

CS753 SEMINAR PRESENTATION

Topic Name:

P-FLOW:

A Fast and Data-Efficient Zero-Shot TTS through Speech Prompting

Team Details:

DO_DIN_MAI_RESEARCH_DOUBLE

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PAPER DETAILS



Paper: ***P-Flow: A Fast and Data-Efficient Zero-Shot TTS through Speech Prompting***



Paper Links: [OpenReview](#), [NeurIPS Poster](#), [NVIDIA ADLR Demo](#) and [GitHub](#)



Paper Accepted at [NeurIPS 2023](#) Conference



No. Of Citations: [1](#) till now











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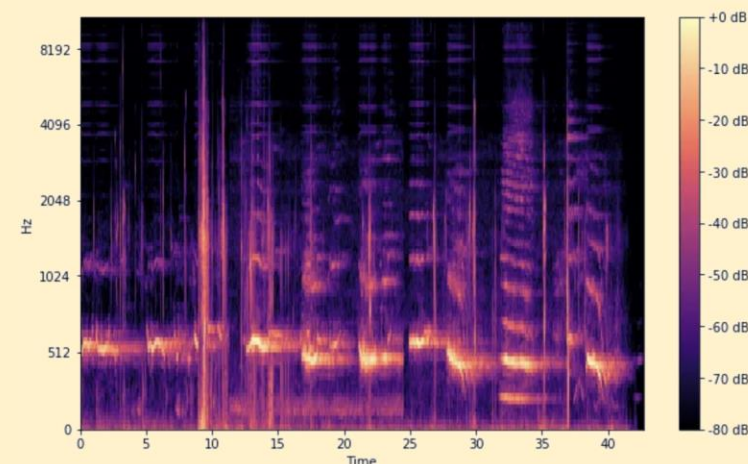
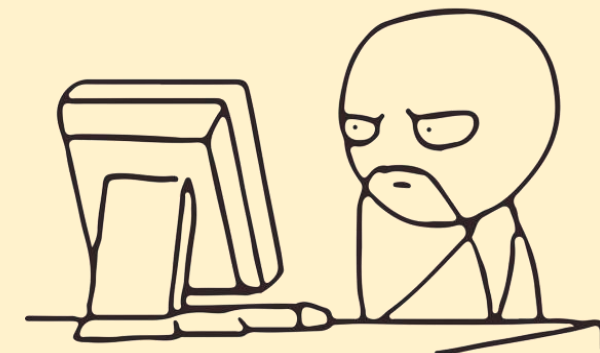
OUR FLOW OF P-FLOW PAPER

	----- {1}	INTRODUCTION TO KEY TERMS [NEW LEARNERS]	{3 mins}
	----- {2}	MOTIVATIONAL BACKGROUND	{2 mins}
	----- {3}	BACKGROUND: TTS, MODELS, NORMALIZING FLOWS	{4 mins}
	----- {4}	PREVIOUS APPROACHES FOR TTS	{6 mins}
	----- {5}	P-FLOW: OVERVIEW, DEMO, METHODOLOGY	{8 mins}
	----- {6}	EXPERIMENTS, ANALYSIS, ABLATION	{2 mins}
	----- {7}	CONCLUSION AND FUTURE WORKS	{2 mins}
	----- {8}	REFERENCES	{1 mins}

INTRODUCTION FOR THE NEWBIES LIKE US

KEY TERMS Introduction

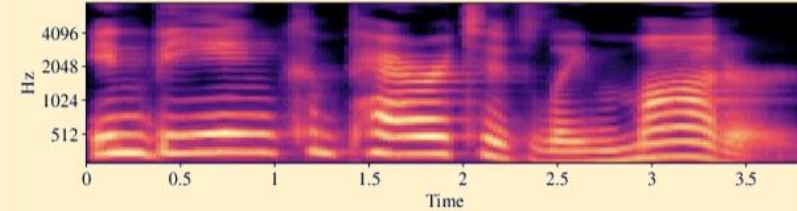
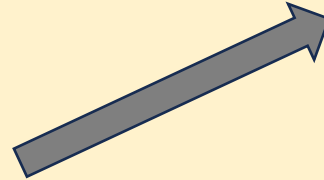
1. What is **Zero-shot TTS** task?
2. What is meant by **Speech Prompt**?
3. What are *mel-spectrograms*? [blog](#)
4. What is a Neural Codec Language Model?: [NCLM article](#)
5. What are Normalizing Flows? [Paper](#)
6. What is **Flow Matching**? [FM Explained](#)
7. What is Simulation Free Training?
8. What are **WER, SECS, CMOS, SMOS** scores



ZERO SHOT TTS

1. Reference speech segment X_p (*Speech Prompt*):

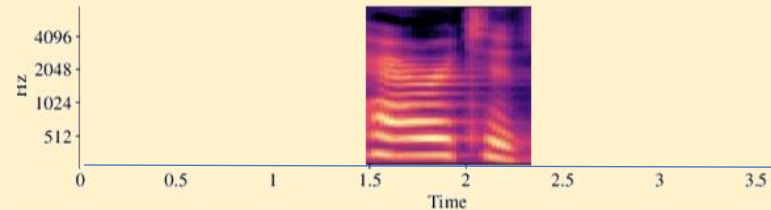
Eg: Voice of Trump



Reference speech: X



Part of the reference speech: X_p



TTS Model



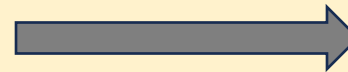
19. Trump on why people would vote for him

"To be blunt, people would vote for me. They just would. Why? Maybe because I'm so good looking."

New York Times, 19/9/99

2. Text to speech input:

"Sorry losers and haters, but my IQ is one of the highest - and you all know it! Please don't feel so stupid or insecure, it's not your fault." : Trump did say this...



BACKGROUND: GENERATIVE MODELS AND TTS

- TTS Methods
 - **Cascaded** [An Acoustic model and Vocoder using mel-spectograms (intermediate)]
 - **End-to-End** [Jointly optimize Acoustic model and Vocoder]
- Most work has been done in the CASCADED setting for TTS from past
- Growing interest for Multi-lingual zero-shot TTS and also need of it
- Works include effective speaker encoding based methods, advanced speaker embeddings-based models were proposed
- Current Research trend in this area is
 - **Efficient** TTS models
 - **Multi-lingual** and **Multi-Speaker** adaptation both efficiently and with possible less samples of diverse speakers
 - As usual reducing the model cost and inference costs

MOTIVATIONAL BACKGROUND: DOES EFFICIENT SOLUTION EXISTS??




1. Large dataset
2. Complicated training setups
3. Additional pretraining tasks
4. Additional quantization steps
5. Computationally expensive autoregressive formulations



1. Simple Training pipeline
2. Significantly less data
3. Faster Inference
4. Good Performance
5. Retain high speaker similarity like VALL-E

