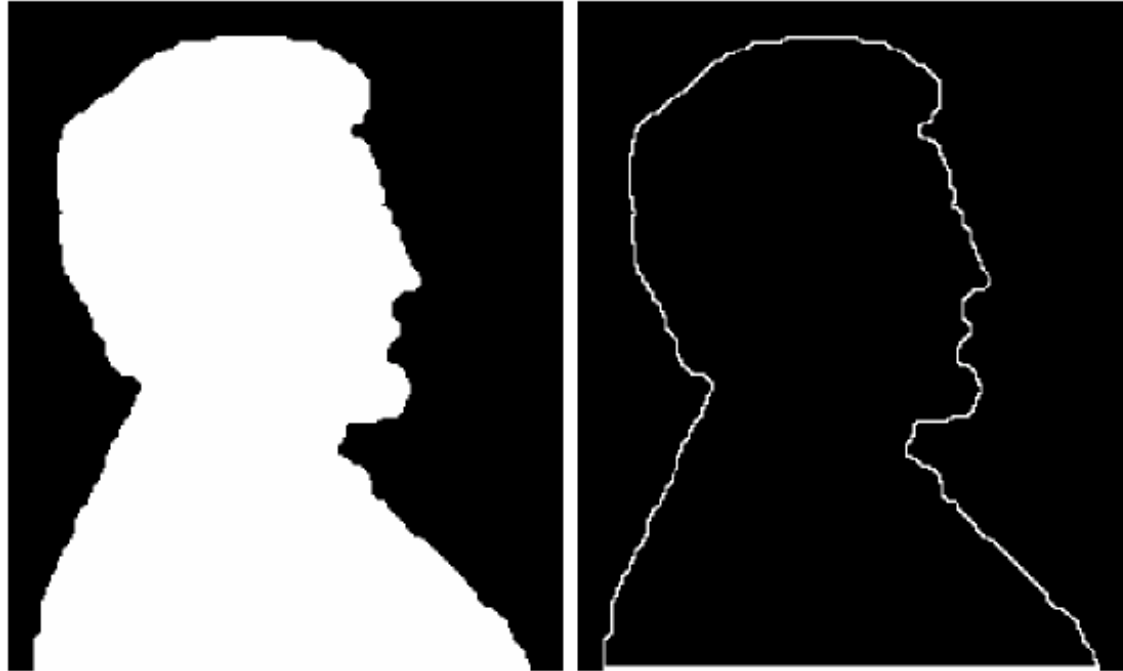


Representation by using Chain Code

Why we focus on a boundary?

The boundary is a good representation of an object shape and also requires a few memory.

Boundary of Binary Objects



X

∂X

- ▶ After an image has been segmented into regions, it is used for further computer processing.
- ▶ Image regions (including segments) can be represented by either the **border** or **the pixels of the region**.
- ▶ This can be represented in terms of its external (boundaries)/ internal (pixel representing the region)
- ▶ The external representation primary focus is in shape characteristics.
- ▶ An internal representation is selected when the primary focus is on regional properties(color/texture.....)
- ▶ Chain codes: represent a boundary of a connected region.

Chain Codes

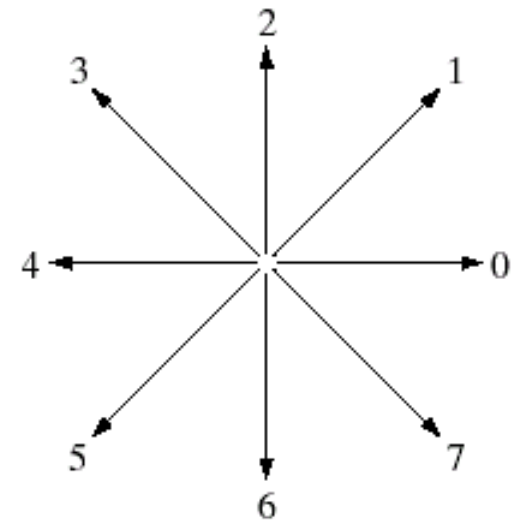
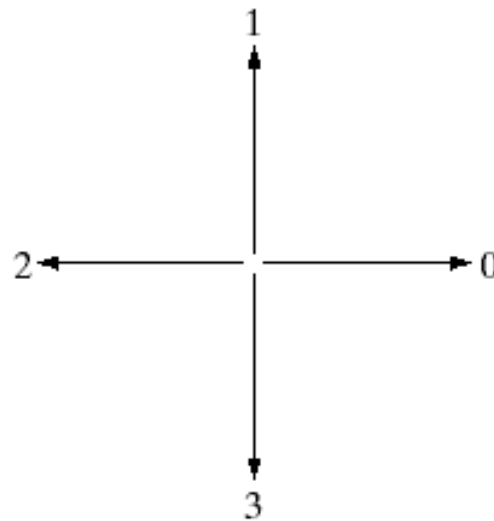
- ▶ This is used to represent a boundary by a connected sequence of straight line segments of specified length and direction.
- ▶ This is based on 4 or 8 connectivity.
- ▶ The direction of each segment is coded by using numbering scheme.
- ▶ Boundary code is formed as a sequence of such directional numbers is referred to as a Freeman chain code.
- ▶ The chain code of a boundary depends on the starting point.

