

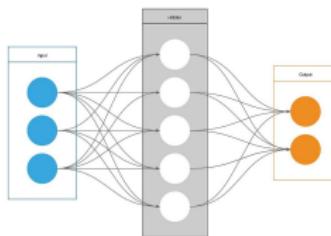
Data Analysis, Neural Networks and the use of Keras

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Organization For
Computational Neurosciences



Workshop en técnicas
de programación científica

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Neural Networks and Keras

What is this talk about?

- What is Machine Learning, Neural Networks, and Deep Learning?
- Neural Networks concepts and topologies.
- A brief review of the use of python ML libraries.

What can we do with data?



We are interested in:

- Data Visualization.
- Data Analysis (Identify features from the data).
- Data Classification.
- Implementation of different algorithms as intelligent as we can get.

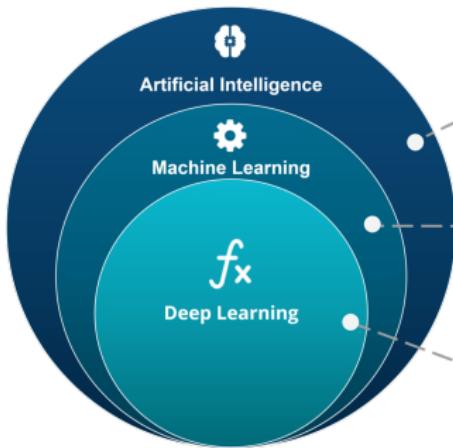
Which are the available algorithms?

Type	Name	Description	Advantages	Disadvantages
Linear	Linear regression	The "best fit" line through all data points. Predictions are numerical.	Easy to understand – you clearly see what the biggest drivers of the model are.	 Sometimes too simple to capture complex relationships between variables.  Tendency for the model to "overfit".
	Logistic regression	The adaptation of linear regression to problems of classification (e.g., yes/no questions, groups, etc.)	Also easy to understand.	 Sometimes too simple to capture complex relationships between variables.  Tendency for the model to "overfit".
Tree-based	Decision tree	A graph that uses a branching method to match all possible outcomes of a decision.	Easy to understand and implement.	 Not often used on its own for prediction because it's also often too simple and not powerful enough for complex data.
	Random Forest	Takes the average of many decision trees, each of which is made with a sample of the data. Each tree is weaker than a full decision tree, but by combining them we get better overall performance.	A sort of "wisdom of the crowd". Tends to result in very high quality models. Fast to train.	 Can be slow to output predictions relative to other algorithms.  Not easy to understand predictions.
	Gradient Boosting	Uses even weaker decision trees, that are increasingly focused on "hard" examples.	High-performing.	 A small change in the feature set or training set can create radical changes in the model.  Not easy to understand predictions.
Neural networks	Neural networks	Mimics the behavior of the brain. Neural networks are interconnected neurons that pass messages to each other. Deep learning uses several layers of neural networks put one after the other.	Can handle extremely complex tasks - no other algorithm comes close in image recognition.	 Very, very slow to train, because they have so many layers. Require a lot of power.  Almost impossible to understand predictions.

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What about machine learning?



ARTIFICIAL INTELLIGENCE

A technique which enables machines to mimic human behaviour

MACHINE LEARNING

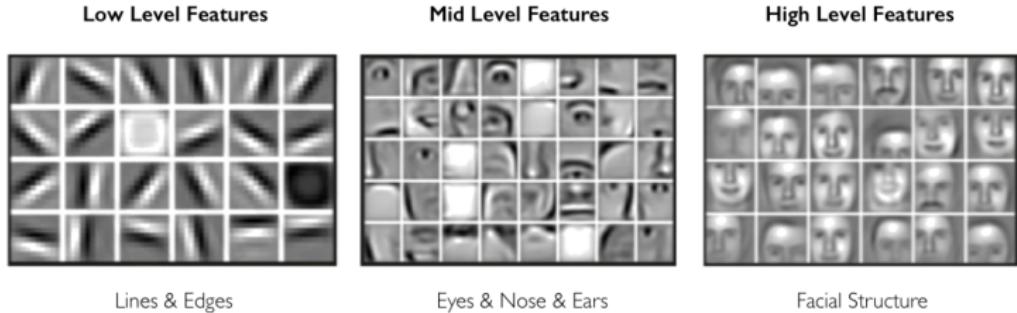
Subset of AI technique which use statistical methods to enable machines to improve with experience

DEEP LEARNING

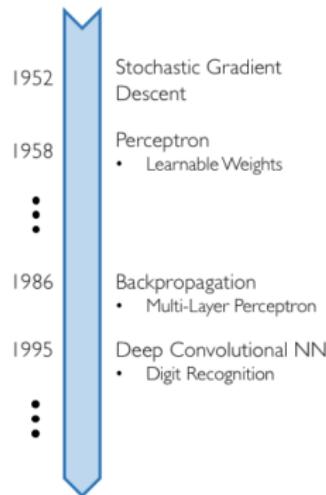
Subset of ML which make the computation of multi-layer neural network feasible

Why Deep Learning?

- Data driven approach.
- Can we learn the underlying features directly from data?



Why Now?



Neural Networks date back decades, so why the resurgence?

1. Big Data

- Larger Datasets
- Easier Collection & Storage



WIKIPEDIA
The Free Encyclopedia

2. Hardware

- Graphics Processing Units (GPUs)
- Massively Parallelizable



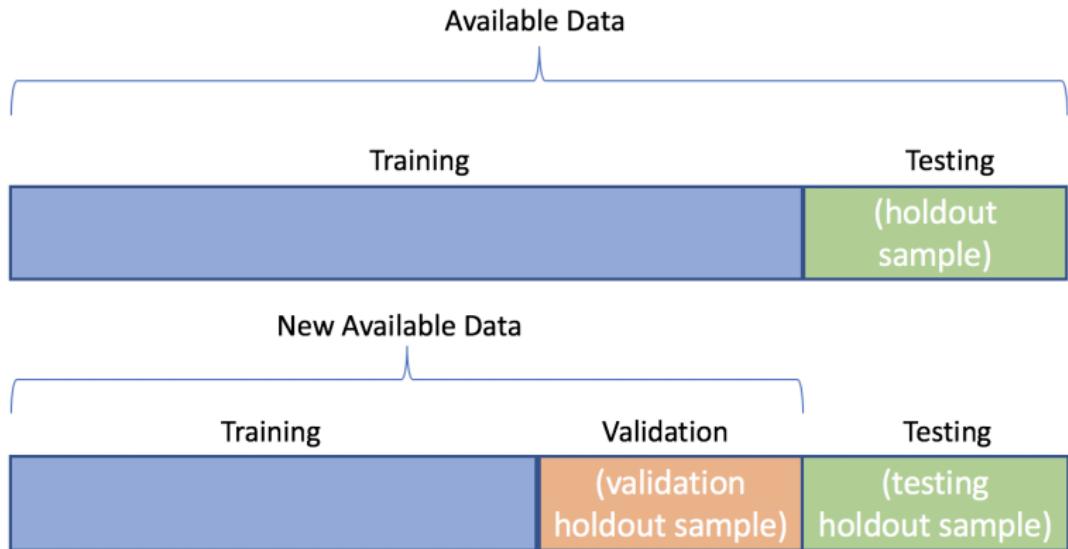
3. Software

- Improved Techniques
- New Models
- Toolboxes



TensorFlow

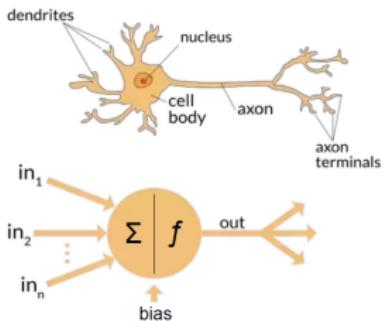
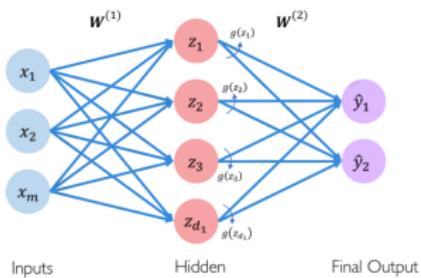
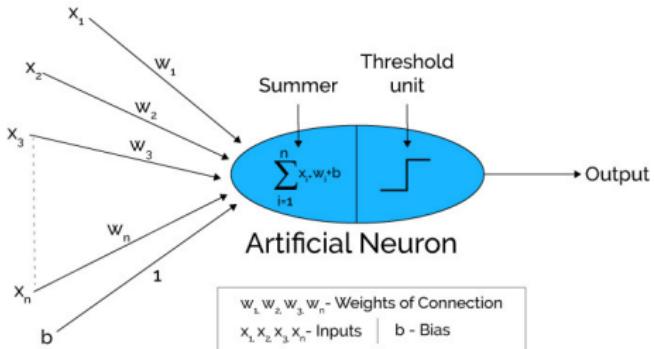
How we split our data to train a model?



