

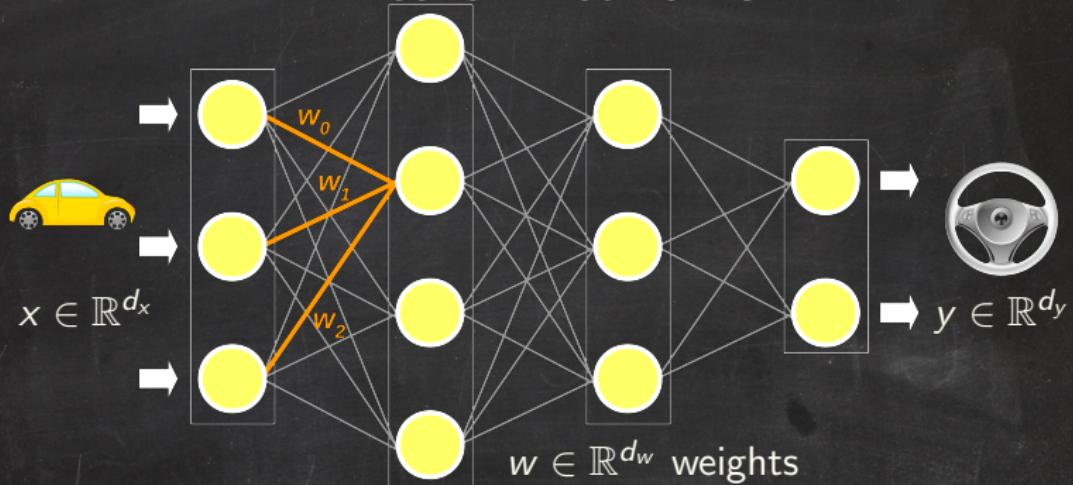
The geometry of neural networks

Kathlén Kohn

KTH Stockholm

joint with Matthew Trager and Joan Bruna
(both at Center for Data Science and Courant Institute at NYU)

Neural Networks



A neural network is defined by a continuous mapping $\Phi : \mathbb{R}^{d_w} \times \mathbb{R}^{d_x} \longrightarrow \mathbb{R}^{d_y}$.

Definition $\mathcal{M}_\Phi := \left\{ \Phi(w, \cdot) : \mathbb{R}^{d_x} \rightarrow \mathbb{R}^{d_y} \mid w \in \mathbb{R}^{d_w} \right\} \subset C(\mathbb{R}^{d_x}, \mathbb{R}^{d_y})$

is called the **neuromanifold** of Φ .

- Observation**
1. Φ piecewise smooth $\Rightarrow \mathcal{M}_\Phi$ manifold with singularities
 2. $\dim \mathcal{M}_\Phi \leq d_w$

Linear Networks

A **linear network** is defined by a map $\Phi : \mathbb{R}^{d_w} \times \mathbb{R}^{d_x} \longrightarrow \mathbb{R}^{d_y}$ of the form

$$\Phi(w, x) = W_h W_{h-1} \dots W_1 x,$$

where $w = (W_h, \dots, W_1)$ and $W_i \in \mathbb{R}^{d_i \times d_{i-1}}$,

(so $d_w = d_h d_{h-1} + \dots + d_1 d_0$, $d_x = d_0$ and $d_y = d_h$).

Example The neuromanifold of the linear network Φ is

$$\mathcal{M}_\Phi = \left\{ M \in \mathbb{R}^{d_h \times d_0} \mid \underbrace{\text{rk}(M)}_{=:r} \leq \min\{d_0, d_1, \dots, d_h\} \right\}.$$

1. If $r = \min\{d_0, d_h\}$, then $\mathcal{M}_\Phi = \mathbb{R}^{d_h \times d_0}$. "filling architecture"
2. If $r < \min\{d_0, d_h\}$, then \mathcal{M}_Φ is a **determinantal variety**.

Note: \mathcal{M}_Φ is neither convex nor smooth ($\text{Sing } \mathcal{M}_\Phi = \{M \mid \text{rk}(M) \leq r-1\}$)

Algebraic varieties

Definition

A **variety** is the common zero set of a system of polynomial equations.

A variety looks like a manifold **almost everywhere**:



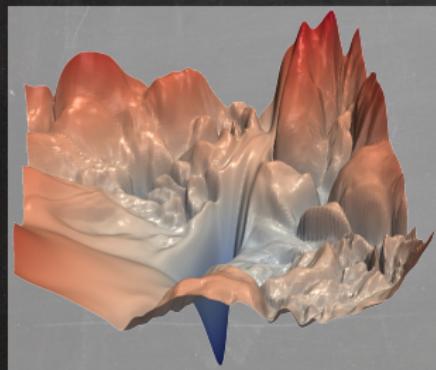
The **determinantal variety** $\mathcal{M}_r = \{M \in \mathbb{R}^{d_h \times d_0} \mid \text{rk}(M) \leq r\}$ is the zero locus of the $(r+1) \times (r+1)$ minors of M .

