

Point-Line Minimal Problems for 3 Cameras with Partial Visibility

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joint work with Timothy Duff (Georgia Tech),
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Reconstruct 3D scenes and camera poses
from 2D images

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- ◆ Step 1: Identify common points and lines on given images



Reconstruct 3D scenes and camera poses from 2D images

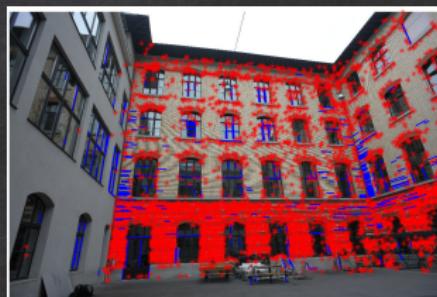
- ◆ Step 1: Identify common points and lines on given images



- ◆ Step 2: Reconstruct coordinates of 3D points and lines as well as camera poses

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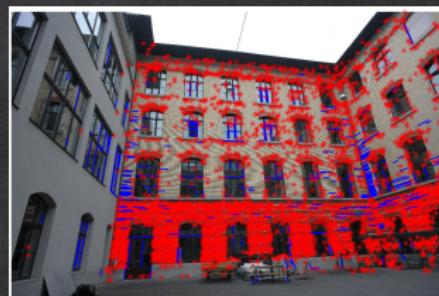
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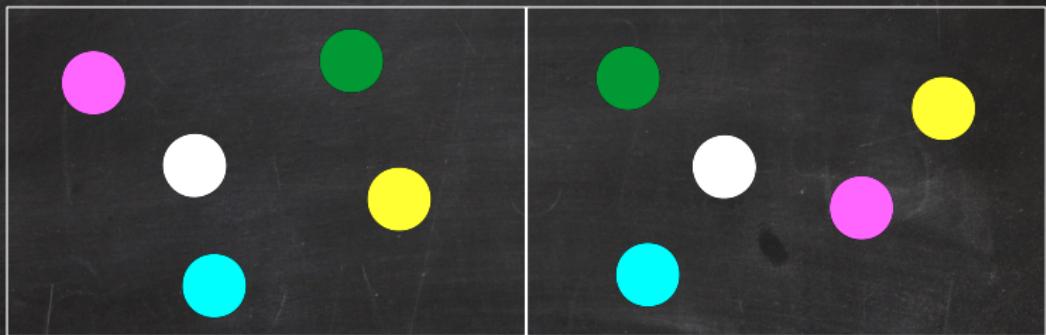


- ◆ Step 2: Reconstruct coordinates of 3D points and lines as well as camera poses

We use calibrated perspective cameras:
each such camera is represented by a matrix
 $[R \mid t]$, where $R \in \text{SO}(3)$ and $t \in \mathbb{R}^3$

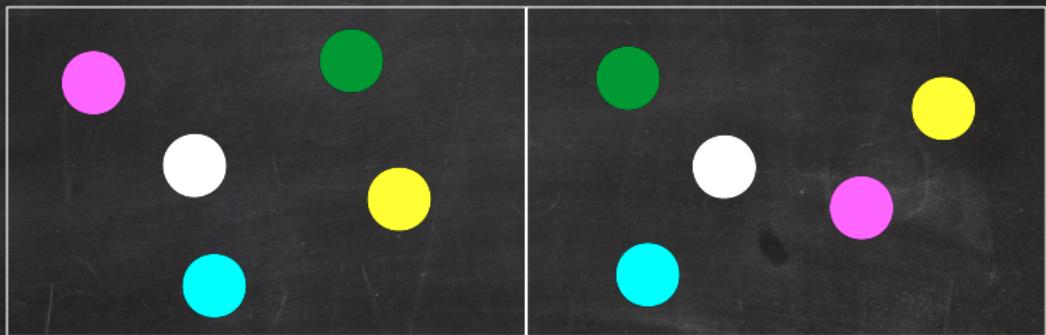
5-Point-Problem

Given 2 images of 5 points, recover 5 points in 3D and both camera poses.



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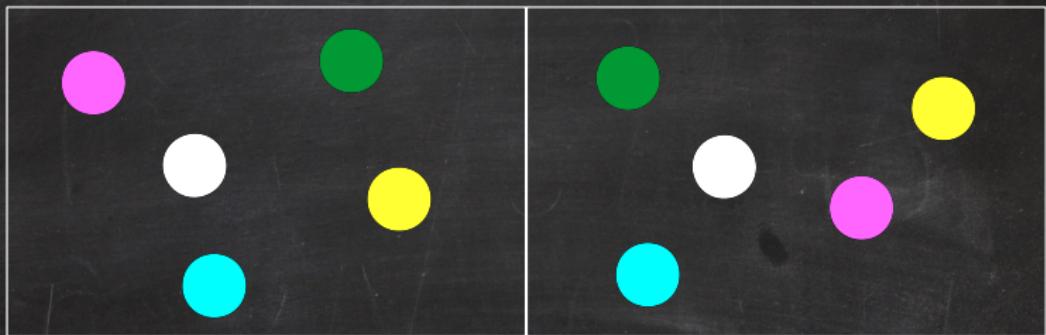


This problem has 20 solutions over \mathbb{C} .