How we use (split) our data to train a model?

- **Training set:** The data where the model is trained on. We train our model, by pairing the input with the expected output.
- **Validation set:** Data the model has not been trained on and is used to tune hyperparameters. Here we estimate how well your model has been trained.
- **Test set:** Same like the validation set.. just used at the final end. This is an Application phase: we apply our developed model to the real-world data and get the results. This fase is split into two parts:
 - First you look at your models and select the best performing approach using the validation data (=validation).
 - Then you estimate the accuracy of the selected approach (=test).

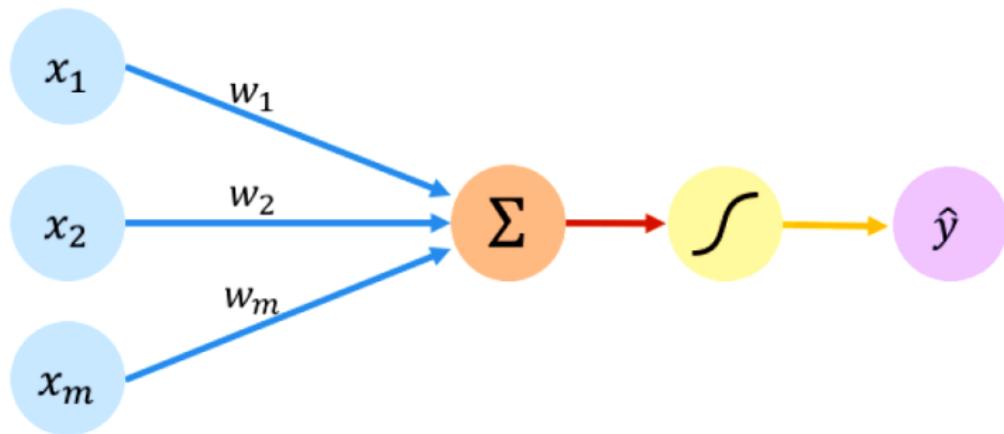
Neural Networks:



The Perceptron: Forward Propagation

The structural building block of Deep Learning

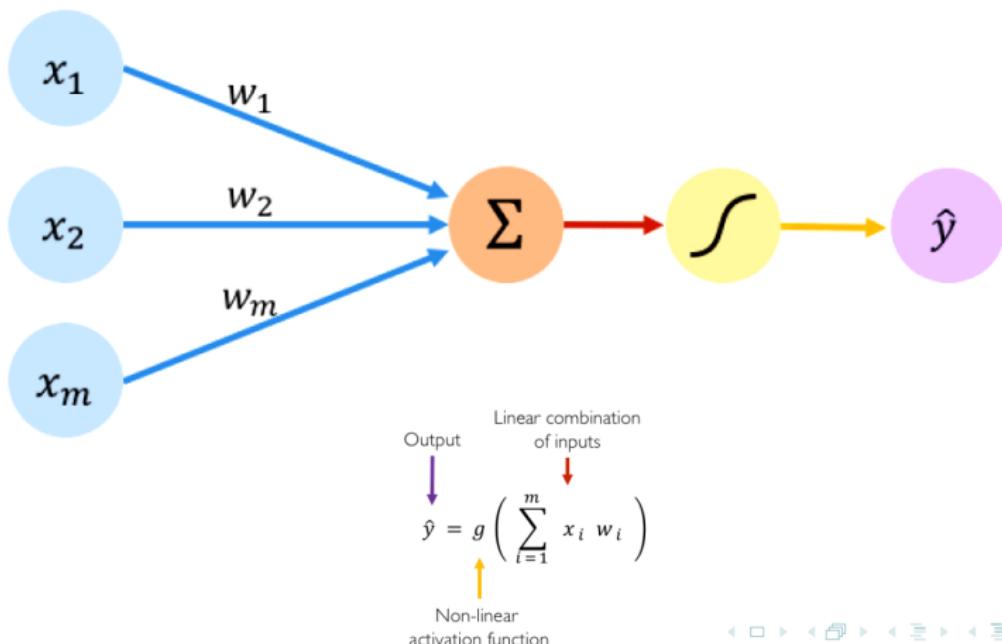
Input → Weights → Sum → Non linearity → Output



The Perceptron: Forward Propagation

The structural building block of Deep Learning:

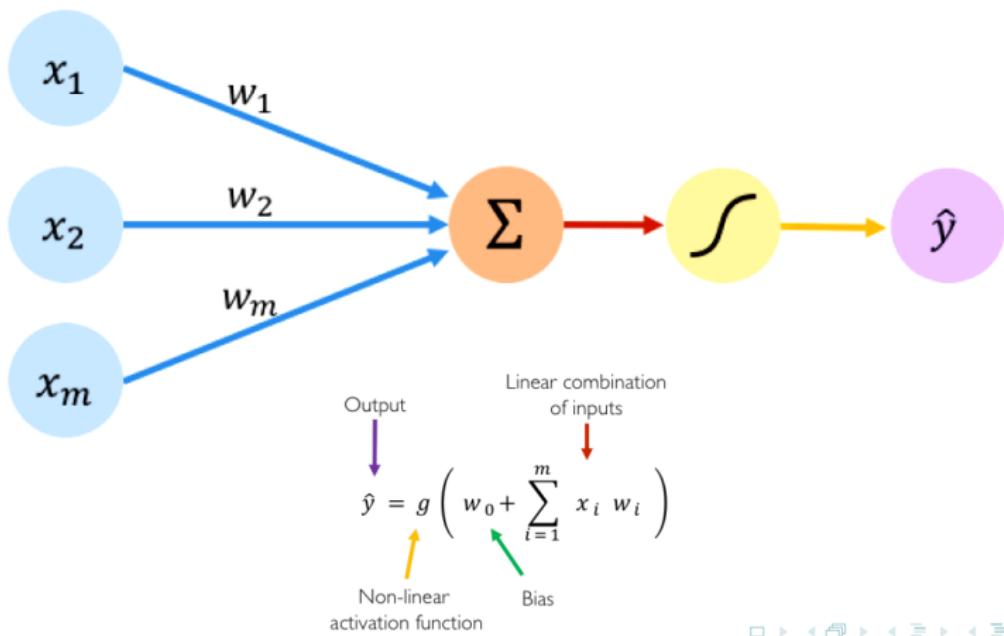
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The Perceptron: Forward Propagation

The structural building block of Deep Learning:

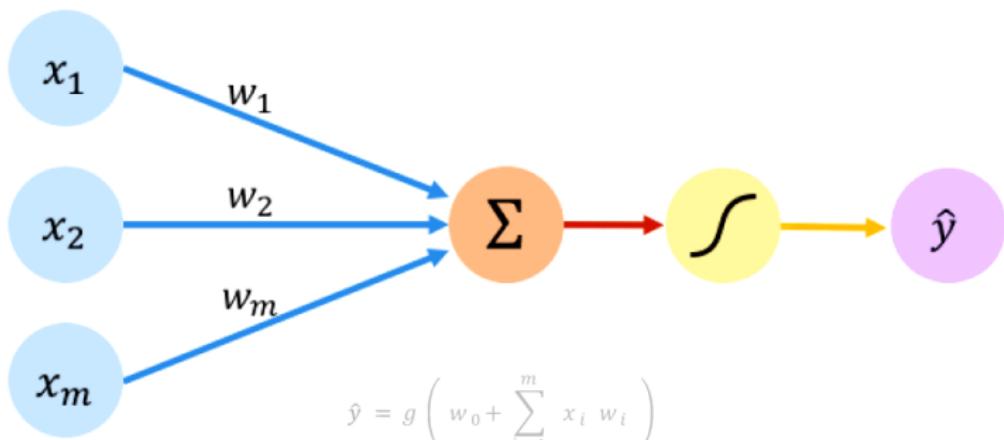
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The Perceptron: Forward Propagation

The structural building block of Deep Learning:

Input → Weights → Sum → Non linearity → Output

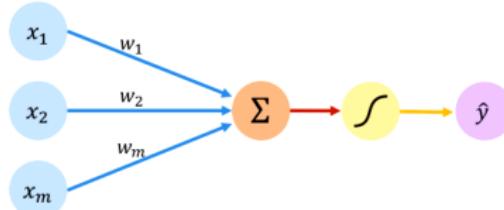


$$\hat{y} = g \left(w_0 + \sum_{i=1}^m x_i w_i \right)$$

$$\hat{y} = g(w_0 + \mathbf{X}^T \mathbf{W})$$

where: $\mathbf{X} = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix}$ and $\mathbf{W} = \begin{bmatrix} w_1 \\ \vdots \\ w_m \end{bmatrix}$

The Perceptron: Forward Propagation

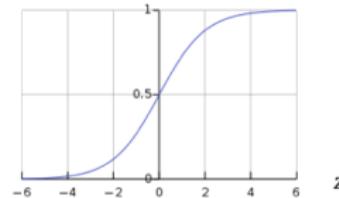


Activation Functions

$$\hat{y} = g(w_0 + X^T W)$$

- Example: sigmoid function

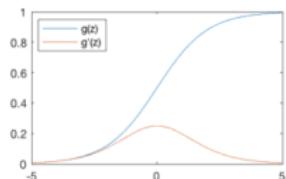
$$g(z) = \sigma(z) = \frac{1}{1 + e^{-z}}$$



Neural Networks: Activation Functions

The purpose of Activation functions is to introduce non linearities into the network

Sigmoid Function

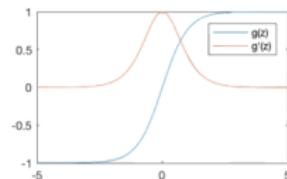


$$g(z) = \frac{1}{1 + e^{-z}}$$

$$g'(z) = g(z)(1 - g(z))$$

`tf.math.sigmoid(z)`

Hyperbolic Tangent



$$g(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

$$g'(z) = 1 - g(z)^2$$

`tf.math.tanh(z)`

Rectified Linear Unit (ReLU)



$$g(z) = \max(0, z)$$

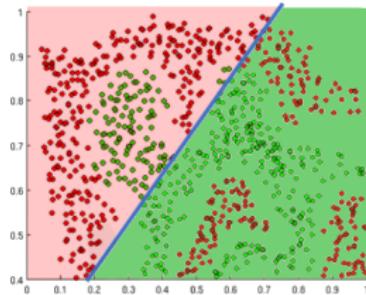
$$g'(z) = \begin{cases} 1, & z > 0 \\ 0, & \text{otherwise} \end{cases}$$

`tf.nn.relu(z)`

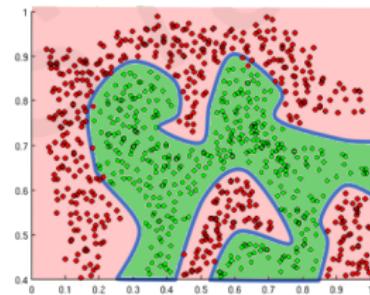
Neural Networks: Activation Functions

Name	Plot	Equation	Derivative
Identity		$f(x) = x$	$f'(x) = 1$
Binary step		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x \neq 0 \\ ? & \text{for } x = 0 \end{cases}$
Logistic (a.k.a Soft step)		$f(x) = \frac{1}{1 + e^{-x}}$	$f'(x) = f(x)(1 - f(x))$
Tanh		$f(x) = \tanh(x) = \frac{2}{1 + e^{-2x}} - 1$	$f'(x) = 1 - f(x)^2$
Arctan		$f(x) = \tan^{-1}(x)$	$f'(x) = \frac{1}{x^2 + 1}$
Rectified Linear Unit (ReLU) ^[2]		$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$
Parametric Rectified Linear Unit (PReLU) ^[2]		$f(x) = \begin{cases} \alpha x & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} \alpha & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$
Exponential Linear Unit (ELU) ^[3]		$f(x) = \begin{cases} \alpha(e^x - 1) & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} f(x) + \alpha & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$
SoftPlus		$f(x) = \log_e(1 + e^x)$	$f'(x) = \frac{1}{1 + e^{-x}}$

Neural Networks: Non linear decision



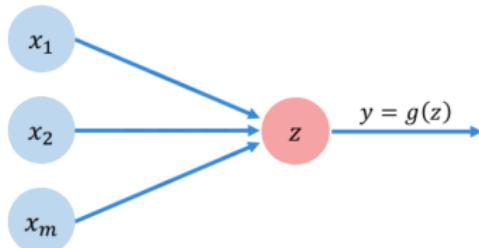
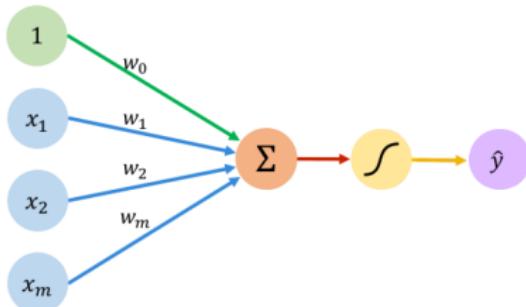
Linear activation functions produce linear decisions no matter the network size



Non-linearities allow us to approximate arbitrarily complex functions

Building Neural Networks with Perceptrons

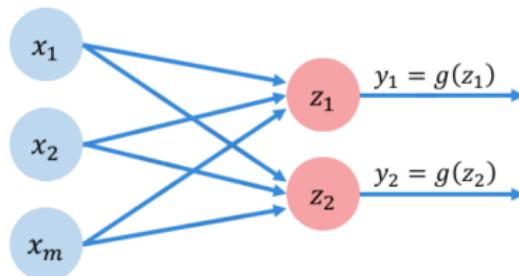
A simplified perceptron:



$$z = w_0 + \sum_{j=1}^m x_j w_j$$

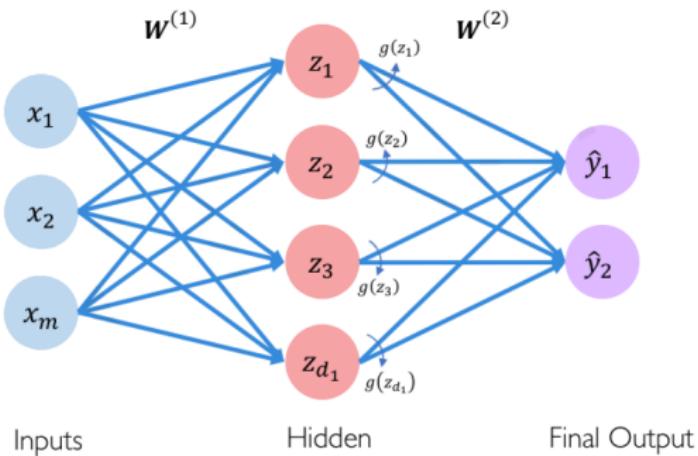
Building Neural Networks: Multi Outputs

Because all inputs are connected to all outputs these are called Dense layers:



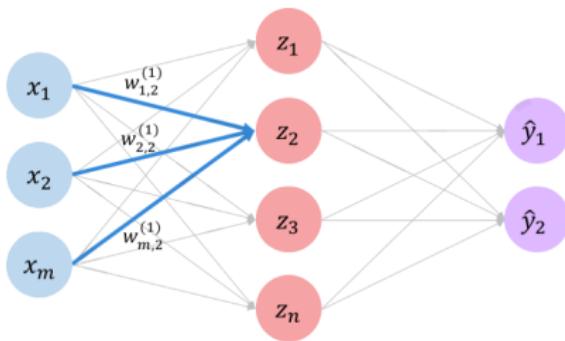
$$z_{\textcolor{blue}{i}} = w_{0,\textcolor{blue}{i}} + \sum_{j=1}^m x_j w_{j,i}$$

Single Layer Neural Network



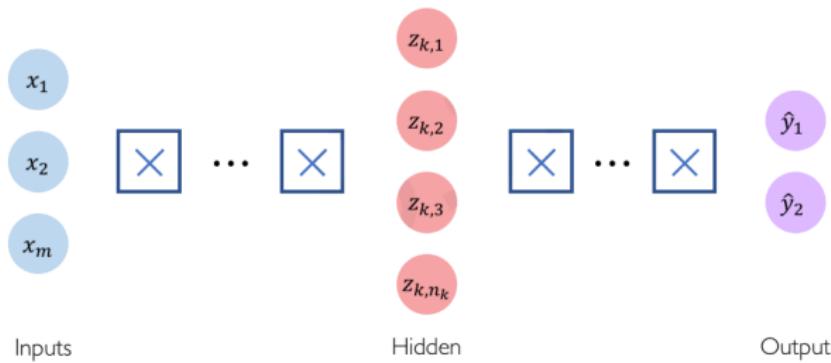
$$z_i = w_{0,i}^{(1)} + \sum_{j=1}^m x_j w_{j,i}^{(1)} \quad \hat{y}_i = g \left(w_{0,i}^{(2)} + \sum_{j=1}^{d_1} g(z_j) w_{j,i}^{(2)} \right)$$

Single Layer Neural Network



$$\begin{aligned} z_2 &= w_{0,2}^{(1)} + \sum_{j=1}^m x_j w_{j,2}^{(1)} \\ &= w_{0,2}^{(1)} + x_1 w_{1,2}^{(1)} + x_2 w_{2,2}^{(1)} + x_m w_{m,2}^{(1)} \end{aligned}$$

A deep neural network structure



$$z_{k,i} = w_{0,i}^{(k)} + \sum_{j=1}^{n_{k-1}} g(z_{k-1,j}) w_{j,i}^{(k)}$$

Neural Networks: Loss Function

(... or Cost Function or Objective Function)

Depends on the kind of problem.

- Regression → Mean square error
- Classification → Cross entropy, binary cross entropy.

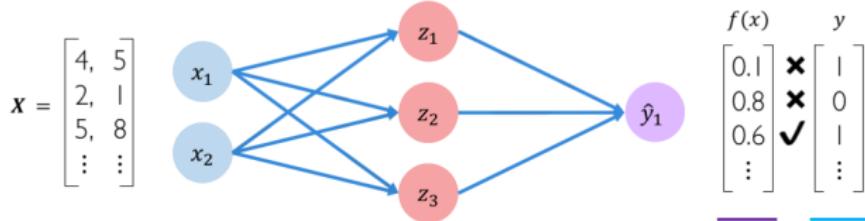
Neural Networks: Loss Functions

symbol	name	equation
\mathcal{L}_1	L ₁ loss	$\ \mathbf{y} - \mathbf{o}\ _1$
\mathcal{L}_2	L ₂ loss	$\ \mathbf{y} - \mathbf{o}\ _2^2$
$\mathcal{L}_1 \circ \sigma$	expectation loss	$\ \mathbf{y} - \sigma(\mathbf{o})\ _1$
$\mathcal{L}_2 \circ \sigma$	regularised expectation loss ^[1]	$\ \mathbf{y} - \sigma(\mathbf{o})\ _2^2$
$\mathcal{L}_\infty \circ \sigma$	Chebyshev loss	$\max_j \sigma(\mathbf{o})^{(j)} - \mathbf{y}^{(j)} $
hinge	hinge [13] (margin) loss	$\sum_j \max(0, \frac{1}{2} - \hat{\mathbf{y}}^{(j)} \mathbf{o}^{(j)})$
hinge ²	squared hinge (margin) loss	$\sum_j \max(0, \frac{1}{2} - \hat{\mathbf{y}}^{(j)} \mathbf{o}^{(j)})^2$
hinge ³	cubed hinge (margin) loss	$\sum_j \max(0, \frac{1}{2} - \hat{\mathbf{y}}^{(j)} \mathbf{o}^{(j)})^3$
log	log (cross entropy) loss	$-\sum_j \mathbf{y}^{(j)} \log \sigma(\mathbf{o})^{(j)}$
log ²	squared log loss	$-\sum_j [\mathbf{y}^{(j)} \log \sigma(\mathbf{o})^{(j)}]^2$
tan	Tanimoto loss	$\frac{-\sum_j \sigma(\mathbf{o})^{(j)} \mathbf{y}^{(j)}}{\ \sigma(\mathbf{o})\ _2^2 + \ \mathbf{y}\ _2^2 - \sum_j \sigma(\mathbf{o})^{(j)} \mathbf{y}^{(j)}}$
D _{CS}	Cauchy-Schwarz Divergence [3]	$-\log \frac{\sum_j \sigma(\mathbf{o})^{(j)} \mathbf{y}^{(j)}}{\ \sigma(\mathbf{o})\ _2 \ \mathbf{y}\ _2}$

See: <https://arxiv.org/pdf/1702.05659.pdf>

Neural Networks: Crossentropy

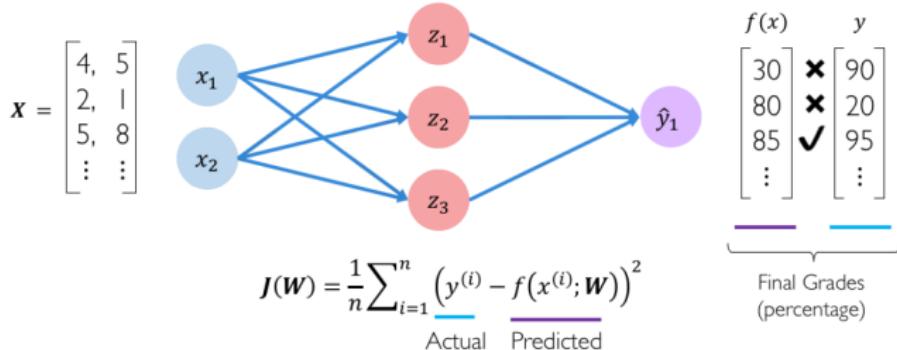
Cross entropy loss can be used with models that output a probability between 0 and 1



$$J(\mathbf{W}) = \frac{1}{n} \sum_{i=1}^n \underbrace{y^{(i)}}_{\text{Actual}} \log \left(f(x^{(i)}; \mathbf{W}) \right) + \underbrace{(1 - y^{(i)})}_{\text{Predicted}} \log \left(1 - f(x^{(i)}; \mathbf{W}) \right)$$

Neural Networks: Mean square error

Mean squared error loss can be used with regression models that output continuous real numbers



Training Neural Networks: Loss Optimization

We want to find the network weights that achieve the lowest loss

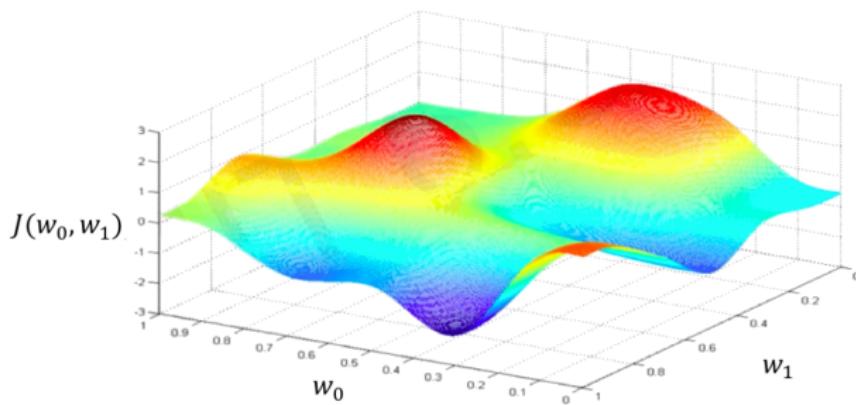
$$\mathbf{W}^* = \operatorname{argmin}_{\mathbf{W}} \frac{1}{n} \sum_{i=1}^n \mathcal{L}(f(x^{(i)}; \mathbf{W}), y^{(i)})$$

$$\mathbf{W}^* = \operatorname{argmin}_{\mathbf{W}} J(\mathbf{W})$$

Training Neural Networks: Loss Optimization

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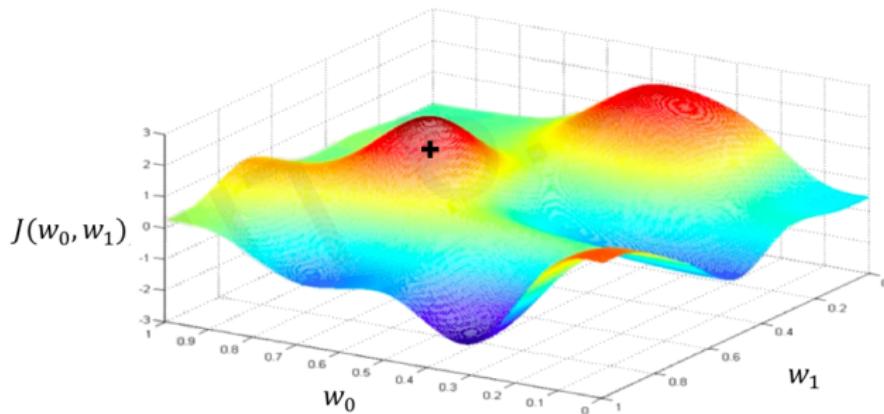
$$\mathbf{W}^* = \underset{\mathbf{W}}{\operatorname{argmin}} J(\mathbf{W})$$



Training Neural Networks: Loss Optimization

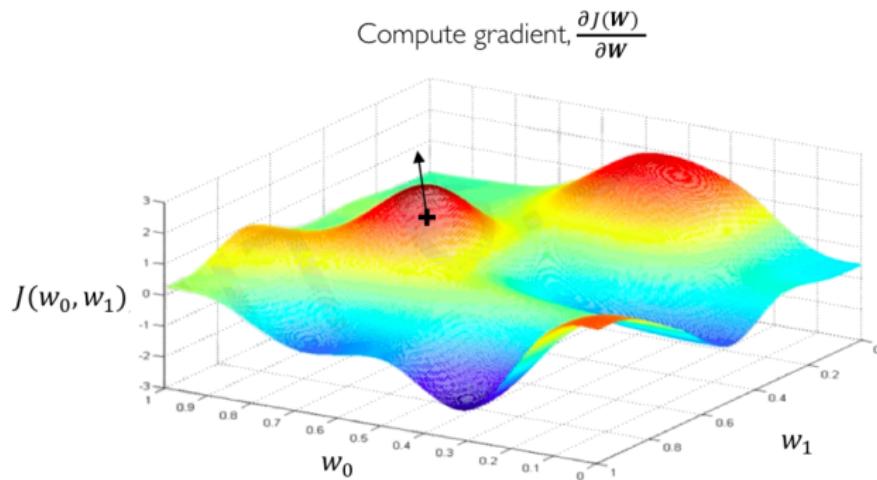
We want to find the network weights that achieve the lowest loss

Randomly pick an initial (w_0, w_1)



Training Neural Networks: Loss Optimization

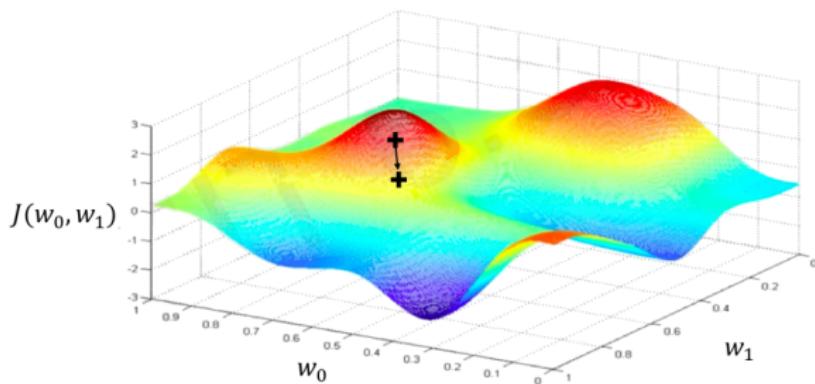
We want to find the network weights that achieve the lowest loss



Training Neural Networks: Loss Optimization

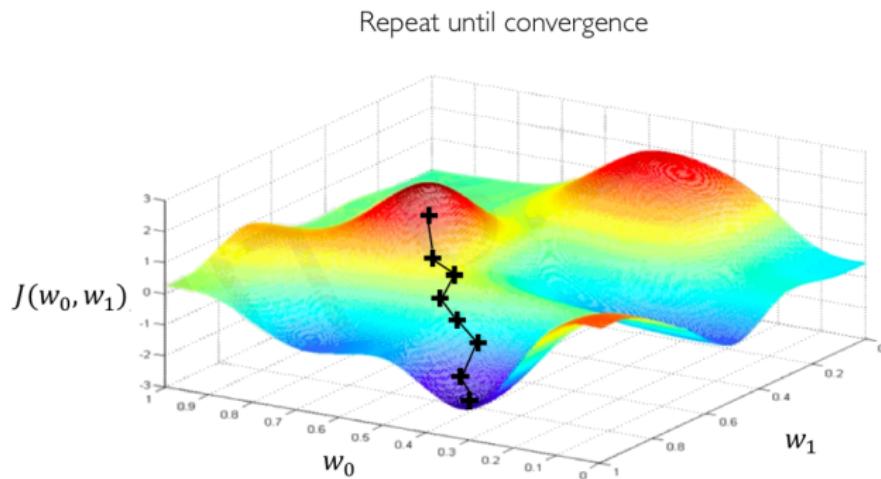
We want to find the network weights that achieve the lowest loss

Take small step in opposite direction of gradient



Training Neural Networks: Loss Optimization

We want to find the network weights that achieve the lowest loss



Algorithm

1. Initialize weights randomly $\sim \mathcal{N}(0, \sigma^2)$
2. Loop until convergence:
3. Compute gradient, $\frac{\partial J(\mathbf{W})}{\partial \mathbf{w}}$
4. Update weights, $\mathbf{W} \leftarrow \mathbf{W} - \eta \frac{\partial J(\mathbf{W})}{\partial \mathbf{w}}$
5. Return weights

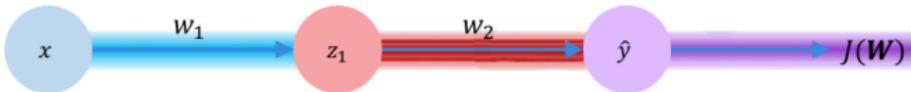
Training Neural Networks: Back propagation

How a small change in one weight affect the loss



Training Neural Networks:

We apply chain rule



$$\frac{\partial J(\mathbf{W})}{\partial w_1} = \underbrace{\frac{\partial J(\mathbf{W})}{\partial \hat{y}}}_{\text{purple}} * \underbrace{\frac{\partial \hat{y}}{\partial z_1}}_{\text{red}} * \underbrace{\frac{\partial z_1}{\partial w_1}}_{\text{blue}}$$

Repeat this for **every weight in the network** using gradients from later layers

Training Neural Networks: Update gradient

Optimization through gradient descent

$$\mathbf{W} \leftarrow \mathbf{W} - \eta \frac{\partial J(\mathbf{W})}{\partial \mathbf{W}}$$

Training Neural Networks: Update gradient

Optimization through gradient descent

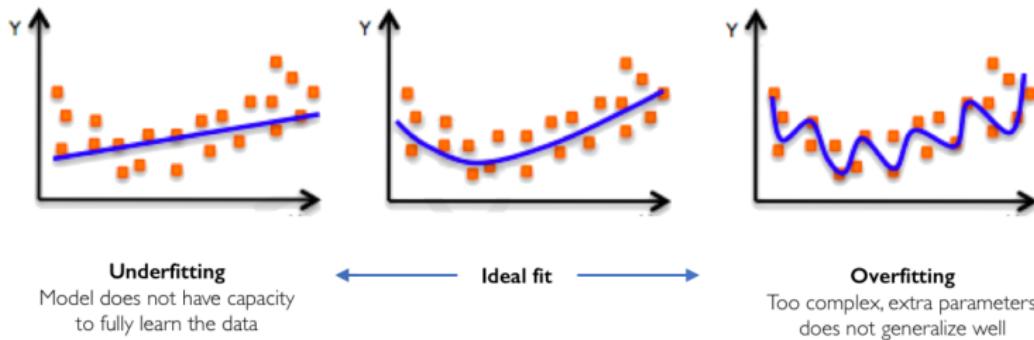
$$\mathbf{W} \leftarrow \mathbf{W} - \eta \frac{\partial J(\mathbf{W})}{\partial \mathbf{W}}$$

How can we set the
learning rate?

