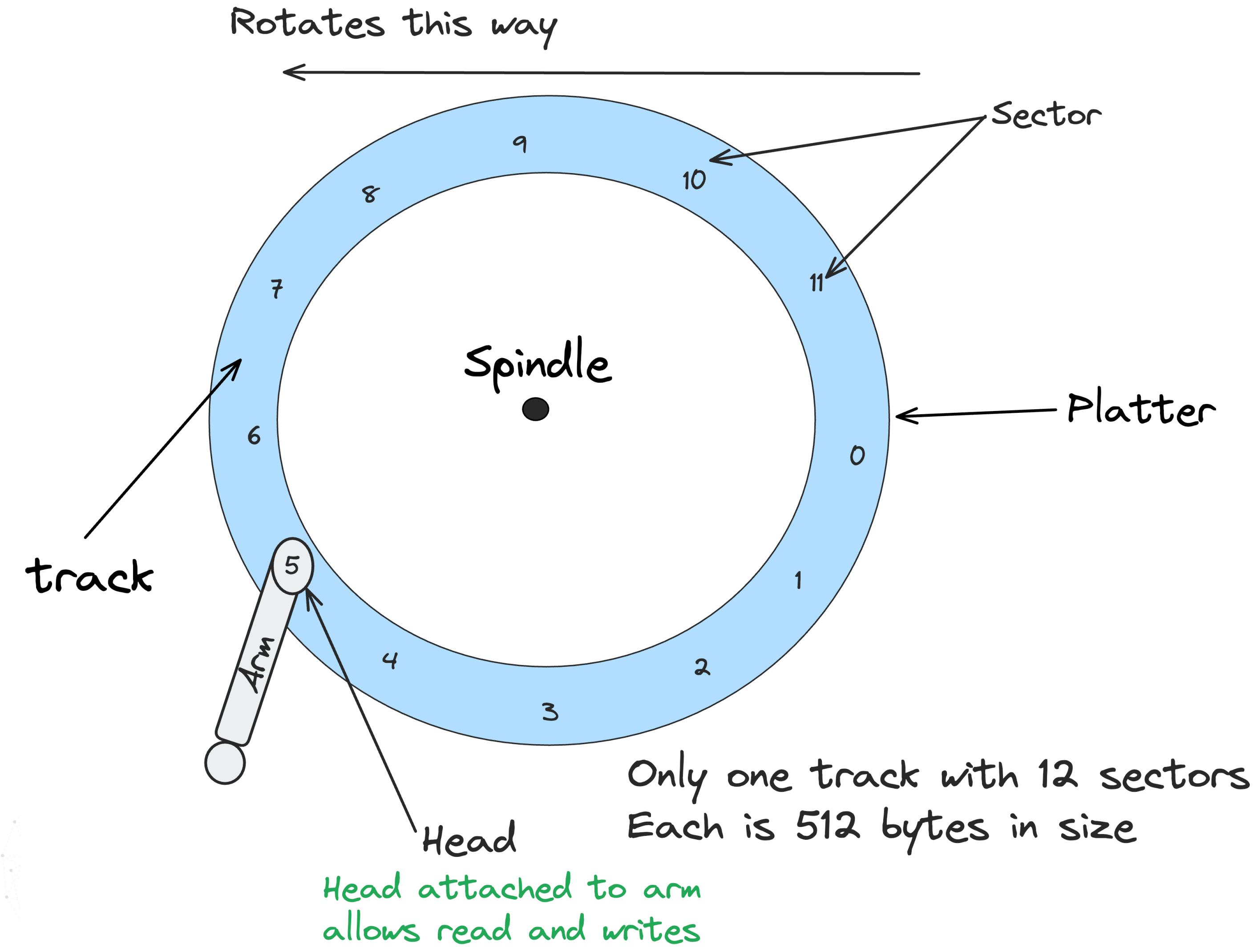
- Drive consists of a number of 512 byte blocks each of which can be read or written
- Sectors are numbered from  $0$  to  $n-1$  on disk with  $n$  sectors - **Address space**
- Many file systems read or write **4 KB** at a time (or more)
- The main guarantee that is provided is that a single 512 byte write is **atomic**
  - Either it happens completely or not at all
- Power loss in between can result in a portion of write becoming incomplete (**torn write**)



