FINITE ELEMENT METHOD FOR MAGNETODYNAMIC APPLICATIONS

2019

Contents

1	The	cory	4
	1.1	2D Magnetodynamic equations	4
	1.2	Boundary condition	4
	1.3	Initial condition	4
	1.4	Force	4
	1.5	Weak formulation	5

Symbols

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[\mathrm{Wb}\cdot\mathrm{m}^{-1}]
                               magnetic vector potential
\boldsymbol{A}
                               magnetic flux density
\boldsymbol{B}
          [T]
f
          Hz
                               frequency
          [A \cdot m^{-2}]
\boldsymbol{J}
                               current density
l
          [m]
                               line
                               length of the model (z coordinate)
L
          \mathbf{m}
                               normal vector
\boldsymbol{n}
          [-]
S
          [\mathrm{m}^2]
                               surface
t
          \mathbf{S}
                               _{\rm time}
          [\mathrm{N}\cdot\mathrm{m}^{-2}]
T, \mathbb{T}
                               Maxwell stress tensor
          [\mathrm{m}\cdot\mathrm{s}^{-1}]
                               velocity
\boldsymbol{v}
          [\mathrm{m}^3]
V
                               volume
          [S \cdot m^{-1}]
                               conductivity
\gamma
\lambda
          [ - ]
                               basis function
          [\mathrm{H}\cdot\mathrm{m}^{-1}]
                               permeability of vacuum
\mu_0
          [\mathrm{H}\cdot\mathrm{m}^{-1}]
                               permeability
\mu
          [ - ]
                               test function
\varphi
\Omega
          [ - ]
                               closed region
          [-]
\partial\Omega
                               boundary of closed region
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1 Theory

1.1 2D Magnetodynamic equations

Cartesian coordinate system (x, y, z)

$$\nabla \times \left(\frac{1}{\mu} \left(\nabla \times \boldsymbol{A}\right)\right) + \gamma \frac{\partial \boldsymbol{A}}{\partial t} - \gamma \left(\boldsymbol{v} \times \left(\nabla \times \boldsymbol{A}\right)\right) = \boldsymbol{J}$$
(1.1)

$$\mathbf{A} = (0, 0, A_z) \tag{1.2}$$

$$\boldsymbol{J} = (0, 0, J_z) \tag{1.3}$$

$$\boldsymbol{v} = (v_x, v_y, 0) \tag{1.4}$$

$$\mathbf{B} = \nabla \times \mathbf{A} = (\partial_y A_x, -\partial_x A_y, 0) = (B_x, B_y, 0) \tag{1.5}$$

$$\boldsymbol{v} \times \boldsymbol{B} = (0, 0, v_x B_y - v_y B_x) \tag{1.6}$$

$$\boldsymbol{A}, \boldsymbol{J}, \boldsymbol{v} = f(x, y, t) \tag{1.7}$$

Linear
$$\mu, \gamma = f(x, y)$$
 Nonlinear $\mu = f(x, y, ||\boldsymbol{B}||)$ (1.8)

1.2 Boundary condition

$$A_z \bigg|_{\partial\Omega} = 0 \tag{1.9}$$

1.3 Initial condition

$$A_z \bigg|_{t=0} = 0 \tag{1.10}$$

1.4 Force

$$T_{ij} = \frac{1}{\mu_0} \left(B_i B_j - \frac{1}{2} B^2 \delta_{ij} \right) \tag{1.11}$$

$$\mathbb{T} = \frac{1}{\mu_0} \begin{pmatrix} B_x B_x & B_x B_y \\ B_y B_x & B_y B_y \end{pmatrix} - \frac{1}{2\mu_0} \begin{pmatrix} B_x^2 + B_y^2 & 0 \\ 0 & B_x^2 + B_y^2 \end{pmatrix}$$
(1.12)

3D
$$\mathbf{F}(x, y, z) = \oint_{\partial \Omega} \mathbb{T} d\mathbf{S} = \int_{\Omega} (\nabla \cdot \mathbb{T}) dV$$
 (1.13)