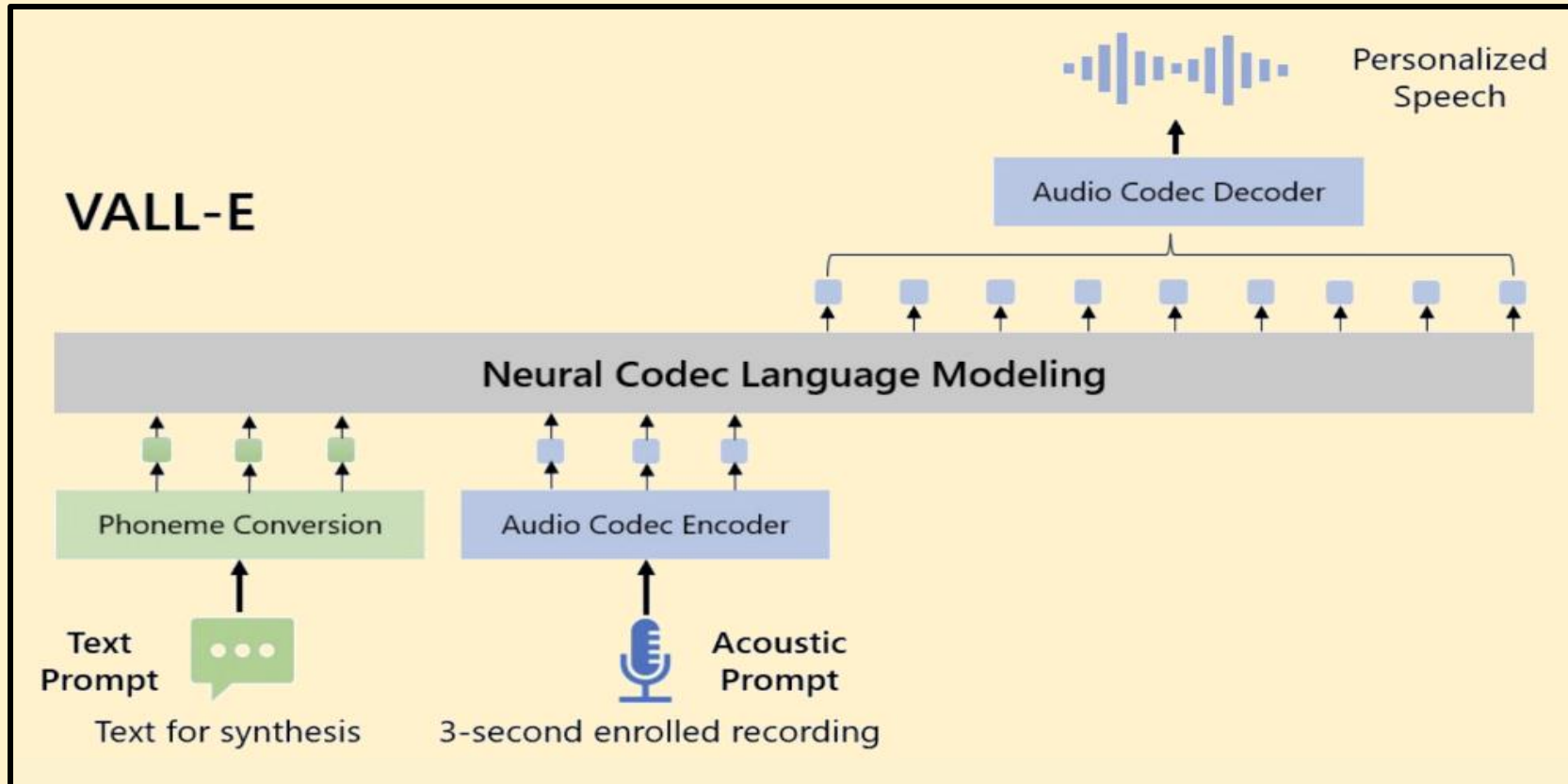


PREVIOUS APPROACHES

Name	Conference	Architecture	Training Data	Sampling speed	Problems
Vall-E	Microsoft Research	Language Model	LibriLight, LibriSpeech	Slow	AR, Codec
YourTTS	ICML	Transformer	VCTK, LibriTTS, MLS-PT	Slow	Instability in stochastic duration predictor, mispronunciations in Portuguese.
GlowTTS	Nips 2020	Transformer	LJSpeech, LibriTTS	Fast	No prompting or Zero shot TTS
SpearTTS	TACL	Transformer cascaded	Librilight + LibriTTS	Very Slow	Cascaded decoupled system
GradTTS	ICML 2021	Diffusion based	LJSpeech	Fast	No prompting or Zero shot TTS
AudioLM	Google Research(2022)	Language Model	LibriLight, LibriSpeech		
A ³ T	ICML 2022	Transformer, uses spectrograms	LJSpeech, VCTK, LibriTTS		
StyleTTS2	Neurips 2023	Generative Model	VCTK, LibriTTS		

BACKGROUND: VALL-E

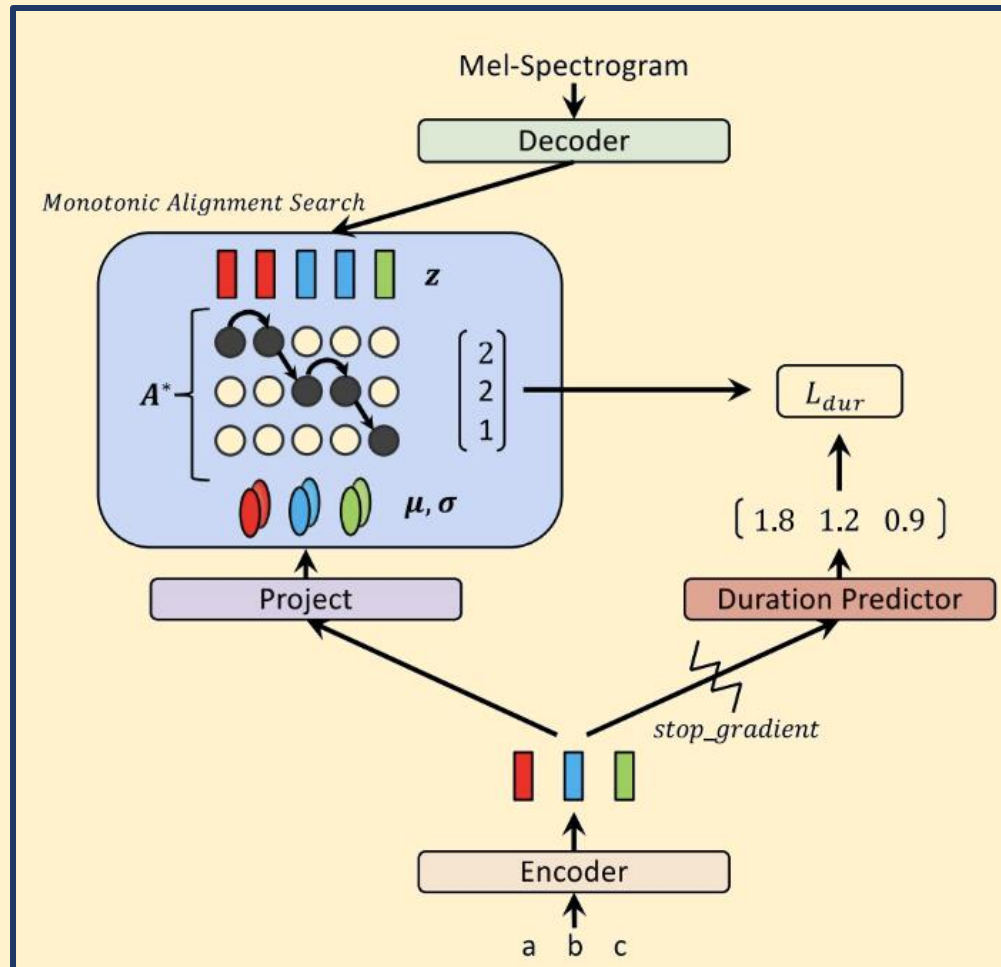
- VALL-E (Wang et al., 2023) [Link](#)



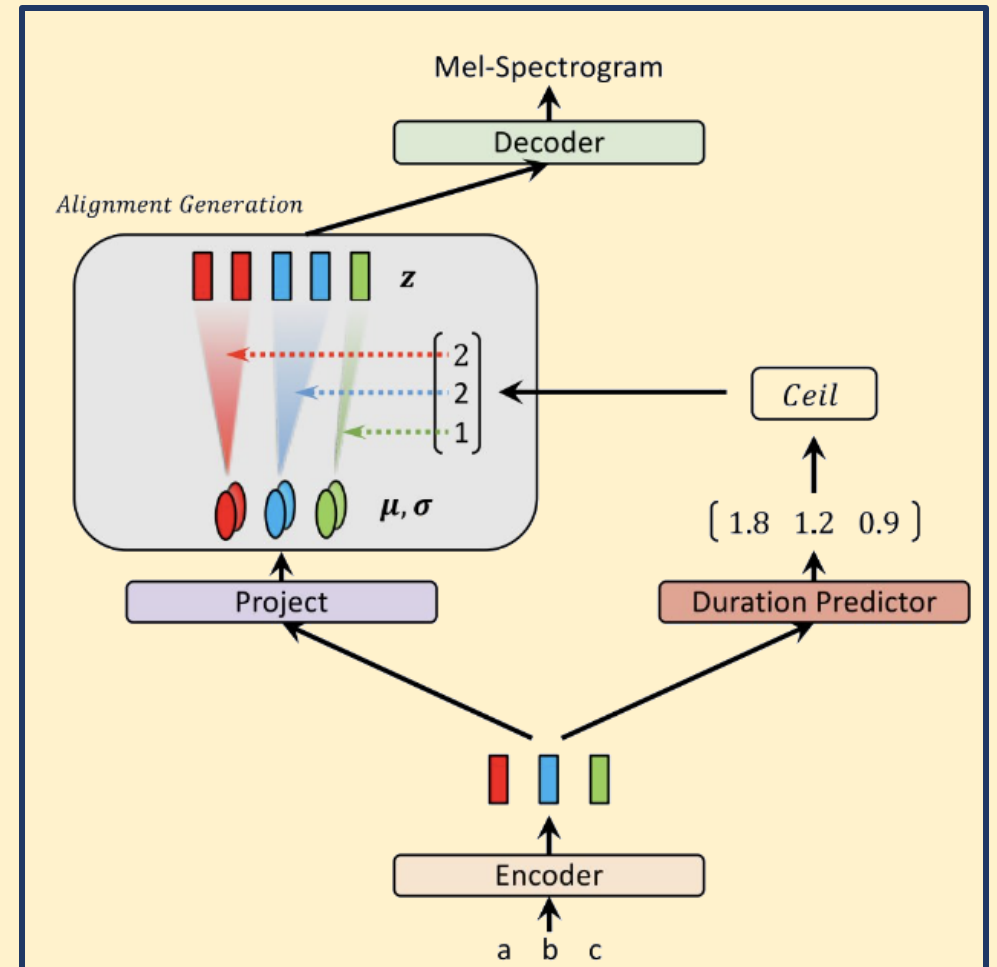
BACKGROUND: GLOW TTS

- GlowTTS (Kim et al., 2020) [Link](#)