(Given 2 images, a solution is 5 points in 3D and 2 camera poses.)

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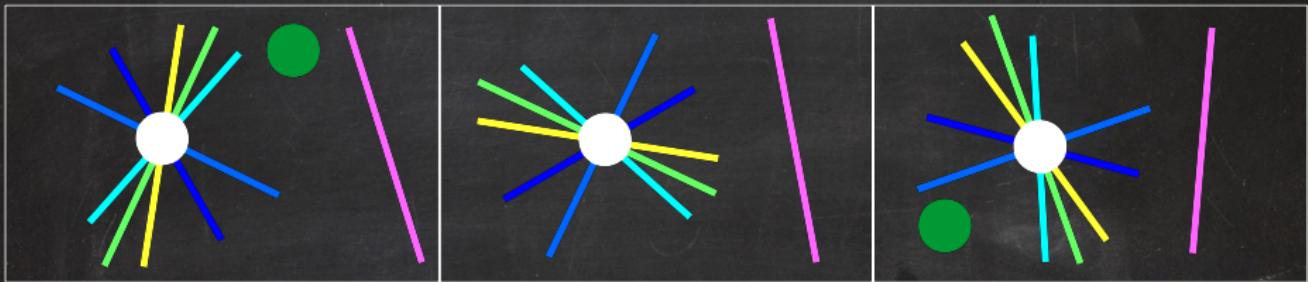
(Given 2 images, a solution is 5 points in 3D and 2 camera poses.)

⇒ The 5-Point-Problem is a minimal problem!

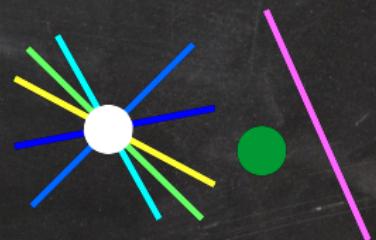
Another minimal problem

with partial visibility

- Given: 3 images like this:



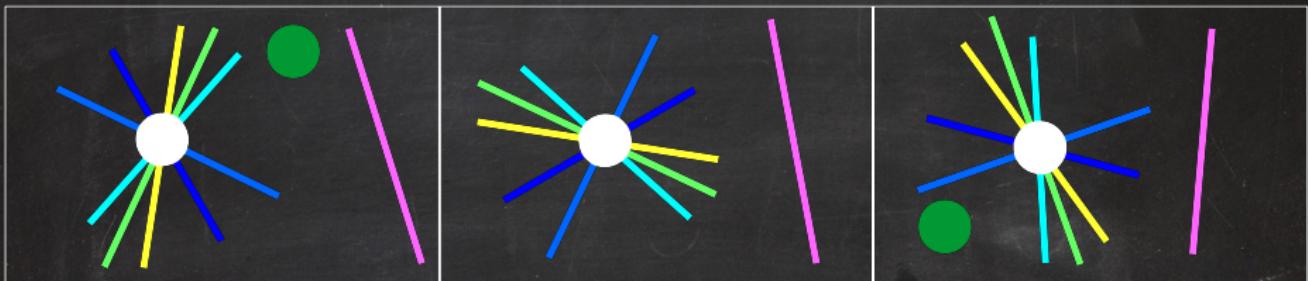
- Recover: 3 camera poses and
3D coordinates of 2 points and 6 lines
with the incidences:



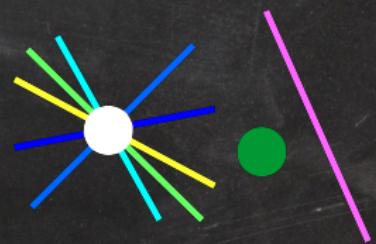
Another minimal problem

with partial visibility

- Given: 3 images like this:



- Recover: 3 camera poses and
3D coordinates of 2 points and 6 lines
with the incidences:



This problem has **240** solutions over \mathbb{C} .

(solution = 3 camera poses and 3D coordinates of points and lines)

⇒ It is a **minimal** problem!

