FINITE ELEMENT METHOD FOR MAGNETODYNAMIC APPLICATIONS

2019

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Symbols

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[\mathrm{Wb}\cdot\mathrm{m}^{-1}]
                              magnetic vector potential
\boldsymbol{A}
                              magnetic flux density
\boldsymbol{B}
          [T]
f
          Hz
                               frequency
          [A \cdot m^{-2}]
\boldsymbol{J}
                               current density
l
          [m]
                               line
                              length of the model (z coordinate)
L
          [m]
                               normal vector
\boldsymbol{n}
          [-]
S
          [\mathrm{m}^2]
                               surface
t
          \mathbf{S}
                               _{\rm time}
          [\mathrm{N}\cdot\mathrm{m}^{-2}]
T, \mathbb{T}
                               Maxwell stress tensor
          [\mathrm{m}\cdot\mathrm{s}^{-1}]
                               velocity
\boldsymbol{v}
          [\mathrm{m}^3]
V
                               volume
          [S \cdot m^{-1}]
                               conductivity
\gamma
\lambda
          [ - ]
                               basis function
          [\mathrm{H}\cdot\mathrm{m}^{-1}]
                               permeability of vacuum
\mu_0
          [\mathrm{H}\cdot\mathrm{m}^{-1}]
                               permeability
\mu
          [ - ]
                               test function
\varphi
\Omega
          [ - ]
                               closed region
          [-]
\partial\Omega
                               boundary of closed region
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1 Theory

1.1 2D Magnetodynamic equations

Cartesian coordinate system (x, y, z)

$$\nabla \times \left(\frac{1}{\mu} \left(\nabla \times \boldsymbol{A}\right)\right) + \gamma \frac{\partial \boldsymbol{A}}{\partial t} - \gamma \left(\boldsymbol{v} \times \left(\nabla \times \boldsymbol{A}\right)\right) = \boldsymbol{J}$$
(1.1)

$$\mathbf{A} = (0, 0, A_z) \tag{1.2}$$

$$\boldsymbol{J} = (0, 0, J_z) \tag{1.3}$$

$$\boldsymbol{v} = (v_x, v_y, 0) \tag{1.4}$$

$$\mathbf{B} = \nabla \times \mathbf{A} = (\partial_y A_x, -\partial_x A_y, 0) = (B_x, B_y, 0) \tag{1.5}$$

$$\boldsymbol{v} \times \boldsymbol{B} = (0, 0, v_x B_y - v_y B_x) \tag{1.6}$$

$$\boldsymbol{A}, \boldsymbol{J}, \boldsymbol{v} = f(x, y, t) \tag{1.7}$$

Linear
$$\mu, \gamma = f(x, y)$$
 Nonlinear $\mu = f(x, y, ||\boldsymbol{B}||)$ (1.8)

1.2 Boundary condition

$$A_z \bigg|_{\partial\Omega} = 0 \tag{1.9}$$

1.3 Initial condition

$$A_z \bigg|_{t=0} = 0 \tag{1.10}$$

1.4 Force

$$T_{ij} = \frac{1}{\mu_0} \left(B_i B_j - \frac{1}{2} B^2 \delta_{ij} \right) \tag{1.11}$$

$$\mathbb{T} = \frac{1}{\mu_0} \begin{pmatrix} B_x B_x & B_x B_y \\ B_y B_x & B_y B_y \end{pmatrix} - \frac{1}{2\mu_0} \begin{pmatrix} B_x^2 + B_y^2 & 0 \\ 0 & B_x^2 + B_y^2 \end{pmatrix}$$
(1.12)

3D
$$\mathbf{F}(x, y, z) = \oint_{\partial \Omega} \mathbb{T} d\mathbf{S} = \int_{\Omega} (\nabla \cdot \mathbb{T}) dV$$
 (1.13)

