

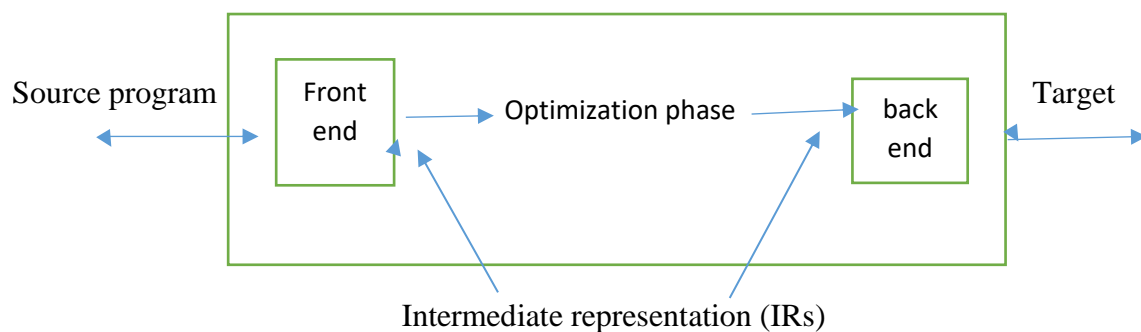
CODE OPTIMIZATION

A compiler performs code optimization to improve the execution efficiency of a program.

Remove unnecessary things in the program .are known as code optimization

It achieves optimization through the following two means:

1. Elimination of redundancies in a program.
2. Rearrangement of computations in a program to make it execute more efficiently. It is axiomatic that code optimization must not change the meaning of a program



Schematic of an optimising compiler

Two practical considerations limit the scope of optimization. First, code optimization seeks to improve a program rather than the algorithm used in a program.

Hence it does not replace an algorithm by a more efficient one. Second, efficient code generation for a specific target machine (eg., by fully exploiting its instruction set) belongs in the back end of a compiler.

Hence it is excluded from the scope of optimization contains a schematic of an optimizing compiler.

It differs from the schematic only in the presence of the optimization phase.

The front end generates an intermediate representation consisting of either triples, quadruples or abstract syntax trees.

The optimization phase analyzes the intermediate representation, performs optimizations and generates an intermediate representation of the optimized program.

The back end of the compiler generates target code from this intermediate representation. Thus, the optimization techniques are independent of both the programming language in which the source program is written and the target machine

The compiler extracts clues for code optimization from the structure of a program and the manner in which it manipulates its data.

Here CS, contains the two occurrences of $b*c$ because values of $b * c$ are identical in these expressions.

The second occurrence of $b*c$ can be eliminated because the first occurrence of $b*c$ would have been executed before the second occurrence would be reached during execution of the program.

Hence the transforms the program to the form shown in the right column.

Now, the value of the first occurrence of $b*c$ would be saved in the temporary location t and it would be used in the assignment to x

3)Dead code elimination:

Code that can be omitted from a program without affecting its results is called dead code.

In the statement $x := \langle \text{exp} \rangle$, the assignment to x is a dead code if the value it assigns to x is not used anywhere in the program, that is, either x is not used in the program or it is used only after it has been assigned some other value.

$\langle \text{exp} \rangle$ constitutes dead code only if its execution does not produce side effects, ie, only if it does not contain function or procedure calls that can produce side effects.

example

for (i=0; i<100;i++)

{

 a=0;

}

4)Frequency reduction/code movement:-Execution time of a program can be reduced by moving code that is situated in a part of the program that is executed very frequently to another part of the program that is executed less frequently.

For example, the transformation of loop optimization moves loop invariant code out of a loop and places it prior to loop entry.

example loop optimization

for i:=1 to 100 do

begin

 z:=i;

 x:=25*a;

 y:=x+z;

end;

Before optimization

 x:= 25*a;

for i := 1 to 100 do

begin

 z := i;

 y :=x+z;

end;

After optimization

Here $x = 25 * a$; is loop invariant because the value of a is not changed inside the for loop, so it is moved to a place prior to loop entry.

This way it is computed only once before entering the loop. $y := x * z$; is not loop invariant. Hence it cannot be subjected to frequency reduction

5) Strength reduction

The strength reduction optimization replaces a time-consuming operation (a "high strength operation") in an expression by a faster operation (a "low strength" operation), e.g., replacement of a multiplication by an addition.

Example (Strength reduction) The following program computes $i * 5$ within the loop for i

for $i := 1$ to 10 do

begin

$k := i * 5$;

end;

itemp := 5;

for $i := 1$ to 10 do

begin

$k :=$ itemp;

itemp := itemp + 5;

end;

before optimization

after optimization

Because the value of i would vary from 1 to 10 in steps of 1 during the program's execution, values of $1 * 5$ in successive iterations would differ by 5.