GlowTTS Training



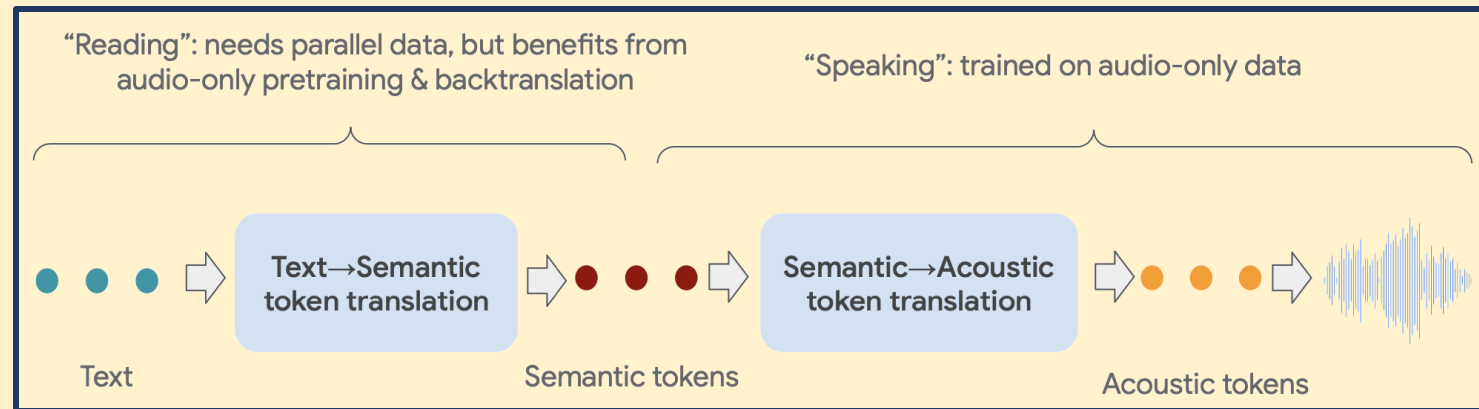
GlowTTS Inference



BACKGROUND: SPEARTTS

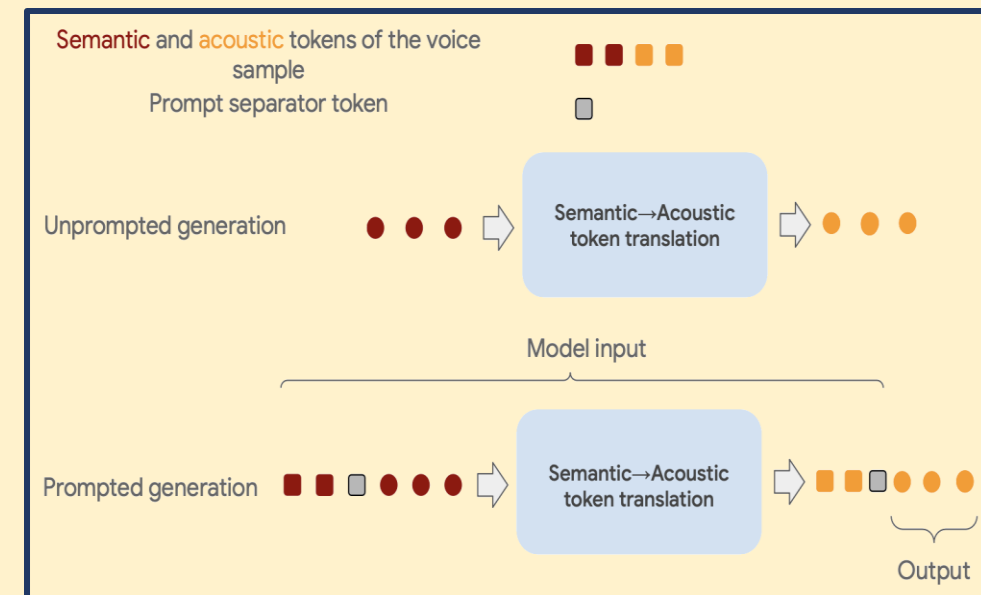
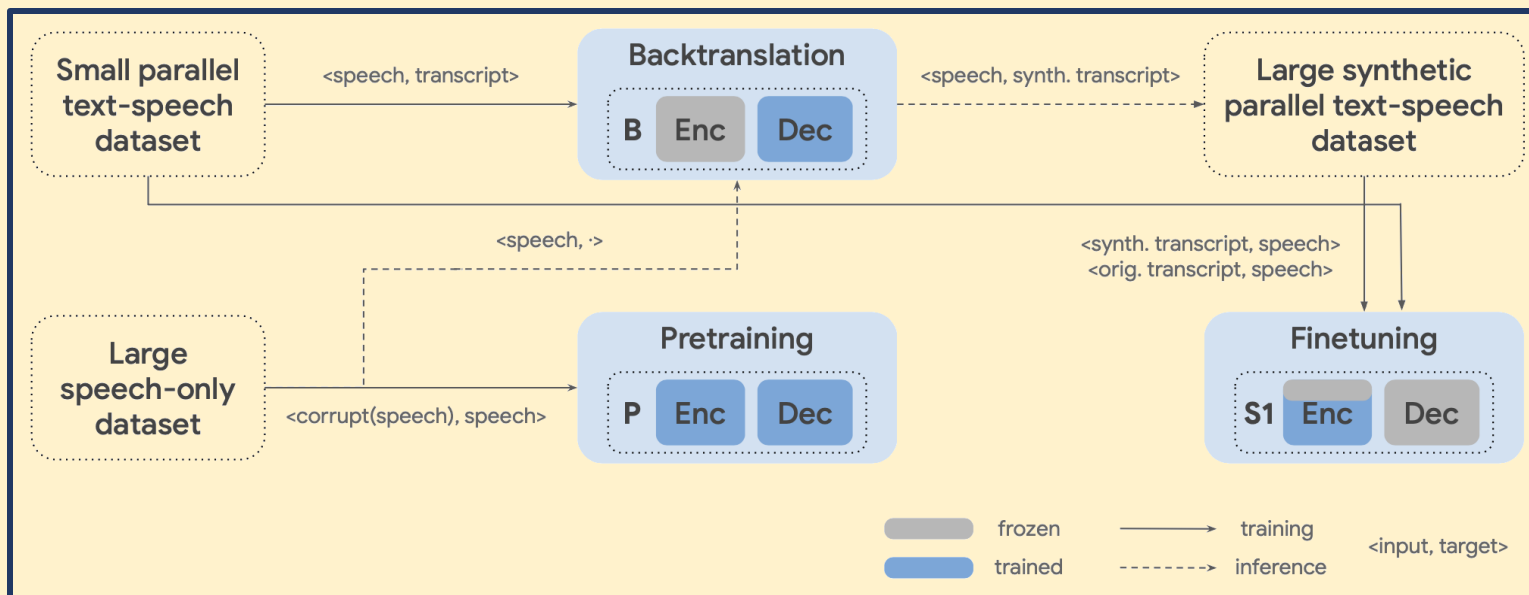
- Spear-TTS (Kharitonov et al., 2023) [Link](#)