Minimal Problems

A **Point-Line-Problem (PLP)** consists of

- ◆ a number m of cameras,
- ◆ a number p of points,
- ◆ a number ℓ of lines,
- ◆ a set \mathcal{I} of incidences between points and lines,
- ◆ for each camera $c \in \{1, \dots, m\}$, sets \mathcal{P}_c & \mathcal{L}_c of observed points & lines.

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Definition

A PLP is **minimal** if, given m generic 2D-images, where the c -th image consists of the points and lines in \mathcal{P}_c and \mathcal{L}_c satisfying the incidences \mathcal{I} , it has a positive and finite number of solutions over \mathbb{C} .

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Can we list **all** minimal PLPs?
How many solutions do they have?

30 Minimal PLPs with Complete Visibility

# views	6	5	5	5	4	4	4	4	4	4
Configuration										
# solutions	$\approx 10^6$	11296	26240	11008	3040	4512	1728	32	544	544
# views	3	3	3	3	3	3	3	3	3	3
Configuration										
# solutions	360	552	480	264	432	328	480	240	64	216
# views	3	3	3	3	3	3	3	2	2	2
Configuration										
# solutions	312	224	40	144	144	144	64	20	16	12

What about Partial Visibility?

1. Minimal PLPs with complete visibility have at most 6 cameras.

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1. Minimal PLPs with complete visibility have at most 6 cameras.
Minimal PLPs with partial visibility exist for arbitrarily many cameras!
2. Even for a fixed number of cameras, minimal PLPs with partial visibility are much **harder to classify** than those with complete visibility!

Assumptions

1. $m = 3$ cameras
- 2.
- 3.
- 4.

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2. Every point or line is observed by at least one camera.
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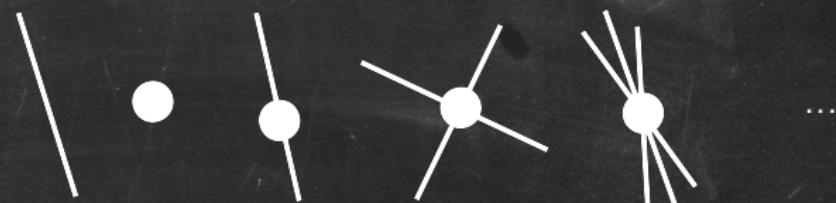
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3. Each intersection point of 2 lines is observed by all cameras which see both lines.
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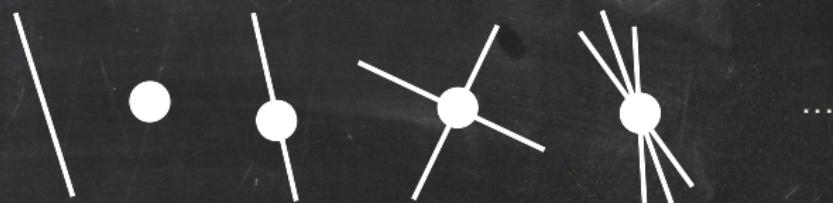
ingredients /
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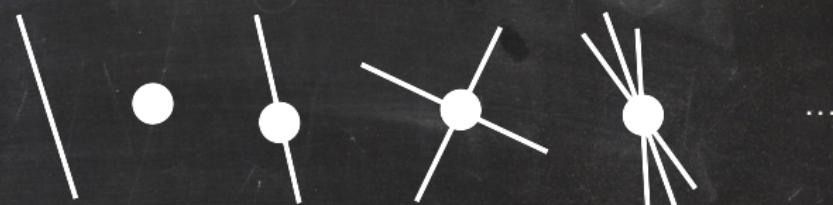


We call a PLP satisfying these assumptions a **PL1P in 3 views**.

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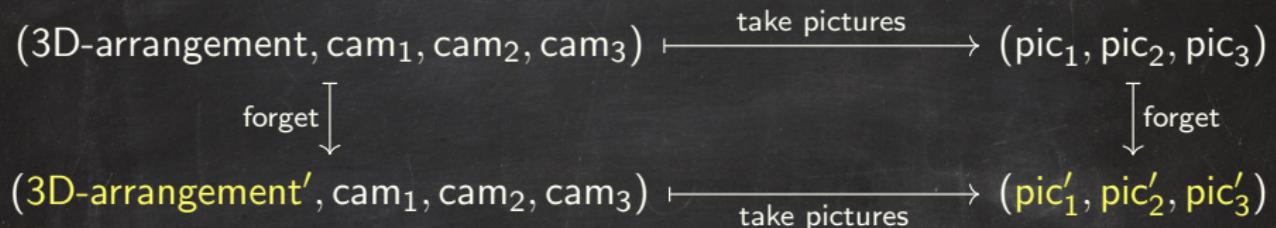


We call a PLP satisfying these assumptions a **PL1P in 3 views**.

