

Bayesian non-parametric approaches for dependent processes

Kaspar Märtens Xenia Miscouridou Paul Vanetti

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Random Measures

Completely Random Measures

- ▶ Distributions over random measures defined on a measurable space Θ .
- ▶ For disjoint subsets $A_1, \dots, A_r \in \Theta$ and a realization $G \sim CRM$, the rv's $G(A_1), \dots, G(A_r)$ are independent.
- ▶ Poisson Process representation
- ▶ e.g. Gamma Process, Beta Process

Normalized Random Measures

- ▶ obtained via normalization of a CRM
- ▶ G is a NRM if $G = \frac{G'}{G'(\Theta)}$, for $G' \sim CRM$
- ▶ e.g. Dirichlet Process is a Normalized Gamma Process

Dirichlet Process

- ▶ $DP(\alpha; G_0)$, on Θ
concentration parameter $\alpha > 0$,
base measure G_0 on Θ
- ▶ A realization $G \sim DP$ can be written as

$$G = \sum_{i=1}^{\infty} \pi_i \delta_{\theta_i} \quad (\text{i.e. a.s. atomic})$$

where $\theta_k \sim G_0$ and π_k obtained via stick breaking:

$$\pi_k = V_k \prod_{l < k} (1 - V_l), \quad V_k \sim \text{Beta}(1, \alpha)$$

- ▶ For measurable disjoint sets $\{A_1, \dots, A_r\} \in \Theta$,
 $(G(A_1), \dots, G(A_r)) \sim \text{Dir}(\alpha G_0(A_1), \dots, \alpha G_0(A_r))$

Exchangeable Priors for Bayesian nonparametric models

- ▶ Dirichlet Process
- ▶ Chinese Restaurant Process
- ▶ Pitman - Yor Process
- ▶ Indian Buffet Process

EXCHANGEABILITY ASSUMPTION

For a sequence $\{x_1, x_2, \dots\}$ to be exchangeable:

$$\mathbb{P}\{(x_1, \dots, x_n)\} = \mathbb{P}\{(x_{\sigma(1)}, \dots, x_{\sigma(n)})\},$$

for any σ permutation of $\{1, \dots, n\}$

Dependent non-parametric random processes

- ▶ Model data containing **spatial or time dependencies**.
- ▶ Extend nonparametric processes from distributions over random measures to distributions over **collections** of random measures.
- ▶ Families of random measures indexed by some **covariate**.
 $\{G^{(x)} : x \in \mathbb{X}\}$ e.g. $\mathbb{X} = \mathbb{R}^+$ for time or $\mathbb{X} = \mathbb{R}^2$ for space

$$G = \sum_{i=1}^{\infty} \pi_i \delta_{\theta_i} \rightarrow G^{(x)} = \sum_{i=1}^{\infty} \pi_i^{(x)} \delta_{\theta_i^{(x)}}$$

- ▶ The closer two covariates are in covariate space the greater amount of overlap among the corresponding processes .

Construction

- ▶ Different forms of dependencies
 1. dependence on atom location; the weights are shared
$$\forall x \pi_k^{(x)} = \pi_k$$
 2. dependence on atom weight; the locations are shared
$$\forall x \theta_k^{(x)} = \theta_k$$
- ▶ Different constructions; many are based on extensions of the Dirichlet process and we focus on two of those namely
 1. **spatial normalized gamma process**
 2. **probit stick-breaking process**

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 - ▶ Marginalize and normalize to yield DP

Spatial Normalized Gamma Process

- ▶ Example: time series.

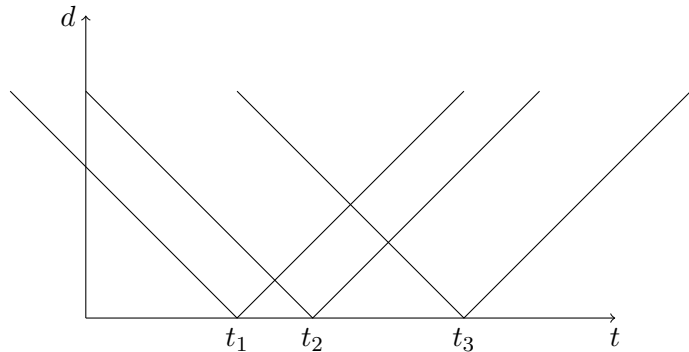
Spatial Normalized Gamma Process

- ▶ Example: time series.
 - ▶ Set extended space over time and duration (t, d)

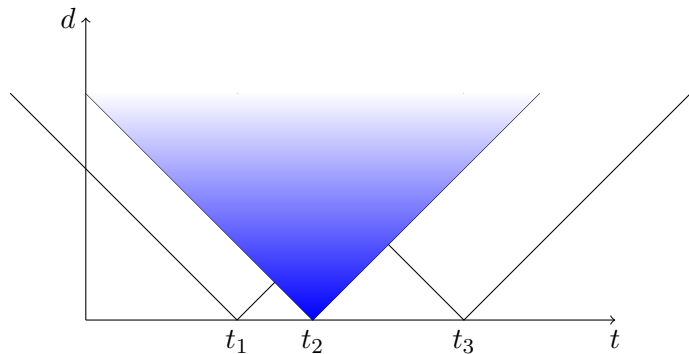
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- ▶ Example: time series.
 - ▶ Set extended space over time and duration (t, d)
 - ▶ Region for time t_i : $\{(t, d) : t - d < t_i < t + d\}$