2D
$$\mathbf{F}(x,y) = L \oint_{\partial\Omega} \mathbb{T} d\mathbf{l} = L \int_{\Omega} (\nabla \cdot \mathbb{T}) dS$$
 (1.14)

$$\nabla \cdot \mathbb{T} = \frac{1}{\mu_0} \left(\partial_x, \partial_y \right) \begin{pmatrix} \frac{1}{2} \left(B_x^2 - B_y^2 \right) & B_x B_y \\ B_y B_x & \frac{1}{2} \left(B_y^2 - B_x^2 \right) \end{pmatrix}$$
(1.15)

$$\nabla \cdot \mathbb{T} = \frac{1}{\mu_0} \left(\frac{1}{2} \partial_x \left(B_x^2 - B_y^2 \right) + \partial_y \left(B_y B_x \right), \frac{1}{2} \partial_y \left(B_y^2 - B_x^2 \right) + \partial_x \left(B_x B_y \right) \right)$$
(1.16)

$$\nabla \cdot \mathbb{T}(x) = \frac{1}{\mu_0} \left(\partial_x B_x B_x - \partial_x B_y B_y + \partial_y B_y B_x + \partial_y B_x B_y \right)$$
 (1.17)

$$\nabla \cdot \mathbb{T}(y) = \frac{1}{\mu_0} \left(\partial_y B_y B_y - \partial_y B_x B_x + \partial_x B_x B_y + \partial_x B_y B_x \right)$$
 (1.18)

1.5 Weak formulation

$$\int_{\Omega} \nabla \times \left(\frac{1}{\mu} (\nabla \times \mathbf{A}) \right) \boldsymbol{\varphi} \, dS = \int_{\Omega} \frac{1}{\mu} (\nabla \times \mathbf{A}) (\nabla \times \boldsymbol{\varphi}) \, dS - \\
- \int_{\partial \Omega} \frac{1}{\mu} (\mathbf{n} \times (\nabla \times \mathbf{A})) \boldsymbol{\varphi} \, dl$$
(1.19)

$$\boldsymbol{\varphi} \in f(\Omega) : \boldsymbol{\varphi}|_{\partial\Omega} = 0 \to -\int_{\partial\Omega} \frac{1}{\mu} \left(\boldsymbol{n} \times (\nabla \times \boldsymbol{A}) \right) \boldsymbol{\varphi} \, \mathrm{d}l = 0$$

$$\mathbf{A}(x,y,t) \approx \sum_{n=1}^{N} A^{n}(t) \lambda^{n}(x,y)$$
 (1.20)

$$\boldsymbol{J}(x,y,t) \approx \sum_{n=1}^{N} J^{n}(t) \lambda^{n}(x,y)$$
(1.21)

$$\varphi(x, y, t) \approx \sum_{n=1}^{N} \varphi^{n}(t) \lambda^{n}(x, y)$$
 (1.22)

$$\int_{\Omega} \frac{1}{\mu} (\nabla \times \mathbf{A}) (\nabla \times \boldsymbol{\varphi}) dS \approx \sum_{n=1}^{N} \int_{T_n} \frac{1}{\mu} A^n (\nabla \times \lambda^n) \varphi^m (\nabla \times \lambda^m) dS$$
 (1.23)

$$\int_{\Omega} \boldsymbol{J} \boldsymbol{\varphi} \, \mathrm{d}S \approx \sum_{n=1}^{N} \int_{T_n} J^n \lambda^n \varphi^m \lambda^m \, \mathrm{d}S$$
 (1.24)

1.6 Magnetostatic case

$$\sum_{n=1}^{N} \int_{T_n} \frac{1}{\mu} A^n (\nabla \times \lambda^n) (\nabla \times \lambda^m) dS = \sum_{n=1}^{N} \int_{T_n} J^n \lambda^n \lambda^m dS$$
 (1.25)

$$\frac{1}{\mu}[S][A] = [M][J] \tag{1.26}$$

$$(\nabla \times \lambda^n) (\nabla \times \lambda^m) = (\partial_y \lambda^n, -\partial_x \lambda^n) (\partial_y \lambda^m, -\partial_x \lambda^m)$$
 (1.27)

$$(\partial_y \lambda^n, -\partial_x \lambda^n) (\partial_y \lambda^m, -\partial_x \lambda^m) = \partial_y \lambda^n \partial_y \lambda^m + \partial_x \lambda^n \partial_x \lambda^m$$
 (1.28)

$$[S]_{T_n} = [S_y]_{T_n} + [S_x]_{T_n} = \int_{T_n} (\partial_y \lambda^n \partial_y \lambda^m) \, dS + \int_{T_n} (\partial_x \lambda^n \partial_x \lambda^m) \, dS$$
 (1.29)

