Kartik Madhira

Personal Website: https://kartikmadhira1.github.io/

Email : kmadhira@terpmail.umd.edu
Mobile : +1-301-204-6989

Education

- **University of Maryland** — College Park, MD
  Masters in Robotics — *August 2018 –present*
- **Nirma University** — Ahmadabad, India
  Bachelors in Instrumentation and Control Engineering — *2013–2017*

Experience

- **Research Assistant**
  RAAS Lab, University of Maryland — *Sept. 2019 - present*
  Deploying and testing of SLAM algorithms for an autonomous bridge inspection UAV. The sensor module consists of a stereo and a 3D lidar.
- **Perception Intern**
  Aeva Inc., Mountain View — *May 2019 – August 2019*
  Quantifying object tracking and detection in the perception pipeline. Implemented and integrated end to end metrics to set benchmarks for tracker and classifier improvements.
- **Research Assistant:**
  Computer Vision Lab, University of Maryland — *August 2018 – April 2019*
  Implementation of supervised deep learning model for optical flow for use on edge inference devices such as Intel Neural Compute Stick.
- **Trainee Data Analyst** (Machine Learning)
  Mu Sigma Inc., India — *June 2017 – February 2018*
  Part of the machine learning team that implemented ARIMA models for predictions of monthly and yearly sales using past inventory data. The client was an E-commerce major in the US specializing in footwear.
- **Research Intern**
  Tethrbox Technologies — *April 2016 - July 2016*
  Pedestrian Flow Counter Contributed to research on effective traffic estimator by developing a people counter prototype using a downward facing camera. The counter used background subtraction and minimum weight assignment algorithm for data association to achieve the up and down counts.

Publications

- **Self balancing robot using complementary filter: Implementation and analysis of complementary filter on SBR**: Kartik Madhira, Ammar Gandhi and Aneesha Gujral, 2016 International Conference on Electrical, Electronics, and Optimization Techniques (ICEEOT), Chennai, 2016, pp. 2950-2954. (Link)

Selected Projects

- **Supervised and Unsupervised HomographyNet**: Implementation of `supervised` and `unsupervised` deep learning approaches in estimating planar homography on TensorFlow. (Link)
- **Clerkbot - A Butler Robot**: Built a prototype of office friendly Autonomous Fetch and Carry UGV (ROS Based) (Link)
- **SnapCut/Rotobrush**: Implemented Adobe After Effects segmentation pipeline SnapCut, a robust video object cutout using localized classifiers (Link)
- **Structure from Motion (SfM)**: A 3D reconstruction of a scene from a set of several snaps from a Quadrotor flying over a mat of AprilTags. (Link)
- **Self Balancing Robot with Complimentary filter**: A self-balancing robot based on Complimentary Filter for the IMU Sensor(MPU-6050). (Link)

Skills

Computer Languages: Python, C/C++,MATLAB, R, LaTeX
Operating System: Linux, Mac OSX, Windows XP/7/8/10
Softwares/Libraries: ROS, TensorFlow, Numpy, Matlplotlib, Keras, RStudio

References

Yiannis Aloimonos
Professor,
University of Maryland

Dr. Waseem A. Malik,
Adjunct Professor,
University of Maryland

Dr. Dilip Kothari,
Professor,
Nirma University