

Calibration results

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Camera-system parameters:

cam0 (main_camera/image_raw/compressed):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.23817822 0.05646082 -0.00034675 0.000473] +- [0.00129306 0.00081967 0.00013742 0.00012659]

projection: [897.8868869 896.13100574 936.5736771 550.18873623] +- [3.92353931 3.83646122 2.083909
2.70838822]

reprojection error: [-0.000003, -0.000000] +- [0.391437, 0.349213]

Target configuration

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Type: aprilgrid

Tags:

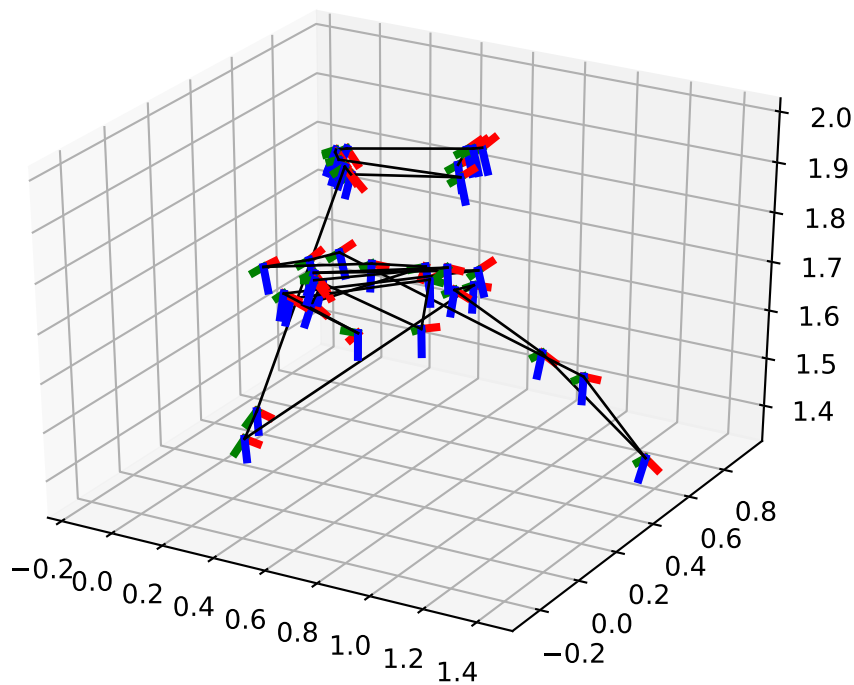
Rows: 6

Cols: 6

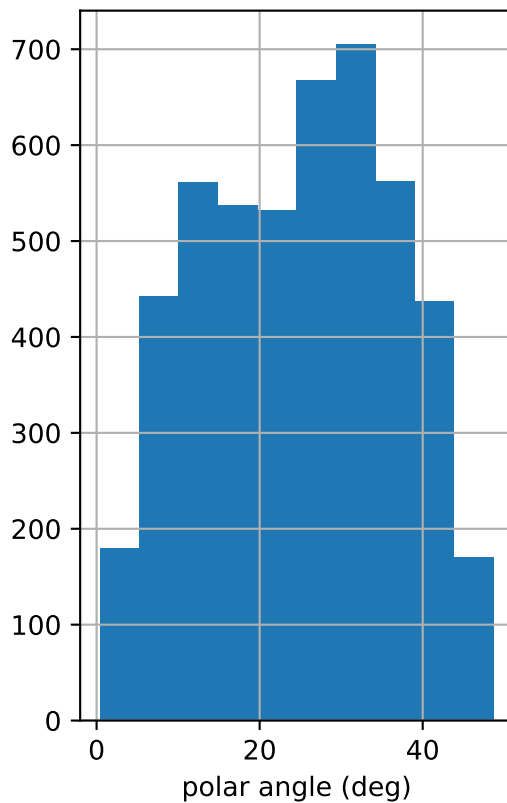
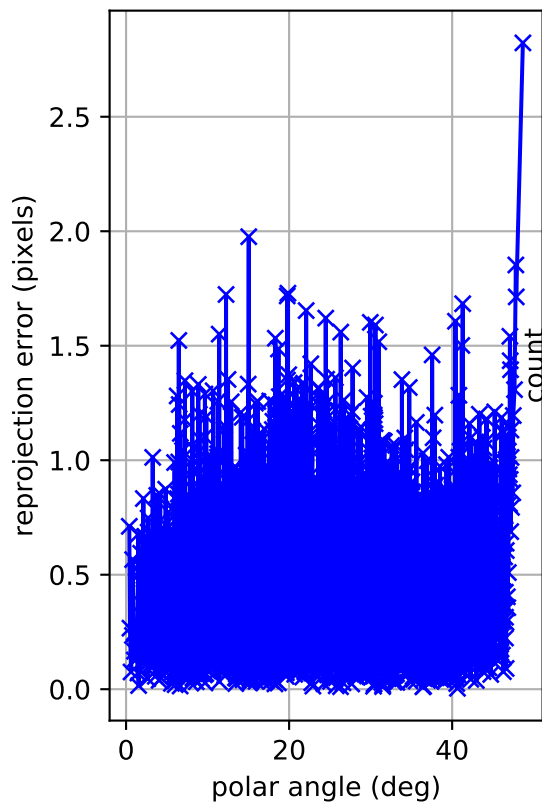
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

