

Compilers & Interpreters

- Aspects of compilation -

What is meant by compilation → compilation is done by compiler.

- What is compiler -

- A compiler bridges the semantic gap between a PL domain & execution domain.

- Two aspects of compilation are -

- i) generate code to implement meaning of source program in the execution domain of source program in the execution domain.
- ii) Provide diagnostic for violation of PL semantics in a source program.

features are -

- Data types
- Data structures
- Scope rules
- Control structures.

i) Data types :-

- A data type is the specification of
 - legal values for variables of the type of
 - legal operations on the legal values of the type

- Following tasks are involved -

- checking legality of an operation for the type of its operands. This ensures that a variable is subjected only to legal operations of its type.

2) - use type conversion operation to convert value of one type into values of another type whenever necessary & permissible according to the rules of a PL

e.g - Handling data types :

- consider the C program

float x, y

int i, j;

y = 10;

x = y + 1;

- While compiling ^{1st} assignment statement .

The compiler must note that y is of type of float.

- it must generate code to convert the value 10. to the floating point .

In the second assignment statement -

- The value of y & i cannot add straightway because they are of different types .

Hence - the compiler must first generate code to convert the value of i to the floating point .

& then generate code to perform the addition of a floating operation .

result . y is floating value .

so compiler convert float value like

y = 10

y = 10.00

result is

x = y + 1

x = 10.00 + 1

x = 11.00 (After compilation)

(Handling a user-defined datatype)

Program. - User-defined data (input, output), type

```
weekday = (mon, tue, wed, thu, fri);  
var
```

```
today : weekday;  
begin { main program }
```

```
today := mon;
```

```
if today = tue then ...
```

- Here a weekday is a user-defined data type

The compiler first decide how to represent the values of the type. - map the values into subrange of int.

e.g. Values Mon -> fri -> mapped into subrange

1 ... 5

value \rightarrow mon. tue. wed. thu. fri
integer \rightarrow 1 2 3 4 5

- This representation does not cause a confusion between days of the week & integer.

- because the compiler could have check legality of each operation in the program before generating code.

Thus, use of an expression like tue+10 in the program would not lead to the value 12. $(2+10)=12$

- if tue is represented value 12, + is not legal operation of type weekday

- so compiler would indicate an error. & prevent the program reaching execution

- 3) Use appropriate instruction seq - of the target machine to implement the operation of type.

Q8) Data Structure :-

- A programming language (PL) permits use of data structure arrays, stack, records, lists etc.
- To compile a reference to an element a data structure, the compiler must develop a memory mapping to access the memory allocated to the element.
- A record which is heterogeneous DS leads to complex memory mapping.

Memory mapping for accessing data structure type

```
employee = record . . .
```

```
    name: array [1..10] of character;
```

```
    id: integer; . . .
```

```
end;
```

```
Var
```

```
    info: array [1..500] of employee;
```

```
    i, j: integer;
```

```
begin { main program }
```

```
    info[i].id := j;
```

```
end.
```

Here - info is an arry of records. - $info[i].id$ - involve use of two diff. kinds of mapping - The first mapping

is used to locate the ref. element of the array. i.e $info[i]$.

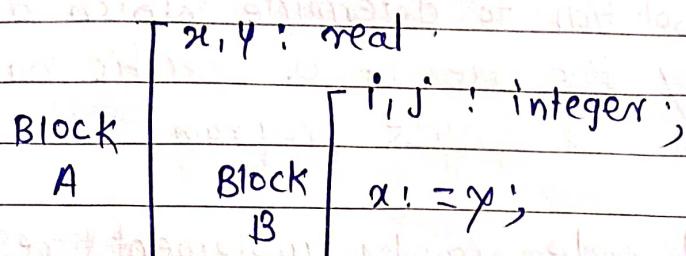
- it involve multiply $i-1$ by size of element of info.

data-type employee & adding result to address of memory

$emp + Am$ - allocated to $info[1]$.

- 2nd mapping - use to access the field id of an emp record.

Scope rule: A variable can be used in a block if it is declared or assigned in that block or in an outer block.

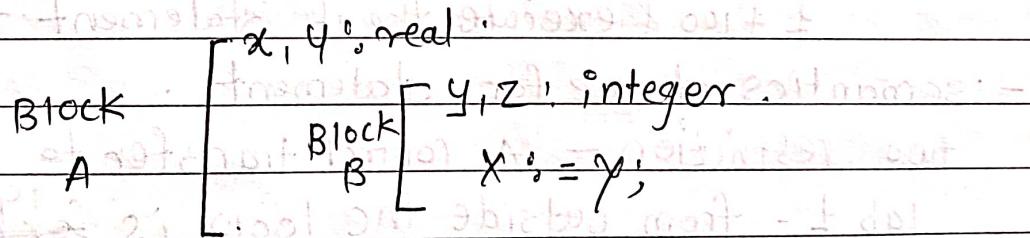


- First rule - those variable assign / declare in particular block. this variable access of particular block.

i.e. x assign block A so x, y variable access block A .