Loss Landscapes

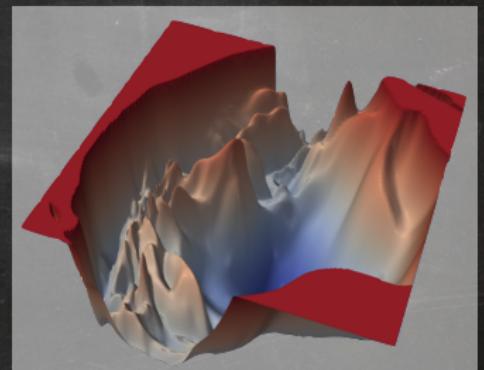
A **loss function** on a neural network $\Phi : \mathbb{R}^{d_w} \times \mathbb{R}^{d_x} \longrightarrow \mathbb{R}^{d_y}$ is of the form

$$L : \mathbb{R}^{d_w} \xrightarrow{\mu} \mathcal{M}_\Phi \xrightarrow{\ell|_{\mathcal{M}_\Phi}} \mathbb{R},$$
$$w \longmapsto \Phi(w, \cdot)$$

where ℓ is a functional defined on a subset of $C(\mathbb{R}^{d_x}, \mathbb{R}^{d_y})$ containing \mathcal{M}_Φ .



Visualizations
of L



Source: Li, Hao, et al. "Visualizing the loss landscape of neural nets." Advances in Neural Information Processing Systems. 2018.

Observation If $\varphi \in \text{Crit}(\ell|_{\mathcal{M}_\Phi})$, then $\mu^{-1}(\varphi) \subset \text{Crit}(L)$.

Linear Networks

A loss function on a linear network is of the form

$$L : \mathbb{R}^{d_h \times d_{h-1}} \times \dots \times \mathbb{R}^{d_1 \times d_0} \xrightarrow{\mu} \mathcal{M}_\Phi \subset \mathbb{R}^{d_h \times d_0} \xrightarrow{\ell} \mathbb{R},$$
$$(W_h, \dots, W_1) \longmapsto W_h \cdots W_1$$

Recall: $\mathcal{M}_\Phi = \{M \in \mathbb{R}^{d_h \times d_0} \mid \text{rk}(M) \leq r\}$, where $r := \min \{d_0, d_1, \dots, d_h\}$.

Theorem Let $M \in \mathcal{M}_\Phi$.

1. If $\text{rk}(M) = r$, then $\mu^{-1}(M)$ has 2^b path-connected components

$$\text{where } b := \# \{i \mid 0 < i < h, d_i = r\}.$$

2. If $\text{rk}(M) < r$, then $\mu^{-1}(M)$ is path-connected.

Linear Networks

A loss function on a linear network is of the form

$$L : \mathbb{R}^{d_h \times d_{h-1}} \times \dots \times \mathbb{R}^{d_1 \times d_0} \xrightarrow{\mu} \mathcal{M}_\Phi \subset \mathbb{R}^{d_h \times d_0} \xrightarrow{\ell} \mathbb{R},$$
$$(W_h, \dots, W_1) \longmapsto W_h \cdots W_1$$

For linear networks, the loss L often has “no bad minima”,
i.e. every local minimum is global.

Proposition Let ℓ be smooth and convex.

L has non-global minima $\Leftrightarrow \ell|_{\mathcal{M}_\Phi}$ has non-global minima.

Corollary [Laurent & von Brecht '17]

If ℓ is smooth convex and $r = \min\{d_0, d_h\}$ (filling architecture),
then all local minima for L are global.

Corollary [Baldi & Hornik '89, Kawaguchi '16]

If ℓ is a quadratic loss, then all local minima for L are global.
(even in the non-filling case!)

The Quadratic Loss

Fixed data matrices $X \in \mathbb{R}^{d_0 \times s}$ and $Y \in \mathbb{R}^{d_h \times s}$ define a **quadratic loss**

$$\ell_{X,Y} : \mathbb{R}^{d_h \times d_0} \longrightarrow \mathbb{R},$$
$$M \longmapsto \|MX - Y\|_F^2$$

Observation If $XX^T = I_{d_0}$ (“whitened data”), then

$$\ell_{X,Y}(M) = \|M - YX^T\|_F^2 + \text{const.}$$

Minimizing $\ell_{X,Y}$ on the determinantal variety $\mathcal{M}_\Phi = \{M \mid \text{rk}(M) \leq r\}$ is equivalent to minimizing the Euclidean distance of YX^T to \mathcal{M}_Φ .

