## Econ 753 Assignment 3

## Katherine Fairley

1. The sequence problem for the firm is:

Choose 
$$i = \{i_1, i_2, ...\}$$
 where  $\forall t, i_t \in \{0, 1\}$ 

to solve:

$$\max_{i} \mathbb{E} \left[ \sum_{t=1}^{\infty} \beta^{t-1} \Pi(a_{t}, i_{t}, \varepsilon_{0t}, \varepsilon_{1t}) \right]$$

$$\iff \max_{i} \mathbb{E} \left[ \sum_{t=1}^{\infty} \beta^{t-1} \left[ i_{t} \times (R + \varepsilon_{1t}) + (1 - i_{t}) \times (\mu a_{t} + \varepsilon_{0t}) \right] \right]$$

2. The Bellman equation is given by:

$$\begin{split} V(a,\varepsilon_0,\varepsilon_1) &= \max_{i \in \{0,1\}} \Pi(a,i,\varepsilon_0,\varepsilon_1) + \beta \, \mathbb{E} \left[ V(a',\varepsilon_0',\varepsilon_1') \right] \\ &= \max \left\{ (R+\varepsilon_1) + \beta \, \mathbb{E} \left[ V(1,\varepsilon_0',\varepsilon_1') \right] \right. , \quad (\mu a + \varepsilon_0) + \beta \, \mathbb{E} \left[ V(\min\{5,a+1\},\varepsilon_0',\varepsilon_1') \right] \right\} \\ &= \max \left\{ \bar{V}_1(a,\varepsilon_0,\varepsilon_1;\theta) \right. , \quad \bar{V}_0(a,\varepsilon_0,\varepsilon_1;\theta) \right\} \end{split}$$

Define:

$$\Pi(a,i) = \begin{cases} R & \text{if } i = 1\\ \mu a & \text{if } i = 0 \end{cases}$$

Then the Bellman equation can be expressed as a function of only the observed state, a:

$$\begin{split} V(a) &= \max_{i \in \{0,1\}} \left\{ \Pi(a,i) + \beta \, \mathbb{E} \left[ V(a') \right] \right\} \\ &= \max \left\{ R + \beta \, V(1) \;\;,\;\; \mu a + \beta \, V(\min\{5,a+1\}) \right\} \\ &= \max \left\{ \bar{V_1}(a;\theta) \;\;,\;\; \bar{V_0}(a;\theta) \right\} \end{split}$$

3. (a) The firm is indifferent between replacing and not when:

$$R + \varepsilon_1 + \beta \mathbb{E}_{\varepsilon'_0, \varepsilon'_1}[V(1)] = 2\mu + \varepsilon_0 + \beta \mathbb{E}_{\varepsilon'_0, \varepsilon'_1}[V(3)]$$

$$\implies \varepsilon_0 - \varepsilon_1 = R - 2\mu + \beta \left( \mathbb{E}_{\varepsilon'_0, \varepsilon'_1}[V(1)] - \mathbb{E}_{\varepsilon'_0, \varepsilon'_1}[V(3)] \right)$$

Where  $\mathbb{E}_{\varepsilon_0',\varepsilon_1'}[V(a')] \equiv EV(a')$  is the expected value function.

Using the log-sum formula, when  $\mu = -1$ , R = -3, and  $\beta = 0.9$ , the expected value function is:

$$EV(a) = log[exp(-3 + 0.9 \cdot EV(1)) + exp(-a + 0.9 \cdot EV(min\{5, a + 1\}))] + \gamma$$

By evaluating this expression for each  $a \in \{1, 2, 3, 4, 5\}$  and solving the resulting system of equations, I obtain:

$$EV(1) = -9.3362$$

$$EV(3) = -10.5746$$

$$EV(5) = -10.7895$$

This gives:

$$\varepsilon_0 - \varepsilon_1 = 0.1145$$

The probability the firm will replace the machine is:

$$P(i=1|a=2;\theta) = \frac{exp(R+\beta \, \mathbb{E}_{\varepsilon_0',\varepsilon_1'}[V(1)])}{exp(-2\mu+\beta \, \mathbb{E}_{\varepsilon_0',\varepsilon_1'}[V(3)]) + exp(R+\beta \, \mathbb{E}_{\varepsilon_0',\varepsilon_1'}[V(1)])}$$