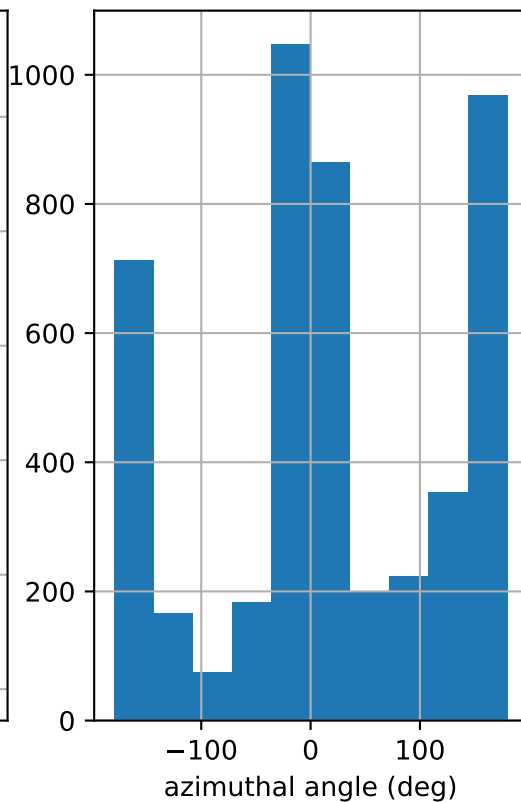
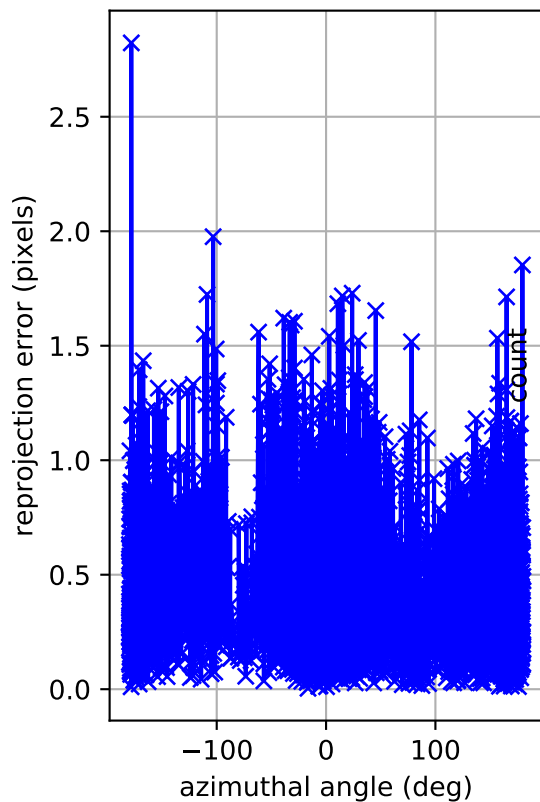
cam0: estimated poses



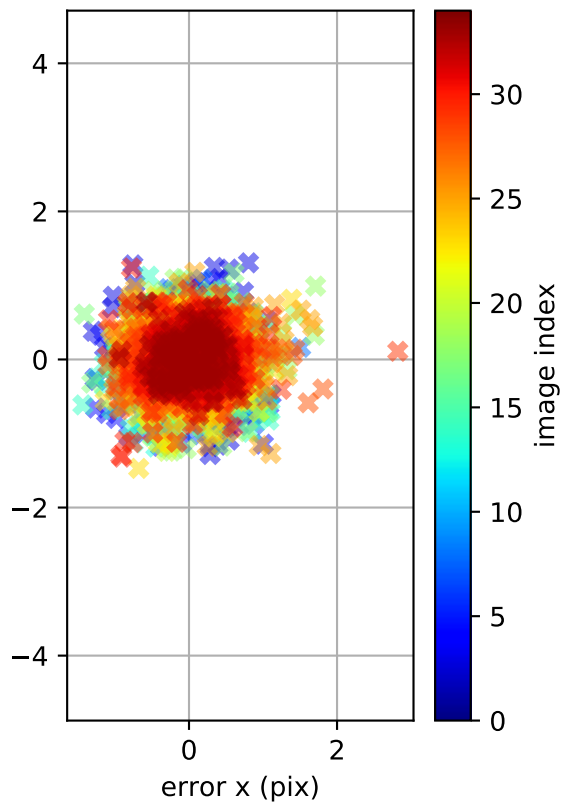
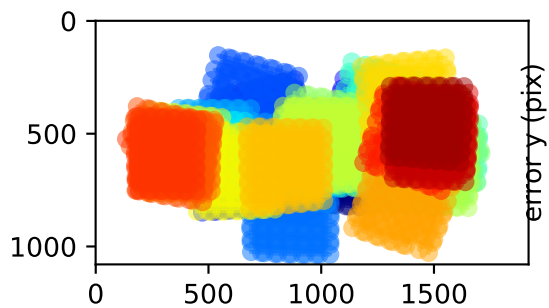
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

