Kasper A. R. Grøntved, Ph.D. Student

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in KasperGrontved

kasperg3

Check out my work at https://blog.grontved.dk



Employment History

2022 – now **Ph.D. student,** SDU UAS Center, The University of Southern Denmark.

2020 – 2022 **Systems Engineer,** A²I Systems A/S.

2018 – 2020 **Student Programmer,** A²I Systems A/S.

Education

2022 – now Ph.D., University of Southern Denmark.

Thesis title: *Cooperative Control of Multirobot Systems in Real-World Applications* Granted PhD position out of 42 applicants.

2018 – 2022 M.Sc. Advanced Robotic Systems, University of Southern Denmark

Thesis title: Multi-Agent Decentralised Coordination using CNRL for Industrial Applications.

Thesis title: Semantic segmentation using a deep neural network for pose estimation of a rigid object.

Research Publications

Journal Articles

M.-T. O. Hoang, K. A. R. Grøntved, N. van Berkel, M. B. Skov, A. L. Christensen, and T. Merritt, "Drone swarms to support search and rescue operations: Opportunities and challenges," *Cultural Robotics:* Social Robots and Their Emergent Cultural Ecologies, pp. 163–176, 2023.

Conference Proceedings

- 1 K. A. R. Grøntved, J. H. Jepsen, A. L. Christensen, K. Jensen, U. P. S. Lundquist, and Miguel Campusano, "Towards autonomous multi-UAV U-space operation planning," in *International Conference on Unmanned Aircraft Systems (ICUAS)*, Under review, 2024.
- E. G. A. Rolland, K. A. R. Grøntved, A. L. Christensen, M. Watson, and T. Richardson, "Autonomous UAV volcanic plume sampling based on machine vision and path planning," in 2024 International Conference on Unmanned Aircraft Systems (ICUAS), Under review, 2024.
- 3 K. A. R. Grøntved, U. P. Schultz, and A. L. Christensen, "Decentralized multi-UAV trajectory task allocation in search and rescue applications," in 21st International Conference on Advanced Robotics, IEEE, 2023.
- 4 A. L. Christensen, K. A. R. Grøntved, M.-T. O. Hoang, et al., "The herd project: Human-multi-robot interaction in search & rescue and in farming," in Adjunct Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, 2022.

Skills

Skills (continued)

Coding C++, Python, Java, sql, LaTeX, ROS, FreeRTOS, PyTorch

Misc. Academic research, Large typesetting and publishing, Unix systems, Docker, Git

Supervision

Nicoline Louise Thomsen, *University of Southern Denmark*, Master Thesis: Robust Area Coverage by a Swarm of Unmanned Aerial Vehicles.

Emil Månsson & Kristian Damkjær Jensen, *University of Southern Denmark*, Master Thesis: Swarm Intelligence for Land-based Mobile Robots Operating in a Large Environment