and so at the given parameter values, this probability is given by:

$$P(i = 1 | a = 2; \mu = -1, R = -3, \beta = 0.9) = 0.5286$$

The value of the firm is given by:

$$V(a, \varepsilon_0, \varepsilon_1) = \max \left\{ (R + \varepsilon_1) + \beta \mathbb{E} \left[ V(1, \varepsilon_0', \varepsilon_1') \right] \right. , \left. (\mu a + \varepsilon_0) + \beta \mathbb{E} \left[ V(\min\{5, a + 1\}, \varepsilon_0', \varepsilon_1') \right] \right\}$$

Evaluated at a = 4,  $\varepsilon_0 = 1$ ,  $\varepsilon_1 = 1.5$ ,  $\mu = -1$ , R = -3, and  $\beta = 0.9$ , this gives:

$$V(4, 1, 1.5) = \max \{-1.5 + 0.9 \cdot EV(1), -3 + 0.9 \cdot EV(5)\}$$

and substituting in the values of EV(1) and EV(5) gives:

$$V(4, 1, 1.5) = \max\{\underbrace{-9.9026}_{\text{replace}}, \underbrace{-12.7105}_{\text{don't}}\} = -9.9026$$

```
1
   % Assignment 3 Econ 753
3
  % Set working directory
4 | cd('C:\Users\KatyK\University of Michigan Dropbox\Katherine Fairley\
      Notability\Spring 2025\753 - Methods\Github')
5
6
7
   %% #3.a.
8
  % Parameters
9 \mid mu = -1;
                % Cost of machine operation per age unit
10 | R = -3;
               % Cost of replacement
11
   beta = 0.9; % Discount factor
   gamma = 0.5772156649; % Euler's constant
12
13
14 \% Create symbolic variables for the expected value functions
15
   syms EV1 EV2 EV3 EV4 EV5 real
16
17 % Set up the system of equations
|8| \% EV(a) = log[exp(R + beta*EV(1)) + exp(-a + beta*EV(min(5,a+1)))] +
      gamma
19
20 | eq1 = EV1 == log(exp(R + beta*EV1) + exp(-1 + beta*EV2)) + gamma;
21 | eq2 = EV2 == log(exp(R + beta*EV1) + exp(-2 + beta*EV3)) + gamma;
   eq3 = EV3 == log(exp(R + beta*EV1) + exp(-3 + beta*EV4)) + gamma;
22
   eq4 = EV4 == log(exp(R + beta*EV1) + exp(-4 + beta*EV5)) + gamma;
24
   eq5 = EV5 == log(exp(R + beta*EV1) + exp(-5 + beta*EV5)) + gamma;
25
26 | % Solve the system of equations
27 | eqs = [eq1, eq2, eq3, eq4, eq5];
28 | vars = [EV1, EV2, EV3, EV4, EV5];
29
   solution = vpasolve(eqs, vars);
30
31 | % Extract and display the solutions with 4 decimal places
   fprintf('Algebraic solution for expected value functions:\n');
33 | EV = zeros(5,1);
34 | for a = 1:5
       varName = sprintf('EV%d', a);
35
36
       EV(a) = double(solution.(varName));
37
       fprintf('EV(%d) = %.4f\n', a, EV(a));
38
   end
39
40 | %Value of epsilon_0 - epsilon_1 for indifference when a = 2
   indiff_threshold = (R - (-2)) + beta * (EV(1) - EV(3));
41
   fprintf('\nQuestion 1: Indifference threshold when a(t) = 2\n');
42
43
   fprintf('epsilon_0 - epsilon_1 = %.4f\n', indiff_threshold);
44
```

```
45 \mid \% Probability of replacement when a = 2
46 | v_1 = R + beta * EV(1);
47 | v_0 = -2 + beta * EV(3);
48 | prob\_replace = 1 / (1 + exp(v_0 - v_1));
49
   fprintf('\nQuestion 2: Probability of replacement when a(t) = 2\n');
   fprintf('P(i(t)=1|a(t)=2) = \%.4f\n', prob_replace);
50
51
52 |\%| Value of the firm at a = 4, epsilon_0 = 1, epsilon_1 = 1.5
v_{keep_4} = -4 + 1 + beta * EV(5);
54 | v_replace_4 = R + 1.5 + beta * EV(1);
55 | value_4 = max(v_keep_4, v_replace_4);
56 | fprintf('\nQuestion 3: Value at a(t) = 4, epsilon_0 = 1, epsilon_1 =
      1.5\n');
57
   fprintf(V(a(t)=4, epsilon_0=1, epsilon_1=1.5) = %.4f\n', value_4);
58
   if v_replace_4 > v_keep_4
59
       fprintf('Optimal action: Replace\n');
60
   else
       fprintf('Optimal action: Keep\n');
61
62 | end
63
64
65
66 | %% Set parameter values
67
   theta = [-1, -3]; % [mu, R]
   beta = 0.9;
                     % Discount factor
68
69
70 | %% #3 - Value Function Iteration
71 | EVO = zeros(10,1); % Set initial guess of expected value function
72
73 % Define transition probability matrix - modified for correct state
      representation
74 | prob = zeros(10, 5);
75 % First 5 rows for ages 1-5 with no replacement (state transitions)
76 | prob(1,1) = 1; \% age 1 -> 2
77
   prob(2,2) = 1; \% age 2 -> 3
78
   prob(3,3) = 1; \% age 3 \rightarrow 4
79
   prob(4,4) = 1; \% age 4 -> 5
80 | prob(5,5) = 1; \% age 5 stays 5
   % Next 5 rows for replacement (always transitions to age 1)
81
82