# Basic Geometry



# Simple Disk Drive



- Disk arm moves across to support reads and writes
- Spindle connected to a motor, spins the platter around at a constant fixed rate
- The rate is measured in rotations per minute (RPM)
- Modern values in range **7200 to 15000 RPM**
- For drive that rotates at 10,000 RPM, single rotations takes at **6ms**

# Single-Track Latency: Rotational Delay

- Consider in the previous case that the access has to be done in block 0
  - Remember that the disk rotates and as soon as the head reaches the desired sector (block), it can read
  - The position of head was at sector 5
  - It has to wait for the disk to rotate and the head to reach at sector 0
  - This is known as **rotational delay** or **rotation delay**
  - What if the read access request arrived for sector 4?

Almost full rotation!!

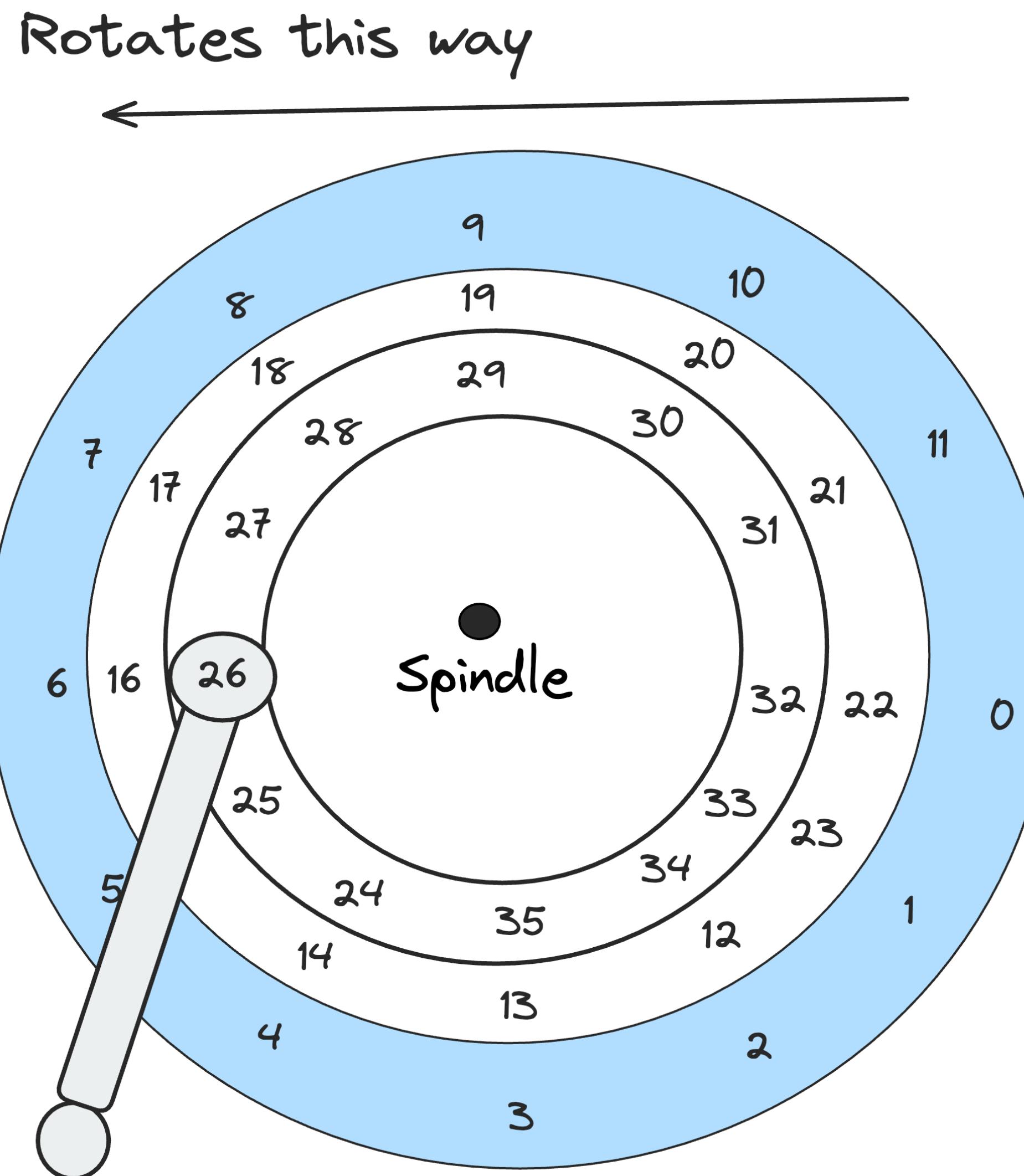


# But Disk is not just about Single Tracks



Source: Times of India

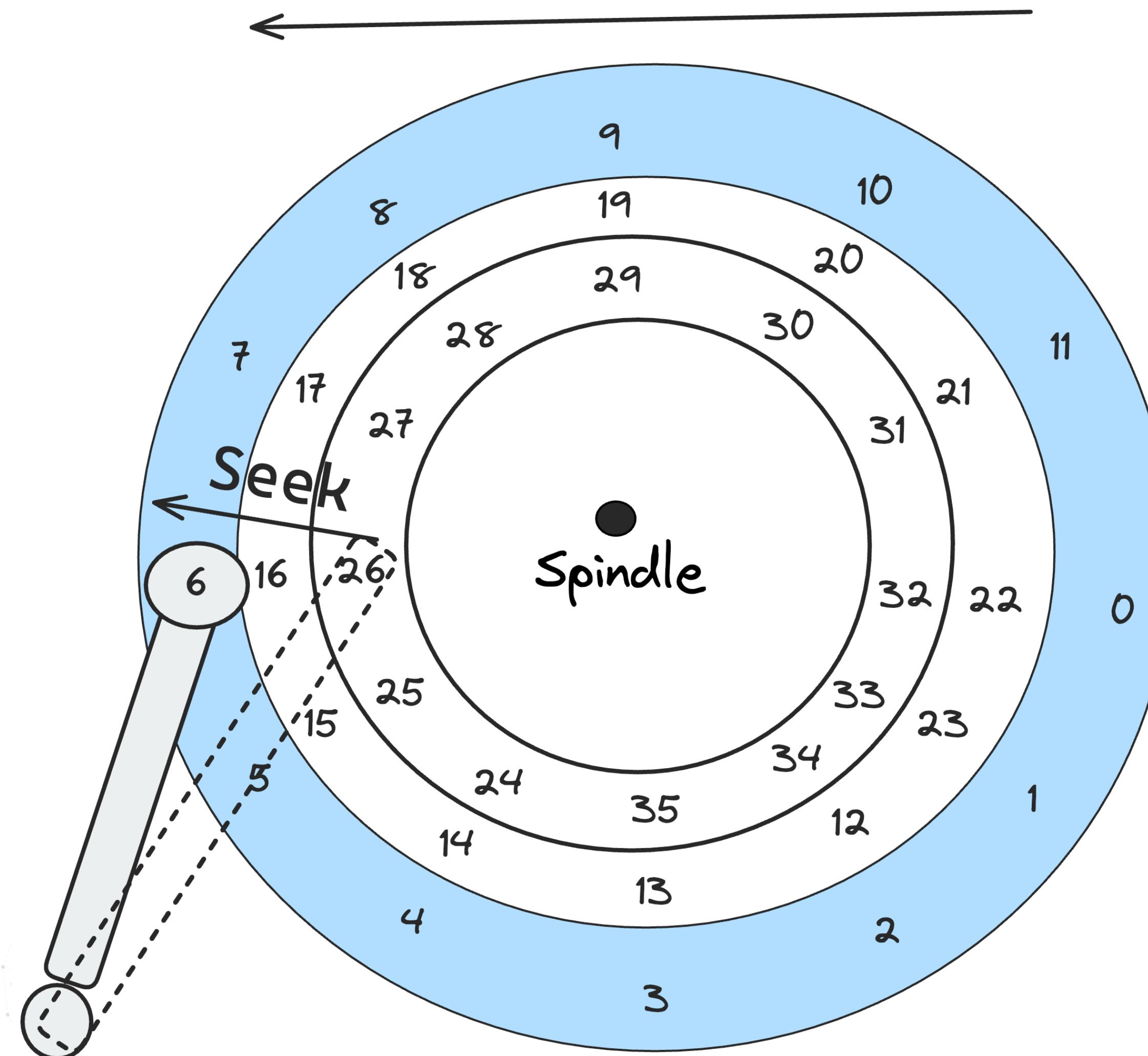
# Multiple Tracks: Seek Time



- Its not just about rotational delay
- In a real setting, a disk surface has 100s of tracks
- Read or write may happen at any block located in different tracks
- Rotation will only help in movement within a track
- Across tracks, the operation performed is **Seek**

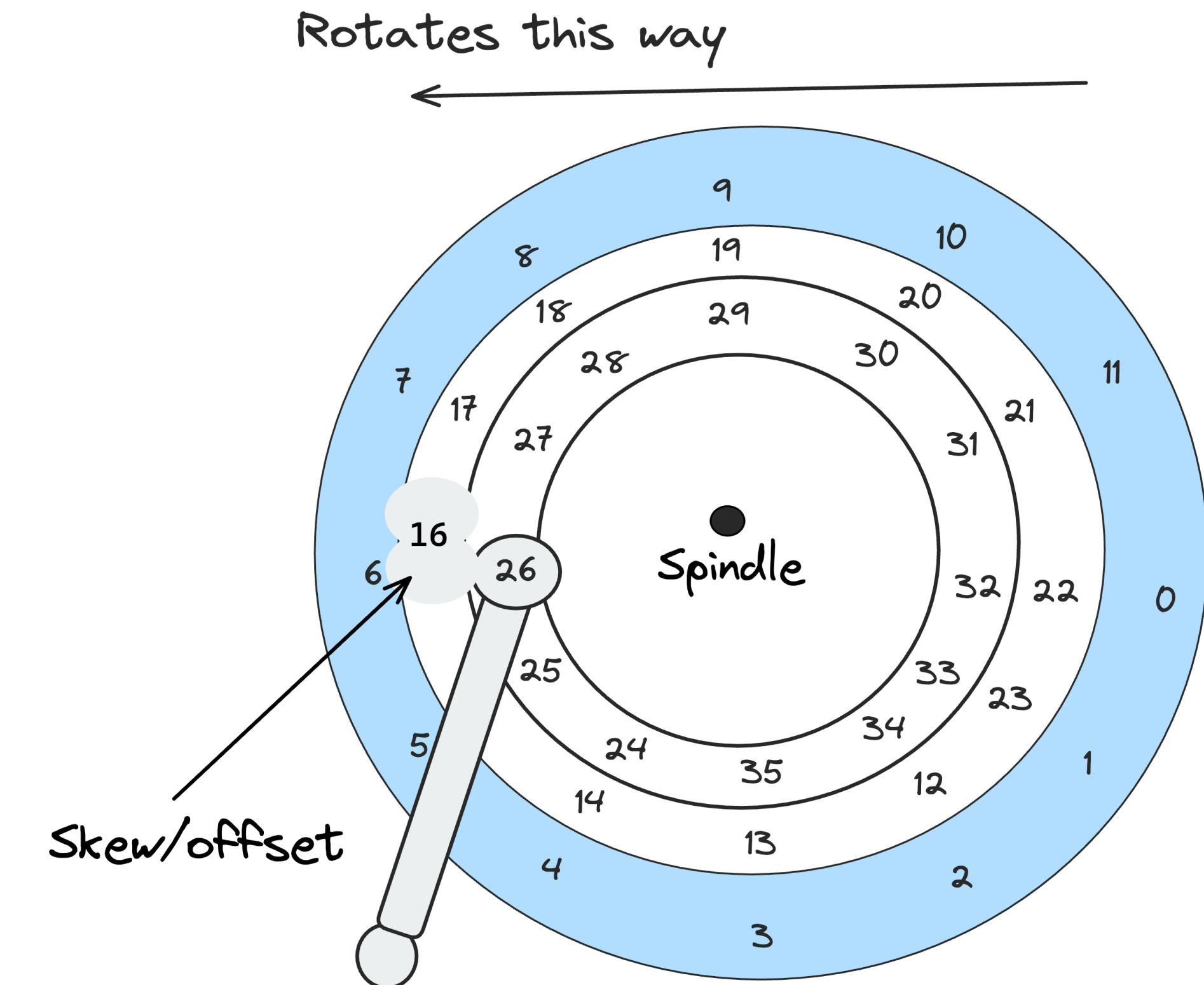
# Multiple Tracks: Seek Time

Rotates this way



- Seek is a costly operation in terms of time
- Seek has multiple phases
  - **Acceleration:** Arm starts moving
  - **Coasting:** Arm moving at full speed
  - **Settling:** Head over correct track
- Settling time is 0.5 - 2ms High!
- Final phase of I/O is **transfer** - Read or write from surface
- **Seek, rotate and transfer** - three key phases

# We may also have to consider skew



- Many drives use some kind of **track skew** to make sure that sequential reads can be properly serviced
- When head moves from one track to another:
  - By the time the head moves, the desired block in the track would have got rotated
  - Head would now have to wait for a longer rotational delay
- To avoid this, the beginning of the next track is slightly offset or **skewed**
- This is done to optimize performance



# Modern Disk Drives also have Cache!

- The cache is often referred to as **Track buffer**
  - Allow the drive to quickly respond to requests
  - Small amount of memory (usually around 8 to 16 MB)
  - Can be used by drive to read from/write to the disk
- **Reads:** When reading from one sector, read all sectors in that track and cache
  - Subsequent reads can be very fast
- **Writes:** Two choices: **Write through** and **Write back**



# Write on Cache

- **Writeback** (Immediate reporting)
  - Acknowledge a write has completed as soon as the data reaches cache memory
  - It makes drives appear very fast but it can be dangerous
  - Especially if order needs to be preserved - **This can lead to problems!**
- **Writethrough**
  - Acknowledge when the write has been written to the disk
  - Here data written to cache is also written to cache and disk simultaneously
  - Overall performance here might be an issue



# Some Analysis

- Disk rotates at **10,000 RPM** and has transfer rate of **100 MB/sec**
  - **How much milliseconds does a single rotation take?**
    - 1 minute = 60 seconds = 60,000 ms
    - 10,000 RPM in 60,000 ms => **6 ms for 1 rotation**
  - **How much time to transfer 512 KB blocks of data?**
    - 0.5 MB of data
    - 100 MB/sec => 0.1 MB/ms => **5 ms for 0.5 MB of data**



# I/O Time of Disk

$$T_{I/O} = T_{seek} + T_{rotation} + T_{transfer}$$

Rate of I/O  $R_{I/O} = \frac{Size_{transfer}}{T_{I/O}}$

- We can perform different analysis given some characteristics
- Assume that there are two different workloads
  - Random workload
  - Sequential workload



# I/O Time of Disks

- **Random Workload**
  - Issues small (4 KB) reads to random locations on the disk
  - Very common in applications like Database management systems
- **Sequential Workload**
  - Reads large number of sectors consecutively from disk
  - These are also quite common!
  - Given workload, can we perform some comparison on the disk performance
  - We would also need some disk characteristics



# Disk Performance Analysis

Characteristic	Cheetah 15K.5	Barracuda
Capacity	300 GB	1 TB
RPM	15,000	7,200
Average Seek	4 ms	9 ms
Max. Transfer	125 MB/s	105 MB/s
Platters	4	4
Cache	16 MB	16/32 MB
Connects Via	SCSI	SATA

- What are some observations about the disks here?



# Some Observations

- One is about performance - Cheetah
  - Drives are engineered to spin as fast as possible
  - Delivers low seek time and fast transfer rate
- Another is about capacity of the storage - Barracuda
  - Cost per byte is important
  - Drives are slow but packs as many bits into given space



# Some Analysis

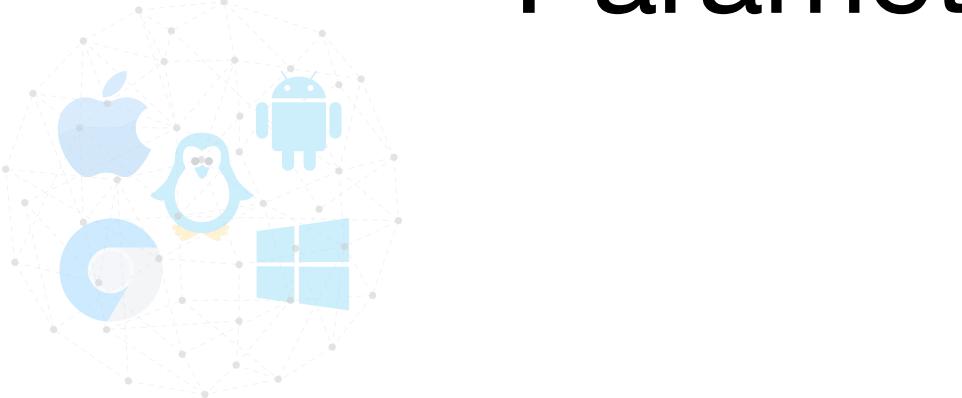
Workload	Metric	Cheetah	Barracuda
Random (4 KB reads)	Tseek	4 ms	9 ms
	Trotation	2 ms	4.2 ms
	Ttransfer	30 micros	38 micros
	TI/O	6 ms	13.2 ms
	RI/O	0.66 MB/s	0.31 MB/s
	Ttransfer	800 ms	950 ms
Sequential (100 MB reads)	TI/O	806 ms	936.2 ms
	RI/O	125 MB/s	105 MB/s

There is large difference in performance between **high-end performance drives** and **low-end capacity drives**

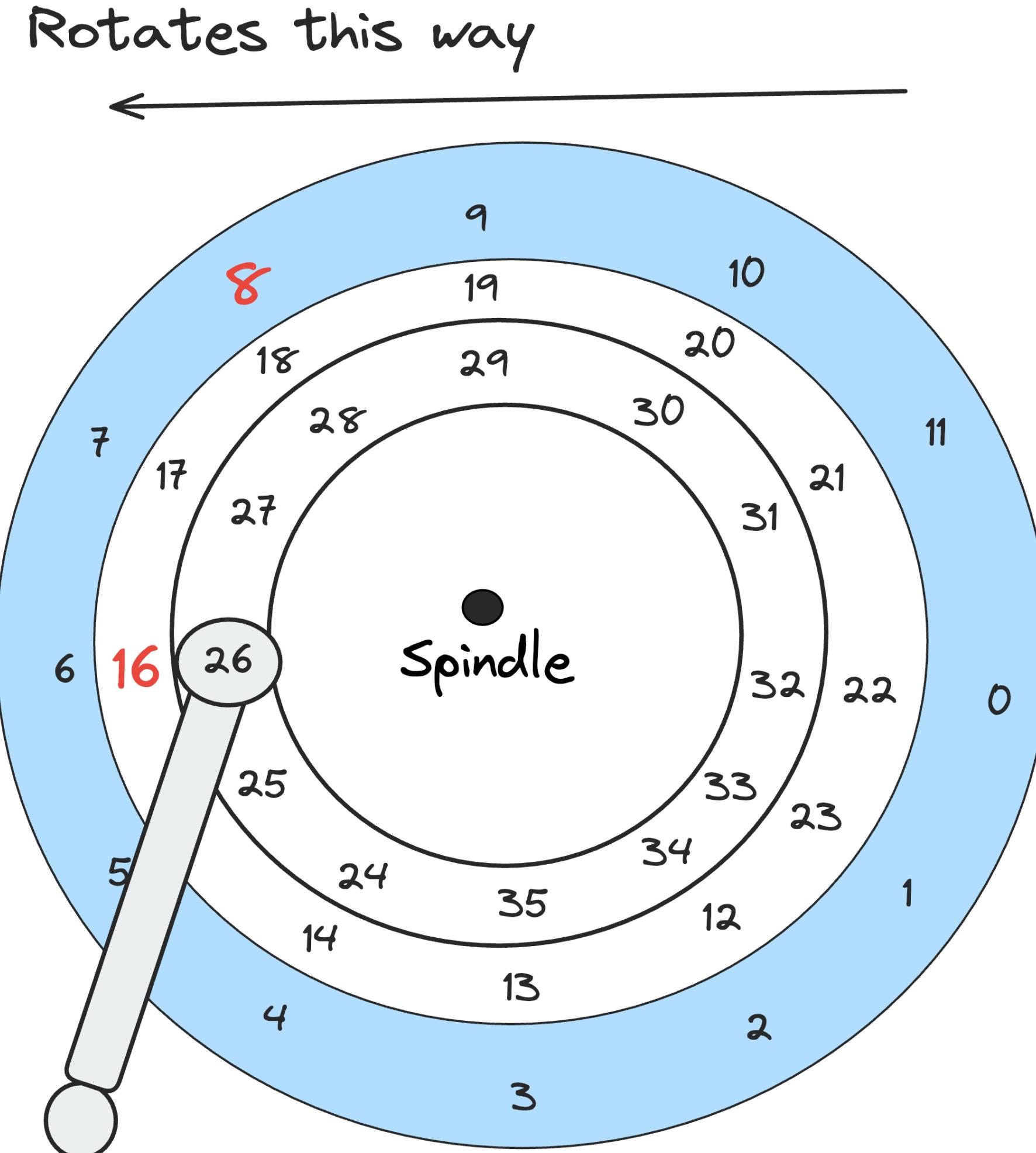


# Disk Scheduling

- OS plays a role in the order of I/O issued to disk
- Given a set of I/O requests, is it possible to schedule them in an order
  - Disk scheduler decides which I/O request to schedule next!
  - Decides which request to schedule to improve performance
- How can disk scheduler make a guess on what request shall be better?
  - Remember: Disk scheduler can estimate how much time each request can take
  - Parameters like rotational delay, transfer, seek are known/easily estimated



# SSTF: Shortest Seek Time First

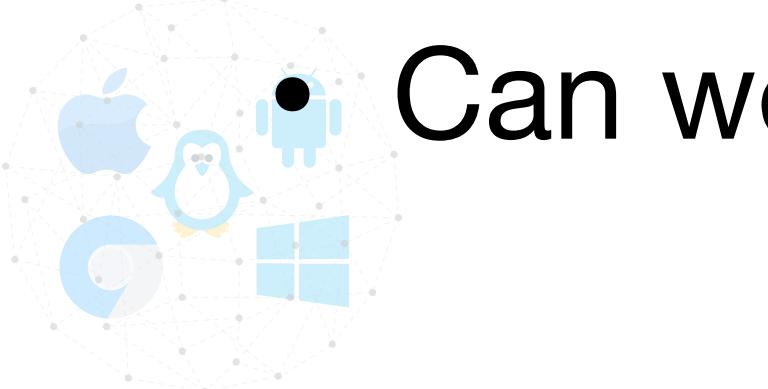


- Orders the queue of I/O requests by track
  - Pick the block in the queue from nearest track to complete first
- In this case
  - The closest one is 16
  - Followed by 8
  - Schedule: 16 → 8

Scheduling Requests: 8, 16

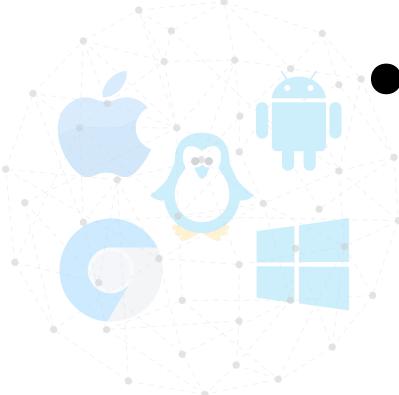
# Two main issues

- Drive geometry is not available to the OS
  - It sees everything as blocks
  - One way out: Implement something like **Nearest Block First (NBF)**
- There is another main issue: **Starvation!**
  - If there is a steady stream of requests to inner tracks
  - Request to outer tracks may be ignored completely leading to starvation
- Can we do something better to avoid starvation?

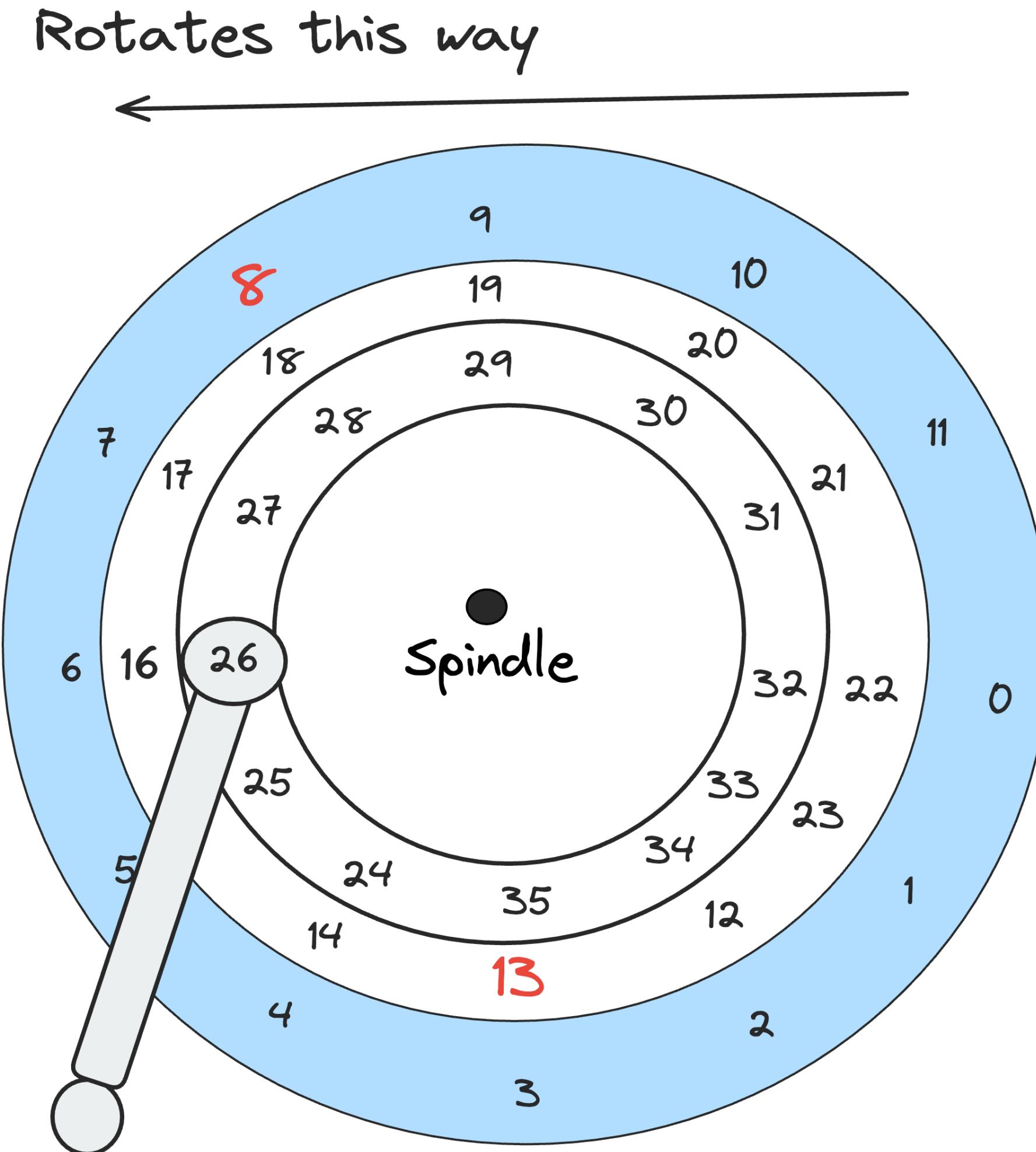


# Elevator (a.k.a SCAN or C-SCAN)

- Simply move back and forth, servicing the requests in order
  - **Sweep:** A Single Pass across the disk
  - If a request comes for a block on a track that has already been serviced in this sweep, it has to wait in a queue till the next sweep
- **F-SCAN**
  - Freeze the queue to be serviced when doing a sweep
  - Avoid starvation of far-away requests
- **C-SCAN (Circular scan)**
  - Sweep from inner-to-outer and outer-to-inner, etc.



# Shortest Positioning Time First



- Rotation and seek needs to be considered
- Which to give preference - **It depends!**
- Assume I/O requests to 8 and 13
  - Seek and rotation both are time consuming
  - Assume that seek is faster than rotation
    - 8 → 13 makes more sense
  - If rotation is faster than seek
    - 13 → 8 makes more sense



**Thank you**

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