Pipeline: S1+S2



S1 Training

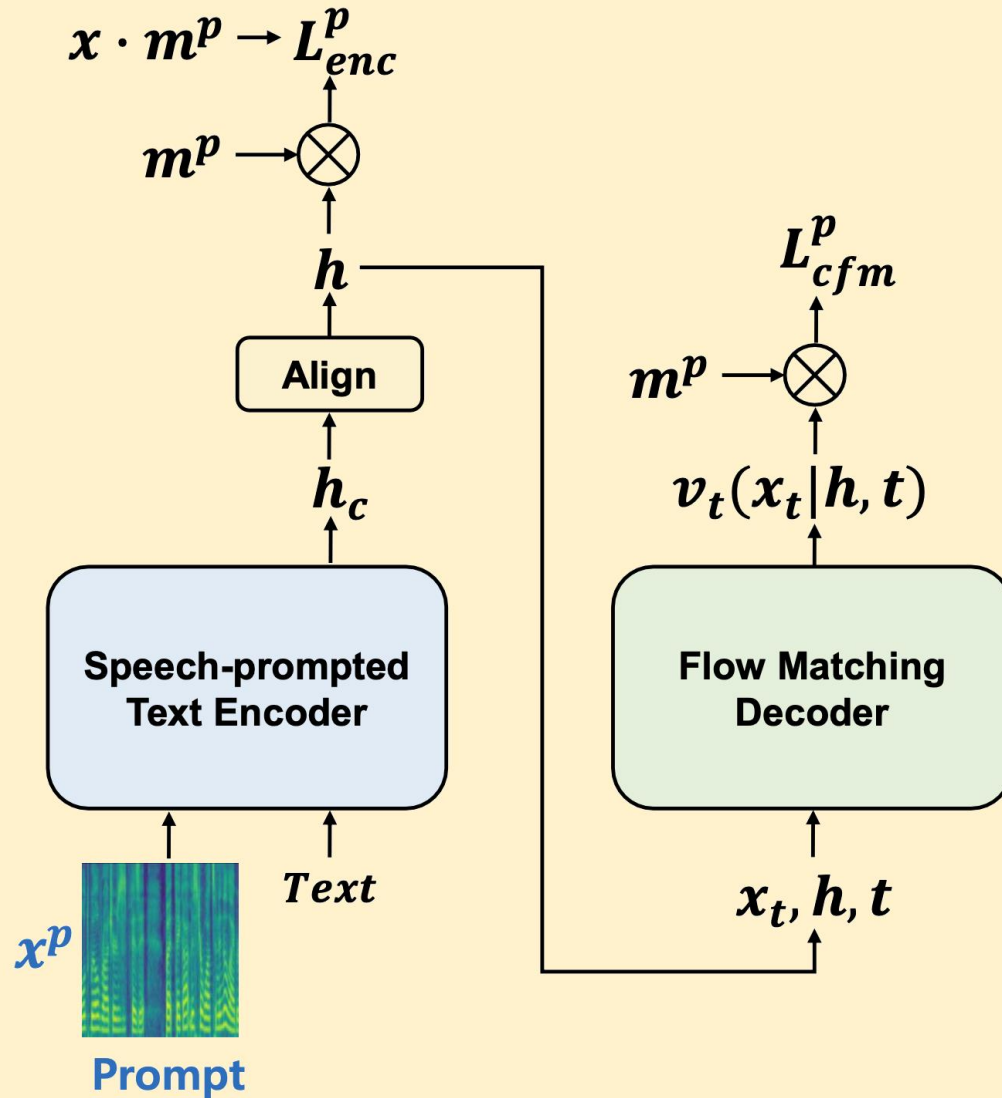
S2 Training



OBSERVATIONAL OVERVIEW

- **P-flow** raises a **challenge** to the recent trends of using feature extraction approaches for speech synthesis
- Main contribution is to achieve **high speaker similarity performance** with very less training and also achieving with **fast inference**, especially on zero-shot TTS task
- This is possible with the novel proposal of a **speech prompted text encoder** to generate speaker-conditional text representation for speaker adaptation
- Another contribution is the introduction of **Flow matching based generative decoder** for fast and efficient speech synthesis with even very few training data

METHODOLOGY - OVERVIEW

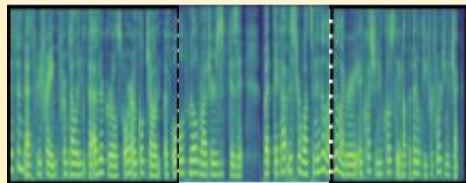


Architectural Diagram of
proposed P-FLOW
model

METHODOLOGY: SPEECH-PROMPTED TEXT ENCODER

1

Original Speech

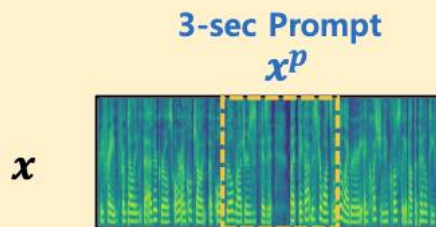
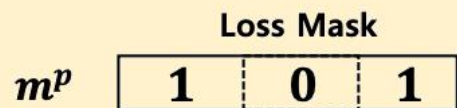
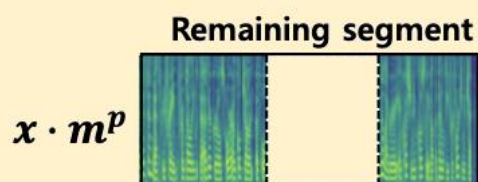


x : mel-spectrogram of input speech

c : original text

m^p : Indicator mask on sequence x

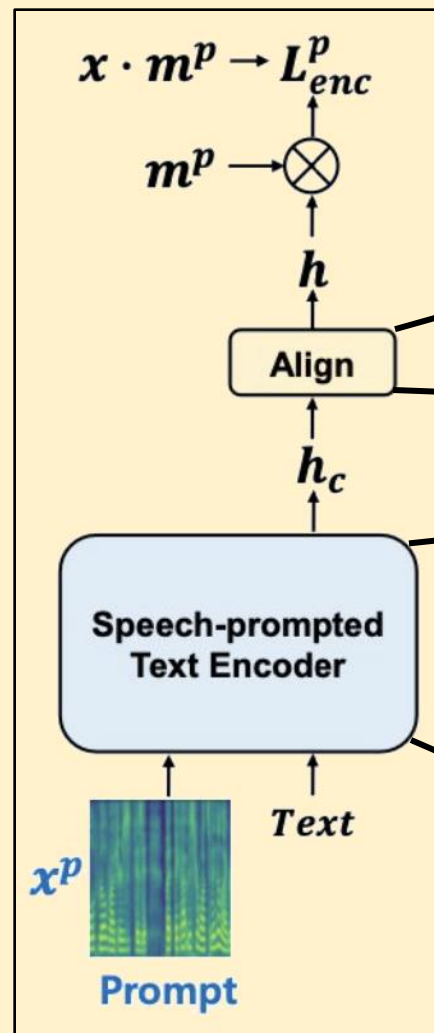
2



x

Speech

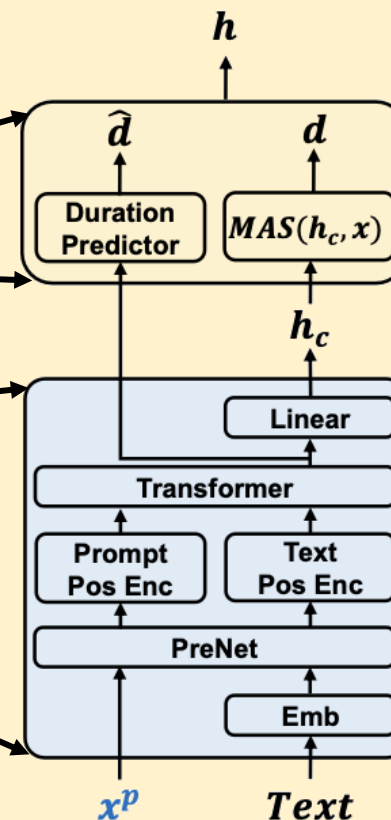
3



6

5

4



MONOTONIC ALIGNMENT SEARCH

Input:

$\mathbf{h}_c = (\mathbf{Y})$ speech prompted text tokens (N_tokens) and \mathbf{X} mel spectrogram frames (M_frames)

Output:

Monotonic alignment \mathbf{A}^* between text tokens and speech frames

Algorithm:

Compute the first row: $Q_{1,j} = \sum_{k=1}^{M_frames} (\log N (X[k] , \mu Y[1], \sigma Y[1]))$

for $j = 2$ to M_frames :

for $i = 2$ to $\min(j, N_tokens)$:

$Q_{i,j} = \max(Q_{i-1,j-1}, Q_{i,j-1}) + \log N (X[j] , \mu Y[i], \sigma Y[i])$ ← DP

end for

end for

for $j = M_frames-1$ to 1 ; do

$\mathbf{A}^*[j] = \operatorname{argmax}_{i \in \{ \mathbf{A}^*[j+1] - 1, \mathbf{A}^*[j+1] \}} Q_{i,j}$ ← Backtrack

end for

Q matrix

Shape = $[N_tokens, M_frames]$

$-\infty$	$-\infty$	$-\infty$	$-\infty$
$-\infty$	$-\infty$	$-\infty$	$-\infty$
$-\infty$	$-\infty$	$-\infty$	$-\infty$

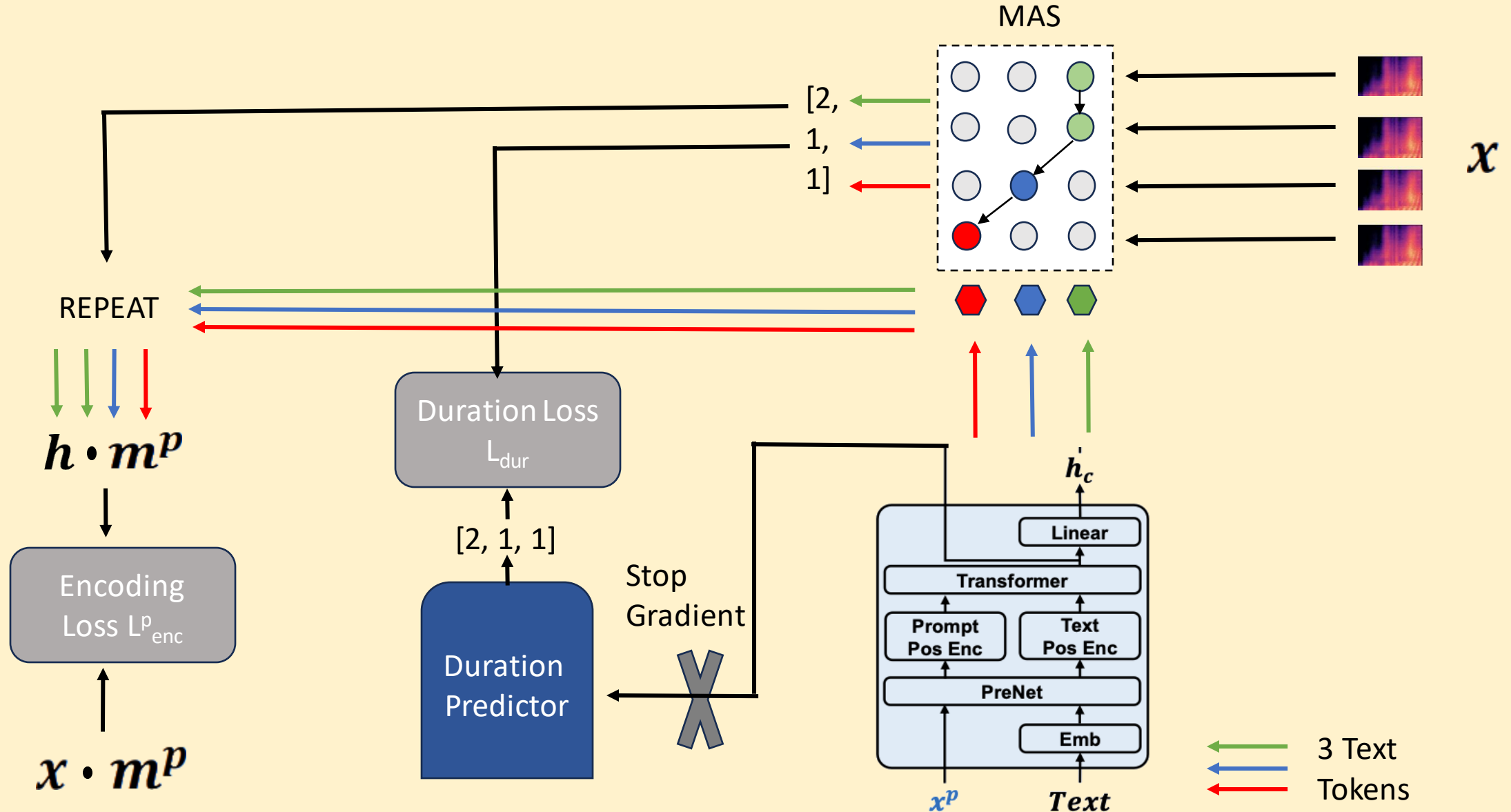
1	1	2	3
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\mathbf{A}^* alignments

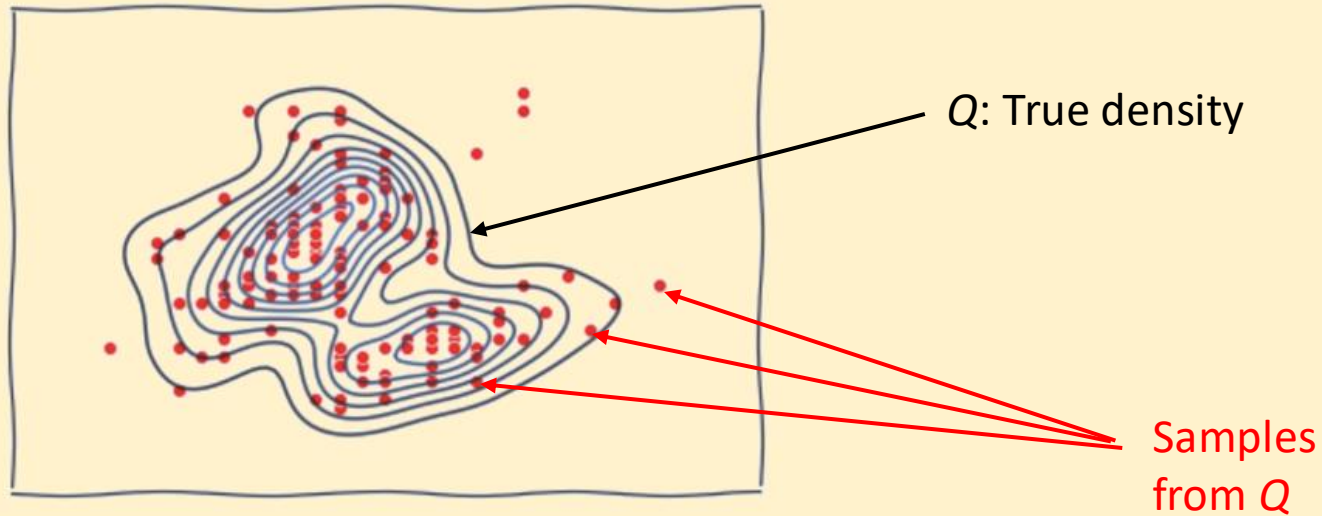
Len = $[M_frames]$

MONOTONIC ALIGNMENT SEARCH

5



BACKGROUND: GENERATIVE MODELS



Task 1:

How to estimate the density of samples.

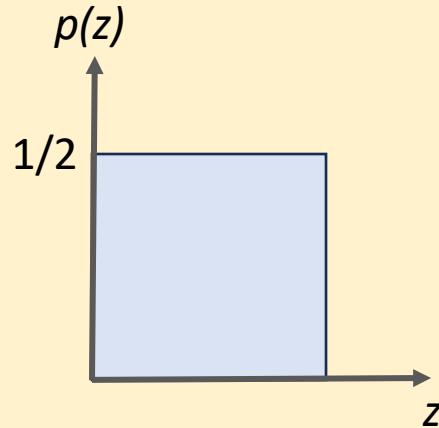
Eg: Consider a distribution Φ that models the images of dogs.

What is $\Pr_{\Phi}(X = \text{Golden retriever})$?

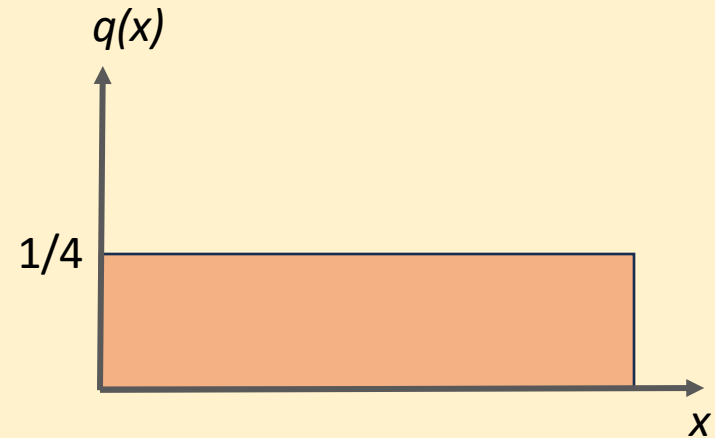
Task 2:

Generating new samples from Q by training on existing samples which are assumed to be generated from the Q distribution.