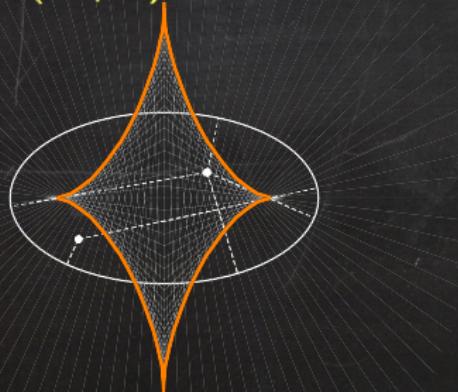
Euclidean Distance to Varieties

Let $\mathcal{Z} \subset \mathbb{R}^N$ be an algebraic variety
(i.e., the common zero locus of some set of polynomials).

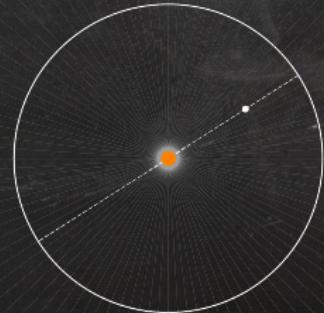
There is a constant $\delta \in \mathbb{Z}_{>0}$ such that for almost all $q \in \mathbb{R}^N$ the minimization problem $\min_{z \in \mathcal{Z}} \|z - q\|_2^2$ has δ complex critical points.
 δ is called the **ED degree** of \mathcal{Z} .

The **other** $q \in \mathbb{R}^N$ form a complex hypersurface, called **ED discriminant** of \mathcal{Z} .

$$\delta(\text{ellipse}) = 4$$



$$\delta(\text{circle}) = 2$$



Eckart-Young Theorem

$\mathcal{M}_r = \{M \mid \text{rk}(M) \leq r\} \subset \mathbb{R}^{m \times n}$ **determinantal variety**

EY Theorem

Let $Q \in \mathbb{R}^{m \times n}$ be of full rank with pairwise distinct singular values.

1. $\min_{M \in \mathcal{M}_r} \|M - Q\|_F^2$ has $\binom{\min\{m,n\}}{r}$ complex critical points.

$$\Rightarrow \text{ED degree } \delta(\mathcal{M}_r) = \binom{\min\{m,n\}}{r}$$

2. All critical points are real.

\Rightarrow ED discriminant has codimension 2 over \mathbb{R}

In fact: ED discriminant = { matrices with ≥ 2 coinciding singular values }

3. $\min_{M \in \mathcal{M}_r} \|M - Q\|_F^2$ has unique local minimum

Corollary [Baldi & Hornik '89, Kawaguchi '16]

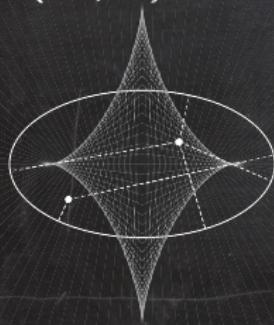
If ℓ is a **quadratic loss**, then all local minima for the loss $L = \ell \circ \mu$ on a linear network are global.
(even in the non-filling case!)

Linear Networks Can Have Bad Local Minima

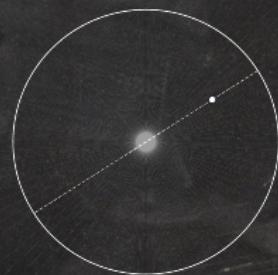
Let $\mathcal{Z} \subset \mathbb{R}^N$ be an algebraic variety.

There is a constant $\delta^{\text{gen}} \in \mathbb{Z}_{>0}$ such that for almost all linear coordinate changes $f : \mathbb{R}^N \rightarrow \mathbb{R}^N$ the ED degree of $f(\mathcal{Z})$ is δ^{gen} .
 δ^{gen} is called the **generic ED degree** of \mathcal{Z} .

$$\delta(\text{ellipse}) = 4$$



$$\delta(\text{circle}) = 2$$



$$\begin{aligned}\delta^{\text{gen}}(\text{circle}) \\= \delta(\text{ellipse}) \\= 4\end{aligned}$$

Equivalently: δ^{gen} is the ED degree of \mathcal{Z}

under the perturbed Euclidean distance $\|f(\cdot)\|_2$.

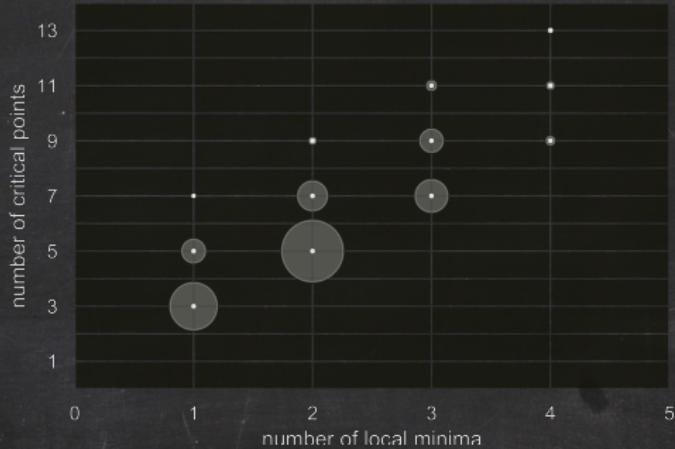
Linear Networks Can Have Bad Local Minima

Example $\mathcal{M}_1 = \{M \mid \text{rk}(M) \leq 1\} \subset \mathbb{R}^{3 \times 3}$

1. $\delta(\mathcal{M}_1) = 3 < 39 = \delta^{\text{gen}}(\mathcal{M}_1)$
2. under almost all perturbed Euclidean distances $\|f(\cdot)\|_2$,
the ED discriminant of \mathcal{M}_1 is a hypersurface over \mathbb{R}
 \Rightarrow different number of real critical points in different open regions of $\mathbb{R}^{3 \times 3}$
3. Also: different number of local minima in different open regions of $\mathbb{R}^{3 \times 3}$,
not all of them global !



Linear Networks Can Have Bad Local Minima



		# real critical points						
		1	3	5	7	9	11	13
# local minima	1	0	476	120	1	0	0	0
	2	0	0	805	190	10	0	0
	3	0	0	0	228	116	21	0
	4	0	0	0	0	16	12	5

All determinantal varieties behave like this ! XII - XIV

Linear Networks Can Have Bad Local Minima

Remark Closed formula for generic ED degree of $\mathcal{M}_r = \{M \mid \text{rk}(M) \leq r\} \subset \mathbb{R}^{m \times n}$ involving only m, n, r difficult to derive.

For $r = 1$,

$$\delta^{\text{gen}}(\mathcal{M}_1) = \sum_{s=0}^{m+n} (-1)^s (2^{m+n+1-s} - 1)(m+n-s)! \left[\sum_{\substack{i+j=s \\ i \leq m, j \leq n}} \frac{\binom{m+1}{i} \binom{n+1}{j}}{(m-i)!(n-j)!} \right]$$

$$\delta(\mathcal{M}_1) = \min\{m, n\}$$

Take Away

- ◆ determinantal varieties are examples of neuromanifolds
- ◆ for linear networks with smooth convex losses:

	quadratic loss	other loss
filling	no bad min.	no bad min.
non-filling	no bad min.	bad min.

↑

special embedding of
determinantal varieties

convex optimization
on vector space

- ◆ future extensions to
 - ◊ convolutional networks
(ongoing work with T. Merkh, G. Montúfar, M. Trager)
 - ◊ networks with polynomial activation functions or
 - ◊ ReLU networks (using semi-algebraic sets)

Informal Part 2: Convergence to Global Minima

joint with Ludwig Hedlin

Convergence to Global Minima

Consider a linear network with a quadratic loss $\ell_{X,Y}$.

Conjecture

For almost all data matrices X and Y and almost all initializations of the network, gradient flow will converge to a global minimum of the loss

$$L_{X,Y} = \ell_{X,Y} \circ \mu.$$

Theorem [Bah, Rauhut, Terstiege, Westdickenberg]

For almost all data matrices X and Y and almost all initializations of the network, gradient flow will converge to a global minimum of the loss

$$L_{X,Y} = \ell_{X,Y} \circ \mu \text{ or to another critical point whose Hessian has no negative eigenvalues.}$$

How can we exclude the latter?

Interesting sub case: Can we show that gradient flow will almost surely avoid $\mathcal{H}_{X,Y} := \{ \text{critical points of } L_{X,Y} \text{ with zero Hessian} \} ?$

Convergence to Global Minima

Consider a linear network with a quadratic loss $\ell_{X,Y}$.

Conjecture 2 (easier version)

For almost all data matrices X and Y and almost all initializations of the network, gradient flow will **not** converge to

$$\mathcal{H}_{X,Y} := \{ \text{ critical points of } L_{X,Y} = \ell_{X,Y} \circ \mu \text{ with zero Hessian } \}.$$

Idea: By [Chitour, Liao, Couillet], we know that the algebraic map

$$\delta : (W_h, W_{h-1}, \dots, W_1) \longmapsto \left(W_h^T W_h - W_{h-1} W_{h-1}^T, \dots, W_2^T W_2 - W_1 W_1^T \right)$$

is constant under gradient flow.

To prove Conjecture 2, it is enough to show

$$\dim(\text{im}(\delta|_{\mathcal{H}_{X,Y}})) < \dim(\text{im}(\delta)) \quad \text{for almost all } X, Y.$$

This holds for $h \leq 5$ ☺ but not for large h ☹