

Problem 1

myDisplayImageGrey.m

```
function myDisplayImageGrey(img,title1)
    imshow (mat2gray(img));
    title(title1);
    colormap(gray(200));
    axis on;
    colorbar;
```

myDisplayTwoImage.m

```
function myDisplayTwoImage(img1,img2)
    figure('Position', [100, 100, 1200, 600]);
    subplot(1,2,1);
    myDisplayImageGrey(img1,"Original Image");
    subplot(1,2,2);
    myDisplayImageGrey(img2,"Sharpened Image");
end
```

myLinearContrastStretching.m

```
function contrastImg = myLinearContrastStretching(input)
    c = size(input,3);
    contrastImg = zeros(size(input));
    input = double(input);
    for l=1:c
        maxIntensity = max(max(input(:, :, l)));
        minIntensity = min(min(input(:, :, l)));
        contrastImg(:, :, l) = (input(:, :, l) - minIntensity) * double(255) /
(maxIntensity - minIntensity);
```

```
end  
end
```

myMainScript.m

```
%% MyMainScript
```

```
tic;  
%% Super Moon Crop  
imageData = load('./data/superMoonCrop.mat');  
image = imageData.imageOrig;  
stretchedImage = myLinearContrastStretching(image);  
sharplImage = myUnsharpMasking(image,1.1,9,1.1);  
sharplImage = myLinearContrastStretching(sharplImage);  
myDisplayTwoImage(stretchedImage,sharplImage);  
%% Lion Crop  
imageData = load('./data/lionCrop.mat');  
image = imageData.imageOrig;  
stretchedImage = myLinearContrastStretching(image);  
sharplImage = myUnsharpMasking(image,1.1,9,1.6);  
sharplImage = myLinearContrastStretching(sharplImage);  
myDisplayTwoImage(stretchedImage,sharplImage);  
toc;
```

myUnsharpMasking.m

```
function filteredImage = myUnsharpMasking(input, sigma, windowSize,  
scale)  
    filteredImage = input -  
scale*imfilter(input,fspecial('log',windowSize,sigma));  
end
```

Problem 2

myBilateralFiltering.m

```
function filteredImage = myBilateralFiltering(input, sigmaSpace,
sigmaIntensity>windowSize)

    % create pre defined filter gaussian space
    filter = fspecial('gaussian',2*windowSize+1 ,sigmaSpace);
    [len,wid] = size(input);
    filteredImage = zeros([len,wid]);
    for i = 1:len
        for j = 1:wid
            x = max(i-windowSize,1);
            X = min(i+windowSize,len);
            y = max(j-windowSize,1);
            Y = min(j+windowSize,wid);
            window = input(x:X,y:Y);
            x1 = max(2+windowSize-i,1);
            X1 = min(2*windowSize+1,len-i+windowSize+1);
            y1 = max(2+windowSize-j,1);
            Y1 = min(2*windowSize+1,wid-j+windowSize+1);
            intensity = exp(-((window-input(i,j)).^2)/(sigmaIntensity^2));
            singleTerm = filter((x1:X1),(y1:Y1)).*intensity;
            individualSum = window.*singleTerm;
            filteredImage(i,j) = sum(individualSum(:))/sum(singleTerm(:));
        end
    end
end
```

myDisplayImageGrey.m

```
function myDisplayImageGrey(img,title1)
    imshow (mat2gray(img));
    title(title1);
    colormap(gray(200));
    axis on;
    colorbar;
```

myDisplayThreelImage.m

```
function myDisplayThreelImage(img1,img2,img3)
    figure('Position', [100, 100, 1200, 600]);
    subplot(1,3,1);
    myDisplayImageGrey(img1,"Original Image");
    subplot(1,3,2);
    myDisplayImageGrey(img2,"Corrupted Image");
    subplot(1,3,3);
    myDisplayImageGrey(img3,"Filtered Image");
end
```

myMainScript.m

```
%% MyMainScript

tic;
%% Barbara
imageData = load('./data/barbara.mat');
image = imageData.imageOrig;
[len, wid] = size(image);
corruptedImage = image +
0.05*(max(max(image))-min(min(image)))*randn(len);
```

```
sigmaSpace = 1.6;
sigmaIntensity = 13.5;
windowSize = 4;
out = myBilateralFiltering(corruptedImage, sigmaSpace, sigmaIntensity,
windowSize);
rmsd = myRmsd(out,image);
display(rmsd);
myDisplayThreeImage(image,corruptedImage,out);
```

```
out1 = myBilateralFiltering(corruptedImage, 0.9*sigmaSpace,
sigmaIntensity, windowSize);
rmsd1 = myRmsd(out1,image);
display(rmsd1);
```

```
out2 = myBilateralFiltering(corruptedImage, 1.1*sigmaSpace,
sigmaIntensity, windowSize);
rmsd2 = myRmsd(out2,image);
display(rmsd2);
```

```
out3 = myBilateralFiltering(corruptedImage, sigmaSpace,
0.9*sigmaIntensity, windowSize);
rmsd3 = myRmsd(out3,image);
display(rmsd3);
```

```
out4 = myBilateralFiltering(corruptedImage, sigmaSpace,
1.1*sigmaIntensity, windowSize);
rmsd4 = myRmsd(out4,image);
display(rmsd4);
```

```
figure;
filter = fspecial('gaussian',2*windowSize+1 ,sigmaSpace);
imshow(filter,'InitialMagnification','fit');
```

```

title("Spatial Gaussian Mask")
colormap(gray(200));
axis on;
colorbar;

%% Grass
image = im2double(imread('../data/grass.png'));
[len, wid] = size(image);
corruptedImage = image +
0.05*(max(max(image))-min(min(image)))*randn(len);

sigmaSpace = 0.71;
sigmaIntensity = 0.31;
windowSize = 2;
out = myBilateralFiltering(corruptedImage, sigmaSpace, sigmaIntensity,
windowSize);
rmsd = myRmsd(out,image);
display(rmsd);
myDisplayThreeImage(image,corruptedImage,out);

out1 = myBilateralFiltering(corruptedImage, 0.9*sigmaSpace,
sigmaIntensity, windowSize);
rmsd1 = myRmsd(out1,image);
display(rmsd1);

out2 = myBilateralFiltering(corruptedImage, 1.1*sigmaSpace,
sigmaIntensity, windowSize);
rmsd2 = myRmsd(out2,image);
display(rmsd2);

out3 = myBilateralFiltering(corruptedImage, sigmaSpace,
0.9*sigmaIntensity, windowSize);
rmsd3 = myRmsd(out3,image);