BACKGROUND: NORMALIZING FLOWS



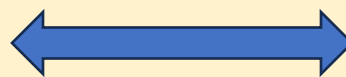
Invertible mapping
function



$$T : Z \rightarrow X$$

$$q(x) = p(z) \left| \frac{dz}{dx} \right|$$

Using change of
variables



$$q(x) = p(z) \left| \frac{\partial T(z)}{\partial z} \right|^{-1}$$

BACKGROUND: NORMALIZING FLOWS

$$T : \mathbf{Z} \rightarrow \mathbf{X}$$

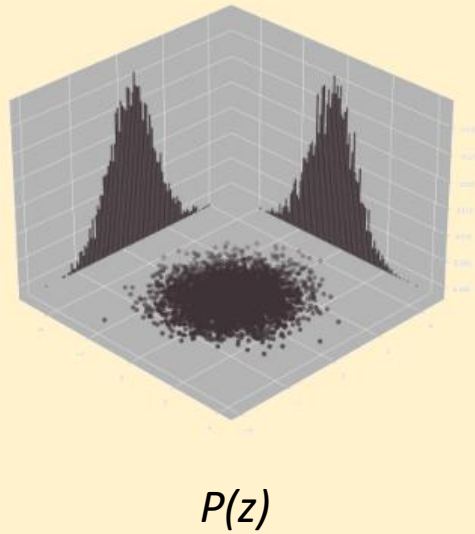
$$q(x) = p(z) \left| \frac{\partial T(z)}{\partial z} \right|^{-1} \quad \xrightarrow{\text{For } n \text{ samples}} \quad \prod_{i=1}^n q(\mathbf{x}_i) = \prod_{i=1}^n p(\mathbf{z}_i) \left| \det(\nabla_{\mathbf{z}} \mathbf{T}(\mathbf{z}_i)) \right|^{-1}$$

Transformations follow LOTUS: Gives rise to exact log likelihood evaluation

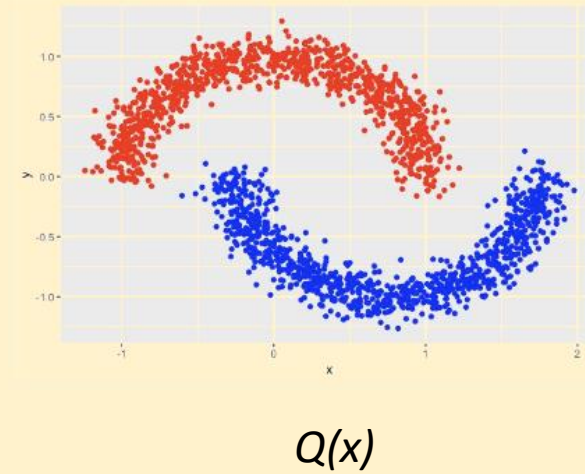
Maximize for T

$$\hat{\mathbf{T}} := \arg \max_{\mathbf{T}} \sum_{i=1}^n \log p(\mathbf{z}_i) - \log \left| \det(\nabla_{\mathbf{z}} \mathbf{T}(\mathbf{z}_i)) \right| \quad \xleftarrow{\text{Maximize Log likelihood}} \quad \hat{\mathbf{T}} := \arg \max_{\mathbf{T}} \prod_{i=1}^n p(\mathbf{z}_i) \left| \det(\nabla_{\mathbf{z}} \mathbf{T}(\mathbf{z}_i)) \right|^{-1}$$

BACKGROUND: NORMALIZING FLOWS



Invertible mapping
function
 T
Bijection



How to estimate density?

$$q(\mathbf{x}) = p(\mathbf{z}) \left| \det(\nabla_{\mathbf{z}} \mathbf{T}(\mathbf{z})) \right|^{-1}$$

How to sample a new x from Q ?

Sample $z \sim P(z)$
Compute $f(z)$

BACKGROUND: CONTINUOUS NFs

- Neural Ordinary Differential Equations (Chen et al., 2018, [Link](#))
- This paper gives a way to backprop through ODE solvers using constant memory requirements.
- Also introduce Continuous time dynamics for Normalizing Flows.
- Theorem (or at least the crux of it): The change in the log probability of a continuous time RV is equal to the negative trace of the Jacobian of the transformation function wrt the RV.

BACKGROUND: CONTINUOUS NFs

Normalizing flow

$$\vec{z}_0 \sim p_0(\vec{z}_0)$$

$$\vec{z}_1 = \vec{f}(\vec{z}_0)$$

\vec{f} invertible and smooth

$$\log p_1(\vec{z}_1) = \log p_0(\vec{z}_0) - \log \left| \det \frac{\partial \vec{f}}{\partial \vec{z}_0} \right|$$

Continuous normalizing flow

$$\vec{z}(t_0) = \vec{z}_0 \sim p_0(\vec{z}_0)$$

$$\frac{d\vec{z}}{dt} = \vec{f}(\vec{z}(t), t)$$

\vec{f} uniformly Lipschitz continuous in \mathbf{z}
and continuous in t

$$\frac{d \log p(\vec{z}(t))}{dt} = - \operatorname{tr} \left(\frac{\partial \vec{f}}{\partial \vec{z}} \right)$$

BACKGROUND: FLOW MATCHING IN CNFs

**General conditional
probability path**

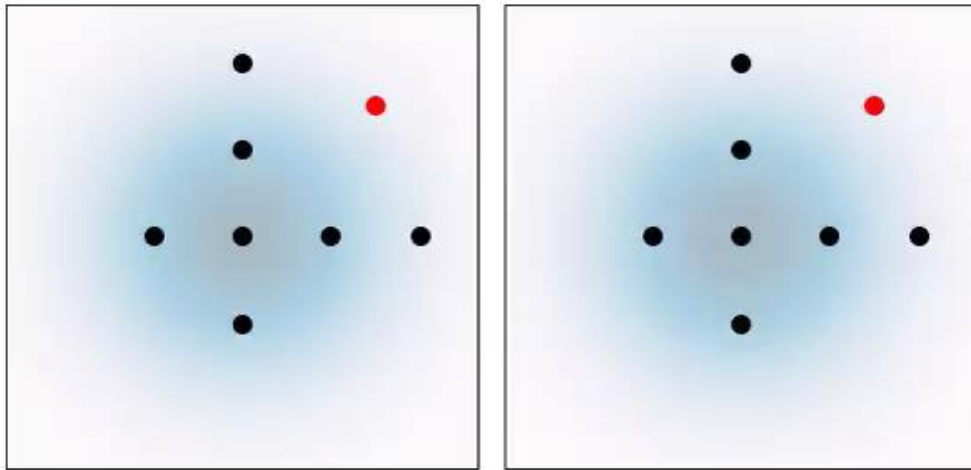
$$p(\mathbf{x}_t | \mathbf{x}_0) = \mathcal{N}(\mu_t(\mathbf{x}_0), \sigma_t^2(\mathbf{x}_0)I)$$