- Second rule - outer block access inner block .
i.e. mean outer block variables access inner block .

i.e. y access block B



- Variable x of block A is accessible in block A & also in the enclosed block B .

- However variable y of block A is not accessible in block B because block B contains a declaration of another variable, named y .

Thus the statement $x := y$ uses variable y of block B & var- y of block A .
variable y & z of block B are not accessible in block A .

- A compiler performs operations called scope analysis's and name resolution to determine which data item is designated by the use of a specific name at a specific place in the source program.
- The generated code simply implements results of these analyses.

(control structures) :-

(Handling control structures).

while compiling the for statement in the program.

for $i = 1$ to 100 do

 lab1: if $i = 10$ then ..

 end;

compiler has to generate code for the value i from 1 to 100 & execute the if statement for each value of i .

- semantics of the for statement.

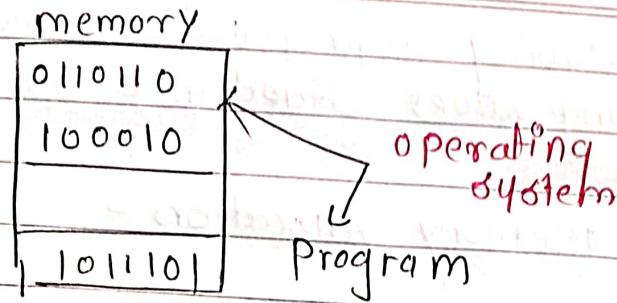
two restriction - A control transfer to the statement.

 lab1 - from outside the loop is ~~forbidden~~ so assignment of value of i is also forbidden.

 - The compiler has to check whether the source program satisfies these restrictions & indicate errors. When it does not.

① Memory Allocation

- Memory allocation is primarily hardware operation i.e - conducted or managed by operating system.



- Method of assigning memory to a process ~~as part of~~ element such variable instructions that need to be stored in main memory in order to get process executed.

Process of allocating physical or virtual memory to process.

Physical memory

Virtual memory

It is an actual RAM of the system.

It is an imaginary memory created in conjunction with hardware to extend the

Address space,

* also known as physical memory.

Memory Allocation

Static Allocation.

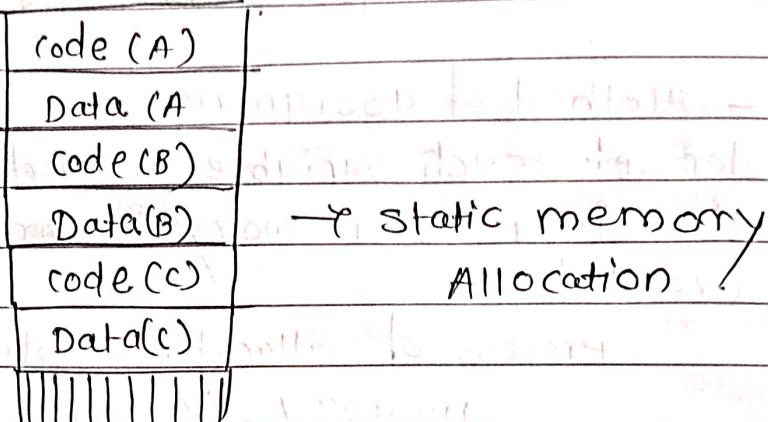
Dynamic Allocation.

Memory allocation involve the following three tasks -

- 1- Determining the amount of memory required for storing the value of a data item.
- 2- Using an appropriate memory allocation model for implementing the lifetimes of data items & scope rules of the language.

3 - Developing appropriate memory mappings for accessing values stored in a data structure.

- Static Memory Allocation -



1) - Static Memory Allocation is made when a program is compiled.

2) - The size required must be known before hand and thus it allots a fixed size.

that means program must specified size required for particular element in program itself.

3) - If data size is not known then the compiler will assign a random size.

- with random memory size with occur two issue

i) - If the allocated size come out to be larger will lead to wastage.

ii) - If the allocated size is smaller it will lead to inappropriate execution.