```

```
display(rmsd3);
```

```
out4 = myBilateralFiltering(corruptedImage, sigmaSpace,  
1.1*sigmaIntensity, windowSize);  
rmsd4 = myRmsd(out4,image);  
display(rmsd4);
```

```
figure;  
filter = fspecial('gaussian',2*windowSize+1 ,sigmaSpace);  
imshow(filter,'InitialMagnification','fit');  
title("Spatial Gaussian Mask")  
colormap(gray(200));  
axis on;  
colorbar;
```

```
%% Honey Comb Real  
image = im2double(imread('../data/honeyCombReal.png'));  
[len, wid] = size(image);  
corruptedImage = image +  
0.05*(max(max(image))-min(min(image)))*randn(len);
```

```
sigmaSpace = 0.82;  
sigmaIntensity = 0.27;  
windowSize = 3;  
out = myBilateralFiltering(corruptedImage, sigmaSpace, sigmaIntensity,  
windowSize);  
rmsd = myRmsd(out,image);  
display(rmsd);  
myDisplayThreeImage(image,corruptedImage,out);
```

```
out1 = myBilateralFiltering(corruptedImage, 0.9*sigmaSpace,  
sigmaIntensity, windowSize);  
rmsd1 = myRmsd(out1,image);
```

```
display(rmsd1);
```

```
out2 = myBilateralFiltering(corruptedImage, 1.1*sigmaSpace,  
sigmaIntensity, windowSize);  
rmsd2 = myRmsd(out2,image);  
display(rmsd2);
```

```
out3 = myBilateralFiltering(corruptedImage, sigmaSpace,  
0.9*sigmaIntensity, windowSize);  
rmsd3 = myRmsd(out3,image);  
display(rmsd3);
```

```
out4 = myBilateralFiltering(corruptedImage, sigmaSpace,  
1.1*sigmaIntensity, windowSize);  
rmsd4 = myRmsd(out4,image);  
display(rmsd4);
```

```
figure;  
filter = fspecial('gaussian',2*windowSize+1 ,sigmaSpace);  
imshow(filter,'InitialMagnification','fit');  
title("Spatial Gaussian Mask")  
colormap(gray(200));  
axis on;  
colorbar;
```

```
toc;
```

myRmsd.m

```
function rmsdVal = myRmsd(img1,img2)  
    [len, wid] = size(img1);  
    rmsdVal = sqrt(sum(sum((img1-img2).^2))/(len*wid));  
end
```


Problem 3

myDisplayImageGrey.m

```
function myDisplayImageGrey(img,title1)
    imshow (mat2gray(img));
    title(title1);
    colormap(gray(200));
    axis on;
    colorbar;
```

myDisplayThreelImage.m

```
function myDisplayThreelImage(img1,img2,img3)
    figure('Position', [100, 100, 1200, 600]);
    subplot(1,3,1);
    myDisplayImageGrey(img1,"Original Image");
    subplot(1,3,2);
    myDisplayImageGrey(img2,"Corrupted Image");
    subplot(1,3,3);
    myDisplayImageGrey(img3,"Filtered Image");
end
```

myMainScript.m

```
%% MyMainScript

tic;

%% Filtering Barbara image
load('./data/barbara.mat');
imageOrig = imgaussfilt(imageOrig,0.66);
```

```

imageOrig = imresize(imageOrig,0.5);
[len, wid] = size(imageOrig);
imgCorrupt = imageOrig +
0.05*(max(max(imageOrig))-min(min(imageOrig)))*randn(len);

h = 1.26;
patchSize = [9,9];
windowSize = [25,25];
out = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h);
rsmd0 = myRsmd(out,imageOrig);
display(rsmd0);
myDisplayThreeImage(imageOrig,imgCorrupt,out);

out1 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*0.9);
rsmd1 = myRsmd(out1,imageOrig);
display(rsmd1);

out2 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*1.1);
rsmd2 = myRsmd(out2,imageOrig);
display(rsmd2);

figure;
gaussianFilter = fspecial('gaussian', patchSize, double(patchSize(1))/6);
imshow(gaussianFilter,'InitialMagnification','fit');
title("Mask for Isotropic Patches")
colormap(gray(200));
axis on;
colorbar;

%% Filtering Grass image
imageOrig = im2double(imread('../data/grass.png'));
[len, wid] = size(imageOrig);

```

```
imgCorrupt = imageOrig +  
0.05*(max(max(imageOrig))-min(min(imageOrig)))*randn(len);
```

```
h = 0.000109;  
patchSize = [9,9];  
windowSize = [25,25];  
out = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h);  
rsmd0 = myRsmd(out,imageOrig);  
display(rsmd0);  
myDisplayThreelImage(imageOrig,imgCorrupt,out);
```

```
out1 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*0.9);  
rsmd1 = myRsmd(out1,imageOrig);  
display(rsmd1);
```

```
out2 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*1.1);  
rsmd2 = myRsmd(out2,imageOrig);  
display(rsmd2);
```

```
figure;  
gaussianFilter = fspecial('gaussian', patchSize, double(patchSize(1))/6);  
imshow(gaussianFilter,'InitialMagnification','fit');  
title("Mask for Isotropic Patches")  
colormap(gray(200));  
axis on;  
colorbar;
```

```
%% Filtering Honey Comb image  
imageOrig = im2double(imread('../data/honeyCombReal.png'));  
[len, wid] = size(imageOrig);  
imgCorrupt = imageOrig +  
0.05*(max(max(imageOrig))-min(min(imageOrig)))*randn(len);
```

```

h = 0.00013;
patchSize = [9,9];
windowSize = [25,25];
out = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h);
rsmd0 = myRsmd(out,imageOrig);
display(rsmd0);
myDisplayThreeImage(imageOrig,imgCorrupt,out);

out1 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*0.9);
rsmd1 = myRsmd(out1,imageOrig);
display(rsmd1);

out2 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*1.1);
rsmd2 = myRsmd(out2,imageOrig);
display(rsmd2);

figure;
gaussianFilter = fspecial('gaussian', patchSize, double(patchSize(1))/6);
imshow(gaussianFilter,'InitialMagnification','fit');
title("Mask for Isotropic Patches")
colormap(gray(200));
axis on;
colorbar;

toc;

```

myPatchBasedFiltering.m

```

function filterImg = myPatchBasedFiltering(img, patchSize, windowSize, h)
    [len, wid] = size(img);

    paddedImage = padarray(img, [(patchSize(1)-1)/2, (patchSize(2)-1)/2],
'symmetric', 'both');

```

```
gaussianFilter = fspecial('gaussian', patchSize, double(patchSize(1))/6);  
gaussianFilter = gaussianFilter/(sum(gaussianFilter(:)));  
gaussianFilterVector = gaussianFilter(:);
```

```
featureImage = im2col(paddedImage, patchSize);  
featureImage = bsxfun(@times, featureImage, gaussianFilterVector);  
% Feature Image is of the same size as of the original image with last  
dimension equal to feature dimension  
featureImage = permute(reshape(featureImage,  
[patchSize(1)*patchSize(2), len, wid]), [2,3,1]);
```

```
constant1 = (windowSize(1)-1)/2;  
constant2 = (windowSize(1)+1)/2;
```

```
filterImg = zeros(size(img));
```

```
for i=1:len  
    for j=1:wid  
        minI = (i-constant1);  
        maxI = (i+constant1);  
        minJ = (j-constant1);  
        maxJ = (j+constant1);  
        if i < constant2  
            minI = 1;  
        elseif i > (len-constant1)  
            maxI = len;  
        end  
        if j < constant2  
            minJ = 1;  
        elseif j > (wid-constant1)  
            maxJ = wid;  
        end  
    end  
end
```

```

        patch = featureImage(minI:maxI, minJ:maxJ, :);
        sumSquareDiffernce = sum(bsxfun(@minus, patch,
featureImage(i,j,:)).^2, 3);
        expSumSquareDiffernce = exp(sumSquareDiffernce*(-1.0/h));
        dotWiseMult = img(minI:maxI,
minJ:maxJ).*expSumSquareDiffernce;
        filterImg(i,j) =
sum(dotWiseMult(:))/sum(expSumSquareDiffernce(:));
    end
end
end

```

myRsmd.m

```

function rsmdVal = myRsmd(img1,img2)
    [len, wid] = size(img1);
    rsmdVal = sqrt(sum(sum((img1-img2).^2))/(len*wid));
end

```

Contents

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- Super Moon Crop
- Lion Crop

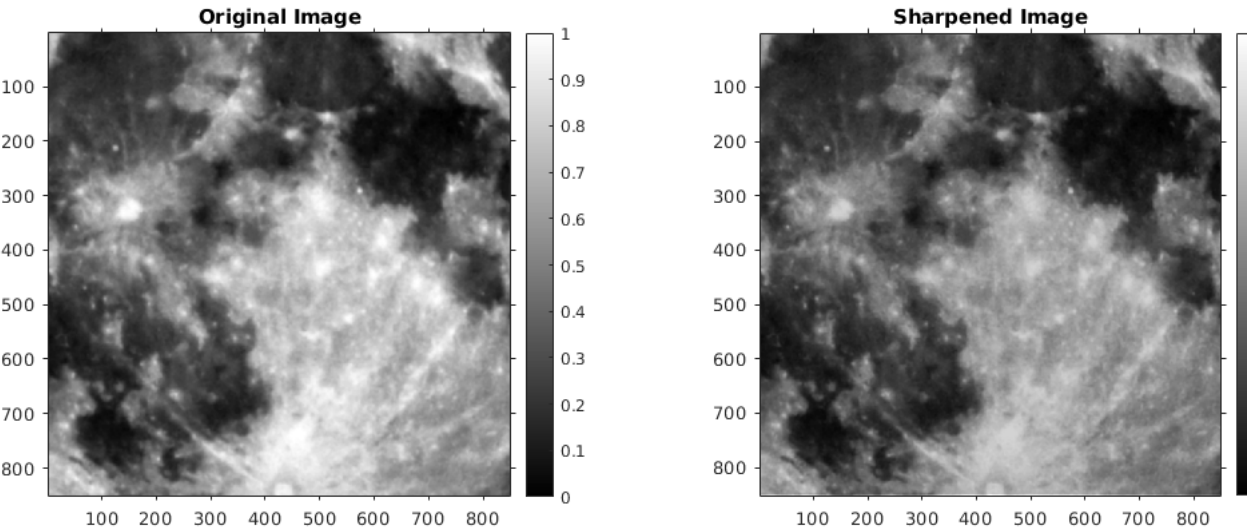
MyMainScript

```
tic;
```

Super Moon Crop

```
imageData = load('../data/superMoonCrop.mat');  
image = imageData.imageOrig;  
stretchedImage = myLinearContrastStretching(image);  
sharpImage = myUnsharpMasking(image,1.1,9,1.1);  
sharpImage = myLinearContrastStretching(sharpImage);  
myDisplayTwoImage(stretchedImage,sharpImage);
```