Training

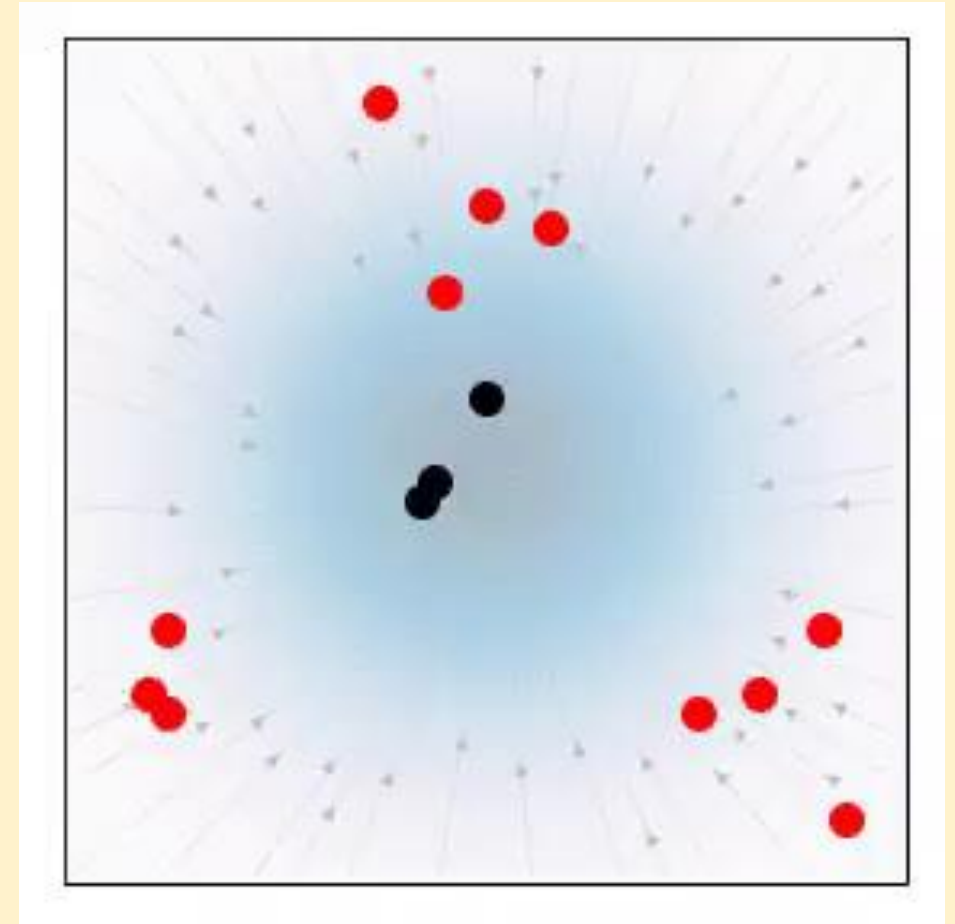
$$\left\| v_{\theta}(\mathbf{x}_t) - u_t(\mathbf{x}_t | \mathbf{x}_0) \right\|^2$$

Sampling

$$\dot{\mathbf{x}}_t = v_{\theta}(\mathbf{x}_t)$$



In contrast to variance preserving diffusion models (left)
CNFs do not overshoot in the final step (right)



Flow Matching directly regresses over the
vector fields of probability paths.

BACKGROUND: FLOW MATCHING IN CNFs

$$\mathcal{L}_{\text{FM}}(\theta) = \mathbb{E}_{t, p_t(x)} \|v_t(x) - u_t(x)\|^2$$

Flow matching objective. Ideal P_t (Path of the flow) and U_t (corresponding vector field) are not known.

$$p_t(x) = \int p_t(x|x_1)q(x_1)dx_1$$

Target probability path can be constructed using simple probability paths.

$$u_t(x) = \int u_t(x|x_1) \frac{p_t(x|x_1)q(x_1)}{p_t(x)} dx_1$$

The marginal vector field generates the marginal probability path.

$$\mathcal{L}_{\text{CFM}}(\theta) = \mathbb{E}_{t, q(x_1), p_t(x|x_1)} \|v_t(x) - u_t(x|x_1)\|^2$$

CFM objective is equivalent (in expectation) to optimizing the FM objective

Gradients coincide

BACKGROUND: FLOW MATCHING IN CNFs

Algorithm 1: Flow Matching training.

Input : dataset q , noise p

Initialize v^θ

while *not converged* **do**

$t \sim \mathcal{U}([0, 1])$ ▷ sample time

$x_1 \sim q(x_1)$ ▷ sample data

$x_0 \sim p(x_0)$ ▷ sample noise

$x_t = \Psi_t(x_0|x_1)$ ▷ conditional flow

 Gradient step with $\nabla_\theta \|v_t^\theta(x_t) - \dot{x}_t\|^2$

Output: v^θ

Algorithm 2: Flow Matching sampling.

Input : trained model v^θ

$x_0 \sim p(x_0)$ ▷ sample "noise"

Numerically solve ODE $\dot{x}_t = v_t^\theta(x_t)$

Output: x_1

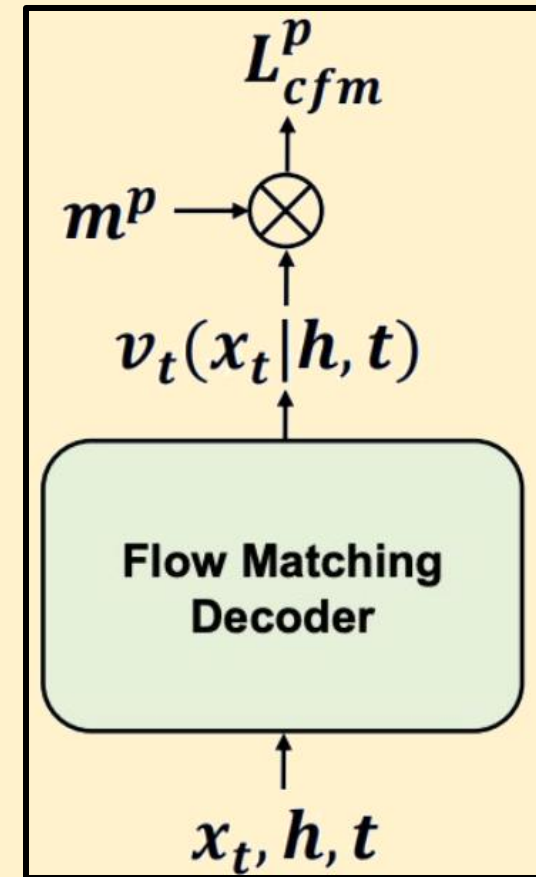
METHODOLOGY : DECODER

$$\frac{d}{dt}\phi_t(x) = v_t(\phi_t(x)); \quad \phi_0(x) = x$$

ODE Defining the transformation

$$\phi_{t,x_1}(x) = \sigma_t(x_1)x + \mu_t(x_1)$$

$$\mu_t(x) = tx_1, \quad \sigma_t(x) = 1 - (1 - \sigma_{\min})t$$



$$L_{CFM}(\theta) = \mathbb{E}_{t \sim U[0,1], x_1 \sim q(x_1), x_0 \sim p(x_0)} \|v_t(\phi_{t,x_1}(x_0); \theta) - \frac{d}{dt}\phi_{t,x_1}(x_0)\|^2$$

METHODOLOGY : DECODER

$$L_{CFM}(\theta) = \mathbb{E}_{t,q(x_1),p(x_0)} \|v_t(\phi_{t,x_1}(x_0); \theta) - (x_1 - (1 - \sigma_{\min})x_0)\|^2$$

Sampling

$$x_0 \sim \mathcal{N}(0, I); \quad x_{t+\frac{1}{N}} = x_t + \frac{1}{N} \hat{v}_\theta(x_t, h, t)$$

After Guided Sampling:

$$x_{t+\frac{1}{N}} = x_t + \frac{1}{N} (\hat{v}_\theta(x_t, h, t) + \gamma(\hat{v}_\theta(x_t, h, t) - \hat{v}_\theta(x_t, \bar{h}, t)))$$

LOSS FUNCTION OF P-FLOW

$$L_{enc} = MSE(h, x)$$

$$L_{enc}^p = MSE(h \cdot m^p, x \cdot m^p)$$

$$L_{cfm}^p$$
 : Loss from the Flow Matching Decoder front

$$L_{dur}$$
 : minimise $MSE(\log(d))$ obtained through MAS while training

Overall Training Loss:

$$L = L_{enc}^p + L_{cfm}^p + L_{dur}$$

DATASETS DETAILS

Dataset Name	Data size	No.of speakers	Languages	Download Link
LibriLight	60,000hrs	7000+	English	https://github.com/facebookresearch/libri-light
Librispeech	982hrs	2484	English	https://www.openslr.org/12
LibriTTS	585hrs	2456	English	https://www.openslr.org/60
VCTK	44hrs	110	English	https://datashare.ed.ac.uk/handle/10283/2651

VALL-E vs P-Flow Methodological Differences

	VALL-E	P-Flow
Speech Representation	Audio Codec Code	Mel-spectograms
Generative Model	Language Model	Flow Matching Generative Model
Training Data	60,000 hours	260 hours
In-context learning	✓	✓
Dataset used	LibriLight	LibriTTS
Evaluation datasets	LibriTTS, LibriSpeech, VCTK	LibriSpeech, VCTK

FAST: 20x times faster than VALL-E

Data-efficient: Less than 0.01x VALL-E's training dataset

Zero-shot: Comparable to VALL-E

Sample Quality, Pronunciation accuracy: P-Flow > VALL-E

EXPERIMENTS AND ABLATION STUDY

DATASET Details

LibreTTS dataset: 580hrs of data(2456 speakers) -> 256hrs subset (need 3sec for prompting)