Gradient Descent Algorithms

Algorithm	TF Implementation	Reference
• SGD	 <code>tf.keras.optimizers.SGD</code>	Kiefer & Wolfowitz: "Stochastic Estimation of the Maximum of a Regression Function." 1952.
• Adam	 <code>tf.keras.optimizers.Adam</code>	Kingma et al. "Adam: A Method for Stochastic Optimization." 2014.
• Adadelta	 <code>tf.keras.optimizers.Adadelta</code>	Zeiler et al. "ADADELTA: An Adaptive Learning Rate Method." 2012.
• Adagrad	 <code>tf.keras.optimizers.Adagrad</code>	Duchi et al. "Adaptive Subgradient Methods for Online Learning and Stochastic Optimization." 2011.
• RMSProp	 <code>tf.keras.optimizers.RMSProp</code>	

The problem of Overfitting

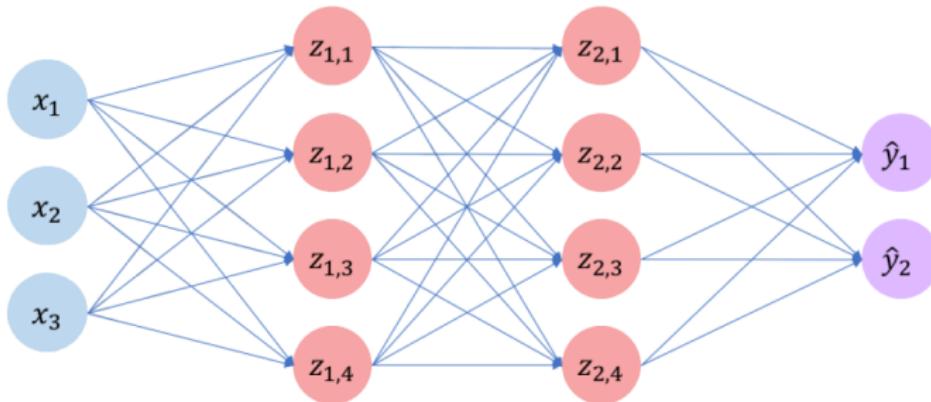


Regularization

- A technique that constraint the optimization problem to avoid complex models.
- We use it to improve the generalization on our model to unseen data.
- There are different kind of methods.

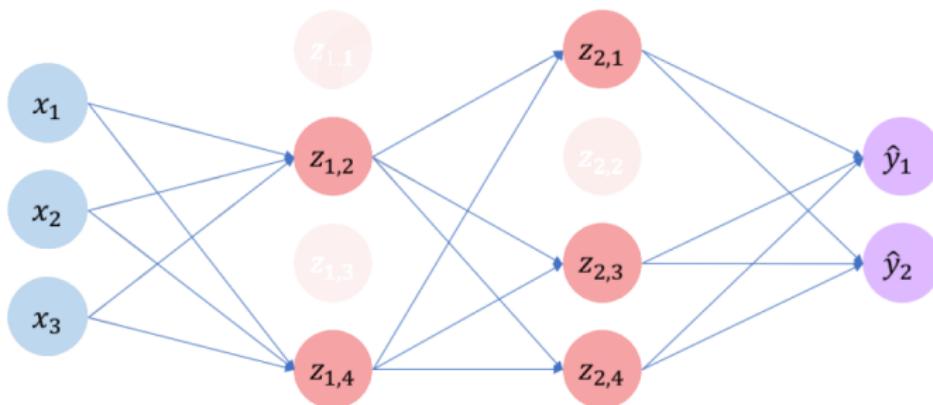
Regularization I: Dropout

During training randomly set some activations to 0.



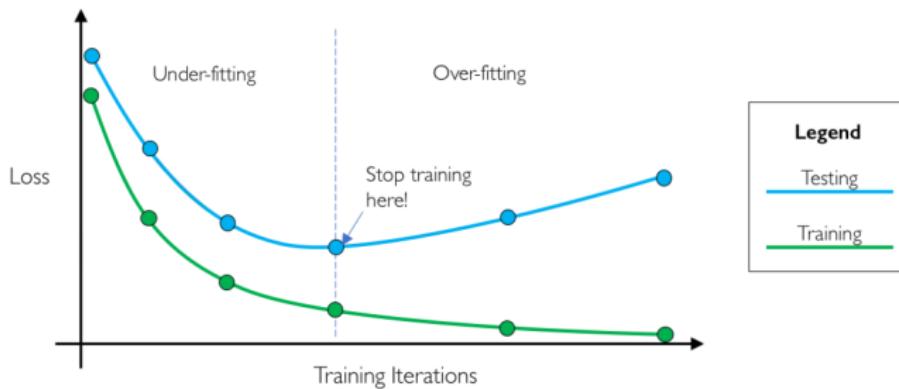
Regularization I: Dropout

During training randomly set some activations to 0.



Regularization II: early stopping

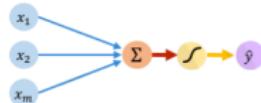
To stop before having the opportunity to overfit by monitoring testing and training data.



Summary

The Perceptron

- Structural building blocks
- Nonlinear activation functions



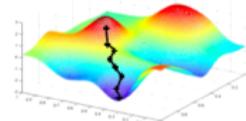
Neural Networks

- Stacking Perceptrons to form neural networks
- Optimization through backpropagation



Training in Practice

- Adaptive learning
- Batching
- Regularization



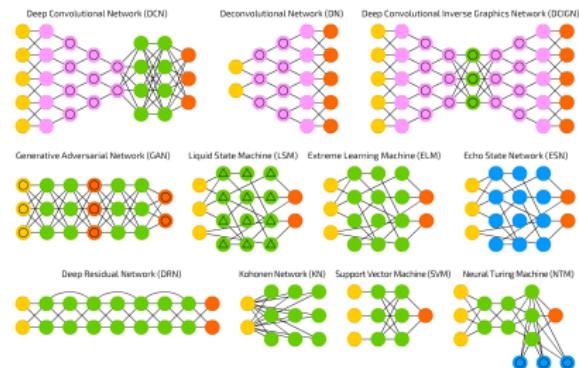
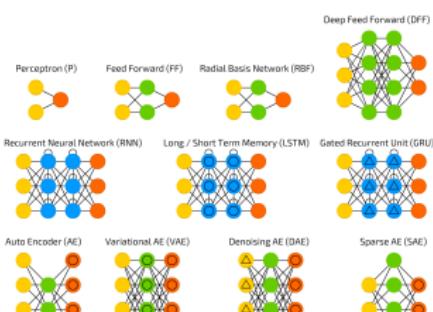
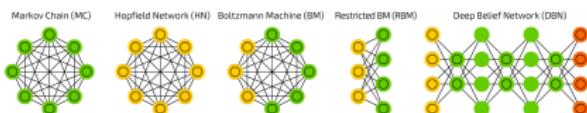
Neural Networks: The Zoo of topologies



Neural Networks: The Zoo of topologies

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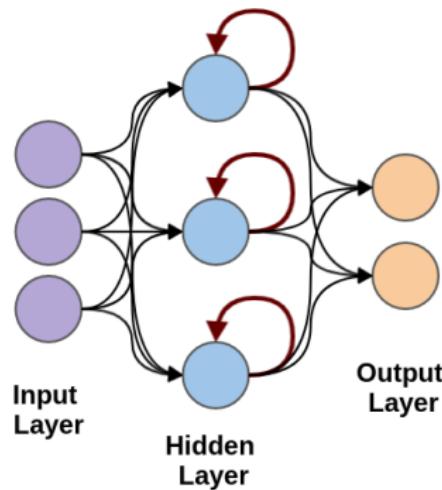
- Backed Input Cell
- Input Cell
- Noisy Input Cell
- Hidden Cell
- Probabilistic Hidden Cell
- Spiking Hidden Cell
- Output Cell
- Match Input Output Cell
- Recurrent Cell
- Memory Cell
- Different Memory Cell
- Kernel
- Convolution or Pool



