

FCFS

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <limits.h>
```

```
struct Process
```

```
{
```

```
    int id, at, bt, ct, tat, wt, pt;
```

```
    int completed; // To track completion
```

```
};
```

```
int findHighestPriority(struct Process p[], int n, int currentTime)
```

```
{
```

```
    int index = -1, highestPriority = INT_MAX;
```

```
    for (int i = 0; i < n; i++)
```

```
    {
```

```
        if (p[i].at <= currentTime && !p[i].completed) // Process must have arrived and not be completed
```

```
        {
```

```
            if (p[i].pt < highestPriority || (p[i].pt == highestPriority && p[i].at < p[index].at))
```

```
            {
```

```
                highestPriority = p[i].pt;
```

```
                index = i;
```

```
            }
```

```
        }
```

```
    }
```

```
    return index;
```

```
}
```

```
void NonPreemptivePriority(struct Process p[], int n)
```

```
{
```

```
    int completedCount = 0, currentTime = 0;
```

```
    float totalTAT = 0, totalWT = 0;
```

```

while (completedCount < n)
{
    int ind = findHighestPriority(p, n, currentTime);

    if (ind == -1) // If no process is available, move time forward
    {
        currentTime++;
    }
    else
    {
        // Process execution
        p[ind].completed = 1;
        completedCount++;
        currentTime += p[ind].bt;
        p[ind].ct = currentTime;
        p[ind].tat = p[ind].ct - p[ind].at;
        p[ind].wt = p[ind].tat - p[ind].bt;
        totalTAT += p[ind].tat;
        totalWT += p[ind].wt;
    }
}

printf("PID\tAT\tBT\tP\tCT\tTAT\tWT\n");

for (int i = 0; i < n; i++)
{
    printf("P%d\t%d\t%d\t%d\t%d\t%d\t%d\n", p[i].id, p[i].at, p[i].bt, p[i].pt, p[i].ct, p[i].tat, p[i].wt);
}

printf("Average TAT = %.2f\n", totalTAT / n);
printf("Average WT = %.2f\n", totalWT / n);
}

```

```
int main()

{

    int n;

    printf("Enter the number of processes: ");

    scanf("%d", &n);


    struct Process p[n];


    printf("Enter Arrival Time (AT), Burst Time (BT), and Priority (P) for each process:\n");

    for (int i = 0; i < n; i++)

    {

        p[i].id = i + 1;

        p[i].completed = 0; // Initially, no process is completed

        printf("P%d (AT, BT, P): ", p[i].id);

        scanf("%d %d %d", &p[i].at, &p[i].bt, &p[i].pt);

    }


    NonPreemptivePriority(p, n);

    return 0;

}
```

LRU

```
#include <stdio.h>

int main()

{

int reference [50],frame[50],fsize,i,j,flag=0,c=0,n,fault=0,k,recent[50],temp,flag1=0;

float miss,hit;

printf("Enter the number of references:");

scanf("%d",&n);

printf("Enter the references:");

for(i=0;i<n;i++)

scanf("%d",&reference[i]);

printf("Enter the frame size:");

scanf("%d",&fsize);

for(i=0;i<fsize;i++)

{

fault++;

frame[i]=reference[i];

recent[i]=reference[i];

c++;

}

recent[c]=0;

for(i=fsize;i<n;i++)

{

for(k=0;k<c;k++)

{

if(reference[i]==recent[k])

{

flag1=1;

break;

}

}

if(flag1==1)

{
```

```
temp=recent[k];

for(j=k;j<c;j++)

recent[j]=recent[j+1];

recent[c-1]=temp;

}

else

{

recent[c]=reference[i];

c++;

recent[c]=0;

}

flag1=0;

for(j=0;j<fsize;j++)

{

if(frame[j]==reference[i])

flag=1;

}

if(flag!=1)

{

fault++;

for(k=0;k<c;k++)

{

for(j=0;j<fsize;j++)

{

if(recent[k]==frame[j])

{

frame[j]=reference[i];

goto end;

}

}

}

}

end:
```

```
flag=0;

}

printf("Total number of fault=%d\n",fault);

miss=((float)fault/n)*100;

hit=((float)(n-fault)/n)*100;

printf("Total number of references = %d\n",n);

printf("Miss ratio=%.2f\n",miss);

printf("No.of Hits=%d\n",(n-fault));

printf("Hit ratio=%.2f\n",hit);

return 0;

}
```

SJF

```
#include <stdio.h>

#include <stdlib.h>

#include <limits.h>

struct Process{

    int id,at,bt,ct,tat,wt,completed;

};

int findshortest(struct Process p[],int n,int currentTime){

    int index=-1,bt=INT_MAX;

    for(int i=0;i<n;i++)

    {

        if(p[i].at<=currentTime&& p[i].completed!=0){

            if(p[i].bt<bt) {

                bt=p[i].bt;

                index=i;

            }

        }

    }

    return index;

}

void sjf(struct Process p[],int n)

