

CS 663, Fall 2023

Assignment 2

Jahanvi Rajput 23D0378
Badri Vishal Kasuba 22M2119
Abhishek Kumar Singh 22M210

Question 2: In bicubic interpolation, the image intensity value is expressed in the form $v(x, y) = \sum_{i=0}^3 \sum_{j=0}^3 a_{ij} x^i y^j$ where a_{ij} are the coefficients of interpolation and (x, y) are spatial coordinates. This uses sixteen nearest neighbors of a point (x, y) . Given the intensity values of these 16 neighbors, explain with the help of matrix based equations, how one can determine the coefficients a_{ij} that determine the function $v(x, y)$? Why do you require 16 neighbors for determining the coefficients?

Solution:

In bicubic interpolation, the image intensity value is expressed in the form

$$v(x, y) = \sum_{i=0}^3 \sum_{j=0}^3 a_{ij} x^i y^j$$

where a_{ij} are the coefficients of interpolation and (x, y) are spatial coordinates. Expanding above equation gives:

$$\begin{aligned} v(x, y) = & a_{00}x^0y^0 + a_{01}x^0y^1 + a_{02}x^0y^2 + a_{03}x^0y^3 + \\ & a_{10}x^1y^0 + a_{11}x^1y^1 + a_{12}x^1y^2 + a_{13}x^1y^3 + \\ & a_{20}x^2y^0 + a_{21}x^2y^1 + a_{22}x^2y^2 + a_{23}x^2y^3 + \\ & a_{30}x^3y^0 + a_{31}x^3y^1 + a_{32}x^3y^2 + a_{33}x^3y^3 \\ v(x, y) = & a_{00} + a_{01}y + a_{02}y^2 + a_{03}y^3 + \\ & a_{10}x + a_{11}xy + a_{12}xy^2 + a_{13}xy^3 + \\ & a_{20}x^2 + a_{21}x^2y + a_{22}x^2y^2 + a_{23}x^2y^3 + \\ & a_{30}x^3 + a_{31}x^3y + a_{32}x^3y^2 + a_{33}x^3y^3 \end{aligned}$$

Now we have 16 coefficients represented by a_{ij} . So finding out these we need 16 equations. Therefore, we have 16 neighbouring pixel intensity values:

$$\begin{aligned} & v(x_1, y_1), v(x_1, y_2), v(x_1, y_3), v(x_1, y_4), \\ & v(x_2, y_1), v(x_2, y_2), v(x_2, y_3), v(x_2, y_4), \\ & v(x_3, y_1), v(x_3, y_2), v(x_3, y_3), v(x_3, y_4), \\ & v(x_4, y_1), v(x_4, y_2), v(x_4, y_3), v(x_4, y_4) \end{aligned}$$

The above intensity value $v(x_1, y_1)$ is given below:

$$\begin{aligned}
v(x_1, y_1) = & a_{00} + a_{01}y_1 + a_{02}y_1^2 + a_{03}y_1^3 + \\
& a_{10}x_1 + a_{11}x_1y_1 + a_{12}x_1y_1^2 + a_{13}x_1y_1^3 + \\
& a_{20}x_1^2 + a_{21}x_1^2y_1 + a_{22}x_1^2y_1^2 + a_{23}x_1^2y_1^3 + \\
& a_{30}x_1^3 + a_{31}x_1^3y_1 + a_{32}x_1^3y_1^2 + a_{33}x_1^3y_1^3 \\
v(x_1, y_1) = & \sum_{i=0}^3 \sum_{j=0}^3 a_{ij}x_1^i y_1^j
\end{aligned}$$

Similarly the other intensity values will be given.

$$\begin{aligned}
v(x_1, y_1) &= \sum_{i=0}^3 \sum_{j=0}^3 a_{ij}x_1^i y_1^j \\
v(x_2, y_2) &= \sum_{i=0}^3 \sum_{j=0}^3 a_{ij}x_2^i y_2^j \\
v(x_3, y_3) &= \sum_{i=0}^3 \sum_{j=0}^3 a_{ij}x_3^i y_3^j \\
v(x_4, y_4) &= \sum_{i=0}^3 \sum_{j=0}^3 a_{ij}x_4^i y_4^j
\end{aligned}$$

