

In[43]:=

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In[44]:= k1 = Mod[441 + 380 + 305 + 379, 2]
          k2 = Mod[441 + 380 + 305 + 379, 2 ^ 2]
          k3 = Mod[441 + 380 + 305 + 379, 2 ^ 3]
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Out[44]= 1

Out[45]= 1

Out[46]= 1

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In[47]:=  $\theta_0 = \pi / k_2$ 
           $\phi_0 = 2 \pi / k_3$ 
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Out[47]= π

Out[48]= 2π

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In[49]:= (Ket[1] = {{0}, {1}}) // MatrixForm
          (Ket[0] = {{1}, {0}}) // MatrixForm
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Out[49]//MatrixForm=

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Out[50]//MatrixForm=

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

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In[51]:= (u1[ $\phi_0$ ] = {{1, 0}, {0, e ^ (I  $\phi_0$ )}}) // MatrixForm
          (u3[ $\theta_0$ , 0, 0] = {{Cos[ $\theta_0$  / 2], - Sin[ $\theta_0$  / 2]}, {Sin[ $\theta_0$  / 2], Cos[ $\theta_0$  / 2]}}) // MatrixForm
          Bra[l_] := Simplify [Ket[l]*]
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Out[51]//MatrixForm=

$$\begin{pmatrix} 1 & 0 \\ 0 & e^{i \phi_0} \end{pmatrix}$$

Out[52]//MatrixForm=

$$\begin{pmatrix} \cos\left[\frac{\theta_0}{2}\right] & -\sin\left[\frac{\theta_0}{2}\right] \\ \sin\left[\frac{\theta_0}{2}\right] & \cos\left[\frac{\theta_0}{2}\right] \end{pmatrix}$$

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In[54]:= (u1[ $\phi_0$ ].u3[ $\theta_0$ , 0, 0].Ket[1]) // MatrixForm
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Out[54]//MatrixForm=

$$\begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

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In[55]:= pxd[0 x] = 0.49125
          pxd[1 x] = 0.50875
          pyd[0 y] = 0.49925
          pyd[1 y] = 0.50075
          pzd[0 z] = 1.0
          pzd[1 z] = 0.0

Out[55]= 0.49125

Out[56]= 0.50875

Out[57]= 0.49925

Out[58]= 0.50075

Out[59]= 1.

Out[60]= 0.

In[61]:= Pxd = pxd[0 x] - pxd[1 x]
          Pyd = pyd[0 y] - pyd[1 y]
          Pzd = pzd[0 z] - pzd[1 z]

Out[61]= -0.0175

Out[62]= -0.0015

Out[63]= 1.

In[64]:= Pdn = {Pxd , Pyd , Pzd}

Out[64]= {-0.0175 , -0.0015 , 1.}

In[65]:= nPd2 = Pdn . Pdn

Out[65]= 1.00031

In[66]:= Pd = (1 / Sqrt[nPd2]) * Pdn

Out[66]= {-0.0174973 , -0.00149977 , 0.999846 }

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In[67]:=  $\sigma_x = \text{PauliMatrix}[1]$ 
 $\sigma_y = \text{PauliMatrix}[2]$ 
 $\sigma_z = \text{PauliMatrix}[3]$ 
 $\sigma = \{\{\sigma_x\}, \{\sigma_y\}, \{\sigma_z\}\}$ 
 $(\sigma Pd = \text{Flatten}[Pd.\sigma, 1]) // \text{MatrixForm}$ 

Out[67]=  $\{\{0, 1\}, \{1, 0\}\}$ 

Out[68]=  $\{\{0, -i\}, \{i, 0\}\}$ 

Out[69]=  $\{\{1, 0\}, \{0, -1\}\}$ 

Out[70]=  $\{\{\{0, 1\}, \{1, 0\}\}, \{\{0, -i\}, \{i, 0\}\}, \{\{1, 0\}, \{0, -1\}\}\}$ 

Out[71]//MatrixForm=

$$\begin{pmatrix} 0.999846 + 0. i & -0.0174973 + 0.00149977 i \\ -0.0174973 - 0.00149977 i & -0.999846 + 0. i \end{pmatrix}$$


In[72]:=  $(\text{wvd} = \text{Eigensystem}[\sigma Pd]) // \text{MatrixForm}$ 

Out[72]//MatrixForm=

$$\begin{pmatrix} -1. & 1. \\ \{-0.00874899 + 0.000749913 i, -0.999961 + 0. i\} & \{0.996308 - 0.0853978 i, -0.00878107 + 0. i\} \end{pmatrix}$$


In[73]:=  $(\text{Ket}[\psi_{nd}] = \{\text{wvd}[[2, 2, 1]], \text{wvd}[[2, 2, 2]]\}) // \text{MatrixForm}$ 

Out[73]//MatrixForm=

$$\begin{pmatrix} 0.996308 - 0.0853978 i \\ -0.00878107 + 0. i \end{pmatrix}$$


In[74]:=  $\text{normad2} = (\text{Flatten}[\text{Chop}[\text{Bra}[\psi_{nd}].\text{Ket}[\psi_{nd}]]][[1]])$ 

Out[74]= 1.

In[75]:=  $(\text{Ket}[\psi_{ud}] = (1 / \text{Sqrt}[\text{normad2}]) * \text{Ket}[\psi_{nd}]) // \text{MatrixForm}$ 

Out[75]//MatrixForm=

$$\begin{pmatrix} 0.996308 - 0.0853978 i \\ -0.00878107 + 0. i \end{pmatrix}$$


In[76]:=  $C0 = (\text{Ket}[\psi_{ud}][[1, 1]]);$ 
 $C1 = (\text{Ket}[\psi_{ud}][[2, 1]]);$ 
 $\phi0 = \text{Arg}[C0];$ 
 $\phi1 = \text{Arg}[C1];$ 
 $mC0 = \text{Abs}[C0];$ 
 $mC1 = \text{Abs}[C1];$ 
 $\phi_w = \phi1 - \phi0$ 

Out[82]= 3.2271

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In[83]:= (Ket[ψd] = Chop[mC0 * Ket[0] + (e^(Defer[i] φw)) * mC1 * Ket[1]] // MatrixForm
(Ket[ψd]) // MatrixForm

$$\begin{pmatrix} 0.9999614456768875 \\ 0.008781068260154172 \, e^{3.227097947267998 i} \end{pmatrix} // N // MatrixForm$$

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Out[83]//MatrixForm=

$$\begin{pmatrix} 0.999961 \\ 0.00878107 \, e^{3.2271 i} \end{pmatrix}$$

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Out[84]//MatrixForm=

$$\begin{pmatrix} 0.999961 \\ 0.00878107 \, e^{3.2271 i} \end{pmatrix}$$

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Out[85]//MatrixForm=

$$\begin{pmatrix} 0.999961 \\ -0.00874899 - 0.000749913 \, i \end{pmatrix}$$

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