

# Binary Classification

Classifying the Red-wine Dataset

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A Club Project



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## 1 Github Repo

[Github Repo for project](#)

## 2 Logistic Regression

Since this is a classification problem, the natural approach would be to apply a regression model, squashed with a Sigmoid, to give the predicted probability of an example being positive or negative. We then find the softmax loss (Binary - case).

### 2.1 Forward Pass

$X \in \mathbb{R}^{N \times D}$  = Input Examples

$D$  = Number of Dimensions of Input Vector

$N$  = Number of Input Examples

$w \in \mathbb{R}^{D \times 2}$

$y \in \mathbb{R}^N$  = Correct Scores

$$z = w^T X + b \quad (1)$$

$$a = \sigma(z) \quad (2)$$

$$L = -1 * (\log(a)y + (1 - a)\log(1 - y)) \quad (3)$$

```
def sigmoid_forward(x, w, b):
    a = sigmoid(np.dot(x, w) + b)
    cache = (x, w, b, a)
    return a, cache

def cross_entropy_loss(a, y):
    y_new = y.reshape(a.shape)
    loss_vector = (-1 * ( y_new * np.log(a) + (1 - y_new) * np.log(1 - a) ) )
    loss = np.sum(loss_vector, axis = 0)
    cache = a, loss_vector, y_new
    return loss, cache
```

### 2.2 Backprop

After the loss we do a standard Backprop, however we can create a layer that does the backward passes of both the BCE and sigmoid layers together, the math is as follows : -

$$\frac{\partial L}{\partial a} = -1 * \left( \frac{y}{a} - \frac{1-y}{1-a} \right) \quad (4)$$

$$\frac{\partial L}{\partial z} = \frac{\partial L}{\partial a} * \frac{\partial a}{\partial z} \quad (5)$$

$$\frac{\partial a}{\partial z} = a(1-a) \dots \text{sigmoid derivative} \quad (6)$$

$$\therefore \frac{\partial L}{\partial z} = a - y \quad (7)$$

$$\boxed{\therefore \frac{\partial L}{\partial w} = X^T \times \frac{\partial L}{\partial z}} \quad (8)$$

```
def cross_entropy_and_sigmoid_backward(cache, y): # utility function for ease
    x, w, b, a = cache
    dz = a - y
    dw = np.dot(x.T, dz)
    db = np.sum(dz, axis=0)
    return dw, db
```

### 3 Solver

I have written code for Batch Gradient Descent and have also added the option of training with Momentum:-

Normal Gradient Descent

$$p = p - \alpha \frac{\partial L}{\partial p}$$

Gradient Descent with momentum See :-  $\mu$  is Just a Friction factor to stop the gradient descent eventually this is a hyper-parameter set to 0.9

$$V_p = \mu V_p - \alpha \frac{\partial L}{\partial p} \quad (9)$$

$$p = p + V_p \quad (10)$$

### 3.1 Results With Momentum

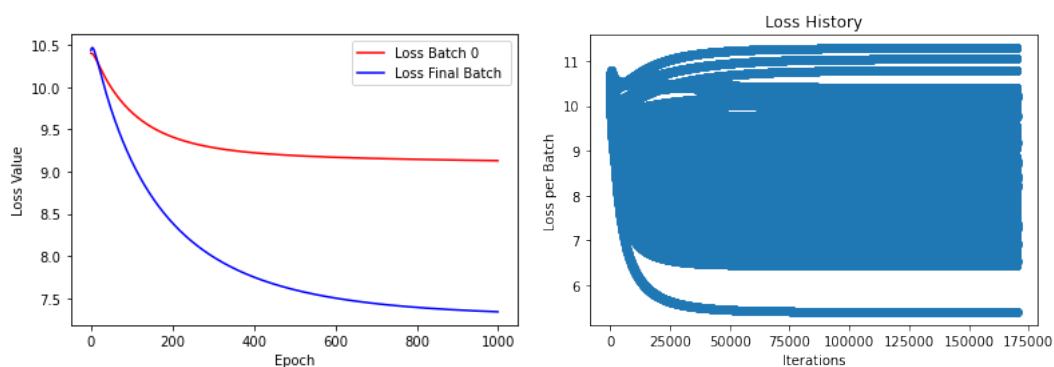


Figure 1: Losses during training  $\alpha = 1.7e - 4, \mu = 0.9$  , batch size = 15