There are **infinitely many minimal PL1Ps in 3 views!!**

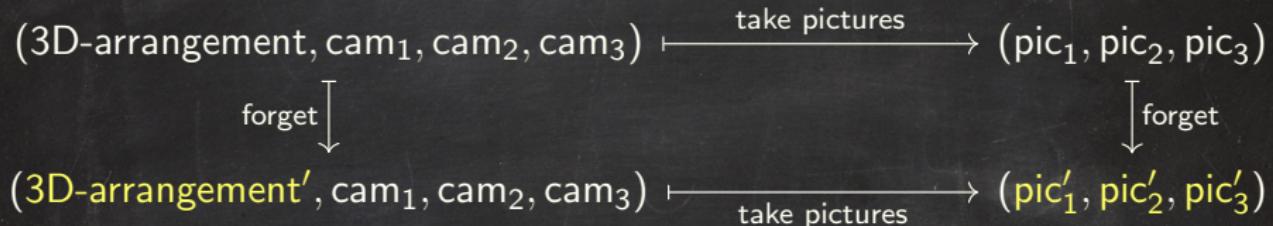
Reduced PL1Ps

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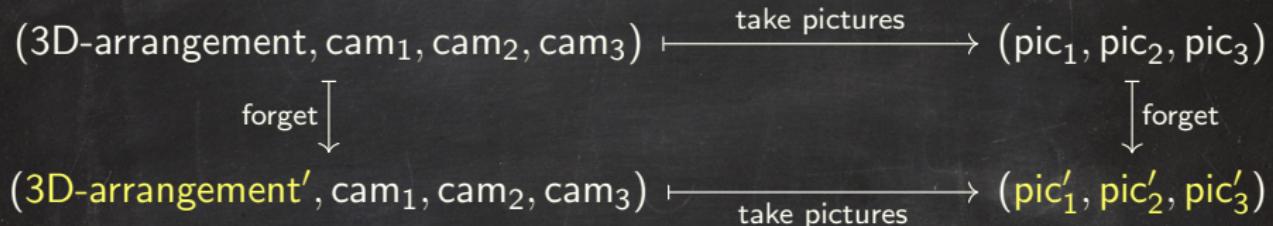
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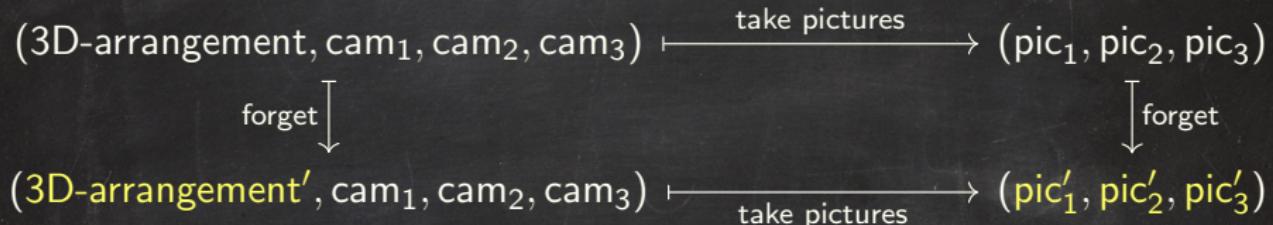
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Definition

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1. both are minimal,
2. for each forgotten point, at most one of its pins is kept, and
3. for generic pictures $(\text{pic}_1, \text{pic}_2, \text{pic}_3)$,
a generic solution of Π' on input $(\text{pic}'_1, \text{pic}'_2, \text{pic}'_3)$
can be lifted to a solution of Π on input $(\text{pic}_1, \text{pic}_2, \text{pic}_3)$.

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Proposition

If a PL1P is reducible to another PL1P,
then both have the same number of solutions (over \mathbb{C}).

Counting Reduced Minimal PL1Ps in 3 views

How do they look?

Theorem

A reduced minimal PL1P in 3 views has ≤ 1 point with ≥ 3 pins.