   prob(6:10,1) = 1;
83
84 | % Value function iteration
85
   EV1 = inner(theta, beta, EV0, prob); % Call function to get first
      iteration
86
87
   tolerance = 1e-6; % Set tolerance level for convergence
88 | iterations = 0;
```

```
89
   max_iter = 1000;
90
91 | while norm(EV1 - EV0) >= tolerance && iterations < max_iter
92
       EV0 = EV1:
93
       EV1 = inner(theta, beta, EV0, prob);
94
       iterations = iterations + 1;
95
   end
96
97
   fprintf('Value function converged after %d iterations\n', iterations)
98
99 | %% #4 - Simulate the Data
   % Simulate data with parameters R = -3, mu = -1, beta = 0.9
100
   [sim_data, value_function, policy_function] =
101
      simulateMachineReplacement(-3, -1, 0.9, 20000);
102
103
   %% #5 - Run NFP Estimation
   % Extract only the required columns for rustNFP from data table
104
   estimation_data = sim_data(:, {'period', 'age', 'replace'});
105
106
   % Run NFP estimation
107
108 [estimates, std_errors, loglik, iterations] = rustNFP(estimation_data
      , beta);
109
110 % Compare true vs estimated parameters
   fprintf('\nComparison of True vs. Estimated Parameters:\n');
111
   fprintf('R: True = \%.4f, Estimated = \%.4f (SE: \%.4f)\n', -3,
112
      estimates(1), std_errors(1));
113
   fprintf('mu: True = \%.4f, Estimated = \%.4f (SE: \%.4f)\n', -1,
      estimates(2), std_errors(2));
114
   fprintf('Log-likelihood: %.4f\n', loglik);
   fprintf('Number of function evaluations: %d\n', iterations);
115
116
   %% #6 - Run CCP Estimation
117
   % Run CCP estimation
118
   [estimates, std_errors, loglik] = hotzMillerCCP(estimation_data, beta
119
      );
120
   %% Inner Function for Value Function Iteration (#3)
121
   function EV1 = inner(theta, beta, EV0, prob)
122
123
       124
       R = theta(2);  % Extract R from parameter vector
125
126
       SS = [1,2,3,4,5]'; % Define state space (vector of possible
          values of a)
127
128
       % Euler's constant (approximately 0.5772)
```

```
129
        gamma = 0.5772156649;
130
131
        % Calculate the expected value for keep and replace options
132
        11 = \log(\exp(mu*SS + beta*EVO(1:5)) + \exp(R*ones(5,1) + beta*EVO)
           (6:10));
133
134
        % Add Euler's constant and multiply by transition probabilities
135
        EV1 = (prob*11) + gamma*ones(10,1);
136
    end
137
138
    %% Data Simulation Functions (#4)
    function [data, value_function, policy_function] =
139
       simulateMachineReplacement(R, mu, beta, T)
140
        % Maximum machine age
        maxAge = 5;
141
142
143
        % Step 1: Solve the dynamic programming problem
144
        [value_function, policy_function] = solveDP(R, mu, beta, maxAge);
145
146
        % Step 2: Simulate decisions based on the solved policy function
        data = simulateDecisions(policy_function, R, mu, T, maxAge);
147
148 end
149
    function [value_function, policy_function] = solveDP(R, mu, beta,
150
       maxAge)
151
        % Setup state space: machine ages from 1 to maxAge
152
        states = 1:maxAge;
153
        n_states = length(states);
154
155
        % Initialize value function
156
        value_function = zeros(n_states, 1);
157
        new_value_function = zeros(n_states, 1);
158
        policy_function = zeros(n_states, 1);
159
160
        % Value function iteration
161
        max_iter = 10000;
162
        tolerance = 1e-6:
163
        converged = false;
164
        iter = 0;
165
166
        % Euler's constant
167
        gamma = 0.5772156649;
168
169
        while ~converged && iter < max_iter</pre>
170
            iter = iter + 1:
171
172
            for i = 1:n_states
```

```
173
                 % Current state (machine age)
174
                 a = states(i);
175
176
                % Option 0: Keep the machine
                % Flow utility from keeping
177
178
                 u0 = mu * a;
179
180
                 % Expected future value if keeping
181
                 if a < maxAge</pre>
                     future_state = a + 1;
182
183
                 else
184