### 3.2 Results without Momentum for same Learning Rate

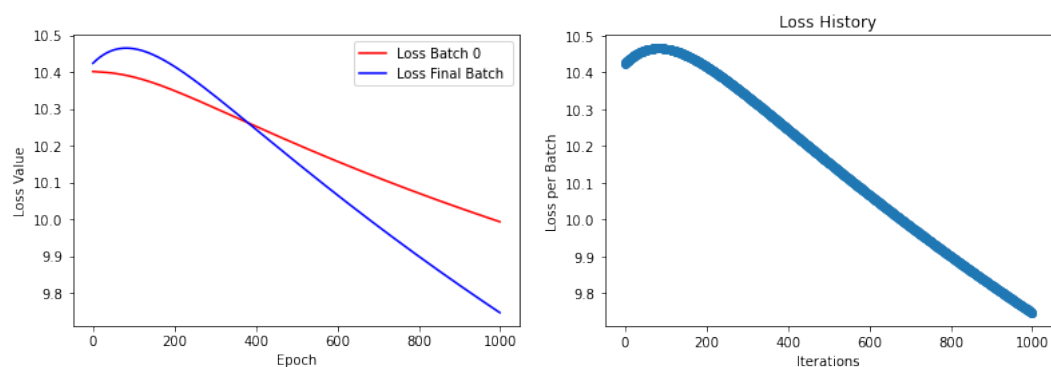


Figure 2: Losses during training

### 3.3 Accuracy

Train Accuracy with Momentum :- 74.43%

Test Accuracy with Momentum :- 73.53%

## 4 Neural Network

I have implemented a simple two Layer Net from Scratch.

Model is :-  $Affine - RELU - Affine - Softmax$

I learnt the necessary Material from the course I was doing :- [CS231N](#)

### 4.1 Back-prop Through a Softmax

$$L = \frac{1}{N} \sum_{i=1}^{i=N} -\log \left( \frac{e^{S_{ij}}}{\sum_j e^{S_{ij}}} \right) \dots S_j \text{ is correct class Score} \quad (11)$$

$$(12)$$

$$\frac{\partial L}{\partial S_{kl}} = \frac{-1}{N} \sum_{i=1}^{i=N} \left( \frac{\sum_j e^{S_{ij}} - e^{S_{ij}}}{\sum_j e^{S_{ij}}} \right) \dots \text{if } k, l = i, j \quad (13)$$

$$\frac{\partial L}{\partial S_{kl}} = \frac{-1}{N} \sum_{i=1}^{i=N} \left( 1 - \frac{e^{S_{ij}}}{\sum_j e^{S_{ij}}} \right) \dots \text{if } k, l = i, j, \frac{\partial L}{\partial S_{kl}} = 0 \dots \text{if } k, l \neq i, j \quad (14)$$

*#code inside Models/Layers.py*

```
def softmax_loss(x, y): # this is a numerically stable version of cross entropy loss
    probs = np.exp(x - np.max(x, axis=1, keepdims=True))
    probs /= np.sum(probs, axis=1, keepdims=True)
    N = x.shape[0]
    loss = -np.sum(np.log(probs[np.arange(N), y])) / N
    dx = probs.copy()
    dx[np.arange(N), y] -= 1
    dx /= N
    return loss, dx
```

Rest of the backprps are obvious.

### 4.2 Training

The training process is still going on, SGD + momentum has been used to train the model.

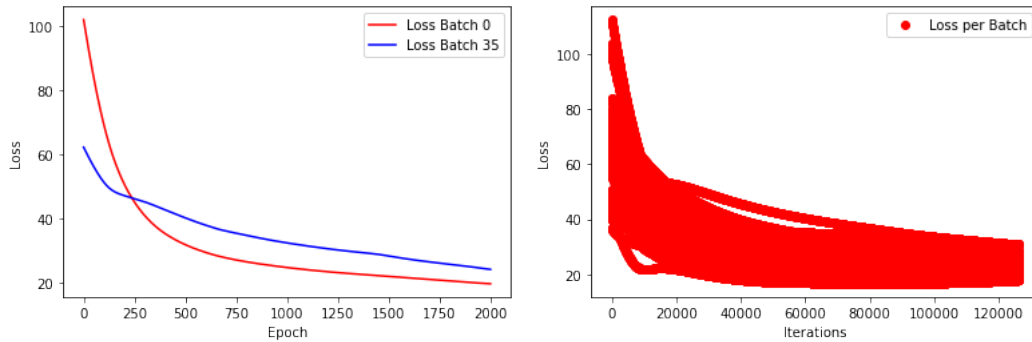


Figure 3: Losses with Momentum

### 4.3 Accuracy

This model is still a work in progress.

Training Accuracy = 51%

Testing Accuracy = 49.375%