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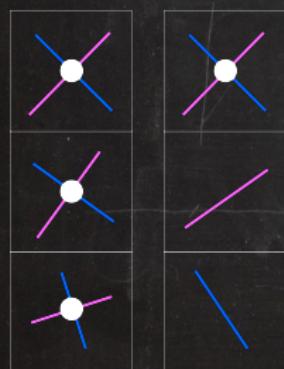
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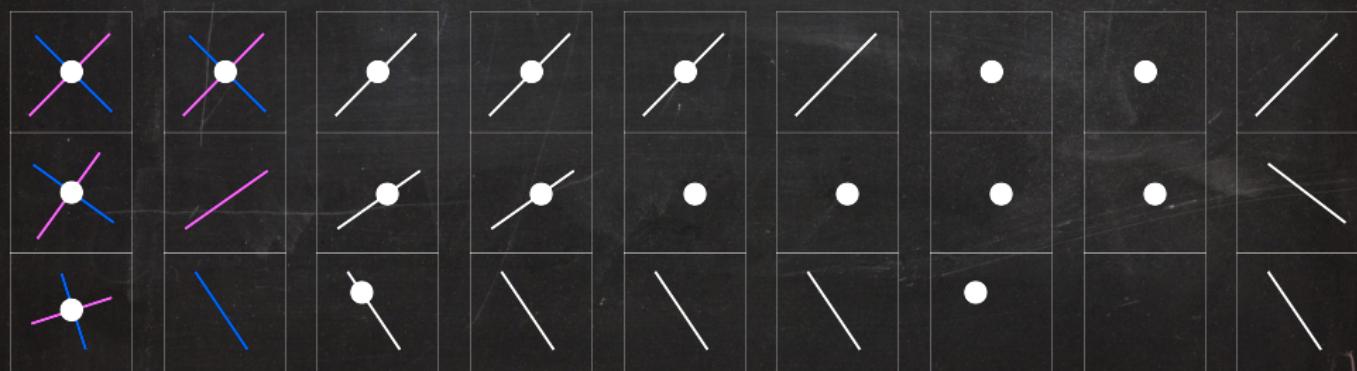
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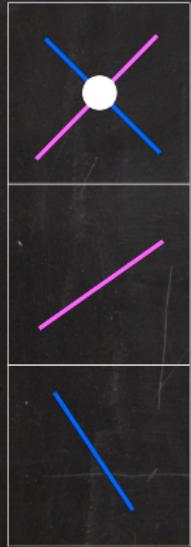
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Degrees of Freedom

3D

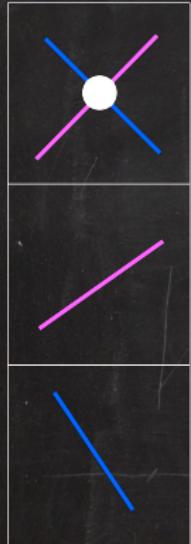


2D

Counting Reduced Minimal PL1Ps in 3 views

Degrees of Freedom

3D



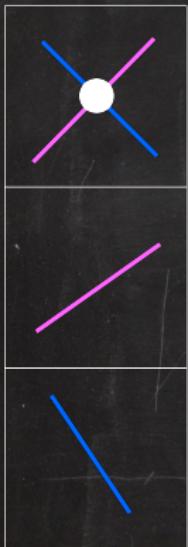
2D

$$3 + 2 + 2$$

$$= 7$$

Counting Reduced Minimal PL1Ps in 3 views

Degrees of Freedom



3D

$$3 + 2 + 2$$

$$= 7$$

2D

$$2 + 1 + 1$$

$$+ 2$$

$$+ 2$$

$$= 8$$

Counting Reduced Minimal PL1Ps in 3 views

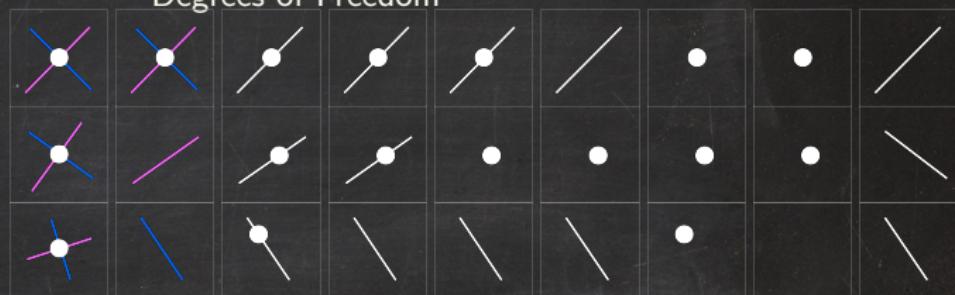
point with

7 6 5 4 3

pins

3D
2D

Degrees of Freedom



Counting Reduced Minimal PL1Ps in 3 views

		Degrees of Freedom									
point with		7	6	5	4	3	7	6	5	4	3
pins		7	6	5	4	3	7	6	5	4	3
3D		17	15	13	11	9	7	7	5	5	5
2D		27	24	21	18	15	12	8	9	8	7

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		Degrees of Freedom									
point with											
7	6	5	4	3							
pins											
3D	17	15	13	11	9	7	7	5	5	5	3
2D	27	24	21	18	15	12	8	9	8	7	6

Lemma:

A minimal PL1P in 3 views satisfies:

$$\text{degrees of freedom in 3D} + \text{camera parameters} = \text{degrees of freedom in 2D}$$