Sigma = 1.1 Window Size = 9 Scaling Factor = 1.1

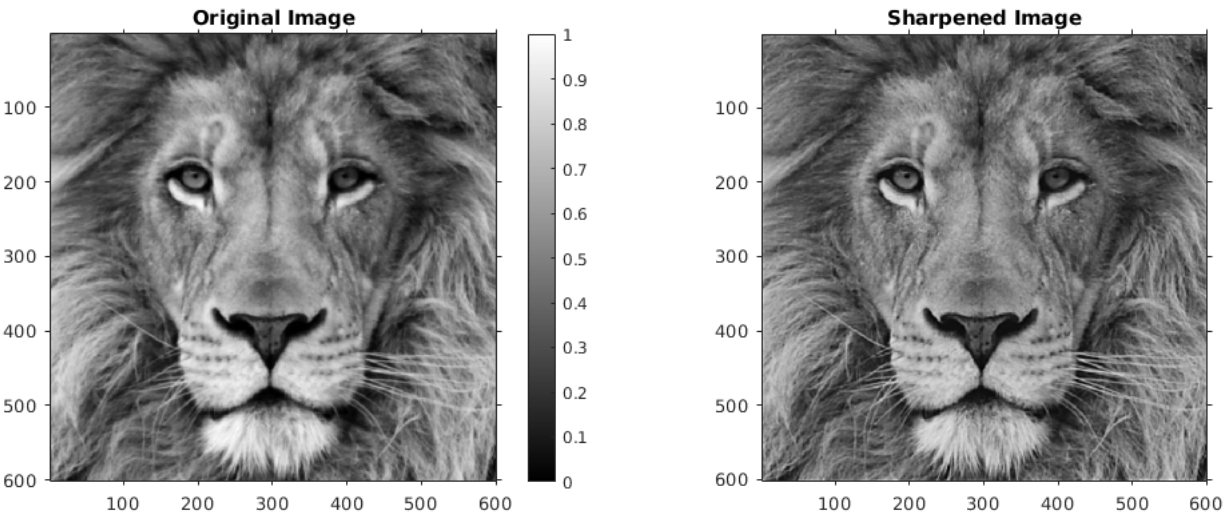


Lion Crop

```
imageData = load('../data/LionCrop.mat');  
image = imageData.imageOrig;  
stretchedImage = myLinearContrastStretching(image);  
sharpImage = myUnsharpMasking(image,1.1,9,1.6);  
sharpImage = myLinearContrastStretching(sharpImage);  
myDisplayTwoImage(stretchedImage,sharpImage);  
toc;
```

Sigma = 1.1 Window Size = 9 Scaling Factor = 1.6

Elapsed time is 1.680347 seconds.



Published with MATLAB® R2018a

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MyMainScript

```
tic;
```

Barbara

```
imageData = load('../data/barbara.mat');
image = imageData.imageOrig;
[len, wid] = size(image);
corruptedImage = image + 0.05*(max(max(image))-min(min(image)))*randn(len);

sigmaSpace = 1.6;
sigmaIntensity = 13.5;
windowSize = 4;
out = myBilateralFiltering(corruptedImage, sigmaSpace, sigmaIntensity, windowSize);
rmsd = myRmsd(out,image);
display(rmsd);
myDisplayThreeImage(image,corruptedImage,out);

out1 = myBilateralFiltering(corruptedImage, 0.9*sigmaSpace, sigmaIntensity, windowSize);
rmsd1 = myRmsd(out1,image);
display(rmsd1);

out2 = myBilateralFiltering(corruptedImage, 1.1*sigmaSpace, sigmaIntensity, windowSize);
rmsd2 = myRmsd(out2,image);
display(rmsd2);

out3 = myBilateralFiltering(corruptedImage, sigmaSpace, 0.9*sigmaIntensity, windowSize);
rmsd3 = myRmsd(out3,image);
display(rmsd3);

out4 = myBilateralFiltering(corruptedImage, sigmaSpace, 1.1*sigmaIntensity, windowSize);
rmsd4 = myRmsd(out4,image);
display(rmsd4);

figure;
filter = fspecial('gaussian',2*windowSize+1 ,sigmaSpace);
imshow(filter,'InitialMagnification','fit');
title("Spatial Gaussian Mask")
colormap(gray(200));
axis on;
colorbar;
```

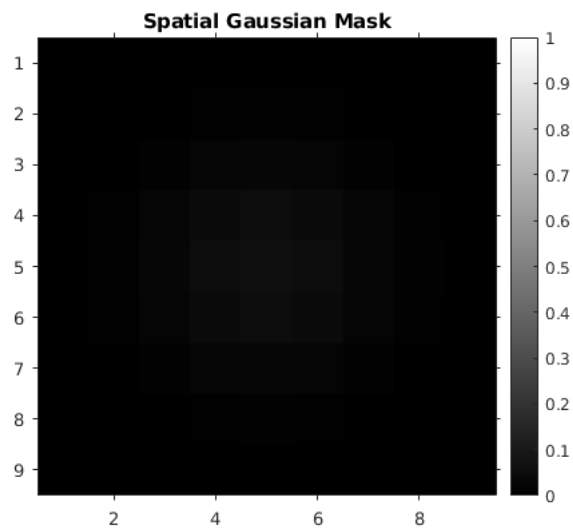
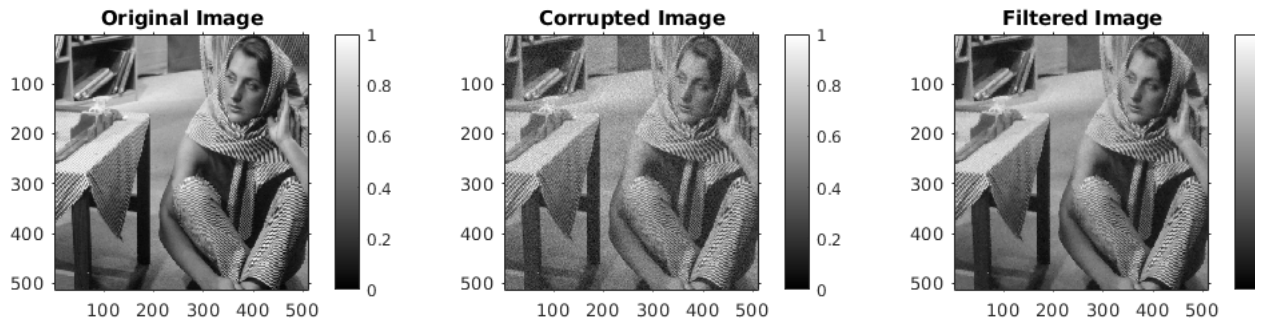
Optimal -> rmsd = 3.2807 (sigmaSpace = 1.6, sigmaIntensity = 13.5, windowSize = 9)

