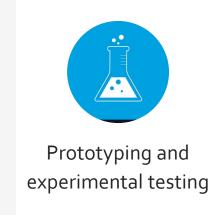
Kartik Naik

Research engineer

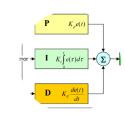
Core areas of interest

Why research?

Research enables both, development of novel technology to help solve problems at a global level, and answer fundamental scientific questions on a personal level.







Dynamic modeling, controls and estimation

A cademic time line

Research experiences and relevant skill development at each academic stage.

B.TECH

Research fundamentals

CAD

Structural and thermal analysis

Control systems

M.S

Space-related

Prototyping: Mechanical

Scripting

Ph.D.

Complex system engineering

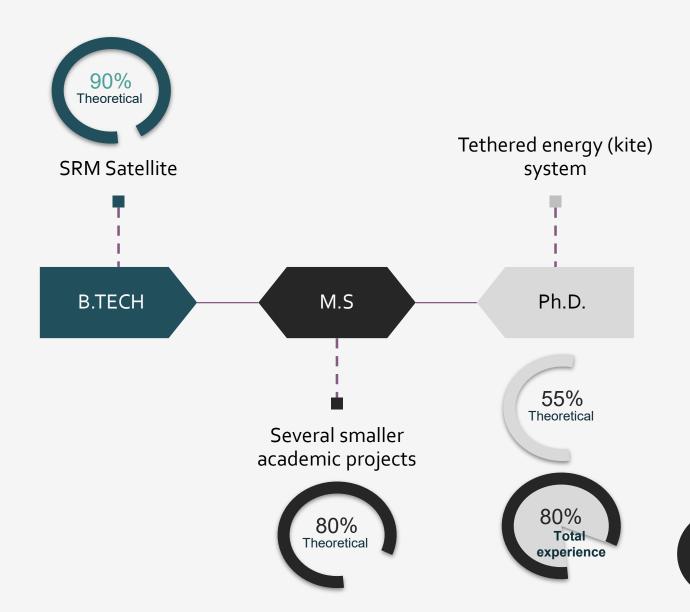
Design optimization

Dynamics, Control and Estimation

Prototyping: Electronics and software

Projects

While projects during my bachelor's and master's enriched theoretical research capabilities, my doctoral research projects were far more practical and complex. Thus, I will focus on projects from my doctoral work in this portfolio.





Research fundamentals

CAD

Structural and thermal analysis

Control systems

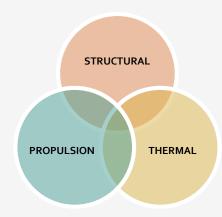
SRMSAT

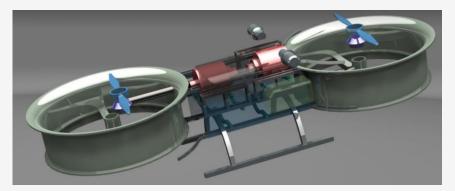
Goal: Design a satellite mission to a Low Lunar Orbit (LLO)

- Led the mechanical systems team
- Software used: Solidworks, Siemens NX, Systems Tool Kit (STK)

Outcomes

- Presented design report to Indian Space
 Research Organization to secure funding
- Relevant publications



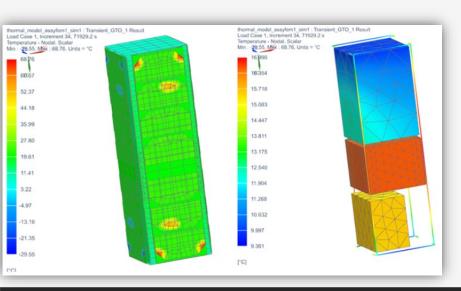


ACADEMIC THESIS

Title: Design of a 2-rotor hoverbike.

Tasked with structural frame, transmission and control design.

Aerospace Engineering - Lulea University, Sweden - University of Wurzburg, Germany - Aalto University, Finland



ACADEMIC PROJECTS

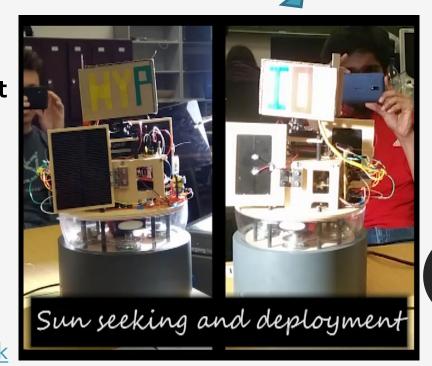
- Floating satellite project

Goal: Prototype and test a satellite concept on a floating bed Control reaction wheel to face light source.