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3D	17	15	13	11	9	7	7	5	5	5	5	3	3	4
2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9	x_{10}	x_{11}	x_{12}	x_{13}	x_{14}

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2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9	x_{10}	x_{11}	x_{12}	x_{13}	x_{14}

Lemma:

A minimal PL1P in 3 views satisfies:

**degrees of freedom + camera parameters = degrees of freedom
in 3D in 2D**

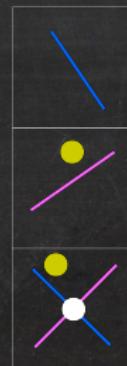
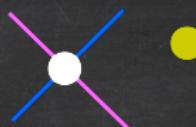
$$\begin{aligned}
 & 17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 & + 11 & = 27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 \\
 & + 7x_6 + 7x_7 + 5x_8 + 5x_9 + 5x_{10} & & + 12x_6 + 8x_7 + 9x_8 + 8x_9 + 7x_{10} \\
 & + 5x_{11} + 3x_{12} + 3x_{13} + 4x_{14} & & + 6x_{11} + 6x_{12} + 4x_{13} + 6x_{14}
 \end{aligned}$$

Permuting single local features...

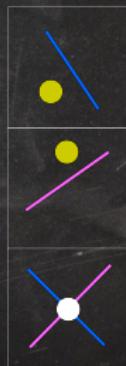
... in the 3 views changes the PL1P!

Example:

3D



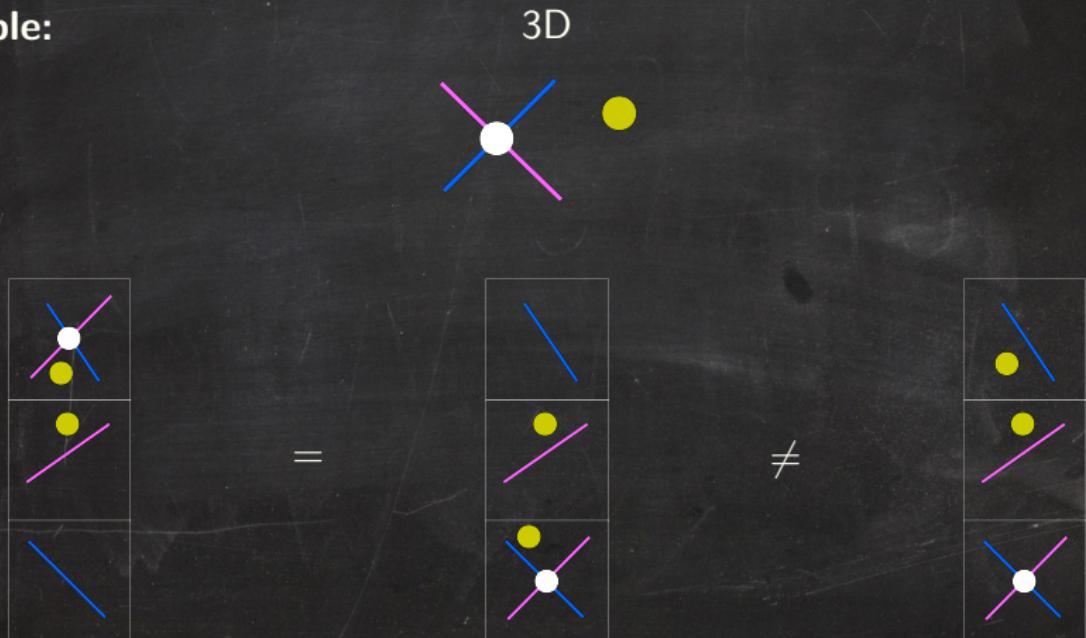
\neq



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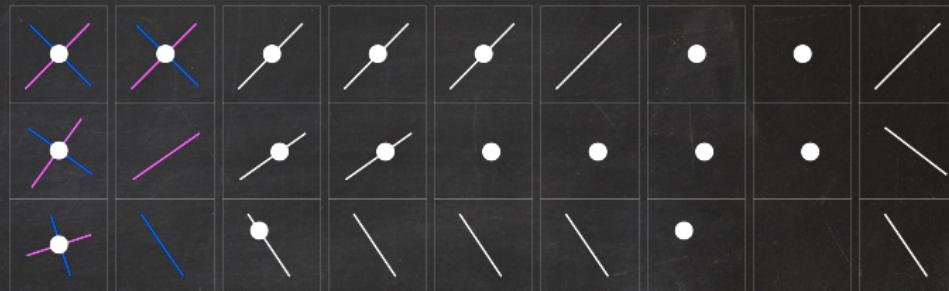
Example:



But relabeling the views does not change the PL1P.