2D
$$\mathbf{F}(x,y) = L \oint_{\partial\Omega} \mathbb{T} d\mathbf{l} = L \int_{\Omega} (\nabla \cdot \mathbb{T}) dS$$
 (1.14)

$$\nabla \cdot \mathbb{T} = \frac{1}{\mu_0} \left(\partial_x, \partial_y \right) \begin{pmatrix} \frac{1}{2} \left(B_x^2 - B_y^2 \right) & B_x B_y \\ B_y B_x & \frac{1}{2} \left(B_y^2 - B_x^2 \right) \end{pmatrix}$$
(1.15)

$$\nabla \cdot \mathbb{T} = \frac{1}{\mu_0} \left(\frac{1}{2} \partial_x \left(B_x^2 - B_y^2 \right) + \partial_y \left(B_y B_x \right), \frac{1}{2} \partial_y \left(B_y^2 - B_x^2 \right) + \partial_x \left(B_x B_y \right) \right)$$
(1.16)

$$\nabla \cdot \mathbb{T}(x) = \frac{1}{\mu_0} \left(\partial_x B_x B_x - \partial_x B_y B_y + \partial_y B_y B_x + \partial_y B_x B_y \right)$$
 (1.17)

$$\nabla \cdot \mathbb{T}(y) = \frac{1}{\mu_0} \left(\partial_y B_y B_y - \partial_y B_x B_x + \partial_x B_x B_y + \partial_x B_y B_x \right)$$
 (1.18)

1.5 Weak formulation

$$\int_{\Omega} \nabla \times \left(\frac{1}{\mu} (\nabla \times \mathbf{A}) \right) \boldsymbol{\varphi} \, dS = \int_{\Omega} \frac{1}{\mu} (\nabla \times \mathbf{A}) (\nabla \times \boldsymbol{\varphi}) \, dS - \\
- \int_{\partial \Omega} \frac{1}{\mu} (\mathbf{n} \times (\nabla \times \mathbf{A})) \boldsymbol{\varphi} \, dl$$
(1.19)

$$\boldsymbol{\varphi} \in f(\Omega) : \boldsymbol{\varphi}|_{\partial\Omega} = 0 \to -\int_{\partial\Omega} \frac{1}{\mu} \left(\boldsymbol{n} \times (\nabla \times \boldsymbol{A}) \right) \boldsymbol{\varphi} \, \mathrm{d}l = 0$$

$$\mathbf{A}(x,y,t) \approx \sum_{n=1}^{N} A^{n}(t) \lambda^{n}(x,y)$$
(1.20)

$$\boldsymbol{J}(x,y,t) \approx \sum_{n=1}^{N} J^{n}(t) \lambda^{n}(x,y)$$
 (1.21)

$$\varphi(x, y, t) \approx \sum_{n=1}^{N} \varphi^{n}(t) \lambda^{n}(x, y)$$
 (1.22)

$$\int_{\Omega} \frac{1}{\mu} (\nabla \times \mathbf{A}) (\nabla \times \boldsymbol{\varphi}) dS \approx \sum_{n=1}^{N} \int_{\Omega} \frac{1}{\mu} A^{n} (\nabla \times \lambda^{n}) \varphi^{m} (\nabla \times \lambda^{m}) dS$$
 (1.23)

$$\int_{\Omega} \boldsymbol{J} \boldsymbol{\varphi} \, \mathrm{d}S \approx \sum_{n=1}^{N} \int_{\Omega} J^{n} \lambda^{n} \varphi^{m} \lambda^{m} \, \mathrm{d}S$$
 (1.24)

$$\int_{\Omega} \gamma \frac{\partial \mathbf{A}}{\partial t} \boldsymbol{\varphi} \, \mathrm{d}S \tag{1.25}$$

$$\int_{\Omega} \gamma \left(\boldsymbol{v} \times (\nabla \times \boldsymbol{A}) \right) \boldsymbol{\varphi} \, \mathrm{d}S \tag{1.26}$$