Hence the expression $i * 5$ occurring within the loop can be replaced by the expression $\text{itemp} + 5$ within the loop and an initialization of itemp before entering the loop.

During execution of the optimized program, the variable itemp would track the value of $i * 5$ through repeated additions

Local and global optimization

Optimization of a program is performed in the following two phases:

1. **Local optimization:** This phase applies optimizing transformations over small sections of a program that consist of a few statements each. It incurs a modest program analysis cost because only a few statements in the program are analyzed at a time; however, it also has limited benefits.

2. **Global optimization:** This phase applies optimizing transformations over a complete function or procedure. It incurs a higher program analysis cost but also provides larger benefits.

Local Optimization

The scope of local optimization is a basic block which is an 'essentially sequential section of code segment in the source program.

The cost of local optimization is low because the sequential nature of the basic block simplifies the analysis needed for optimization. The benefits are limited because certain optimizations such as loop optimization are beyond the scope of local optimization.

Basic block- A basic block is a sequence of program statements ($s_1, s_2 \dots s_n$) such that only s_n can be a transfer of control statement and only s_1 can be the destination of a transfer of control statement.

Thus, a basic block b_i , is a section of code that has a single entry point.

If control reaches statement s_1 during program execution, all statements s_1, s_2, \dots, s_n will be executed.

The 'essentially sequential' nature of a basic block simplifies local optimization. discusses this aspect. Use of basic blocks for local optimization also simplifies global optimization. For example, let a basic block b_i contains n occurrences of an expression $a+b$.

After local common subexpression elimination has been performed over b_i , global optimization needs to consider elimination of only the first occurrence of $a+b$ -other occurrences of $a+b$ are either not redundant or would have been already eliminated!

local optimization

consider the local optimization

$a := x * y;$

$b := x * y;$

labi: $c := x * y;$

$t := x * y$

$a := t;$

$b := t;$

labi : $c := x * y;$

before optimization

After optimization

Local optimization identifies two basic blocks in the program because presence of the label labi implies the possibility of a control transfer to the statement shown against that label.

The first basic block extends up to the end of the statement $b := x * y;$ Its optimization leads to elimination of the second occurrence of $x * y$.

The second basic block contains only the last statement. The occurrence of $x * y$ in it cannot be eliminated because it may be reached without executing the first basic block.

Global Optimization

Compared to local optimization, global optimization requires more program analysis effort to establish the feasibility of an optimization. Consider global common subexpression elimination.

if some expression $x * y$ occurs in a set of basic blocks SB of program P. its occurrence in a block b_j be eliminated if the following two conditions are satisfied for every possible execution of P:

1. Basic block b_j is executed only after some block b_y that is included in SB has been executed.
2. No assignments to x or y have been executed after the last (or only)

SB means set of basic block

evaluation of $x*y$ in block b ensures that $x*y$ would be evaluated before execution reaches block b_j , while condition 2 ensures that the value resulting from that evaluation would be equivalent to the value of $x*y$ in block b_j .

due to presence conditional statements in the program, different blocks in SB may satisfy condition 1 for different executions of P . Common subexpression elimination is realized by saving the value of $x*y$ in a temporary location in all blocks by which satisfy condition 1 and using the saved value in block b , instead of evaluating $x*y$.

Note the emphasis on the words 'every possible execution'. This requirement is introduced to ensure that the meaning of the program is unaffected by the optimization. In this section we use the word 'always' to imply 'in every possible evaluation'. Unlike local optimization, which is performed over a basic block, global optimization is performed over a function or procedure.

Hence the global optimization phase has to consider the effect of conditional statements and loops while analyzing a program. To simplify this task, it performs two kinds of analysis. It first analyzes a program by using the techniques of control flow analysis to find how control may flow during execution of a program and whether loops exist in it.

then analyzes the manner in which variables are likely to be assigned values and referenced during execution by using the techniques of data flow analysis.

- **Parameter passing mechanisms**

A programming language specifies the semantics of use of a parameter inside a function, thereby defining the kind of side effects a function can produce on its actual parameters.

A parameter passing mechanism is an arrangement used in the target code to realize passing and accessing of actual parameters and production of side effects on them.

This section discusses the side effect producing capability and execution efficiency of three common parameter passing mechanisms.

Call by value

the call by value parameter passing mechanism passes values of actual parameters to the called function through the parameter list.

If any statement in the function modifies the value of a formal parameter, the copied value of the corresponding actual parameter would change but the change would not be reflected on the value of the actual parameter.

Thus a function cannot produce any side effects on its parameters. The compiler can implement call by value as follows:

It can allocate memory to formal parameters of a function as if they were local variables of the function and generate code at the start of a function that would copy values of actual from the parameter list into the corresponding formal parameters.

This way a formal parameter can be accessed the same way a local variable would be accessed.

This arrangement simplifies code generation for accesses to formal parameters.

The call by value mechanism is efficient for formal parameters that are scalar variables; however, the copy operation would incur substantial overhead for parameters that are arrays. It is commonly used for built-in functions of a language because they do not need to produce side effects on parameters and typically have scalar formal parameters.

Call by value-result

Call by value-result extends the capabilities of the call by value mechanism by copying back the values of formal parameters into corresponding actual parameters while returning control to the calling program.

Thus, if statements in the function modify values of formal parameters, side effects would be realized at return.

This mechanism inherits the simplicity of the call by value mechanism.

Call by reference

Call by reference passes the address of an actual parameter to the called function.

If the actual parameter is an expression in the calling program, the compiler generates code that would evaluate the expression, store its value in a temporary location, and pass the address of the temporary location to the called function.

If a parameter is an array element, the compiler generates code to compute its address and pass it in the parameter list.

The parameter list is thus a list of addresses of actual parameters. To compile a reference to a formal parameter p in a statement in the function, the compiler generates code that would obtain the address of the corresponding actual parameter from

Call by name

Call by name has the effect as if every occurrence of a formal parameter in the body of the called function was substituted by the name of the corresponding actual parameter through string replacement.

Call by name achieves instantaneous side effects.

It also has the implication that the actual parameter that corresponds to a formal parameter may change during the execution of a function, thus providing additional expressive power.

$z := d[i];$ statement 1

$i := i+1;$ statement 2

$x := d[i]+5;$ statement 3

name substitution implies replacement of the string a by the string $d[i]$ in the body of α during the execution of α . Thus the call $\alpha(d[1], x)$ has the same effect as execution of the statements

When the value of i is modified, the name $d[i]$ of the actual parameter effectively changes. Hence the formal parameter a corresponds to two different elements of d in the first and third statements above.

Call by name is implemented as follows: While compiling a function call, the compiler builds a parameter descriptor for each parameter that is the address of a routine that would compute the address of the corresponding actual parameter.

The routine itself would also be generated at this time

- **pure & Impure Interpreter-**

There are 2 types of interpreter. i) pure ii) impure

- Pure interpreter can be defined as an interpreter that maintains a source program in its source form till it completely gets interpreted

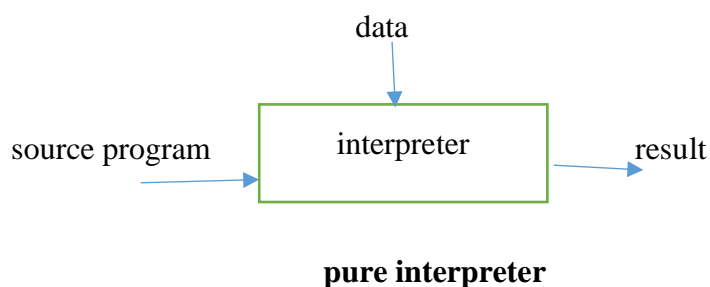
An impure Interpreter is defined as one that does Source program's preliminary processing throughout interpretation to minimize cost of analysis

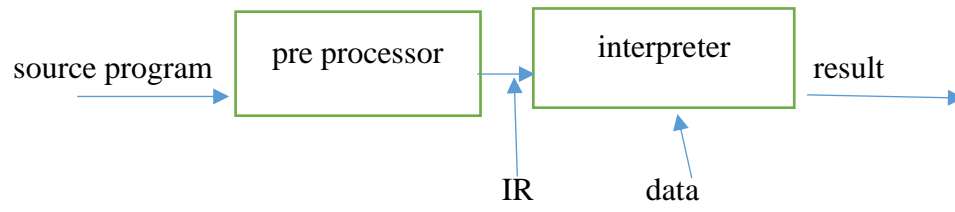
In the process of pure interpreter the original program of Source Code has to be maintained in the memory. This causes overhead of analysis when a statement is interpreted (line by line evaluation)

- for decreasing overhead (time, memory, bandwidth.) overhead means time is more required for pure interpreter.

- for decreasing overhead of analysis in the process of interpretation, an impure interpreter does few processing related to Source program.

- The program is converted into Intermediate Representation (CIR) during the process of interpretation. This is used for speeding up the interpretation process as a trade component. But since the entire program has to be preprocessed after any modification, it adds a fixed overhead at the start of interpretation





impure interpreter