                     future_state = a; % Age stays at maxAge
185
                 end
186
187
                 v0 = u0 + beta * value_function(future_state);
188
189
                 % Option 1: Replace the machine
                 % Flow utility from replacing
190
                 u1 = R:
191
192
193
                 % Future state is always 1 (new machine)
194
                 v1 = u1 + beta * value_function(1);
195
                 % Compute choice-specific value functions
196
197
                v = [v0, v1];
198
199
                 % Compute expected value using the "log-sum-exp" formula
                    for Type-1 EV
200
                 % Include Euler's constant in the calculation
201
                 new_value_function(i) = log(exp(v0) + exp(v1)) + gamma;
202
203
                 % Compute choice probabilities
204
                 prob\_replace = exp(v1) / (exp(v0) + exp(v1));
205
206
                 % Store the policy (probability of replacement)
                 policy_function(i) = prob_replace;
207
208
            end
209
210
            % Check for convergence
211
            diff = max(abs(new_value_function - value_function));
212
            if diff < tolerance</pre>
213
                 converged = true;
214
            end
215
216
            % Update value function
217
            value_function = new_value_function;
218
        end
```

```
219
220
        if ~converged
221
            warning('Value function iteration did not converge after %d
               iterations', max_iter);
222
        end
223
   end
224
225
    function data = simulateDecisions(policy_function, R, mu, T, maxAge)
226
        % Initialize data structure
        data = struct('period', {}, 'age', {}, 'replace', {}, 'epsilon0',
227
            {}, 'epsilon1', {});
228
229
        % Initialize machine age (start with a new machine)
230
        age = 1;
231
232
        % Simulate decisions over time
233
        for t = 1:T
234
            % Draw extreme value errors
235
            epsilon0 = -log(-log(rand())); % Type-1 extreme value
236
            epsilon1 = -log(-log(rand())); % Type-1 extreme value
237
238
            % Compute deterministic components of utility
239
            u0 = mu * age;
240
            u1 = R;
241
242
            % Compute total utilities including random components
243
            total_u0 = u0 + epsilon0;
244
            total_u1 = u1 + epsilon1;
245
246
            % Make replacement decision based on utilities
247
            replace = (total_u1 > total_u0);
248
249
            % Policy based on age - this is for comparison
250
            policy_prob = policy_function(age);
251
252
            % Store the data
253
            idx = length(data) + 1;
254
            data(idx).period = t;
255
            data(idx).age = age;
256
            data(idx).replace = replace;
257
            data(idx).epsilon0 = epsilon0;
258
            data(idx).epsilon1 = epsilon1;
259
            data(idx).policy_prob = policy_prob;
260
261
            % Update machine age based on decision
262
            if replace
263
                age = 1; % New machine
```

```
264
            else
265
                age = min(maxAge, age + 1); % Age the machine
266
            end
267
        end
268
269
        % Convert struct to table for easier analysis
270
        data = struct2table(data);
271
   end
272
273
    %% Nested Fixed Point (NFP) Estimation Functions (#5)
274
    function [estimates, std_errors, loglik, iterations] = rustNFP(data,
      beta)
275
        % Input:
276
            data - table with columns: period, age, replace
            beta - discount factor (fixed in estimation)
277
278
279
        % Output:
            estimates - estimated parameters [R; mu]
280
        %
281
        % std_errors - standard errors of the estimates
282
            loglik - log likelihood at the optimum
        %
            iterations - number of function evaluations
283
284
285
        % Start with initial parameter guess
286
        % Define initial values for the structural parameters close to