{

    int completed=0,currentTime=0;

    float tot_tat=0,tot_wt=0;

    while(completed<n)

    {

        int ind=findshortest(p,n,currentTime);

        if(ind!=-1)

        {

            currentTime++;

        }

        else{

            currentTime=p[ind].bt+currentTime;

        }

    }

}
```

```

completed++;

p[ind].completed=0;

p[ind].ct=currentTTime;

p[ind].tat=p[ind].ct-p[ind].at;

p[ind].wt=p[ind].tat-p[ind].bt;

tot_tat+=p[ind].tat;

tot_wt+=p[ind].wt;

}

}

printf("PID\tAT\tBT\tCT\tTAT\tWT\n");

for(int i=0;i<n;i++)

{

printf("P%d\t%d\t%d\t%d\t%d\t%d\n",p[i].id,p[i].at,p[i].bt,p[i].ct,p[i].tat,p[i].wt);

}

printf("Average TAT=%f\n",tot_tat/n);

printf("Average WT=%f\n",tot_wt/n);

}

void main()

{

int n;

printf("Enter the number of process:");

scanf("%d",&n);

struct Process p[n];

printf("Enter the Arrival time(AT) and Burst Time(BT) \n");

for(int i=0;i<n;i++)

{

p[i].id=i+1;

printf("P%d(AT,BT):",p[i].id);

scanf("%d%d",&p[i].at,&p[i].bt);

p[i].completed=-1;

}

sjf(p,n);

}

```


BANKERS

```
#include<stdio.h>

struct pro
{
    int all[10],max[10],need[10];

    int flag;

} p[10];

int i,j,pno,r,id,k=0,safe=0,exec,count=0;

int aval[10],seq[10];

void safeState()
{
    while(count!=pno)
    {
        for(i=0;i<pno;i++)

            if(p[i].flag)

            {
                exec=r;

                for(j=0;j<r;j++)

                    if(p[i].need[j]>aval[j])

                        exec=0;

                if(exec==r)

                {
                    for(j=0;j<r;j++)

                        aval[j]+=p[i].all[j];

                    p[i].flag=0;

                    seq[k++]=i;

                    safe=1;

                    count++;

                }}

        if(!safe)

        {

            printf("System is in Unsafe State\n");

            break;
```

```

}

}

if(safe)

{

printf("System is in safe State.The Safe sequence: ");

for(i=0;i<pno;i++)

    printf("P[%d] ",seq[i]);

printf("\n");

}

}

int main()

{

printf("Enter no of process: ");

scanf("%d",&pno);

printf("Enter no of resources: ");

scanf("%d",&r);

printf("Enter available resources of each type:");

for(j=0;j<r;j++)

    scanf("%d",&aval[j]);

printf("Enter process details: ");

for(i=0;i<pno;i++)

{

printf("\n Process %d\n",i);

printf("Allocation Matrix:\t");

for(j=0;j<r;j++)

    scanf("%d",&p[i].all[j]);

printf("Maximum Matrix:\t\t");

for(j=0;j<r;j++)

    scanf("%d",&p[i].max[j]);

p[i].flag=1;

for(j=0;j<r;j++)

    p[i].need[j]=p[i].max[j]-p[i].all[j];

}

```

```
printf("\nProcess details\n");

printf("PID\t\tALL\t\tMax\t\tNeed\n");

for(i=0;i<pno;i++)

{

printf("%d\t\t",i);

for(j=0;j<r;j++)

printf("%d ",p[i].all[j]);

printf("\t\t");

for(j=0;j<r;j++)

printf("%d ",p[i].max[j]);

printf("\t\t");

for(j=0;j<r;j++)

printf("%d ",p[i].need[j]);

printf("\n");

}

safeState();

return 0;

}
```

BESTFIT

```
#include <stdio.h>

#define max 25

int i,j,k=0,nb,nf,temp=0,lowest=999,flag=0;

void bestfit(int b[],int f[])

{
    for(i=1;i<=nf;i++)
    {
        for(j=1;j<=nb;j++)
        {
            temp=b[j]-f[i];

            if(temp>=0)
            {
                if(lowest>temp)
                {
                    k=j;

                    lowest=temp;
                }
            }
        }

        if(lowest!=999)
            printf("\nFile Size %d is put in %d partition\n",f[i],b[k]);

        else

            printf("\nFile Size %d must wait",f[i]);

        b[k]=lowest;

        lowest=999;
    }
}

int main()

{
    int b[max],f[max];

    printf("\nMemory Management Scheme-Best Fit");

    printf("\nEnter the number of blocks:");
```

```
scanf("%d",&nb);

printf("\nEnter the number of files:");

scanf("%d",&nf);

printf("\nEnter the size of the blocks:\n");

for(i=1;i<=nb;i++)

{

printf("Block %d:",i);

scanf("%d",&b[i]);

}

printf("Enter the size of the files:\n");

for(i=1;i<=nf;i++)

