

## EE23BTECH11024 - G.Karthik Yadav\*

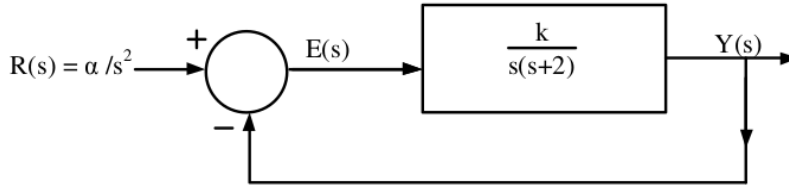
GATE 2023 EC 41

from eq (1)

1. A Closed loop system is shown in the figure where  $k > 0$  and  $\alpha > 0$ .

The Steady State error due to a ramp input ( $R(s) = \alpha s^{-2}$ ) is given by (GATE 2023 EC 41)

$$e_s = \frac{2\alpha}{k} \quad (6)$$



- 1)  $\frac{2\alpha}{k}$
- 2)  $\frac{\alpha}{k}$
- 3)  $\frac{\alpha}{2k}$
- 4)  $\frac{\alpha}{4k}$

**Solution:**

Symbol	Parameters	value
$R(s)$	Ramp input signal	$\alpha s^{-2}$
$G(s)$	Open Loop transfer function	$\frac{k}{s(s+2)}$
$e_s$	Steady State Error	?
$K_v$	velocity constant	?

TABLE I  
INPUT PARAMETERS

from table I The Steady State error is

$$e_s = \frac{\alpha}{K_v} \quad (1)$$

$$G(s) = \frac{k}{s(s+2)} \quad (2)$$

From the figure

$$K_v = \lim_{s \rightarrow 0} sG(s) \quad (3)$$

$$= \lim_{s \rightarrow 0} s \frac{k}{s(s+2)} \quad (4)$$

$$K_v = \frac{k}{2} \quad (5)$$