This can be represented as form of matrix.

$$A = \begin{bmatrix} 1 & x_1 & x_1^2 & x_1^3 & y_1 & x_1 y_1 & x_1^2 y_1 & \dots & x_1^2 y_1^3 & x_1^3 y_1^3 \\ 1 & x_1 & x_1^2 & x_1^3 & y_2 & x_1 y_2 & x_1^2 y_2 & \dots & x_1^2 y_2^3 & x_1^3 y_2^3 \\ 1 & x_1 & x_1^2 & x_1^3 & y_3 & x_1 y_3 & x_1^2 y_3 & \dots & x_1^2 y_3^3 & x_1^3 y_3^3 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & x_4 & x_4^2 & x_4^3 & y_3 & x_4 y_3 & x_4^2 y_3 & \dots & x_4^2 y_3^3 & x_4^3 y_3^3 \\ 1 & x_4 & x_4^2 & x_4^3 & y_4 & x_4 y_4 & x_4^2 y_4 & \dots & x_4^2 y_4^3 & x_4^3 y_4^3 \end{bmatrix}$$

$$x = \begin{bmatrix} a_{00} \\ a_{10} \\ a_{20} \\ \vdots \\ a_{23} \\ a_{33} \end{bmatrix}, \quad b = \begin{bmatrix} v(x_1, y_1) \\ v(x_1, y_2) \\ v(x_1, y_3) \\ \vdots \\ v(x_4, y_3) \\ v(x_4, y_4) \end{bmatrix},$$

where A is the coefficient matrix for linear equations of $v(x_i, y_j)$, x is coefficients of interpolation which needs to be solved and b is given intensity values. For solving this we need to solve:

$$Ax = b$$

$$\begin{bmatrix} 1 & x_1 & x_1^2 & x_1^3 & y_1 & x_1 y_1 & x_1^2 y_1 & \dots & x_1^2 y_1^3 & x_1^3 y_1^3 \\ 1 & x_1 & x_1^2 & x_1^3 & y_2 & x_1 y_2 & x_1^2 y_2 & \dots & x_1^2 y_2^3 & x_1^3 y_2^3 \\ 1 & x_1 & x_1^2 & x_1^3 & y_3 & x_1 y_3 & x_1^2 y_3 & \dots & x_1^2 y_3^3 & x_1^3 y_3^3 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & x_4 & x_4^2 & x_4^3 & y_3 & x_4 y_3 & x_4^2 y_3 & \dots & x_4^2 y_3^3 & x_4^3 y_3^3 \\ 1 & x_4 & x_4^2 & x_4^3 & y_4 & x_4 y_4 & x_4^2 y_4 & \dots & x_4^2 y_4^3 & x_4^3 y_4^3 \end{bmatrix} \begin{bmatrix} a_{00} \\ a_{10} \\ a_{20} \\ \vdots \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} v(x_1, y_1) \\ v(x_1, y_2) \\ v(x_1, y_3) \\ \vdots \\ v(x_4, y_3) \\ v(x_4, y_4) \end{bmatrix},$$

Hence the solution for x is given by:

$$x = A^{-1}b$$

We need 16 neighbors for determining the coefficients for bicubic interpolation. The reason for this is given below:

- i. In Bicubic interpolation the polynomial is used that is having cubic degree in both the x and y direction. A cubic polynomial has four coefficients, and since we are using it in both x and y directions, we have a total of $4 \times 4 = 16$ coefficients (a_{ij}) to determine. The same is seen in the above equation.

- ii. The aim of Bicubic interpolation is to produce a smooth and continuous interpolated surface. The more neighboring points help achieve smoothness by ensuring that the polynomial function can adapt to local variations in the data.
- iii. Local method, bicubic interpolation, calculates the pixel value at a position (x, y) depending on the values of the pixels nearby. There must be sufficient data points to accurately represent a cubic polynomial function. In the case of bicubic interpolation, 16 neighboring pixels offer sufficient details to allow a bicubic polynomial function to be fitted smoothly through these points.