Representation

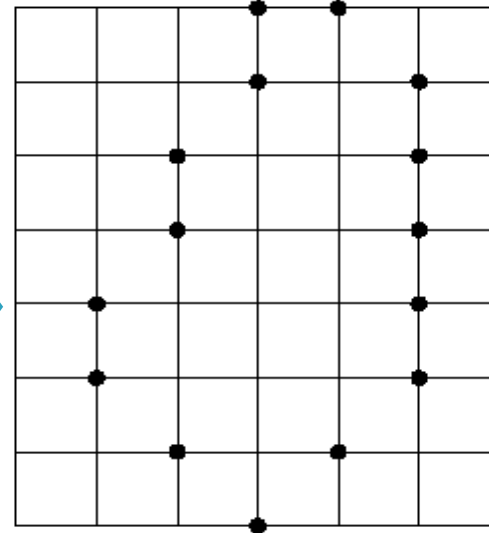
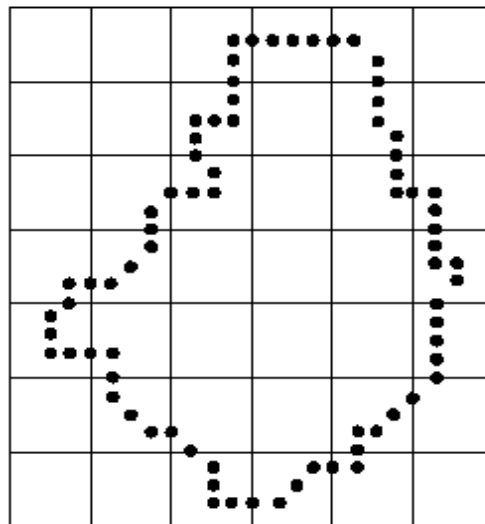
a b

FIGURE 11.1

Direction numbers for (a) 4-directional chain code, and (b) 8-directional chain code.



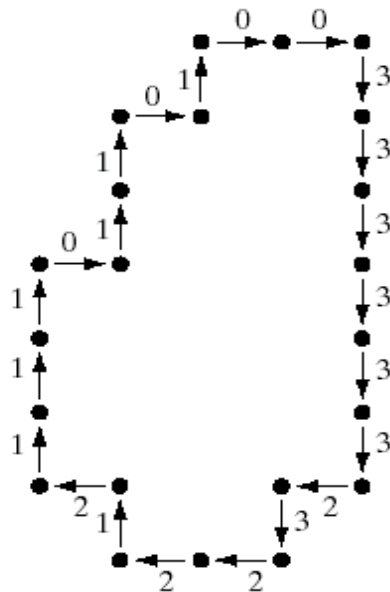
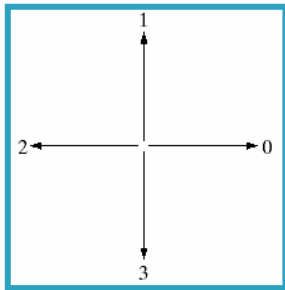
Representation Chain Codes



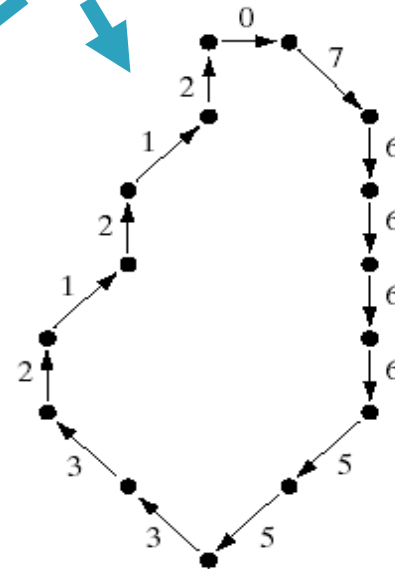
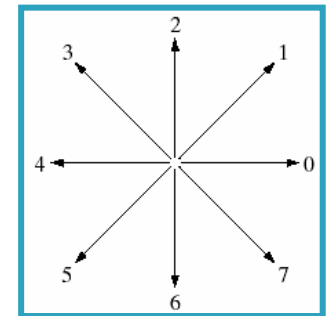
a	b
c	d

FIGURE 11.2

(a) Digital boundary with resampling grid superimposed.
 (b) Result of resampling.
 (c) 4-directional chain code.
 (d) 8-directional chain code.



4-directional chain code:
 0033333323221211101101



8-directional chain code:
 07666553321212

- The chain code of a boundary depends on the starting point.
- We can normalize also for rotation by using the *first difference* of the chain code instead of the code itself.
- The first-difference of the 4-direction chain code 10103322 is 3133030.
- If we elect to treat the code as a circular.
- Here, the result is 33133030.

The first difference is rotational invariant.

The normalized/first difference boundary code results in a significant reduction in the amount of data needed to store the boundary.

For Ex:

The 8-directional freeman chain code of the boundary is

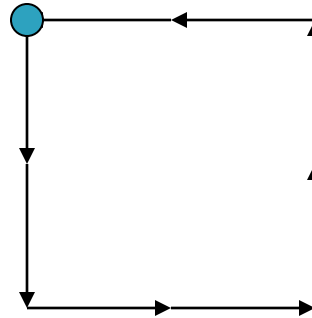
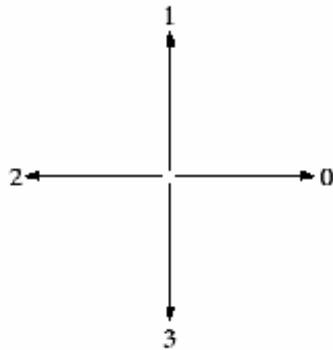
0 0 0 0 6 0 6 6 6 6 6 6 6 6 4 4 4 4 4 4 2 4 2 2 2 2 2 0 2 2 0 2

The first difference code is

0 0 0 6 2 6 0 0 0 0 0 0 6 0 0 0 0 0 6 2 6 0 0 0 0 6 2 0 6 2 6

- The method generally is unacceptable for two principal reasons:
 - (1) The resulting chain of codes tends to be quite long and,
 - (2) any small disturbances along the boundary due to noise or imperfect segmentation cause changes in the code that may not be related to the shape of the boundary.

Normalization Strategy

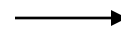


33001122

33001122
30011223
00112233
01122330
11223300
12233001
22330011
23300112

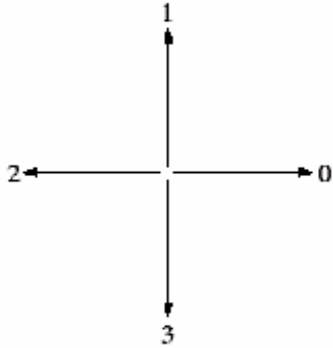
Sort
rows

00112233
01122330
11223300
12233001
22330011
23300112
33001122
30011223

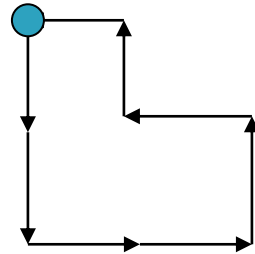


First row gives the
normalized chain code
00112233

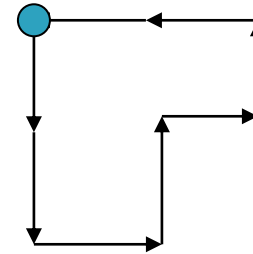
Shape Numbers= Normalized Differential Chain Codes



Differential code:
 $d_k = c_k - c_{k-1} \pmod{4}$



33001212
 ↓ differentiate
 10101131
 ↓ normalize
 01011311



33010122
 ↓ differentiate
 10113110
 ↓ normalize
 01011311

Note that the shape numbers of two objects related by 90° rotation are indeed identical

Direction is Anti-clock wise
 2 to 3 is 1, 3 to 0 is 1 etc....

Chain Codes

Noisy 570x570
image

9x9 averaging
mask

Otsu
thresholded

Single-point
from Otsu
thresholding
(ignored)



8-directed chain code:
0000606666666644444424222202202
Minimum magnitude integer:
0000606666666644444424222202202
First difference:
00062600000006000006260000620626

Longest outer
boundary

Resampled on a
50x50 pixel grid

Joining resampled pixels
by straight lines

a b c
d e f

FIGURE 11.5 (a) Noisy image. (b) Image smoothed with a 9×9 averaging mask. (c) Smoothed image, thresholded using Otsu's method. (d) Longest outer boundary of (c). (e) Subsampled boundary (the points are shown enlarged for clarity). (f) Connected points from (e).