           true values
287
        theta0 = [-4; -0.5]; % Initial guess for [R; mu]
288
289
        % Set maximum age
290
        maxAge = 5;
291
292
        % Setup optimization options for the parameter search
        options = optimset('Display', 'iter', 'TolFun', 1e-6, 'TolX', 1e
293
           -6, 'MaxFunEvals', 1000);
294
295
        % Define objective function for optimization (negative log
           likelihood)
296
        objFun = @(theta) negLogLikelihood(theta, data, beta, maxAge);
297
298
        % Run optimization to find parameter estimates
299
        [theta_hat, fval, ~, output] = fminunc(objFun, theta0, options);
300
301
        % Extract results
302
        estimates = theta_hat;
303
        loglik = -fval; % Convert back to positive log likelihood
304
        iterations = output.funcCount;
305
        % Compute standard errors using numerical Hessian
306
```

```
307
        H = numHessian(objFun, theta_hat);
308
        std_errors = sqrt(diag(inv(H)));
309
310
        % Display results
311
        fprintf('Estimation Results:\n');
312
        fprintf('R: %.4f (SE: %.4f)\n', estimates(1), std_errors(1));
313
        fprintf('mu: %.4f (SE: %.4f)\n', estimates(2), std_errors(2));
314
        fprintf('Log-likelihood: %.4f\n', loglik);
315
        fprintf('Number of function evaluations: %d\n', iterations);
316
    end
317
318
   % Negative Log-Likelihood Function
319
    function [nll, grad] = negLogLikelihood(theta, data, beta, maxAge)
320
        % Extract parameters
321
        R = theta(1);
322
        mu = theta(2);
323
324
        % Solve for conditional value functions using contraction mapping
325
        [V0, V1] = solveValueFunctions(R, mu, beta, maxAge);
326
327
        % Compute choice probabilities using logit formula
328
        loglik = 0;
329
        for i = 1:height(data)
330
            age = data.age(i);
331
            replace = data.replace(i);
332
333
            % Compute choice probability using logit formula
334
            prob\_replace = exp(V1(age)) / (exp(V0(age)) + exp(V1(age)));
335
336
            % Add log-likelihood contribution
            if replace
337
338
                loglik = loglik + log(prob_replace);
339
            else
340
                loglik = loglik + log(1 - prob_replace);
341
            end
342
        end
343
344
        % Return negative log-likelihood (for minimization)
345
        nll = -loglik;
346
347
        % No analytical gradient provided
348
        grad = [];
349
    end
350
   % Solve for value functions using contraction mapping
351
352
    function [V0, V1] = solveValueFunctions(R, mu, beta, maxAge)
353
        % Initialize value functions
```

```
354
        V = zeros(maxAge, 1);
355
        V_new = zeros(maxAge, 1);
356
357
        % Value function iteration parameters
358
        max_iter = 1000;
359
        tolerance = 1e-8:
360
        % Euler's constant
361
362
        gamma = 0.5772156649;
363
364
        % Contraction mapping (fixed point iteration)
        for iter = 1:max_iter
365
             % For each state (machine age)
366
367
             for a = 1:maxAge
                 % Option 0: Keep the machine
368
369
                 % Deterministic utility from keeping
370
                 u0 = mu * a;
371
372
                 % Next state if keeping
373
                 next_a = min(a + 1, maxAge);
374
375
                 % Value of keeping
376
                 v0 = u0 + beta * V(next_a);
377
378
                 % Option 1: Replace the machine
379
                 % Deterministic utility from replacing
380
                 u1 = R;
381
382
                 % Next state if replacing (always a new machine)
383
                 % Value of replacing
                 v1 = u1 + beta * V(1);
384
385
386
                 % Compute the expected value function (log-sum-exp
                    formula for Type 1 EV)
                 % Include Euler's constant in the calculation
387
388
                 V_{new}(a) = log(exp(v0) + exp(v1)) + gamma;
389
             end
390
391
            % Check for convergence
