#### 1

### **CONTENTS**

1	Stability	1
	1.1 Second order System	1
2	<b>Routh Hurwitz Criterion</b>	1
3	Compensators	1
4	Nyquist Plot	1
5	Gain Margin	1

Abstract—This manual is an introduction to control systems based on GATE problems.Links to sample Python codes are available in the text.

Download python codes using

### 1 STABILITY

# 1.1 Second order System

## 2 Routh Hurwitz Criterion

- 3 Compensators
- 4 NYOUIST PLOT
- 5 Gain Margin

The figure below shows the Bode magnitude and phase plots of a stable transfer function:

$$G(s) = \frac{n_0}{s^3 + d_2 s^2 + d_1 s + d}$$
 (5.0.1)

Consider the negative unity feedback configuration with gain k in the feed forward path. The closed loop is stable for . The maximum value of  $k_o$  is:

### **Solution:**

$$K_g = \frac{1}{|G(j\omega)|} \tag{5.0.2}$$

 $K_g$  is the gain margin at the frequency at which phase angle is -180°.

In terms of decibels:

$$K_{g}dB = -20log(|G(j\omega)|)dB \qquad (5.0.3)$$

- 1.For a stable system, Gain margin at the phase cross-over frequency > 0dB.
- 2.The phase crossover frequency is the frequency at which the phase angle first reaches  $-180^{\circ}$ .
- 3. The gain margin refers to the amount of gain, which can be increased or decreased

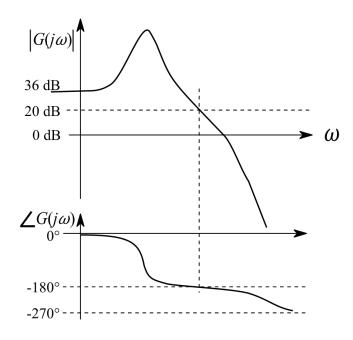


Fig. 5.0.1

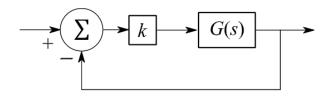


Fig. 5.0.2

without making the system unstable.

- 4.Gain margin is the factor by which the gain must be multiplied at the phase crossover to have the value 1.
- 5.The phase crossover frequency is the frequency at which the phase angle first reaches -180° and thus is the point where the Nyquist plot crosses the real axis.

For a stable system, Gain margin at the phase cross-over frequency > 1.

G(s) is cascaded with k, so,

$$G_1(s) = kG(s)$$
 (5.0.4)

$$K_g = \frac{1}{|G_1(j\omega_{pc})|} > 1$$
 (5.0.5)

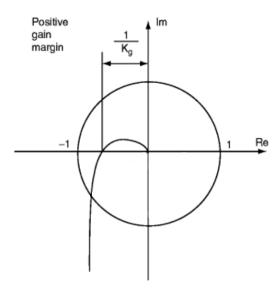


Fig. 5.0.3: nyquist plot of stable transfer function

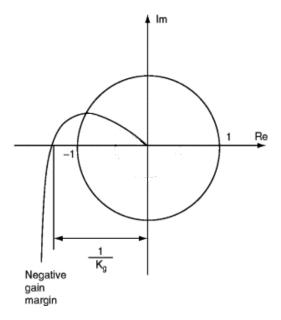


Fig. 5.0.4: nyquist plot of unstable transfer function

$$\implies K_{g(dB)} = -20log(|G_1(j\omega_{pc})|) > 0dB$$
(5.0.6)
$$\implies -20log(|G(j\omega_{pc})k|) > 0dB$$
(5.0.7)
$$\implies -20 - 20log(|k|) > 0dB$$
(5.0.8)
$$\implies 20log(k) < -20$$
(5.0.9)
$$\implies k < 10^{-1}$$
(5.0.10)

$$\implies k_{max} = 0.1 \tag{5.0.11}$$

$$\therefore k_o = 0.1$$