{

printf("File %d:",i);

scanf("%d",&f[i]);

}

bestfit(b,f);

return 0;

}
```

NON PREEMPTIVE PRIORITY

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <limits.h>
```

```
struct Process
```

```
{
```

```
    int id, at, bt, ct, tat, wt, pt;
```

```
    int completed; // To track completion
```

```
};
```

```
int findHighestPriority(struct Process p[], int n, int currentTime)
```

```
{
```

```
    int index = -1, highestPriority = INT_MAX;
```

```
    for (int i = 0; i < n; i++)
```

```
    {
```

```
        if (p[i].at <= currentTime && !p[i].completed) // Process must have arrived and not be completed
```

```
        {
```

```
            if (p[i].pt < highestPriority || (p[i].pt == highestPriority && p[i].at < p[index].at))
```

```
            {
```

```
                highestPriority = p[i].pt;
```

```
                index = i;
```

```
            }
```

```
        }
```

```
    }
```

```
    return index;
```

```
}
```

```
void NonPreemptivePriority(struct Process p[], int n)
```

```
{
```

```
    int completedCount = 0, currentTime = 0;
```

```
    float totalTAT = 0, totalWT = 0;
```

```

while (completedCount < n)
{
    int ind = findHighestPriority(p, n, currentTime);

    if (ind == -1) // If no process is available, move time forward
    {
        currentTime++;
    }
    else
    {
        // Process execution
        p[ind].completed = 1;
        completedCount++;
        currentTime += p[ind].bt;
        p[ind].ct = currentTime;
        p[ind].tat = p[ind].ct - p[ind].at;
        p[ind].wt = p[ind].tat - p[ind].bt;
        totalTAT += p[ind].tat;
        totalWT += p[ind].wt;
    }
}

printf("PID\tAT\tBT\tP\tCT\tTAT\tWT\n");

for (int i = 0; i < n; i++)
{
    printf("P%d\t%d\t%d\t%d\t%d\t%d\t%d\n", p[i].id, p[i].at, p[i].bt, p[i].pt, p[i].ct, p[i].tat, p[i].wt);
}

printf("Average TAT = %.2f\n", totalTAT / n);
printf("Average WT = %.2f\n", totalWT / n);
}

```

```
int main()

{

    int n;

    printf("Enter the number of processes: ");

    scanf("%d", &n);


    struct Process p[n];


    printf("Enter Arrival Time (AT), Burst Time (BT), and Priority (P) for each process:\n");

    for (int i = 0; i < n; i++)

    {

        p[i].id = i + 1;

        p[i].completed = 0; // Initially, no process is completed

        printf("P%d (AT, BT, P): ", p[i].id);

        scanf("%d %d %d", &p[i].at, &p[i].bt, &p[i].pt);

    }


    NonPreemptivePriority(p, n);

    return 0;

}
```


IPC

WRITER

```
#include <sys/types.h>

#include <sys/ipc.h>

#include <sys/shm.h>

#include <stdio.h>

#include <stdlib.h>

#include <string.h>

int main()

{

    key_t key=ftok("shmfile",65);

    int shmid=shmget(key,1024,0666 | IPC_CREAT);

    char *data=(char *)shmat(shmid,NULL,0);

    printf("Enter a string:");

    fgets(data,1024,stdin);

    return 0;

}
```

READER

```
#include <sys/types.h>

#include <sys/ipc.h>

#include <sys/shm.h>

#include <stdio.h>

#include <stdlib.h>

#include <string.h>

int main()

{

    key_t key=ftok("shmfile",65);

    int shmid=shmget(key,1024,0666);

    char *data=(char *)shmat(shmid,NULL,0);

    printf("Data from writer: %s",data);

    return 0;

}
```

SEMAPHORE

```
#include <sys/types.h>

#include <sys/ipc.h>

#include <sys/shm.h>

#include <stdio.h>

#include <stdlib.h>

#include <string.h>

int mutex=1,full=0,empty=3,x=0;

int signal(int s)

{

return (++s);

}

int wait(int s)

{

return (--s);

}

void producer()

{

empty=wait(empty);

mutex=wait(mutex);

x++;

printf("\n Producer Produces the item %d",x);

mutex=signal(mutex);

full=signal(full);

}

void consume()

{

full=wait(full);

mutex=wait(mutex);

printf("\n Consumer consumes the item %d",x);

x--;

mutex=signal(mutex);

empty=signal(empty);
```

```
}

void main()

{

int n;

while(1)

{

printf("\n1.Producer\n2.Consumer\n3.Exit\n");

printf("\nEnter your choice: \n");

scanf("%d",&n);

switch(n)

{

case 1:

if((mutex==1)&&(empty!=0))

producer();

else

printf("\nBuffer is Full\n");

break;

case 2:

if((mutex==1)&&(full!=0))

consume();

else

printf("\nBuffer is Empty\n");

break;

case 3:

exit(0);

break;

}

}

}
```