Graded Assignment 1

a)
$$\vec{\theta} = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix}$$
 $\mathbf{X}^{(i)} = \begin{bmatrix} \mathbf{x}_0 \\ \mathbf{x}_1 \\ \vdots \\ \mathbf{x}_n \end{bmatrix}$

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$$h_{\theta}(x) = \theta_0 x_1 + \theta_1 x_1 + \dots + \theta_n x_n$$

so the vectorized expression is:

$$h_{\theta}(X) = \vec{\theta}^{\mathsf{T}} \cdot X^{(i)}$$

We use $\vec{\theta}^T$ because for the dot-product we need one $(m \times n)$ vector and one $(n \times m)$ vector.

The vectorized expression of the cost function is:

$$\overline{J}(\vec{\theta}) = \frac{1}{2m} \sum_{i=1}^{m} (\vec{\theta}^T \cdot \mathbf{X}^{(i)} - \mathbf{y}^{(i)})^2$$

c)
$$\frac{\partial J(\theta)}{\partial \theta} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial J(\theta)}{\partial \theta_0} \end{pmatrix} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial J(\theta)}{\partial \theta_0} \end{pmatrix} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial J(\theta)}{\partial \theta_0} \end{pmatrix} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial J(\theta)}{\partial \theta_0} \end{pmatrix} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial J(\theta)}{\partial \theta_0} \end{pmatrix} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial J(\theta)}{\partial \theta_0} \end{pmatrix} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial J(\theta)}{\partial \theta_0} \end{pmatrix} = \begin{pmatrix} \frac{\partial J(\theta)}{\partial \theta_0} \\ \frac{\partial 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d) The update rule of θ in the gradient descent procedure looks like this:

$$\theta_j := \theta_j - \alpha \frac{\partial J(\theta)}{\partial \theta_j}$$

So the vectorized expression looks like this:

$$\theta_j := \theta_j - \frac{\infty}{m} \sum_{i=1}^{n} (\vec{\theta}^T \cdot \vec{X}^{(i)} - \vec{y}^{(i)}) \vec{x}_j^{(i)}$$