Counting Reduced Minimal PL1Ps in 3 views

point with



7 6 5 4 3

pins

3D	17	15	13	11	9	7	7	5	5	5	5	3	3	4
2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9	x_{10}	x_{11}	x_{12}	x_{13}	x_{14}

$$\begin{aligned}
 & 17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 \\
 & + 7x_7 + 5x_8 + 5x_9 + 5x_{10} \\
 & + 5x_{11} + 3x_{12} + 3x_{13} + 4x_{14}
 \end{aligned}$$

$$\begin{aligned}
 & + 11 = \\
 & 27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6 \\
 & + 8x_7 + 9x_8 + 8x_9 + 7x_{10} \\
 & + 6x_{11} + 6x_{12} + 4x_{13} + 6x_{14}
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7	6	5	4	3										
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2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9	x_{10}	x_{11}	x_{12}	x_{13}	x_{14}
perm	1	1	1	1	1	1		1				1		1

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 & 17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 \\
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#	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9	x_{10}	x_{11}	x_{12}	x_{13}	x_{14}
perm	1	1	1	1	1	1	3	1				1	3	1

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perm	1	1	1	1	1	1	3	1				1	3	1

$$\begin{aligned}
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3D	17	15	13	11	9	7	7	5	5	5	5	3	3	4
2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7^1, x_7^2, x_7^3	x_8	x_9^1, x_9^2, x_9^3	$x_{10}^1 \dots x_{10}^6$	$x_{11}^1, x_{11}^2, x_{11}^3$	x_{12}	$x_{13}^1, x_{13}^2, x_{13}^3$	x_{14}
perm	1	1	1	1	1	1	3	1	3	6	3	1	3	1

$$\begin{aligned}
 & 17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 \\
 & + 7x_7 + 5x_8 + 5x_9 + 5x_{10} \\
 & + 5x_{11} + 3x_{12} + 3x_{13} + 4x_{14}
 \end{aligned}$$

+11 =

$$\begin{aligned}
 & 27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6 \\
 & + 8x_7 + 9x_8 + 8x_9 + 7x_{10} \\
 & + 6x_{11} + 6x_{12} + 4x_{13} + 6x_{14}
 \end{aligned}$$

Counting Reduced Minimal PL1Ps in 3 views

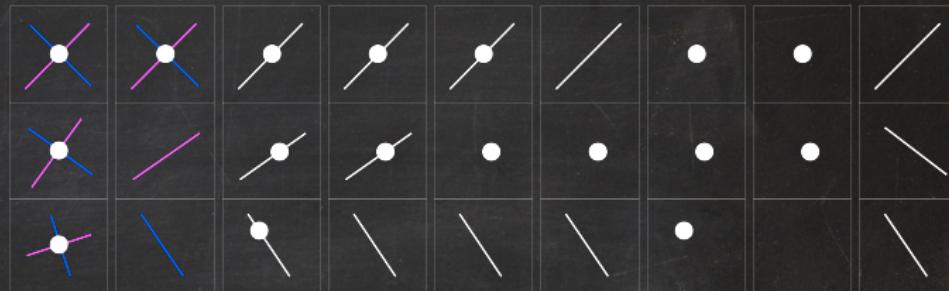
		point with												
		7	6	5	4	3								
		pins												
3D	17	15	13	11	9	7	7	5	5	5	5	3	3	4
2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7^1, x_7^2, x_7^3	x_8	x_9^1, x_9^2, x_9^3	$x_{10}^1 \dots x_{10}^6$	$x_{11}^1, x_{11}^2, x_{11}^3$	x_{12}	$x_{13}^1, x_{13}^2, x_{13}^3$	x_{14}
perm	1	1	1	1	1	1	3	1	3	6	3	1	3	1

$$17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 + 11 = 27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6$$

$$+ 7(x_7^1 + x_7^2 + x_7^3) + 5x_8 + 5(x_9^1 + x_9^2 + x_9^3) + 5(x_{10}^1 + \dots + x_{10}^6) + 8(x_7^1 + x_7^2 + x_7^3) + 9x_8 + 8(x_9^1 + x_9^2 + x_9^3) + 7(x_{10}^1 + \dots + x_{10}^6) \\ + 5(x_{11}^1 + x_{11}^2 + x_{11}^3) + 3x_{12} + 3(x_{13}^1 + x_{13}^2 + x_{13}^3) + 4x_{14} + 6(x_{11}^1 + x_{11}^2 + x_{11}^3) + 6x_{12} + 4(x_{13}^1 + x_{13}^2 + x_{13}^3) + 6x_{14}$$

Counting Reduced Minimal PL1Ps in 3 views

point with



3D	17	15	13	11	9	7	7	5	5	5	5	3	3	4
2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7^1, x_7^2, x_7^3	x_8	x_9^1, x_9^2, x_9^3	$x_{10}^1 \dots x_{10}^6$	$x_{11}^1, x_{11}^2, x_{11}^3$	x_{12}	$x_{13}^1, x_{13}^2, x_{13}^3$	x_{14}
perm	1	1	1	1	1	1	3	1	3	6	3	1	3	1

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Every reduced minimal PL1Ps in 3 views yields a non-negative integer solution of this equation!