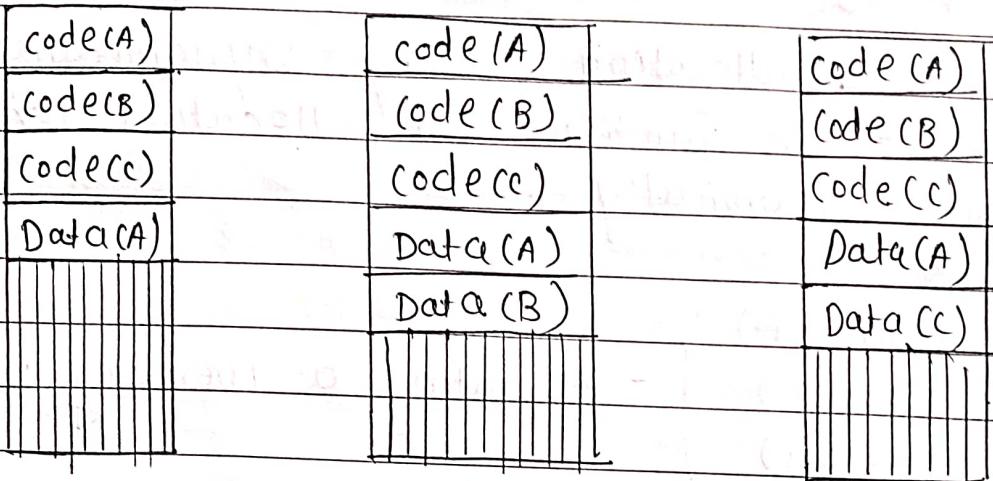
4) - If the allocated size -

Advantages of static memory allocation

- It provide fast & efficient execution of the process.

Disadvantages - you can not increase or decrease the fixed size memory allotted during static memory allocation.

• Dynamic Memory Allocation



Dynamic Memory allocation

- 1) Dynamic memory allocation is conducted during the execution time.
- 2) It allocates memory to program elements when they are used first time when program is running.
- 3) Dynamic memory allocation takes place in heap memory.
- 4) Exact amount of memory is allocated to program elements.
- 5) It makes execution flexible & improve system performance.

Advantages -

- Allocate the exact memory required.
- Reduce memory wastage.

- makes execution flexible.
- Improve the performance of the system.

disadvantage:

- Increases overhead of operating system
- slowing down execution

function of allocating memory Dynamically.

- Built-in functions for allocating or deallocating memory dynamically

malloc()

calloc()

realloc()

- Allocating a memory

free()

- deallocated a memory

- We use pointers for accessing the memory that are allocated dynamically.

⑥ Storage Allocation in Block structured language -

`x1,y : real;`

Block
A

Block
B

`y,z : integer`

- Diagram

floatptr - means floating pointer

floatptr1

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(a) heap

(b) - A hole in the allocation when memory is deallocated.

compiler performing following task.

- 1- Determine the static nesting level of
- 2- Determine the variable var; destined by the name name; in accordance with the scope rules.
- 3- Determine the static nesting level of the block in which name; is defined. Determine the value of dvari in the activation record of the block.
- 4- Generate the code indicated in diagram.

symbol table for a block structured language.

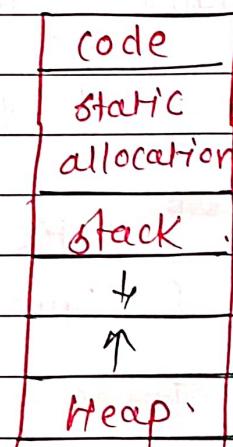
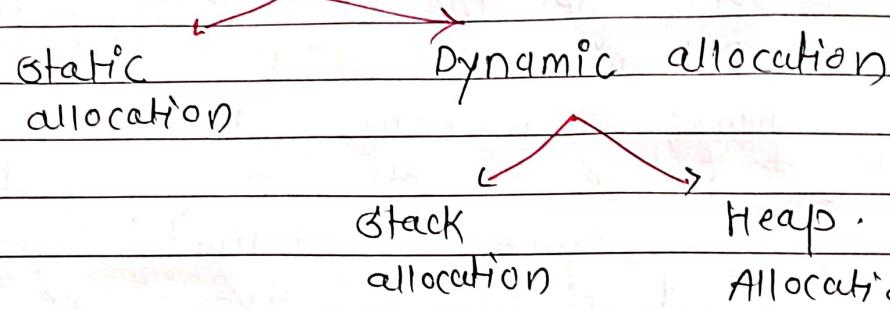
symtab _A	symtab _B	symtab _C	static nesting level	symbol table
			1	
	X 2			
		Z 2 W 3	2	Y 2

This activation record of a block contains the block's static nesting level & its symbol table.

- each entry in the symbol table shows only symbol & its displacement in the activation record.
- The search for variable x accessed in the statement $x := z;$ of block C terminates on finding the entry of x in the symbol table for block A.