0.9*sigmaSpace -> rmsd1 = 3.2824 (sigmaSpace = 1.6*0.9, sigmaIntensity = 13.5, windowSize = 9)

1.1*sigmaSpace -> rmsd2 = 3.2847 (sigmaSpace = 1.6*0.1, sigmaIntensity = 13.5, windowSize = 9)

0.9*sigmaIntensity -> rmsd3 = 3.3102 (sigmaSpace = 1.6, sigmaIntensity = 13.5*0.9, windowSize = 9)

1.1*sigmaIntensity -> rmsd4 = 3.2895 (sigmaSpace = 1.6, sigmaIntensity = 13.5*1.1, windowSize = 9)



Grass

```
image = im2double(imread('../data/grass.png'));
[len, wid] = size(image);
corruptedImage = image + 0.05*(max(max(image))-min(min(image)))*randn(len);

sigmaSpace = 0.71;
sigmaIntensity = 0.31;
windowSize = 2;
out = myBilateralFiltering(corruptedImage, sigmaSpace, sigmaIntensity, windowSize);
rmsd = myRmsd(out, image);
display(rmsd);
myDisplayThreeImage(image, corruptedImage, out);

out1 = myBilateralFiltering(corruptedImage, 0.9*sigmaSpace, sigmaIntensity, windowSize);
rmsd1 = myRmsd(out1, image);
display(rmsd1);

out2 = myBilateralFiltering(corruptedImage, 1.1*sigmaSpace, sigmaIntensity, windowSize);
rmsd2 = myRmsd(out2, image);
display(rmsd2);

out3 = myBilateralFiltering(corruptedImage, sigmaSpace, 0.9*sigmaIntensity, windowSize);
rmsd3 = myRmsd(out3, image);
display(rmsd3);

out4 = myBilateralFiltering(corruptedImage, sigmaSpace, 1.1*sigmaIntensity, windowSize);
rmsd4 = myRmsd(out4, image);
display(rmsd4);

figure;
```

```

filter = fspecial('gaussian',2*windowSize+1,sigmaSpace);
imshow(filter,'InitialMagnification','fit');
title("Spatial Gaussian Mask")
colormap(gray(200));
axis on;
colorbar;

```

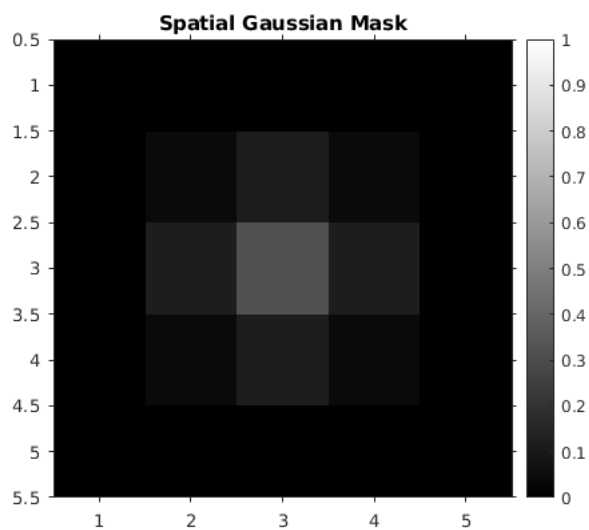
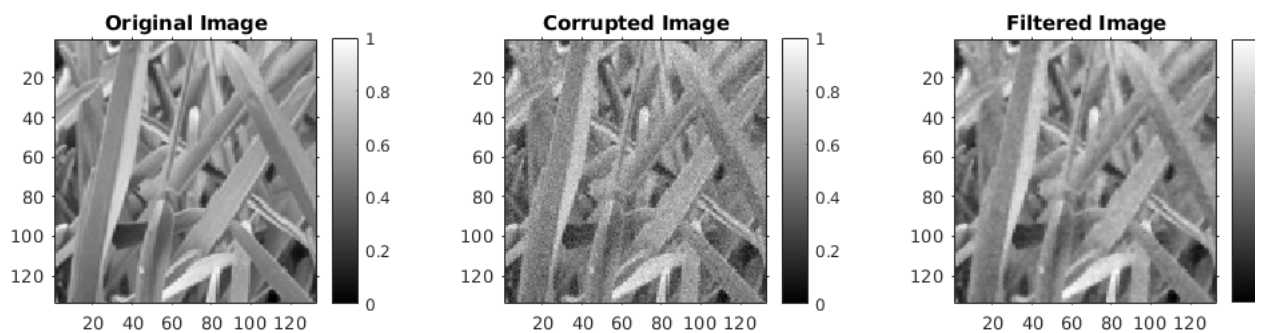
Optimal -> rmsd = 0.0289 (sigmaSpace = 0.71, sigmaIntensity = 0.31, windowSize = 5)

0.9*sigmaSpace -> rmsd1 = 0.0293 (sigmaSpace = 0.71*0.9, sigmaIntensity = 0.31, windowSize = 5)

1.1*sigmaSpace -> rmsd2 = 0.0290 (sigmaSpace = 0.71*0.1, sigmaIntensity = 0.31, windowSize = 5)

0.9*sigmaIntensity -> rmsd3 = 0.0289 (sigmaSpace = 0.71, sigmaIntensity = 0.31*0.9, windowSize = 5)

1.1*sigmaIntensity -> rmsd4 = 0.0289 (sigmaSpace = 0.71, sigmaIntensity = 0.31*1.1, windowSize = 5)



Honey Comb Real

```

image = im2double(imread('../data/honeyCombReal.png'));
[len, wid] = size(image);
corruptedImage = image + 0.05*(max(max(image))-min(min(image)))*randn(len);

```

```
sigmaSpace = 0.82;
sigmaIntensity = 0.27;
windowSize = 3;
out = myBilateralFiltering(corruptedImage, sigmaSpace, sigmaIntensity, windowSize);
rmsd = myRmsd(out,image);
display(rmsd);
myDisplayThreeImage(image,corruptedImage,out);

out1 = myBilateralFiltering(corruptedImage, 0.9*sigmaSpace, sigmaIntensity, windowSize);
rmsd1 = myRmsd(out1,image);
display(rmsd1);

out2 = myBilateralFiltering(corruptedImage, 1.1*sigmaSpace, sigmaIntensity, windowSize);
rmsd2 = myRmsd(out2,image);
display(rmsd2);

out3 = myBilateralFiltering(corruptedImage, sigmaSpace, 0.9*sigmaIntensity, windowSize);
rmsd3 = myRmsd(out3,image);
display(rmsd3);

out4 = myBilateralFiltering(corruptedImage, sigmaSpace, 1.1*sigmaIntensity, windowSize);
rmsd4 = myRmsd(out4,image);
display(rmsd4);

figure;
filter = fspecial('gaussian',2*windowSize+1 ,sigmaSpace);
imshow(filter,'InitialMagnification','fit');
title("Spatial Gaussian Mask")
colormap(gray(200));
axis on;
colorbar;

toc;
```

Optimal -> rmsd = 0.0288 (sigmaSpace = 0.82, sigmaIntensity = 0.27, windowSize = 7)

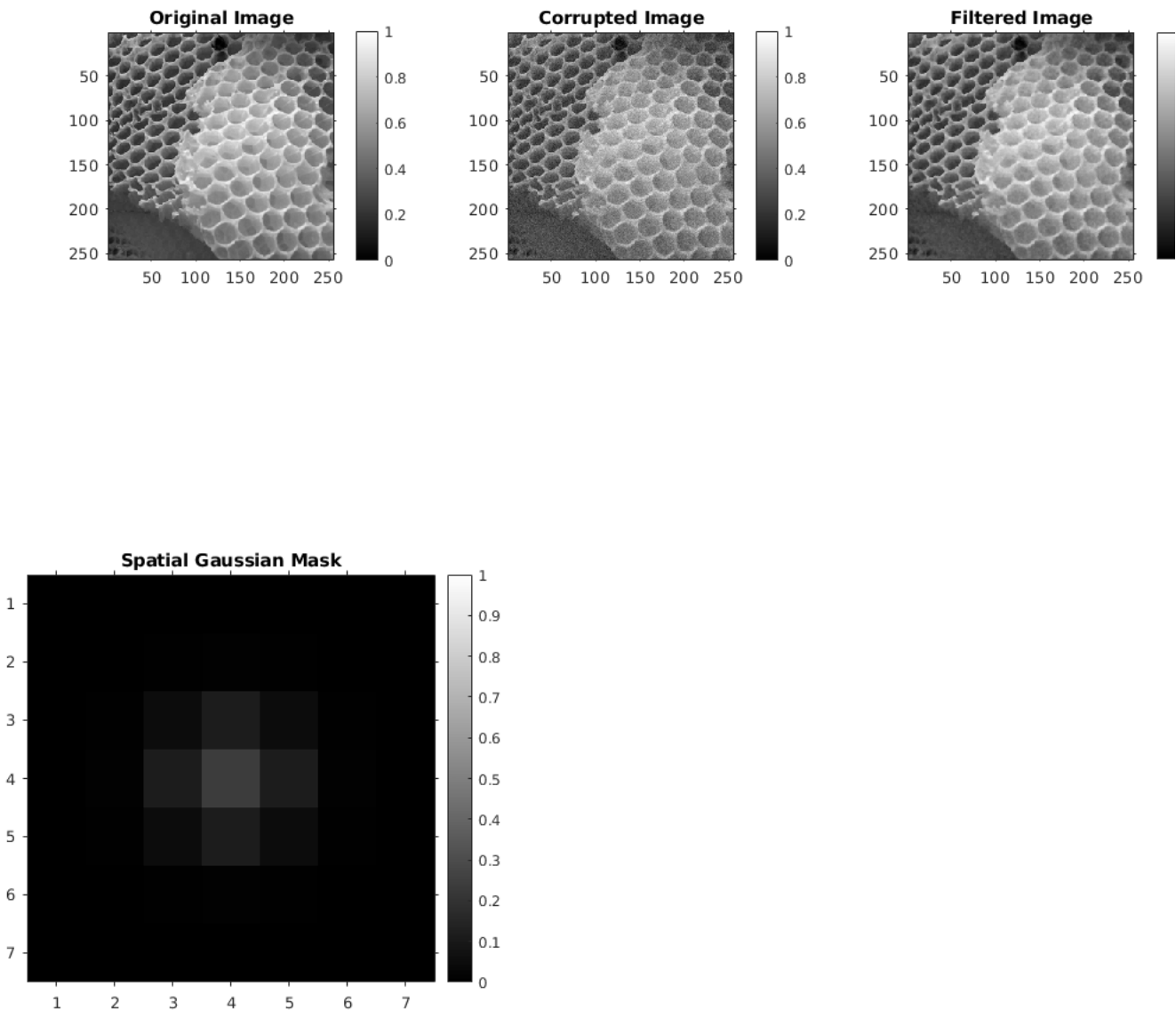
0.9*sigmaSpace -> rmsd1 = 0.0292 (sigmaSpace = 0.82*0.9, sigmaIntensity = 0.27, windowSize = 7)