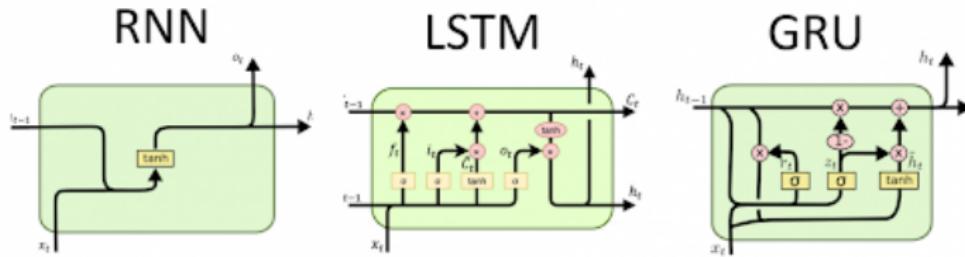
Topologies

- Feed Foward networks (already seen).
- Recurrent neural networks — simple, LSTM, and GRU.
- Convolutional neural networks

Topologies: Recurrent neural networks



Topologies: Recurrent neural networks



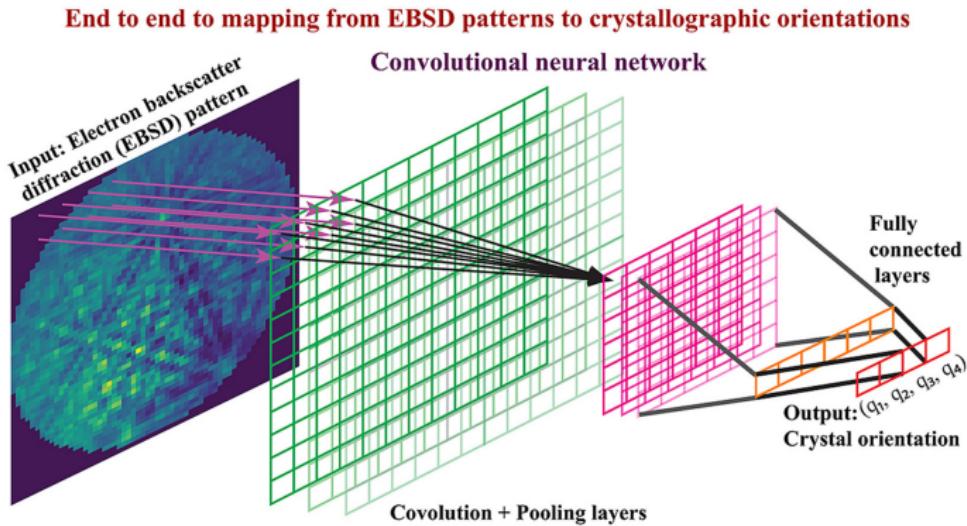
RNN — simple, LSTM, and GRU

- Recurrent neural networks are a class of neural networks that exploit the sequential nature of their input.
- Inputs could be: a text, a speech, time series, and anything else where the occurrence of an element in the sequence is dependent on the elements that appeared before it.

Convolutional and pooling layers

- ConvNets are a class of neural networks using convolutional and pooling operations for progressively learning rather sophisticated models based on progressive levels of abstraction.
- This learning via progressive abstraction resembles vision models that have evolved over millions of years inside the human brain.
- People called it deep with 3-5 layers a few years ago, and now it has gone up to 100-200.

Convolutional Neural Networks.



About environment and installation



Where can we work?

- Locally in Virtual env:

Main purpose of Python virtual env is to create an isolated environment for Python projects. Each project can have its own dependencies, regardless of what dependencies every other project has.

<https://realpython.com/python-virtual-environments-a-primer/>

- Google Cloud ML.

<https://cloud.google.com/ai-platform/docs/getting-started-keras>

- other Services

About installation Local: What is Anaconda for?

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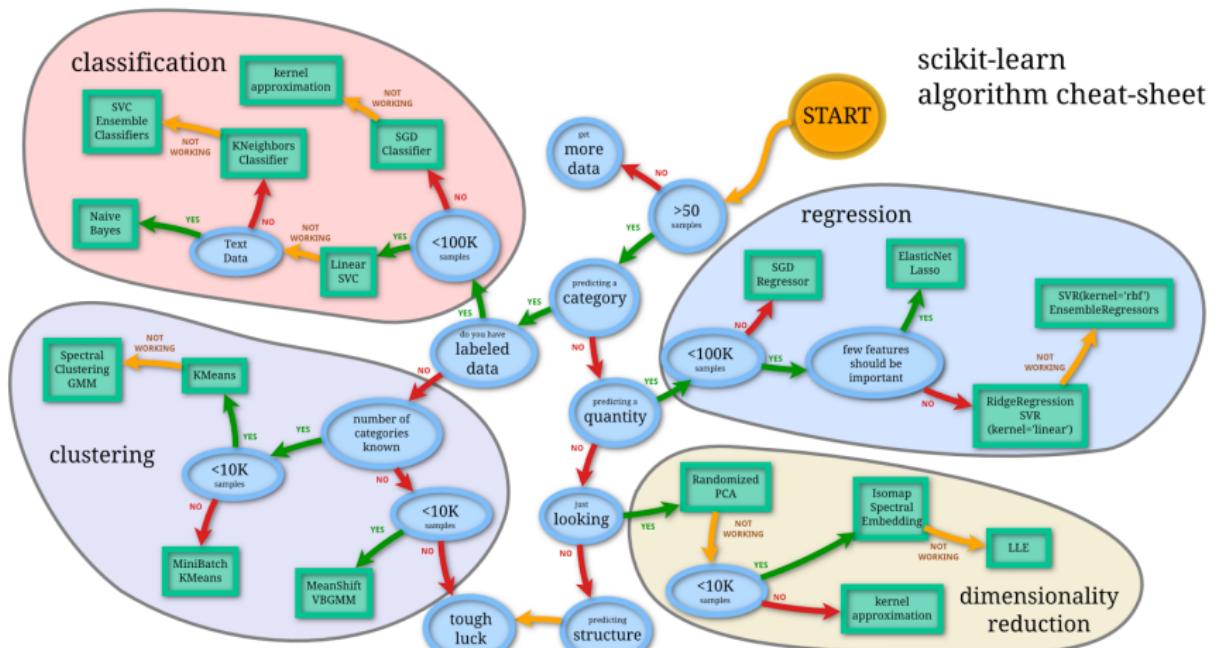
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We can use Scikit learn also...



How do we implement this algorithms?

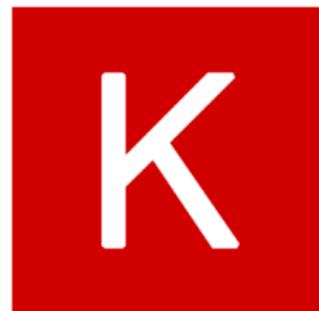
- From zero with math libraries and python.
- Using dedicated open source frameworks:
 - Tensorflow.
 - Keras.

Tensorflow:



TensorFlow

Tensorflow is an end-to-end open source platform for machine learning. It has a comprehensive, flexible ecosystem of tools, libraries and community resources that lets researchers push the state-of-the-art in ML and developers easily build and deploy ML powered applications.



Keras

Keras: A high-level neural networks API, written in Python and capable of running on top of TensorFlow, CNTK, or Theano. It was developed with a focus on enabling fast experimentation. Being able to go from idea to result with the least possible delay is key to doing good research.

Keras is now embedded in Tensorflow



<https://www.tensorflow.org/guide/keras/functional>

Keras Basics:

- **Modularity**: A model is either a sequence or a graph of standalone modules that can be combined together like LEGO blocks for building neural networks
- **The libraries** predefines a large number of modules implementing different types of neural layers, cost functions, optimizers, initialization schemes, activation functions, and regularization schemes.
- **Minimalism**: The library is implemented in Python and each module is kept short and self-describing.
- **Easy extensibility**: The library can be extended with new functionalities.