             if max(abs(V - V_new)) < tolerance</pre>
392
393
                 break;
394
             end
395
396
            % Update value function
397
            V = V_{new};
398
        end
399
```

```
400
        % Compute the choice-specific value functions for return
401
        V0 = zeros(maxAge, 1);
402
        V1 = zeros(maxAge, 1);
403
        for a = 1:maxAge
404
405
             % Option 0: Keep
             u0 = mu * a;
406
             next_a = min(a + 1, maxAge);
407
408
             V0(a) = u0 + beta * V(next_a);
409
410
             % Option 1: Replace
411
             u1 = R;
             V1(a) = u1 + beta * V(1);
412
413
        end
414
    end
415
416
    % Numerical Hessian computation
417
    function H = numHessian(func, x)
418
        % Compute numerical Hessian matrix using finite differences
419
        k = length(x);
420
        H = zeros(k, k);
421
        h = 1e-5; % Step size
422
423
        for i = 1:k
424
             for j = 1:k
425
                 x1 = x;
426
                 x1(i) = x(i) + h;
427
                 x1(j) = x(j) + h;
428
429
                 x2 = x;
                 x2(i) = x(i) + h;
430
431
432
                 x3 = x;
433
                 x3(j) = x(j) + h;
434
435
                 x4 = x;
436
437
                 f1 = func(x1);
438
                 f2 = func(x2);
                 f3 = func(x3):
439
440
                 f4 = func(x4);
441
442
                 H(i,j) = (f1 - f2 - f3 + f4) / (h^2);
443
             end
444
        end
445
    end
446
```

```
447 \%% Functions for #6
448
449 % Implementation of Hotz and Miller (1993) and Hotz et al. (1994)
       approach
    function [estimates, std_errors, loglik] = hotzMillerCCP(data, beta)
450
451
        % Input:
            data - table with columns: period, age, replace
452
            beta - discount factor (fixed in estimation)
453
454
455
        % Output:
456
        % estimates - estimated parameters [R; mu]
457
            std_errors - standard errors of the estimates
458
            loglik - log likelihood at the optimum
459
460
        % Maximum machine age
461
        maxAqe = 5;
462
463
        % (a) Estimate replacement probabilities non-parametrically
464
        % Calculate the empirical replacement probability for each state
           (age)
465
        P_hat = estimateReplacementProbabilities(data, maxAge);
466
467
        % (b.i.) Construct conditional state transition matrices
468
        [F0, F1] = constructTransitionMatrices(maxAge);
469
470
        % Setup optimization for parameter search
        options = optimset('Display', 'iter', 'TolFun', 1e-8, 'TolX', 1e
471
           -8, 'MaxIter', 1000);
472
473
        % Initial parameter values - starting at the true values
474
        theta0 = [-4; -0.5]; % Initial guess for [R; mu]
475
476
        % Define objective function for optimization using a simplified
           approach
477
        objFun = @(theta) simplifiedCCPLogLikelihood(theta, data, beta,
           maxAge, P_hat, F0, F1);
478
479
        % Run the optimization
        [theta_hat, fval, ~, ~, hessian] = fminunc(objFun, theta0,
480
           options);
481
482
        % Extract results
483
        estimates = theta_hat;
484
        loglik = -fval; % Convert back to positive log likelihood
485
486
        % Compute standard errors
487
        std_errors = sqrt(diag(inv(hessian)));
```

```
488
489
        % Display results
        fprintf('CCP Estimation Results:\n');
490
491
        fprintf('R: %.4f (SE: %.4f)\n', estimates(1), std_errors(1));
        fprintf('mu: %.4f (SE: %.4f)\n', estimates(2), std_errors(2));
492
493
        fprintf('Log-likelihood: %.4f\n', loglik);
494
    end
495
496
    % (a) Function to estimate replacement probabilities
497
    function P_hat = estimateReplacementProbabilities(data, maxAge)
498
        % Initialize array for replacement probabilities
499
        P_{\text{hat}} = zeros(maxAge, 1);
500
501
        % Calculate empirical probability of replacement at each age
502
        for a = 1:maxAge
503