Evaluation on LibriSpeech

Training Configurations	Important
Used 1 NVIDIA A100 GPU	Euler steps : 10
Learning rate : 0.0001	Guidance scale: 1
Optimizer : Adam	Preprocessing: G2P model into IPA format
Batch size : 64	Postprocessing: Hifi-GAN mel-spectrogram to audio wav file WS : 1024, hop length: 256, 22kHz representation

HYPERPARAMETERS OF MODEL FOR EXPERIMENTS

Speech-prompted Text Encoder	Phoneme Embedding Dim	192
	PreNet Conv Layers	3
	PreNet Hidden Dim	192
	PreNet Kernel Size	5
	PreNet Dropout	0.5
	Transformer Layers	6
	Transformer Hidden Dim	192
	Transformer Feed-forward Hidden Dim	768
	Transformer Attention Heads	2
	Transformer Dropout	0.1
	Prompt Embedding Dim	192
	Number of Parameters	3.37M
Duration Predictor	Conv Layers	3
	Conv Hidden Dim	256
	LayerNorm Layers	2
	Dropout	0.1
	Number of Parameters	0.36M
Flow Matching Decoder	WaveNet Residual Channel Size	512
	WaveNet Residual Blocks	18
	WaveNet Dilated Layers	3
	WaveNet Dilation Rate	2
	Number of Parameters	40.68M

EVALUATION METRICS

OBJECTIVE METRICS

1. Word Error Rate (**WER**):

The number of errors(Insertion, substitution, deletion) divided by the total words

2. Speaker Embedding Cosine Similarity (**SECS**):

An evaluation metric measuring speaker similarity between generated and original speech.

3. Inference Latency

SUBJECTIVE METRICS

1. Comparative Mean Opinion Score (**CMOS**):

Used for comparing the voice quality of two TTS systems

2. Comparative Speaker similarity Mean Opinion Score (**SMOS**):

Used for comparing the similarity of waves compared with recording waves

RESULTS AND ANALYSIS

MODEL	DATA (HOURS)	WER↓	SECS↑	INFERENCE LATENCY(S)↓
GT (HIFI-GAN)		2.4	0.64	
YOURTTS [†]	500+	7.7	0.337	
VALL-E [†]	60,000	5.9	0.580	2.515 ± 0.040
VALL-E CONTINUAL [†]	60,000	3.8	0.508	2.515 ± 0.040
P-FLOW (PROPOSED)	260	2.6	0.544	0.115 ± 0.004

On LibriSpeech

MODEL	WER↓	SECS↑
VALL-E	4.3	0.452
P-FLOW (PROPOSED)	2.4	0.465

On VCTK

Dataset	CMOS \hat{I}	SMOS \hat{I}
LibreSpeech	0.27 ± 0.10	0.23 ± 0.13
VCTK	0.188 ± 0.10	0.267 ± 0.166

Subjective Metrics:
P-FLOW > VALL-E

EXPERIMENTS AND ABLATION STUDY

MODEL	WER↓	SECS↑
GT (HIFI-GAN)	2.4	0.64
P-FLOW (W/O PROMPT)	2.9	0.373
P-FLOW	2.6	0.544

P-Flow with and without Prompt
(Importance of Speech prompting)

MODEL	WER↓	SECS↑
P-FLOW (EULER METHOD, $N = 10$)	2.6	0.544
P-FLOW (HEUN'S METHOD, $N = 4$)	2.6	0.552
P-FLOW (MIDPOINT METHOD, $N = 4$)	2.7	0.540

Different ODE Sampling methods

MODEL	N	MOS↑	SECS	INFERENCE LATENCY(S)↓
P-FLOW	1	3.55 ± 0.16	0.420	0.028 ± 0.004
	2	3.71 ± 0.12	0.522	0.037 ± 0.004
	5	4.01 ± 0.10	0.549	0.067 ± 0.004
	10	4.08 ± 0.10	0.544	0.115 ± 0.004
	20	4.14 ± 0.10	0.540	0.210 ± 0.005

Euler steps and Accoustic quality
through Mean Opinion score(MOS)

Effect of variations in
1. guidance scale γ
2. Euler steps N

MODEL	γ	N	WER↓	SECS↑	INFERENCE LATENCY(S)↓
P-FLOW (DEFAULT)	1	10	2.6	0.544	0.115 ± 0.004
P-FLOW	0	10	3.7	0.492	0.115 ± 0.004
P-FLOW	2	10	2.6	0.546	0.115 ± 0.004
P-FLOW	1	1	2.7	0.420	0.028 ± 0.004
P-FLOW	1	2	2.9	0.522	0.037 ± 0.004
P-FLOW	1	5	2.6	0.549	0.067 ± 0.004
P-FLOW	1	20	2.7	0.540	0.210 ± 0.005

P-FLOW DEMO

GROUND TRUTH



3-SEC REFERENCE



*GENERATED
AUDIO*

P-FLOW



VALL-E



They moved thereafter cautiously about the hut, groping before and about them to find something to show that Warrenton had fulfilled his mission.

P-FLOW DEMO

GROUND TRUTH



3-SEC REFERENCE



*GENERATED
AUDIO*

P-FLOW



VALL-E



We have made a couple of Albums

P-FLOW IN ACTION

P-Flow in Action

- Paper: [SCALING NVIDIA'S MULTI-SPEAKER MULTI-LINGUAL TTS SYSTEMS WITH ZERO-SHOT TTS TO INDIC LANGUAGES](#)
- P-flow implementation secured **1s rank** in MMITS-VC 2024 Challenge for Zero shot TTS track
- MMITS-VC : **M**ulti-speaker, **M**ulti-lingual **I**ndic **TTS** with **VOICE CLONING**
- **Organized as part of** ICASSP's Signal Processing Grand Challenge 2024

Team name	MOS(avg)	MOS(std)
NVIDIA	4.4	0.73
SJTU_XLANCE_VC	4.23	0.79
TalTech	3.93	1.16
reply_2024	3.12	1.16
Shabdh	3.09	1.1
LIMITLESS	2.82	1.42
nwpu	2.31	1.26

← **Naturalness**

Speaker Similarity →

[RESULTS](#)

Team name	Score(avg)	Score(std)
NVIDIA	3.62	1.3076
Shabdh	3.44	1.3296
LIMITLESS	3.37	1.4172
TalTech	3.12	1.3261
reply_2024	3.04	1.27
nwpu	2.38	1.3003
SJTU_XLANCE_VC	2.26	1.1823

CONCLUSION

- P-flow paper presents three main components of P-Flow architecture:
 - A conditional flow matching decoder for faster sampling
 - A speech prompted text encoder to better speech prompting
 - A MAS algorithm minimizes distance between speech frames and text representations.
- P-flow avoids probability paths which lead to overshooting as transformations reach the target distribution, hence leads to better convergence during sampling.
- Establishes a challenge to data-hungry LMs in recent trends for need of large data
- Other notable works which use flow matching for TTS:
 - [Link:](#) Voicebox: Text-Guided Multilingual Universal Speech Generation at Scale
 - [Link:](#) Audiobox: Unified Audio Generation with Natural Language Prompts
 - [Link:](#) GENERATIVE PRE-TRAINING FOR SPEECH WITH FLOW MATCHING
 - [Link:](#) REFLOW-TTS: A RECTIFIED FLOW MODEL FOR HIGH-FIDELITY TEXT-TO-SPEECH

FUTURE DIRECTIONS

1. Larger dataset is not required for achieving comparable naturalness and speaker adaptation from P-Flow, trying it out for accented TTS, multi-lingual TTS, where various variety of speech is possible through fewer samples
2. Low resource language speeches could be experimented with p-flow using transfer learning.
3. Zero-shot capabilities of duration predictor remain limited
4. High-quality zero-shot TTS might cause social impact, so steps to detect synthetic audio is required

LEARNINGS

Through the P-Flow paper, we learnt the details of following concepts

1. Current SOTA models and their workflow in the domain of zero-shot TTS
2. Usage of mel-spectrograms in Speech as representations
3. Concepts of Flow Matching and their effectiveness
4. Metrics evaluated for the problems of TTS, subjective and objective
5. Need of efficient TTS models and their usecases along with social impact

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THANK YOU SLIDE

THANK
YOU FOR
YOUR TIME

Q&A



REFERENCES AND TUTORIALS

- Normalizing flows :
- Conditional Flow matching: