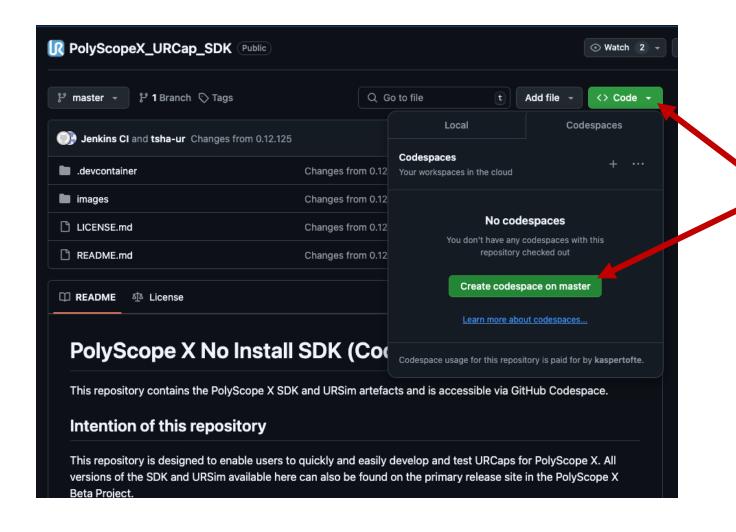
Polyscope X

Create an account on github

- Create and account and login on github.com
- github is a place where developers can share code
- Navigate to https://github.com/UniversalRobots/PolyScopeX URCap SDK

Kick off the SDK



Click here

Then here

Kick off the simulator

- Go through the README.md:
 - In 'TERMINAL' type './run-simulator' and press enter
 - Wait until you see: runtime-1 | web-bootstrapper-1 | 2024/10/28 11:33:06 [INFO] Done, time to sleep forever
 - Choose 'PORTS', click 'Forward a Port', add port '80'
 - Click the globus in the 'Forwarded Address' field (appears on mouse-over)
 - You should now have an instance of the Polyscope X simulator running

Polyscope X demo

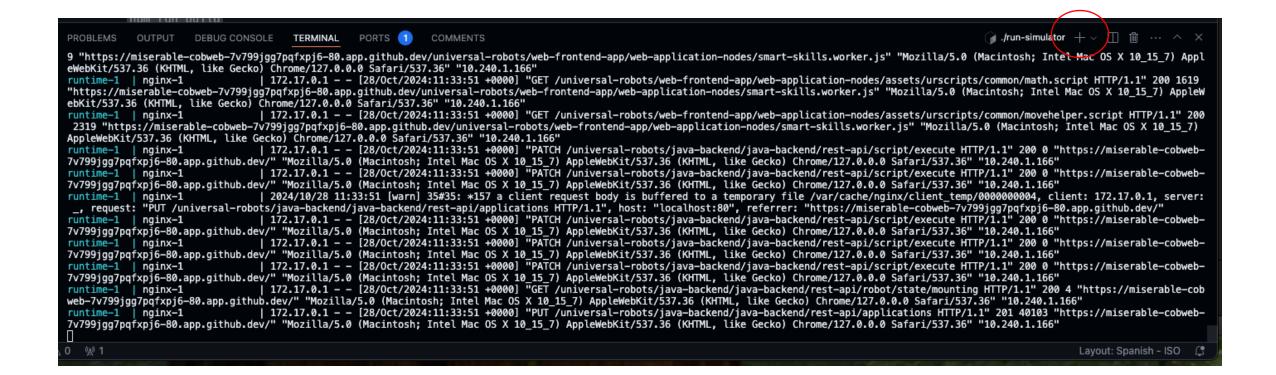
Documentation

- Documentation for SDK: https://docs.universal-robots.com/PolyScopeX_SDK_Documentation/build/PSX-SDK-v0.12/index.html
- UI library: https://psx-storybook.universal-robots.com/0.17.5/?path=/docs/welcome--docs
- Script manual: https://docs.universal-robots.com/PolyScopeX_SDK_Documentation/build/PSX-SDK-v0.12/_downloads/4dfc6a57b84e54a4c81b585d33472730/scriptManualG5.pdf

Make your own program node

Open a new terminal

In the 'TERMINAL' tab hit the '+'



Getting started

- In the new terminal run:
 - ./newurcap.sh
 - You will be prompted with a series of questions:
 - Include a Web Contribution (frontend): y
 - Include a Docker Container Contribution (backend): n
 - Name of Vendor: your name
 - Id of Vendor: your initials (or name without spaces)
 - Name of URCap Contribution: DemoContribution (or give it a name)
 - Id of URCap Contribution: demo
 - What type of URCap Web contribution should be created?: Angular
 - Include Program Node: y
 - Name of Program Node: name of programnode (no spaces), fx. KaspersPopUpProgramNode
 - Include Application Node: y
 - Name of Application Node: name of application node (not the same as name of the program node)
 - Include Smart Skill: y
 - Name of Smart Skill: name of smar skill (not the same as the program node or application node)