Keras Basics:

Python For Data Science Cheat Sheet

Keras

Learn Python for data science interactively at www.DataCamp.com



Keras

Keras is a powerful and easy-to-use deep learning library for Theano and TensorFlow that provides a high-level neural networks API to develop and evaluate deep learning models.

A Basic Example

```
>>> import numpy as np
>>> from keras.models import Sequential
>>> from keras.layers import Dense
>>> data = np.random.randint(10000, 1000)
>>> labels = np.random.randint(2, size=(10000, 1))
>>> model = Sequential()
>>> model.add(Dense(32,
    activation='relu',
    input_dim=100))
>>> model.add(Dense(1, activation='sigmoid'))
>>> model.compile(optimizer='rmsprop',
    loss='binary_crossentropy',
    metrics=['accuracy'])
>>> model.fit(data, labels, epochs=10, batch_size=32)
>>> predictions = model.predict(data)
```

Data

Also see NumPy, Pandas & Scikit-Learn

Your data needs to be stored as NumPy arrays or as a list of NumPy arrays. Ideally, add the data in training and test sets, for which you can also resort to the `train_test_split` module of `sklearn.cross_validation`.

Keras Data Sets

```
>>> from keras.datasets import boston_housing,
    mnist,
    cifar10,
    lmbd
>>> (x_train,y_train), (x_test,y_test) = mnist.load_data()
>>> (x_train,y_train), (x_test,y_test) = boston_housing.load_data()
>>> (x_train,y_train), (x_test,y_test) = cifar10.load_data()
>>> (x_train,y_train), (x_test,y_test) = lmbd.load_data(num_words=20000)
>>> num_classes = 10
```

Other

```
>>> from urllib.request import urlopen
>>> data = np.loadtxt(urlopen("http://archive.ics.uci.edu/ml/machine-learning-databases/pima-indians-diabetes/pima-indians-diabetes.data"), delimiter=",")
>>> x = data[:,0:-1]
>>> y = data[:, -1]
```

Preprocessing

Sequence Padding

```
>>> from keras.preprocessing import sequence
>>> x_train4 = sequence.pad_sequences(x_train, maxlen=80)
>>> x_test4 = sequence.pad_sequences(x_test, maxlen=80)
```

One-Hot Encoding

```
>>> from keras.utils import to_categorical
>>> Y_train = to_categorical(y_train, num_classes)
>>> Y_test = to_categorical(y_test, num_classes)
>>> Y_train3 = to_categorical(x_train3, num_classes)
>>> Y_test3 = to_categorical(x_test3, num_classes)
```

Model Architecture

Sequential Model

```
>>> from keras.models import Sequential
>>> model1 = Sequential()
>>> model2 = Sequential()
>>> model3 = Sequential()
```

Multi-layer Perceptron (MLP)

Binary Classification

```
>>> from keras.layers import Dense
>>> model.add(Dense(32,
    input_dim=8,
    kernel_initializer='uniform',
    activation='relu'))
>>> model.add(Dense(1, kernel_initializer='uniform',activation='sigmoid'))
```

Multi-Class Classification

```
>>> from keras.layers import Dropout
>>> model.add(Dense(32,activation='relu',input_shape=(784,)))
>>> model.add(Dense(16,activation='relu'))
>>> model.add(Dense(8,activation='relu'))
>>> model.add(Dropout(0.2))
>>> model.add(Dense(10,activation='softmax'))
```

Regression

```
>>> model.add(Dense(64,activation='relu',input_dim=x_train.shape[1]))
>>> model.add(Dense(1))
```

Convolutional Neural Network (CNN)

```
>>> from keras.layers import Activation,Conv2D,MaxPooling2D,Flatten
>>> model2.add(Conv2D(32,(3,3),padding='same',input_shape=x_train.shape[1:]))
>>> model2.add(Activation('relu'))
>>> model2.add(MaxPooling2D(pool_size=(2,2)))
>>> model2.add(Activation('relu'))
>>> model2.add(Conv2D(64,(3,3),padding='same'))
>>> model2.add(Activation('relu'))
>>> model2.add(Conv2D(64,(3,3)))
>>> model2.add(Activation('relu'))
>>> model2.add(MaxPooling2D(pool_size=(2,2)))
>>> model2.add(Activation('relu'))
>>> model2.add(Flatten())
>>> model2.add(Dense(512))
>>> model2.add(Activation('relu'))
>>> model2.add(Dropout(0.5))
>>> model2.add(Dense(num_classes))
>>> model2.add(Activation('softmax'))
```

Recurrent Neural Network (RNN)

```
>>> from keras.layers import Embedding,LSTM
>>> model3.add(Embedding(10000,128))
>>> model3.add(LSTM(128,dropout=0.2,recurrent_dropout=0.2))
>>> model3.add(Dense(1,activation='sigmoid'))
```

Train and Test Sets

```
>>> from sklearn.model_selection import train_test_split
>>> X_train,X_test,y_train,y_test = train_test_split(x,
    y,
    test_size=0.33,
    random_state=42)
```

Also see NumPy & Scikit-Learn

Standardization/Normalization

```
>>> from sklearn.preprocessing import StandardScaler
>>> scaler = StandardScaler().fit(x_train2)
>>> standardized_x_train = scaler.transform(x_train2)
>>> standardized_x_test = scaler.transform(x_test2)
```

Inspect Model

```
>>> model.output_shape
>>> model.summary()
>>> model.get_config()
>>> model.get_weights()
```

Model output shape
Model summary representation
Model configuration
List all weight tensors in the model

Compile Model

```
>>> model1.compile(optimizer='adam',
    loss='binary_crossentropy',
    metrics=['accuracy'])
MLP: Multi-Class Classification
>>> model2.compile(optimizer='rmsprop',
    loss='categorical_crossentropy',
    metrics=['accuracy'])
MLP: Regression
>>> model3.compile(optimizer='rmsprop',
    loss='mse',
    metrics=['mse'])
```

Recurrent Neural Network

```
>>> model3.fit(x_train,
    y_train,
    batch_size=32,
    epochs=15,
    validation_data=(x_test,y_test))
```

Model Training

Evaluate Your Model's Performance

```
>>> score = model3.evaluate(x_test,
    y_test,
    batch_size=32)
```

Prediction

```
>>> model3.predict(x_test4, batch_size=32)
>>> model3.predict_classes(x_test4,batch_size=32)
```

Save/Reload Models

```
>>> from keras.models import load_model
>>> model3.save('model_file.h5')
>>> my_model = load_model('my_model.h5')
```

Model Fine-tuning

Optimization Parameters

```
>>> from keras.optimizers import RMSProp
>>> opt = RMSProp()
>>> model2.compile(loss='categorical_crossentropy',
    optimizer=opt,
    metrics=['accuracy'])
```

Early Stopping

```
>>> from keras.callbacks import EarlyStopping
>>> early_stopping_monitor = EarlyStopping(patience=2)
>>> model3.fit(x_train4,
    y_train,
    batch_size=32,
    epochs=15,
    validation_data=(x_test4,y_test4),
    callbacks=[early_stopping_monitor])
```

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Keras Basics: code example

You can create a Sequential model by passing a list of layer instances to the constructor:

```
1
2 from keras.models import Sequential
3 from keras.layers import Dense,
4     Activation
5
6 model = Sequential([
7     Dense(32, input_shape=(784,)),
8     Activation('relu'),
9     Dense(10),
10    Activation('softmax'),
11])
```

You can also simply add layers via the `.add()` method:

```
1 model = Sequential()
2 model.add(Dense(32, input_dim=784))
3 model.add(Activation('relu'))
```

More:

https://github.com/katejarne/Keras_tensorflow_course

Classes and material will be at:

<http://ceciliajarne.web.unq.edu.ar/cns-2020-tutorial/>

References:

- Deep Learning (The MIT Press Essential Knowledge series)
- <http://introtodeeplearning.com/> MIT course.
- <https://www.tensorflow.org/>
- <https://keras.io/> Francois Chollet et al. Keras. 2015.
- Martín Abadi, et al. TensorFlow: Large-scale machine learning on heterogeneous systems, 2015.