Counting Reduced Minimal PL1Ps in 3 views

point with														
7	6	5	4	3										
pins														
3D	17	15	13	11	9	7	7	5	5	5	5	3	3	4
2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
#	x_1	x_2	x_3	x_4	x_5	x_6	x_7^1, x_7^2, x_7^3	x_8	x_9^1, x_9^2, x_9^3	$x_{10}^1 \dots x_{10}^6$	$x_{11}^1, x_{11}^2, x_{11}^3$	x_{12}	$x_{13}^1, x_{13}^2, x_{13}^3$	x_{14}
perm	1	1	1	1	1	1	3	1	3	6	3	1	3	1

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Every reduced minimal PL1Ps in 3 views yields a non-negative integer solution of this equation!

Which solutions are minimal reduced PL1Ps?

Counting Reduced Minimal PL1Ps in 3 views

Every reduced minimal PL1Ps in 3 views yields a non-negative integer solution of

$$\begin{aligned} & 17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 + 11 = 27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6 \\ & + 7(x_7^1 + x_7^2 + x_7^3) + 5x_8 + 5(x_9^1 + x_9^2 + x_9^3) + 5(x_{10}^1 + \dots + x_{10}^6) + 8(x_7^1 + x_7^2 + x_7^3) + 9x_8 + 8(x_9^1 + x_9^2 + x_9^3) + 7(x_{10}^1 + \dots + x_{10}^6) \\ & + 5(x_{11}^1 + x_{11}^2 + x_{11}^3) + 3x_{12} + 3(x_{13}^1 + x_{13}^2 + x_{13}^3) + 4x_{14} + 6(x_{11}^1 + x_{11}^2 + x_{11}^3) + 6x_{12} + 4(x_{13}^1 + x_{13}^2 + x_{13}^3) + 6x_{14} \end{aligned}$$

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- ◆ This equation has **845161** non-negative integer solutions.

Counting Reduced Minimal PL1Ps in 3 views

Every reduced minimal PL1Ps in 3 views yields a non-negative integer solution of

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- ◆ This equation has **845161** non-negative integer solutions.
- ◆ Some solutions correspond to PL1Ps which are the same up to relabeling the 3 views.

Counting Reduced Minimal PL1Ps in 3 views

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- ◆ This equation has **845161** non-negative integer solutions.
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- ◆ So the 845161 solutions describe only **143494** different PL1Ps.

Counting Reduced Minimal PL1Ps in 3 views

Every reduced minimal PL1Ps in 3 views yields a non-negative integer solution of

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- ◆ This equation has **845161** non-negative integer solutions.
- ◆ Some solutions correspond to PL1Ps which are the same up to relabeling the 3 views.
- ◆ So the 845161 solutions describe only **143494** different PL1Ps.
- ◆ **Which of these 143494 PL1Ps are minimal?**

Minimality Check

Lemma

A PL1P in 3 views satisfying the integer equation on the previous slide is **minimal** if and only if the **differential** of the map

$$(3\text{D-arrangement}, \text{cam}_1, \text{cam}_2, \text{cam}_3) \xrightarrow{\text{take pictures}} (\text{pic}_1, \text{pic}_2, \text{pic}_3)$$

is **surjective** at a generic point in its domain.

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It turns out that only **5707** of the 143494 PL1Ps described by the integer equation are **not minimal**.

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Final Result

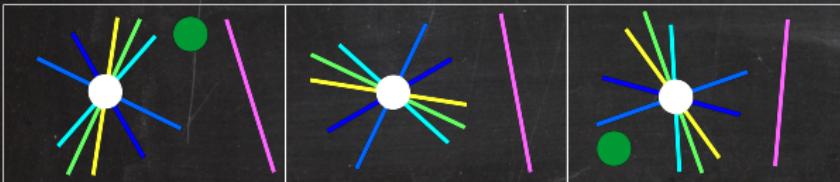
There are **137787** reduced **minimal** PL1Ps in 3 views.

Computing the generic number of solutions

Ongoing work

using homotopy continuation and monodromy
(state-of-the-art methods in
numerical algebraic geometry)

Problem 20 in our list of 137787 minimal problems



has generically **240 solutions**