Basis functions on reference triangle (r, s, t)

$$\beta_1 = 1 - r - s \tag{1.30}$$

$$\beta_2 = r \tag{1.31}$$

$$\beta_3 = s \tag{1.32}$$

$$[\partial \beta] = \begin{pmatrix} \partial_r \beta_1 & \partial_r \beta_2 & \partial_r \beta_3 \\ \partial_s \beta_1 & \partial_s \beta_2 & \partial_s \beta_3 \end{pmatrix} = \begin{pmatrix} -1 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$
(1.33)

Coordinate transformation

$$\Phi\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + \begin{pmatrix} x_2 - x_1 & x_3 - x_1 \\ y_2 - y_1 & y_3 - y_1 \end{pmatrix} \begin{pmatrix} r \\ s \end{pmatrix}$$
(1.34)

$$\lambda(x,y) = (\beta \circ \Phi^{-1})(x,y) \tag{1.37}$$

$$|\det (\nabla \Phi)| = \left| \det \begin{pmatrix} x_2 - x_1 & x_3 - x_1 \\ y_2 - y_1 & y_3 - y_1 \end{pmatrix} \right|$$
 (1.38)

$$(\nabla \Phi)^{-1} = \frac{1}{|\det(\nabla \Phi)|} \begin{pmatrix} y_3 - y_1 & -(x_3 - x_1) \\ -(y_2 - y_1) & x_2 - x_1 \end{pmatrix}$$
(1.39)

$$[S_y]_{T_n} = \int_{T_n} (\partial_y \lambda^n \partial_y \lambda^m) \, dS = \int_{T_n} (\partial_y (\beta^n \circ \Phi^{-1}) \, \partial_y (\beta^m \circ \Phi^{-1})) \, dS$$
 (1.40)

$$\partial_y \left(\beta^n \circ \Phi^{-1} \right) = \left(\partial_{\Phi^{-1}} \beta^n \right) \left(\partial_y \Phi^{-1} \right) \tag{1.41}$$

$$[S_y]_{T_n} = \int_{T_n} (\partial_{\Phi^{-1}} \beta^n) \left(\partial_y \Phi^{-1} \right) \left(\partial_{\Phi^{-1}} \beta^m \right) \left(\partial_y \Phi^{-1} \right) dS$$
 (1.42)

$$[S_y]_{T_r} = |\det(\nabla \Phi)| (0,1) \int_{T_r} [\partial \beta] (\nabla \Phi)^{-1} dS$$
(1.43)

$$[S_x]_{T_r} = \frac{1}{2} (1,0) [\partial \beta] (\nabla \Phi)^{-1} |\det (\nabla \Phi)|$$
(1.44)

$$[S_y]_{T_r} = \frac{1}{2} (0,1) [\partial \beta] (\nabla \Phi)^{-1} |\det (\nabla \Phi)|$$
(1.45)

LocalMatrices.m

$$\begin{split} \text{edet} &= |\text{det}\left(\nabla\Phi\right)| \\ \text{dFinv} &= (\nabla\Phi)^{-1} \\ \text{dphi} &= (\nabla\Phi)^{-1}\left[\partial\beta\right] \\ \text{slocxx} &= \left[S_x\right]_{T_r} = 1/2 \, * \, \text{dphi}(\texttt{1,:}) \, * \, * \, \text{dphi}(\texttt{1,:}) \, * \, * \, \text{edet} \\ \text{slocyy} &= \left[S_y\right]_{T_r} = 1/2 \, * \, \text{dphi}(\texttt{2,:}) \, * \, * \, \text{dphi}(\texttt{2,:}) \, * \, * \, \text{edet} \end{split}$$