CSL361 Problem set 1: Numerical computations - pitfalls

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1 Discretization

Because of the "discrete" nature of the floating point numbers, numerical problem solving requires discretization. Here are a few examples.

1. Derive the trapezoidal rule for numerical integration which goes somewhat like:

$$\int_{a}^{b} f(x)dx \simeq \sum_{k=0}^{n-1} \frac{1}{2} h[f(x_k) + f(x_{k+1})]$$

for discrete values of x_k in interval [a, b]. Compute $\int_0^{\pi} \sin(x) dx$ using trapezoidal rule (use h = 0.1, h = 0.01 and h = 0.001) and compare with the exact result.

2. Consider the differential equation

$$y'(x) = 2xy(x) - 2x^2 + 1, \quad 0 \le x \le 1$$

 $y(0) = 1$

- (a) Show/verify that the exact solution is the function $y(x) = e^{x^2} + x$.
- (b) If we approximate the derivative operation with a divided difference

$$y'(x_k) = (y_{k+1} - y_k)/(x_{k+1} - x_k)$$

then show that solution can be approximated by the iteration

$$y_{k+1} = y_k + h(2x_ky_k - 2x_k^2 + 1), \quad k = 0, 1, \dots, n$$

 $y_0 = 1$

where $x_k = kh$, k = 0, 1, ..., n and h = 1/n.

- (c) Use h = 0.1 to solve the differential equation numerically and compare (plot) your answers with the exact solution.
- 3. (a) Derive the Newton's iteration for computing $\sqrt{2}$ given by

$$\begin{array}{rcl} x_{k+1} & = & \frac{1}{2}[x_k + (2/x_k)], & k = 0, 1, \dots \\ x_0 & = & 1 \end{array}$$

- (b) Show the Newton's iteration takes $O(\log n)$ steps to obtain n decimal digits of accuracy.
- (c) Numerically compute $\sqrt{2}$ using Newton's iteration and verify the rate of convergence.
- 4. We have discussed rounding errors in the class. Truncation errors are those that occur because of termination of a computational process after a finite number of steps. Which of the following are rounding errors and which are truncation errors?
 - (a) Replace sin(x) by $x (x^3/3!) + (x^5)/5! \dots$
 - (b) Use 3.1415926536 for π .
 - (c) Use the value x_{10} for $\sqrt{2}$, where x_k is given by Newton's iteration above.
 - (d) Divide 1.0 by 3.0 and call the result 0.3333.

2 Unstable and Ill-conditioned problems

1. Consider the differential equation

$$y'(x) = (2/\pi)xy(y-\pi), 0 \le x \le 10$$

 $y(0) = y_0$

(a) Show/verify that the exact solution to this equation is

$$y(x) = \pi y_0 / [y_0 + (\pi - y_0)e^{x^2}]$$

- (b) Taking $y_0 = \pi$ compute the solution for
 - i. an 8 digit rounded approximation for π
 - ii. a 9 digit rounded approximation for π

What can you say about the results?

2. Solve the system

$$\begin{array}{rcl}
2x & - & 4y & = & 1 \\
-2.998x & + & 6.001y & = & 2
\end{array}$$

using any method you know. Compare the solution with the solution to the system obtained by changing the last equation to -2.998x+6y=2. Is this problem stable?

3. Examine the stability of the equation

$$x^3 - 102x^2 + 201x - 100 = 0$$

which has a solution $x^* = 1$. Change one of the coefficients (say 201 to 200) and show that $x^* = 1$ is no longer even close to a solution.

3 Unstable methods

1. Consider the quadratic

$$ax^2 + bx + c = 0, \quad a \neq 0$$

Consider a = 1, b = 1000.01, c = -2.5245315. Suppose that $\sqrt{b^2 - 4ac}$ is computed correctly to 8 digits, what is the number of digits of accuracy in x? What is the source of the error?

2. Show that the solution to the quadratic can be re-written as

$$x = -2c/(b^2 + \sqrt{b^2 - 4ac})$$

Write a program to evaluate x for several values of a, b and c (with b large and positive and a, c of moderate size). Compare the results obtained with the usual formula and the formula above.

3. Consider the problem of determining the value of the integral

$$\int_0^1 x^{20} e^{x-1} dx$$

If we let

$$I_k = \int_0^1 x^k e^{x-1} dx$$

Then, integration by parts gives us (please verify)

$$I_k = 1 - kI_{k-1}$$

 $I_0 = \int_0^1 e^{x-1} dx = 1 - (1/e)$

Thus we can compute I_{20} by successively computing I_1, I_2, \ldots Compute the (k, I_k) table with a program, plot, and see if it makes sense. What are the errors due to?

Compare the results with that obtained using the following recursion (which you can *easily!* derive by integrating by parts twice).

$$I_k = (1/\pi) - [k(k-1)/\pi^2]I_{k-2}, \quad k = 2, 4, 6, \dots$$

4. The standard deviation of a set of numbers x_1, x_2, \ldots, x_n is defined as

$$s = (1/n) \sum_{i=1}^{n} (x_i - \bar{x})^2$$

where \bar{x} is the average. An alternative formula that is often used is

$$s = (1/n) \sum_{i=1}^{n} x_i^2 - \bar{x}^2$$

- (a) Discuss the instability of the second formula for the case where the x_i are all very close to each other.
- (b) Observe that s should always be positive. Write a small program to evaluate the two formulas and find values of x_1, \ldots, x_{10} for which the second one gives negative results.
- 5. Under fixed point arithmetic, if we add n numbers, then either we get the exact answer or we get an "overflow" error. This is not true for floating point arithmetic. Consider the Matlab program sumtrouble.py. You might want to play with the program, changing n or h or computing the difference between the computed sums and the true ones in order to understand what is happening.
 - (a) Is *sum*1 equal to the true value? If not, why not? (Please try be specific it is not enough to say "round off caused the error" (in typical IITD style).
 - (b) Are any of *sum*2 and *sum*3 equal to their true value? If not, why not? Why are they different?
 - (c) Ditto for sum4 and sum5.