1.1*sigmaSpace -> rmsd2 = 0.0289 (sigmaSpace = 0.82*0.1, sigmaIntensity = 0.27, windowSize = 7)

0.9*sigmaIntensity -> rmsd3 = 0.0288 (sigmaSpace = 0.82, sigmaIntensity = 0.27*0.9, windowSize = 7)

1.1*sigmaIntensity -> rmsd4 = 0.0290 (sigmaSpace = 0.82, sigmaIntensity = 0.27*1.1, windowSize = 7)

Elapsed time is 12.311102 seconds.



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- [Filtering Honey Comb image](#)

MyMainScript

```
tic;
```

Filtering Barbara image

```
load('../data/barbara.mat');
imageOrig = imgaussfilt(imageOrig,0.66);
imageOrig = imresize(imageOrig,0.5);
[len, wid] = size(imageOrig);
imgCorrupt = imageOrig + 0.05*(max(max(imageOrig))-min(min(imageOrig)))*randn(len);

h = 1.26;
patchSize = [9,9];
windowSize = [25,25];
out = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h);
rsmd0 = myRsmd(out,imageOrig);
display(rsmd0);
myDisplayThreeImage(imageOrig,imgCorrupt,out);

out1 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*0.9);
rsmd1 = myRsmd(out1,imageOrig);
display(rsmd1);

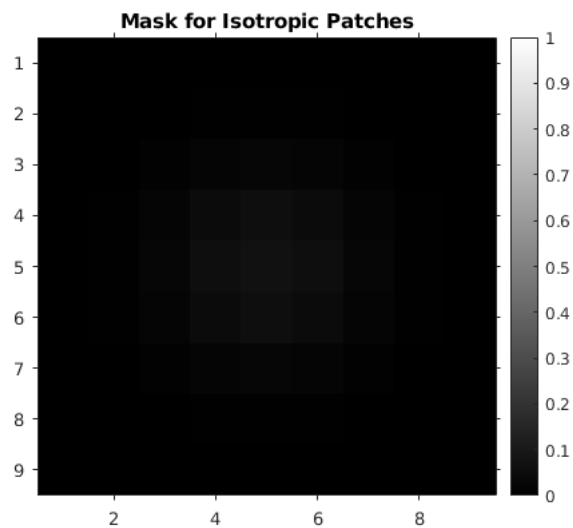
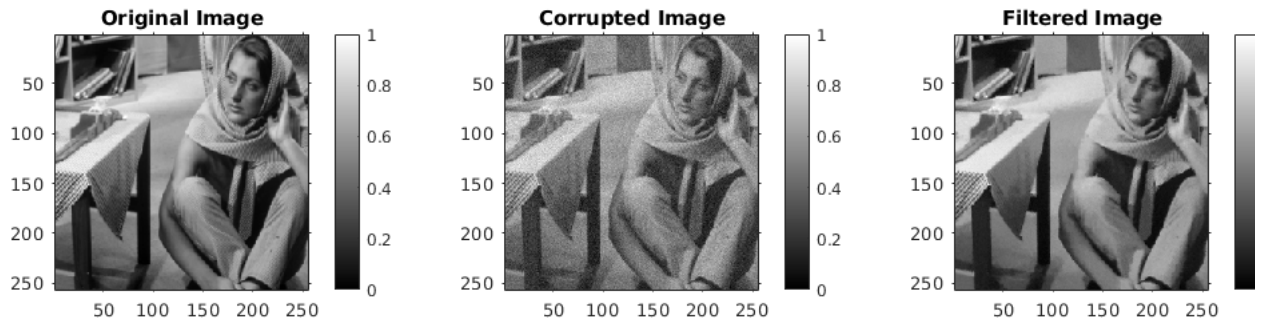
out2 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*1.1);
rsmd2 = myRsmd(out2,imageOrig);
display(rsmd2);

figure;
gaussianFilter = fspecial('gaussian', patchSize, double(patchSize(1))/6);
imshow(gaussianFilter,'InitialMagnification','fit');
title("Mask for Isotropic Patches")
colormap(gray(200));
axis on;
colorbar;
```

```
optimal h-> rsmd0 = 2.4216 (h=1.26)
```

```
0.9*h-> rsmd1 = 2.4295 (h=1.26*0.9)
```

```
1.1*h-> rsmd2 = 2.4309 (h=1.26*1.1)
```