Enable hot-reload

- A new folder is now generated (id of urcap) expand the folder and find manifest.yml
- Add 'devUrl: http://host.gateway.ip:4200/' in the webArchives section:

webArchives:

- id: demonode

folder: demonode

devUrl: http://host.gateway.ip:4200/

Build and install your program node

- In the terminal enter the following commands one at a time, followed by enter:
 - 'cd demo' (or the id of your contribution)
 - npm install
 - npm run build
 - npm run install-urcap
 - npm run start

See your urcap in Polyscope X

- In the browser tab running Polycope X
- Press the Application icon and see your new URCap
- Go to the Program tab
- Hit the blue button to insert your new program node

Test hot reload and start development

- In the explorer, find the html file for your programnode:
 - src > apps > components > 'programnode' > 'din program knude'.components.html
- Add some text to the html file:

```
<div *ngIf class="inline-component">
  some text
</div>
```

- Await recompilation of the component, it's done when the terminal reports 'Compiled sucesfully'
- Reload the tab running Polyscope X.
- When done, insert a new Program Node and see your change

Add some user interface

- In the HTML files we describe how the component should look like. We will add a text input field, so the user can give inputs to the component.
- We have made a set of components that can be reusedyou can find them in the 'UI components library'. Here you can also test out their behaviours.
- Find 'Form -> DialogInput -> Docs'
- Try out the component
- Click 'Show code' and copy the content to the html of your program node.

Add some user interface (continued)

- Delete the following lines:
 - disabled
 - placeholder
 - validators
 - translations
 - currentvalue
 - handleChange
 - validChange
 - blurred
 - focused
 - handleClick

<div *ngIf ...
 <ur-dialog-input
 [type]="'text'"
 [label]="'Header'"
 [message]="'Helper text'"
 [validation]="{required: true, maxlength: 20}"
 [value]="'Value text'"
 (valueChanged)="valueChanged(\$event)"
 ></ur-dialog-input>
 </div>

- After your code has compiled you can see the new text input in Polyscope X
- Please experiment with 'label', 'message' and 'validation' what happens?

Persist data?

• What happens if you change the value in the input field and navigates away and back again?

We do not persist the changes

Prepare the data model

- Remove the ? from parameters
- replace '[key: string]: any;' med 'text': string

Correct program nodes behaviour

- In In In rogram node .behaviour.worker.ts we can describe what our program node should be doing with the data. Right now we just need to provide some initial data.
- Find the createProgramNode method and add an initial value to the variable 'text'

```
const createProgramNode = ...
    ...
    parameters: {
        'text': 'Hello world'
     }
}):
```

Correct createProgramNodeLabel, so we use our new variable:

```
const createProgramNodeLabel = ... => node.parameters.text
```

 Can you see any changes in Polyscope X? (Ypu migh get an error – just create a new program)

Save changes from the user input

- In In In In In program node name.component.ts we can change how our program node should behave on user input. When the user changes the 'value', so when 'valueChanged' is triggered on our ur-dialog-input,we want to save it to our program node.
- In *.component.ts file, add:

```
async saveNode() {
    ...
}
async valueChanged($event: string) {
    this.contributedNode.parameters.text = $event;
    await this.saveNode()
}
```

• in *.component.html 'value' should be changed to:

```
[value]="contributedNode.parameters.text"
```

Generate some URScript

- Back to *.behaviour.worker.ts
- Find the method generateScriptCodeBefore
- Replace 'new ScriptBuilder();' with

```
{
  const sb = new ScriptBuilder();
  sb.popup(node.parameters.text, 'title', PopupLevel.INFO, true);
  return sb;
}
```

 Insert your program node and play your program (delete the program node you already inserted)

Congratulations you have now build a program node

- You can now build on the functionality of yoyur program node.
- You can find inspiration for your new user interface component in the UI component library: https://psx-storybook.universal-robots.com/0.17.5/?path=/docs/welcome--docs
- You can find inspiration for URScript in the 'Script manual':

 https://docs.universal-robots.com/PolyScopeX_SDK_Documentation/build/PSX-SDK-v0.12/_downloads/4dfc6a57b84e54a4c81b585d33472730/scriptManualG5.pdf

Bonus slide

Find something you find interesting

Install your urcap on the robot

- For now you have tested the urcap in a simulator. Let's try it on the robot.
- In the target/ folder, right-click and download the urcapx file:
- Put it on a USB stick and install it on the robot.

Try an application node or a smart skill

- Each contribution type is available in the components directory and has a similar structor
- De har samme opbygning som program bidrager:
 - *.node.ts
 - *.component.ts
 - *.behaviour.worker.ts