- Mars mission design project
- European Space Agency's concurrent engineering project

ACADEMICTHESIS

A Thermal Investigation and Comparative Study of the Foresail missions (high earth orbital satellite).



Prototyping

Video li

Design optimization

Dynamics, Control and Estimation

In depth: Ph.D.

Mechanical & Aerospace Dept. NC State University, US

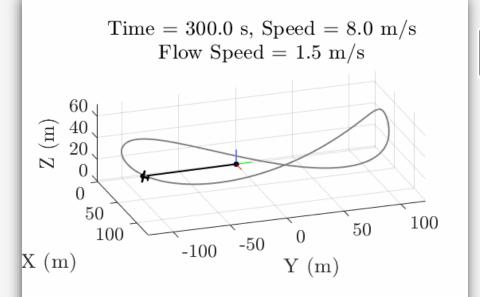
What are tethered energy systems?

- Harvest a flow resource (like wind or ocean current)
- Better than turbines
- Kite (plane-like) at the end of tether

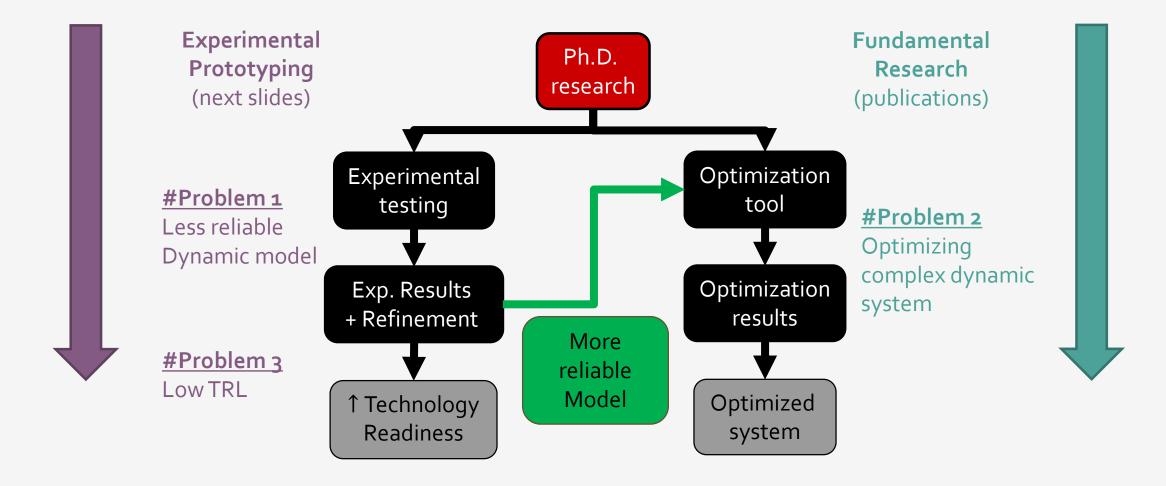


 $P_{generated} \gg P_{used}$ ⇒ Net Positive Power

Animation link: Simulated with high fidelity Dynamic model developed in MATLAB

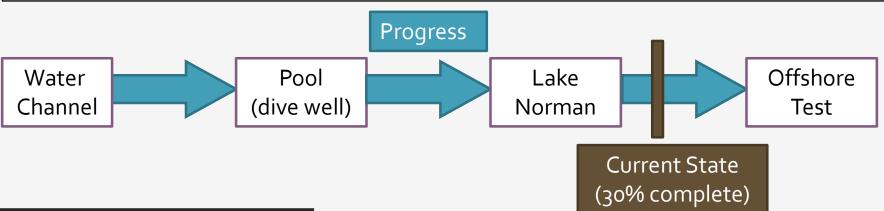


Spool Out (Power Gen)
Spool In (Power Use)



Road to ocean deployment

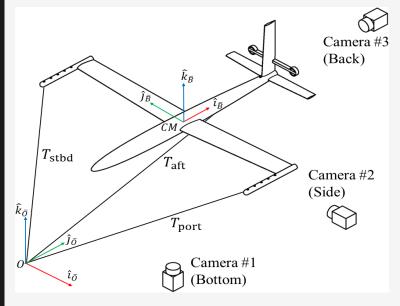
	Water Channel	Swimming Pool	Lake Norman
System Scale	15/1000	1/10	1/10
Kite actuation	3 tether spooling	Control surfaces	Control surfaces
Flow emulation	Motor to move water through test section	Raft actuation in pool	Boat moving in lake
Scientific validation	Dynamic model	Dynamic model + Flight controller	Flight controller + Spooling controller
Max. tether length	50 cm	2.6 m	15 M

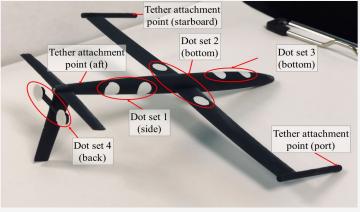


Water channel testing

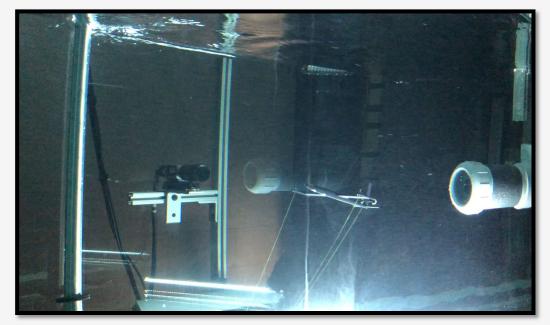
Dynamic model validation

Kite 3D printed with form 3!





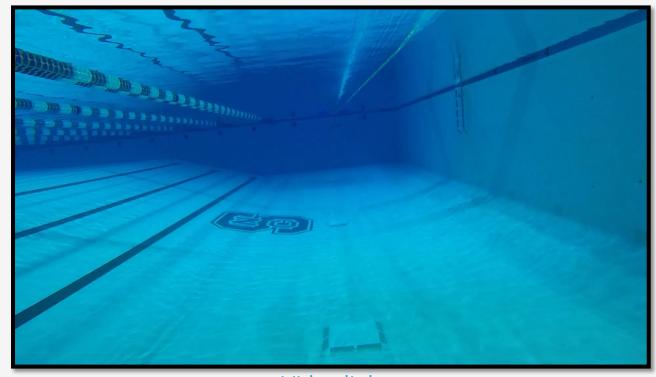
Cameras track dots to estimate position for real-time control



Video link

Pool testing

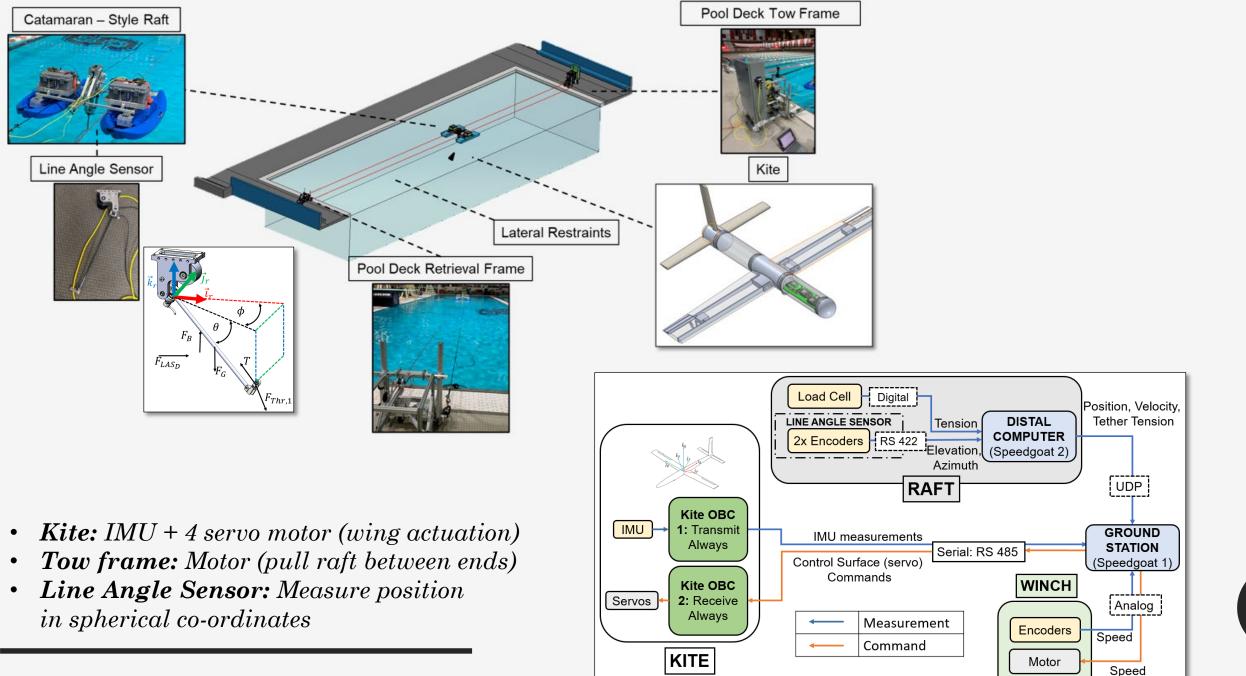
Automatic flight controller deployment + validation



Video link

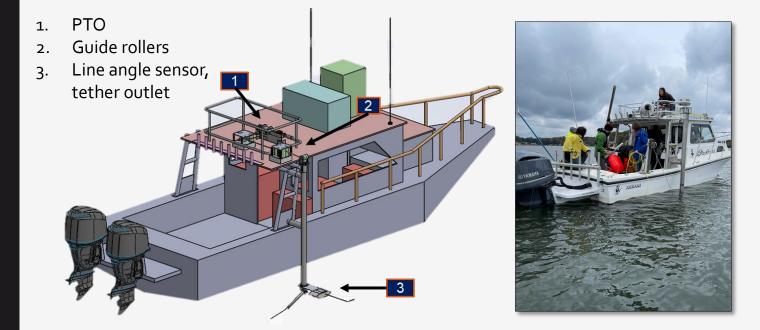


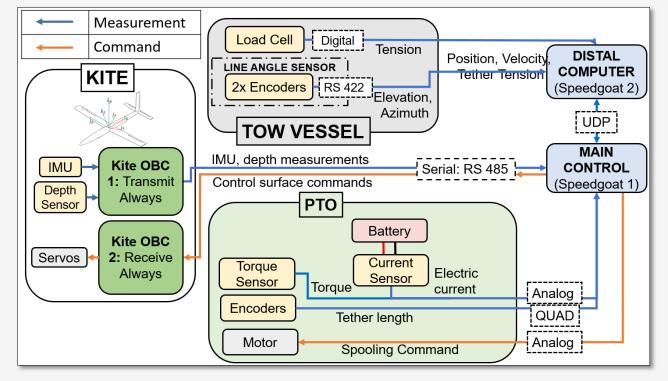
Command



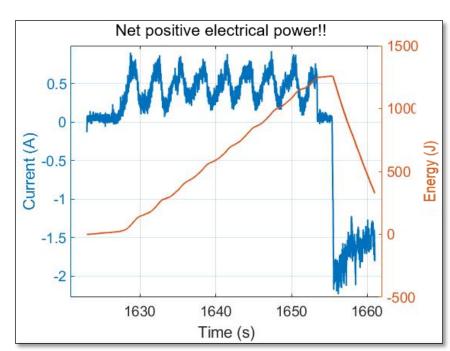
Lake testing

Robust flight + spooling controller operation + validation

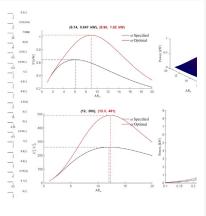




Highlights



Let there be light.



Optimization tool (Matlab app)



All 3 experimental campaigns successful



Power generated!! (Lake testing)



Multi-disciplinary technical skills



Team management skills

Awards and recognition



Bachelors: Academic scholarship



Masters: ERASMUS+ academic scholarship



Masters: 1st place in Mars society international competition



Ph.D: ACC Publication related award



High school: 1st place in nationwide eco-competition