            % Get all observations with current age
504
            idx = data.age == a;
505
506
            if sum(idx) > 0
507
                % Calculate empirical replacement probability
                P_hat(a) = mean(data.replace(idx));
508
509
510
                % Add a small epsilon to avoid 0 or 1 probabilities
511
                % which would cause problems in the logit inversion
                epsilon = 1e-6;
512
513
                P_hat(a) = max(min(P_hat(a), 1-epsilon), epsilon);
514
            else
515
                % No observations for this age, use a default or
                   interpolate
516
                warning('No observations found for age %d. Using default
                   value.', a);
517
                P_hat(a) = 0.2; % Default value
518
            end
519
        end
520
521
        fprintf('Estimated replacement probabilities:\n');
522
        for a = 1:maxAge
523
            fprintf('Age %d: %.4f\n', a, P_hat(a));
524
        end
525
    end
526
527
    % (b) Function to construct conditional transition matrices
528
    function [F0, F1] = constructTransitionMatrices(maxAge)
        % F0: Transition matrix if the machine is kept (action = 0)
529
530
        F0 = zeros(maxAge, maxAge);
531
532
        % F1: Transition matrix if the machine is replaced (action = 1)
```

```
533
       F1 = zeros(maxAge, maxAge);
534
535
       % Fill transition matrices according to the deterministic state
          transition
        for i = 1: maxAge
536
537
           % If kept, age increases by 1 up to maxAge
538
            if i < maxAge</pre>
539
                F0(i, i+1) = 1;
540
            else
541
                FO(i, i) = 1; % At max age, stays at max age
542
            end
543
544
           % If replaced, age becomes 1 regardless of current age
545
           F1(i, 1) = 1;
546
       end
547
   end
548
549
   % (c) log-likelihood function
550
    function [nll, grad] = simplifiedCCPLogLikelihood(theta, data, beta,
      maxAge, P_hat, F0, F1)
551
       % Extract parameters
552
       R = theta(1);  % Replacement cost
553
       mu = theta(2);  % Maintenance cost parameter
554
555
       % Compute flow utilities
556
        flow_u0 = zeros(maxAge, 1); % Utility from keeping
557
        flow_u1 = zeros(maxAge, 1); % Utility from replacing
558
559
        for a = 1: maxAge
560
            561
            flow_u1(a) = R;
                                  % Replacement cost is constant
562
        end
563
       % Using finite dependence property for the bus engine replacement
564
           problem
       % The property allows us to simplify the computation of value
565
          function differences
566
       % Initialize value function differences
567
       v_diff = zeros(maxAge, 1);
568
569
570
        for a = 1:maxAge
571
           % Immediate utility difference
572
           v_{diff}(a) = flow_u1(a) - flow_u0(a);
573
574
           % Future value difference using finite dependence
575
           % After replacement, the state is always 1 (new machine)
```

```
576
            % The future value term is zero because of the finite
               dependence property
577
            % The paths from either action converge to the same state
578
        end
579
580
        % Calculate log likelihood
581
        loglik = 0;
582
        for i = 1:height(data)
583
            age = data.age(i);
            action = data.replace(i);
584
585
586
            % Calculate probability of replacement using logit
            prob_replace = 1 / (1 + exp(-v_diff(age)));
587
588
589
            % Ensure numerical stability
590
            prob_replace = max(min(prob_replace, 1-1e-10), 1e-10);
591
            % Add to log likelihood
592
593
            if action
594
                 loglik = loglik + log(prob_replace);
595
            else
596
                 loglik = loglik + log(1 - prob_replace);
597
            end
598
        end
599
600
        % Return negative log likelihood for minimization
        nll = -loglik;
601
        grad = [];
602
603
    end
```