Karthik Valmeekam

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Research Interests

My current research primarily focuses on the intersection of Large Language Models (LLMs) and reasoning, with a special emphasis on examining the planning capabilities of LLMs. This research involves two key aspects:

- o Identifying the inherent limitations of LLMs in generating plans, particularly in classical planning, and
- Demonstrating the constructive applications of LLMs as complementary tools alongside the robust planners developed in the AI Planning community.

Experience

May 2024 – August 2024 **3 mazon Science**, Applied Scientist Intern, Palo Alto, CA, United States.

Education

Fall 2021 - Spring 2026 Arizona State University, Tempe, AZ, United States

(Expected) Ph.D. in Computer Science, Advisor: Prof. Subbarao Kambhampati

Research: Large Language Models, Automated Planning, Reinforcement

Learning

GPA: 4.0/4.0

Fall 2019 - Spring 2021 Arizona State University, Tempe, AZ, United States

M.S. in Computer Science, Advisor: Prof. Subbarao Kambhampati

Thesis: A Study of Explainable Decision Support for Longitudinal Sequential

Decision Making

GPA: 4.0/4.0

Fall 2015 - Spring 2019 Vellore Institute of Technology, Vellore, TN, India

B.Tech. in Computer Science and Engineering

GPA: 9.19/10.0

Selected Publications and Manuscripts

ICML 2024 Subbarao Kambhampati, **Karthik Valmeekam**, Lin Guan, Kaya Stechly, Mudit Verma, Siddhant Bhambri, Lucas Saldyt, Anil Murthy. <u>LLMs Can't Plan, But Can Help Planning in LLM-Modulo Frameworks</u>. In Forty-first

International Conference on Machine Learning, 2024.

Arxiv Preprint Atharva Gundawar, Mudit Verma, Lin Guan, **Karthik Valmeekam**, Siddhant (Under Review) Bhambri, Subbarao Kambhampati. Robust Planning with LLM-Modulo Framework: Case Study in Travel Planning. arXiv preprint arXiv:2405.20625, 2024.

- Arxiv Preprint Kaya Stechly, **Karthik Valmeekam**, Subbarao Kambhampati. <u>Chain</u> (Under Review) of thoughtlessness: An analysis of cot in planning. arXiv preprint arXiv:2405.04776, 2024.
- Arxiv Preprint Subbarao Kambhampati, **Karthik Valmeekam**, Lin Guan. On the self-verification limitations of large language models on reasoning and planning tasks. arXiv preprint arXiv:2402.08115, 2024.
 - AAAI 2024 Subbarao Kambhampati, **Karthik Valmeekam**, Lin Guan. On the role of large language models in planning. Tutorial at the AAAI Conference on Artificial Intelligence, 2024.
 - NeurIPS 2023 Karthik Valmeekam, Matthew Marquez, Sarath Sreedharan, Subbarao Kambhampati. On the Planning Abilities of Large Language Models—A Critical Investigation. In Thirty-seventh Conference on Neural Information Processing Systems, 2023.

 Spotlight paper (Top 3%).
 - NeurIPS 2023 Lin Guan*, **Karthik Valmeekam*** (equal contribution), Sarath Sreedharan, Subbarao Kambhampati. Leveraging Pre-trained Large Language Models to Construct and Utilize World Models for Model-based Task Planning. In Thirty-seventh Conference on Neural Information Processing Systems, 2023.
 - NeurIPS 2023 Karthik Valmeekam, Matthew Marquez, Alberto Olmo, Sarath Sreedharan, Subbarao Kambhampati. PlanBench: An Extensible Benchmark for Evaluating Large Language Models on Planning and Reasoning about Change. In Thirty-seventh Conference on Neural Information Processing Systems Datasets and Benchmarks Track, 2023.
- FMDM @ NeurIPS 2023 Karthik Valmeekam*, Matthew Marquez* (equal contribution), Subbarao Kambhampati. Can Large Language Models Really Improve by Self-critiquing Their Own Plans?. In NeurIPS 2023 Foundation Models for Decision Making Workshop, 2023.
 - ICAPS 2023 Subbarao Kambhampati, **Karthik Valmeekam**, Matthew Marquez, Lin Guan. On the role of large language models in planning. Tutorial at the International Conference on Automated Planning and Scheduling (ICAPS), 2023.
 - ICLR 2023 Lin Guan, **Karthik Valmeekam**, Subbarao Kambhampati. Relative Behavioral Attributes: Filling the Gap between Symbolic Goal Specification and Reward Learning from Human Preferences. In The Eleventh International Conference on Learning Representations, 2023.
 - ICAPS 2022 Karthik Valmeekam, Sarath Sreedharan, Sailik Sengupta, Subbarao Kambhampati. RADAR-X: An Interactive Mixed Initiative Planning Interface
 Pairing Contrastive Explanations and Revised Plan Suggestions. In Proceedings of the International Conference on Automated Planning and Scheduling (Vol. 32, pp. 508-517), 2022.

Projects

2021 Reinforcement Learning for Imperfect Information Games

On a two-player imperfect information game (Sequence), an agent was trained offline by *approximation in value and policy space* using neural networks. In the test phase, the agent used one-step look-ahead using the trained network to make a move. This improved win percentage (upto 60%) with more training against a random agent.

2020 **High-Speed Autonomous Drifting using Deep Reinforcement Learning** An end-to-end drift controller which utilizes a state-of-the-art model-free reinforcement learning algorithm is modelled using *Pytorch*. This RL problem is devised as a trajectory following problem. The resulting agent was able to generate the required behavior.

Teaching & Service

Teaching Assistant 2021: CSE471-Intro to Artificial Intelligence by Prof. Subbarao Kamb-

hampati.

Reviewer/PCM 2024: ICLR, NeurIPS, AAAI-Student Program, ICRA.

2023: ICLR, NeurIPS, ICAPS, HAXP@ICAPS, GenPlan@NeurIPS.

2022: **XAIP@ICAPS.**

Student Volunteer 2021: AAAI, ICAPS.

Skills

Programming Python, C++, HTML/CSS, JavaScript, Bash, SAP-ABAP, SQL, PDDL

Frameworks Pytorch, Transformers (HuggingFace), PyTorch Lightning, Scikit-Learn,

Numpy, Pandas, OpenAl gym, Keras, NLTK, Flask, JQuery, Bootstrap

Misc Adobe Premiere Pro, Lightroom, Photoshop, Git, Latex

Honors

2024 SCAI Doctoral Fellowship (Merit-Based), Arizona State University.

2021 CIDSE Doctoral Fellowship (Merit-Based), Arizona State University.

2018 Vice Chair Management of the student chapter CODECHEF-VIT, Vellore Institute of Technology