Filtering Grass image

```
imageOrig = im2double(imread('./data/grass.png'));
[len, wid] = size(imageOrig);
imgCorrupt = imageOrig + 0.05*(max(max(imageOrig))-min(min(imageOrig)))*randn(len);

h = 0.000109;
patchSize = [9,9];
windowSize = [25,25];
out = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h);
rsmd0 = myRsmd(out, imageOrig);
display(rsmd0);
myDisplayThreeImage(imageOrig, imgCorrupt, out);

out1 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*0.9);
rsmd1 = myRsmd(out1, imageOrig);
display(rsmd1);

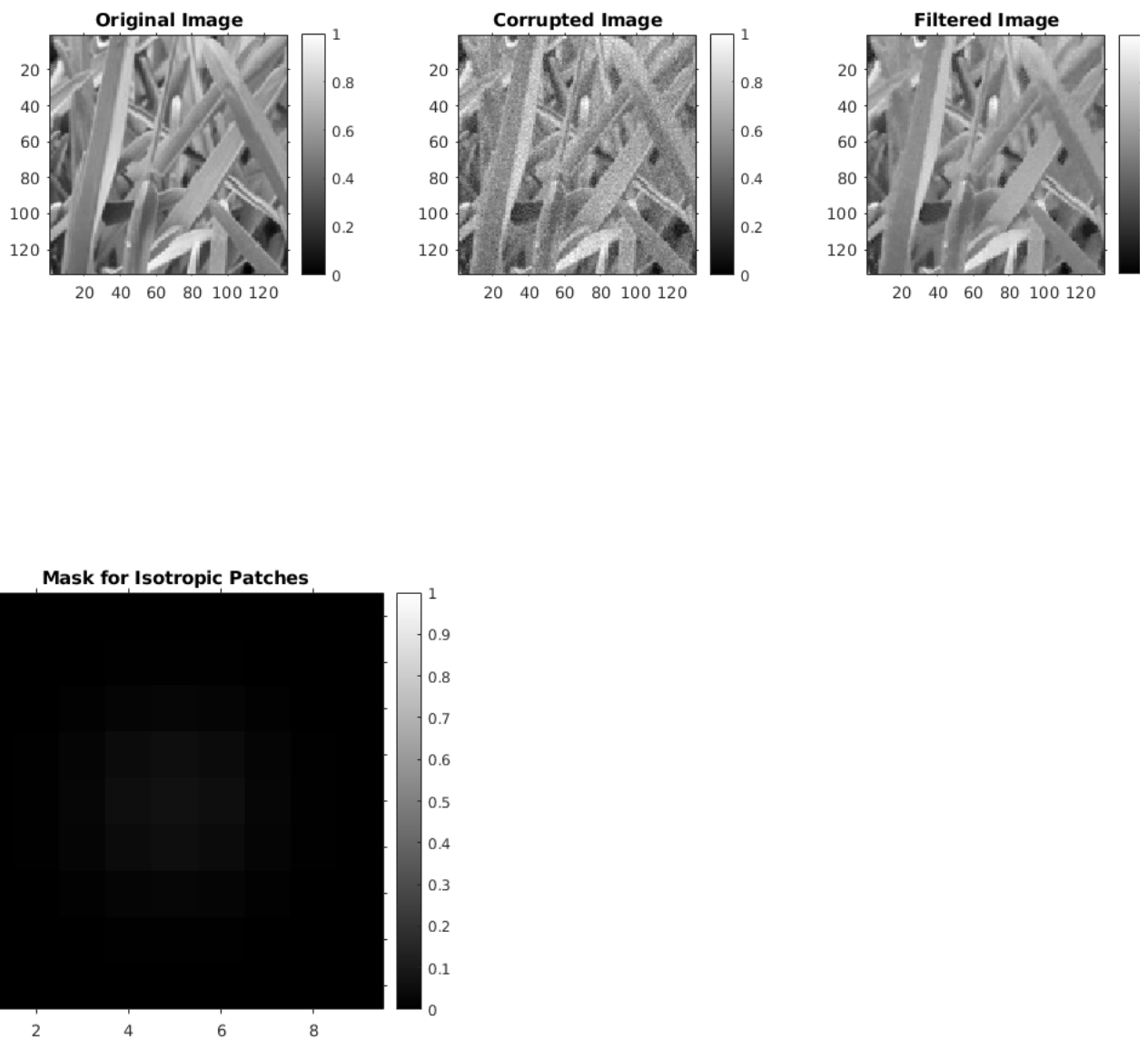
out2 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*1.1);
rsmd2 = myRsmd(out2, imageOrig);
display(rsmd2);

figure;
gaussianFilter = fspecial('gaussian', patchSize, double(patchSize(1))/6);
imshow(gaussianFilter, 'InitialMagnification', 'fit');
title("Mask for Isotropic Patches")
colormap(gray(200));
axis on;
colorbar;
```

```

optimal h-> rsmd0 = 0.0291 (h=0.000109)
0.9*h-> rsmd1 = 0.0293 (h=0.000109*0.9)
1.1*h-> rsmd2 = 0.0293 (h=0.000109*1.1)

```



Filtering Honey Comb image

```

imageOrig = imread('data/honeyCombReal.png');
[ len, wid] = size(imageOrig);
imgCorrupt = imageOrig + 0.05*(max(max(imageOrig))-min(min(imageOrig)))*randn(len);

h = 0.00013;
patchSize = [9,9];
windowSize = [25,25];
out = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h);
rsmd0 = myRsmd(out,imageOrig);
display(rsmd0);
myDisplayThreeImage(imageOrig,imgCorrupt,out);

out1 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*0.9);
rsmd1 = myRsmd(out1,imageOrig);
display(rsmd1);

out2 = myPatchBasedFiltering(imgCorrupt, patchSize, windowSize, h*1.1);
rsmd2 = myRsmd(out2,imageOrig);
display(rsmd2);

```



```

figure;
gaussianFilter = fspecial('gaussian', patchSize, double(patchSize(1))/6);
imshow(gaussianFilter, 'InitialMagnification', 'fit');
title("Mask for Isotropic Patches")
colormap(gray(200));
axis on;
colorbar;

toc;

```

optimal h-> rsmd0 = 0.0291 (h=0.00013)

0.9*h-> rsmd1 = 0.0293 (h=0.00013*0.9)

1.1*h-> rsmd2 = 0.0291 (h=0.00013*1.1)

Elapsed time is 115.620351 seconds.

