

Vectors

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \begin{bmatrix} \text{orange} \\ \text{grapefruit} \\ \text{apple} \end{bmatrix} \quad \begin{bmatrix} 120 \\ 250 \\ 100 \end{bmatrix}$$

$$[\text{orange grapefruit apple}] \quad \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \text{total fruits}$$

$$\begin{bmatrix} 1 & 1 & 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \text{total citrus}$$

$$\begin{bmatrix} 120 & 250 & 100 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \text{total weight}$$

$$G = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

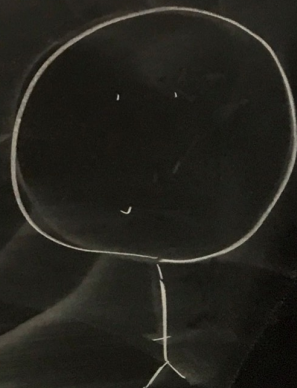
$$\begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} \quad \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

3x1 2x1

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 2 \end{bmatrix} + \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$

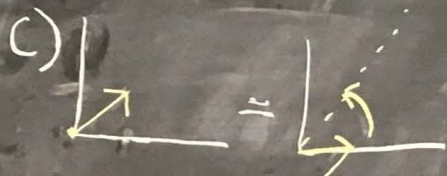


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$$a) \vec{v} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



$$b) a = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$



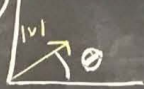
$$d) b = \begin{bmatrix} \cos(30) & -\sin(30) \\ \sin(30) & \cos(30) \end{bmatrix} \cdot \vec{v} = \begin{bmatrix} \cos(30) & -\sin(30) \\ \sin(30) & \cos(30) \end{bmatrix} = \begin{bmatrix} \cos(30) \\ \sin(30) \end{bmatrix}$$



f)

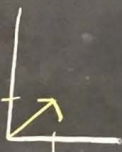
$$\begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$$

g)



$$\Rightarrow \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \text{ rotates vectors}$$

h)



$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \vec{w}$$

I)

$$S = RW$$

$$S = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

J)