- The static nesting level of A is 1. $dx = 2$ if static nesting level of C, the current block.
- This information is adequate for generating code.

Run time Storage Allocation strategies



- Divide into 4 parts -

code, static allocation, stack and Heap .

static Allocation -

1) In static environment there are number of restrictions:

- size of data are known at compile time
- no recursive procedures
- no dynamic memory allocation .

2) only one copy of each procedure activation record exist .

- we can allocate storage of compile time
- Bindings do not change at runtime .
- Every time a procedure is called , the bindings occurs .

- The storage is organised as stack.
- Activation records are push & pop.
- Activation record contains locals so that they are bound to fresh storage in each activation record.
- The value of locals is deleted when the activation ends.
- supports recursive procedure.

Heap allocation.

- Variables local to a procedure are allocated & de-allocated only at runtime.
- Dynamically allocate memory to variables claiming it back when the variable are no more required.
- support recursive.

• Compilation of Expression •

- During code generation for expressions, the compiler has to ensure correctness of the generated code and its execution efficiency.
 - Major issues in code generation for expressions
 - 1) determination of the order in which operators used in an expression should be evaluated.
 - 2) choice of instruction for performing an operation.
 - 3) use of CPU registers & handling of partial results in the generated code.
 - A modern computer provides different ways of performing operation.

The compiler has to make a suitable choice from these alternatives depending on the type & length of the operands, & the addressability of each operand.

→ Operand descriptors / Address descriptors

- telling location / address of number
- An operand descriptor has 2 fields
 1. **Attributes** - contains the subfields type and length.
 2. **Addressability** - specifies where the operand is located, & how it can be accessed.
 - it has two subfields
 - a) **Addressability code** - this code takes the values 'm' - operand is in memory & 'r' - operand is in register. other addressabilities such as address in a register ('A r') & address in memory ('A m') are also possible;
 - b) **Address** - Address of a memory word or a CPU register
- An operand descriptor is built for each id, constant & partial result.
- A descriptor would be built for an id or constant when it is encountered in the expression. encountered means - evaluating expression.

2) Register descriptors -

A register descriptor fields -

- 1) status - contains the code free or occupied to indicate register status
- 2) operand descriptor #. If status = occupied, this field contains the descriptor # for the operand contained in the register.

- The code generator builds a register descriptor for every CPU register at the start of its operation & store all these descriptors in an array named Register-descriptor.

example - use of operand descriptors & register descriptors -

code is to be generated for the expression $a * b$.

Assuming a, b to be a type integer which occupies 1 memory word, the code generator builds two descriptors

$a * b$

Attributes Addressability

operand_descriptor[1]	(int, f)	m, addr(a)
operand_descriptor[2]	(int, l)	m, addr(b)

The code generated now generates the instruction

MOVER AREG, A

MULT AREG, B

To perform the multiplication & builds the descriptor for the partial result.

Attributes Addressability Comments

operand_descriptor[3]	(int, l)	R, addr(AREG)	Descriptor for $a * b$
-----------------------	----------	---------------	------------------------

It also updates the register descriptor for AREG

status : operand-descriptor#

occupied	# 3
----------	-----

which indicates that register AREG contains the operand described by descriptor # 3.

- **Triples -**

- The optimization of common subexpression elimination described later removed some of the evaluation of a subexpression from a program if doing so does not change the meaning & results of a program.

- Its application requires knowledge of whether a subexpression occurs many times in a program.

- The intermediate codes called triples & quadruples facilitate efficient implementation of this operation.

- A triple represents the evaluation of an operator

- The intermediate code of a program consists of a sequence of triples.

triple format

operator	operand 1	Operand 2
----------	-----------	-----------

quad tuples

format

operator	operand1	operand2	result

- are not temporary location for holding partial results.

- They are simply names.

- some of these become temporary locations when common subexpression elimination is implemented.

$$\text{e.g. } -(a \cdot b) + (c \cdot d + e)$$

$$t_1 = a * b$$

$$t_2 = -t_1$$

$$t_3 = c * d$$

$$t_4 = t_3 + e$$

$$t_5 = t_2 + t_4$$

quad tuples

	operator	operand1	operand2	result
0	*	a	b	t ₁
1	-	t ₁		t ₂
2	*	c	d	t ₃
3	+	t ₃	e	t ₄
4	+	t ₂	t ₄	t ₅

in triple remove result.

	operator	operand1	operand2
0	*	a	b
1	*	(0)	
2	*	c	d
3	+	(2)	
4	+	(1)	(3)

↑
index
value

quaduples

1) If move statement || 2) do not move statement

2) use Extra space

or use less space.