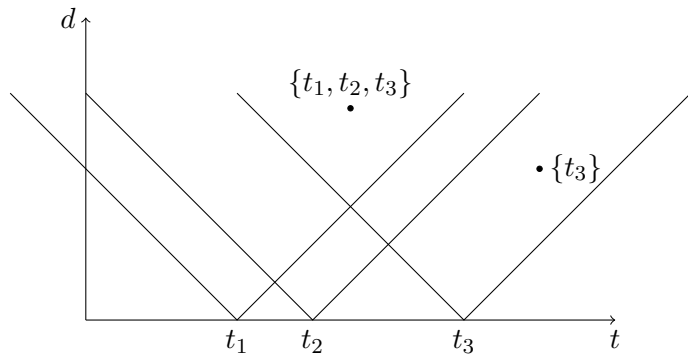
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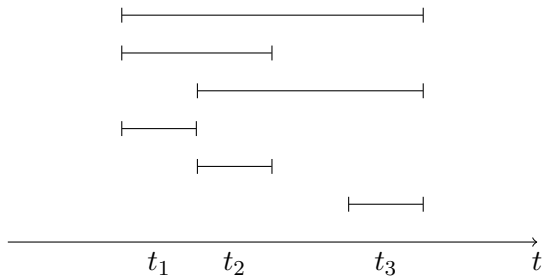
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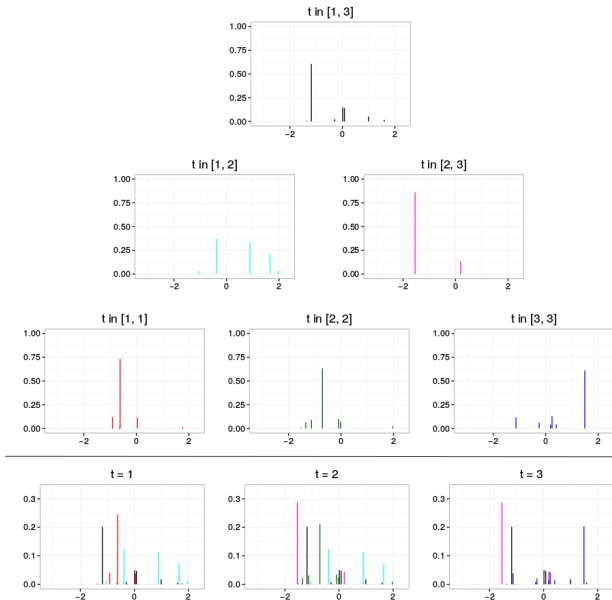
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Dependence via stick-breaking

Recall the stick-breaking construction

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Several ways to model $V_k^{(x)}$, e.g.

- ▶ Kernel stick-breaking process
- ▶ Probit stick-breaking process

Kernel stick-breaking process

Idea: associate each stick to a covariate location μ_k , and specify

$$V_k^{(x)} = U_k K(x, \mu_k)$$

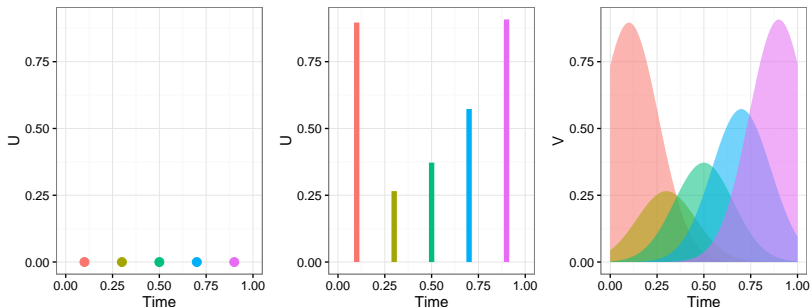
for some kernel function $K(\cdot, \cdot)$

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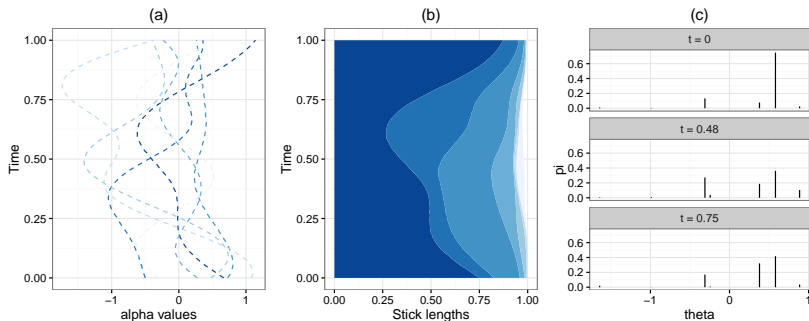
where $\alpha_k^{(x)}$ is a latent Gaussian process.

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References



Vinayak Rao and Yee W Teh.

Spatial normalized gamma processes.

In *Advances in neural information processing systems*,
pages 1554–1562, 2009.