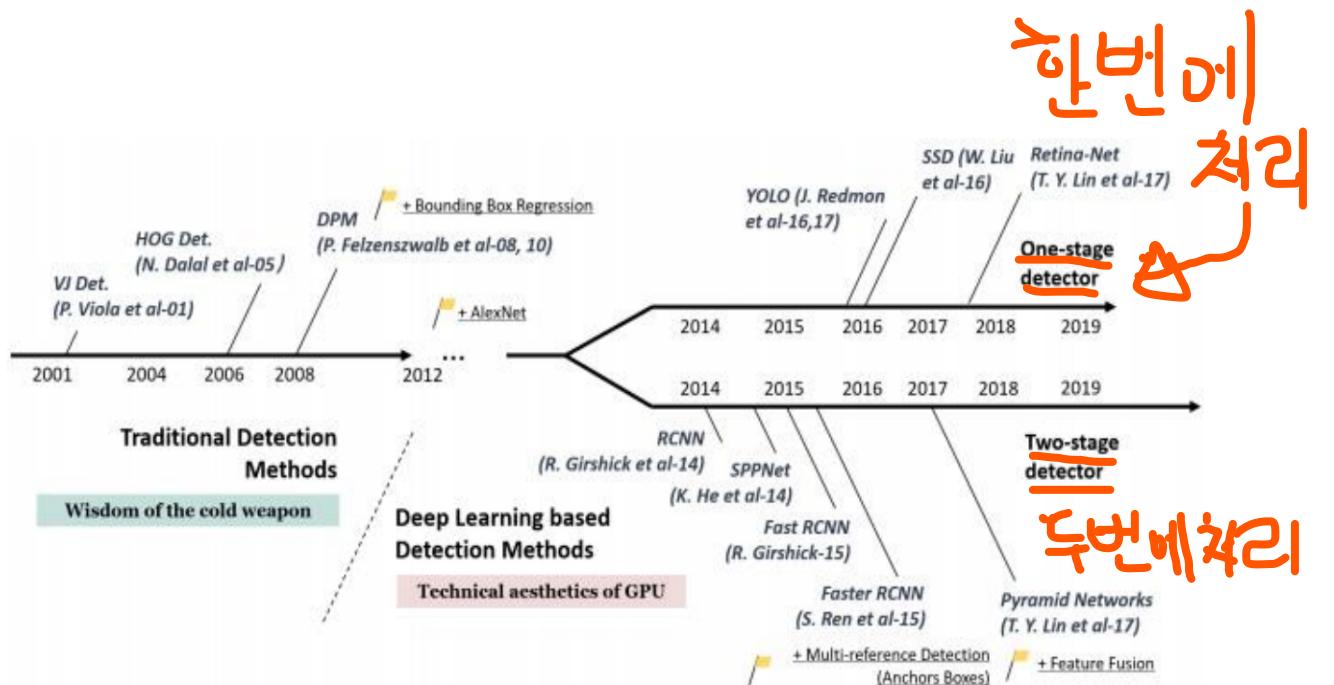
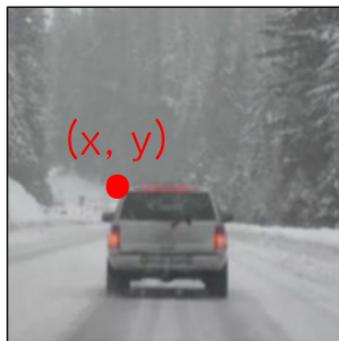
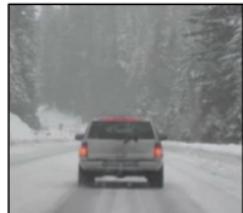
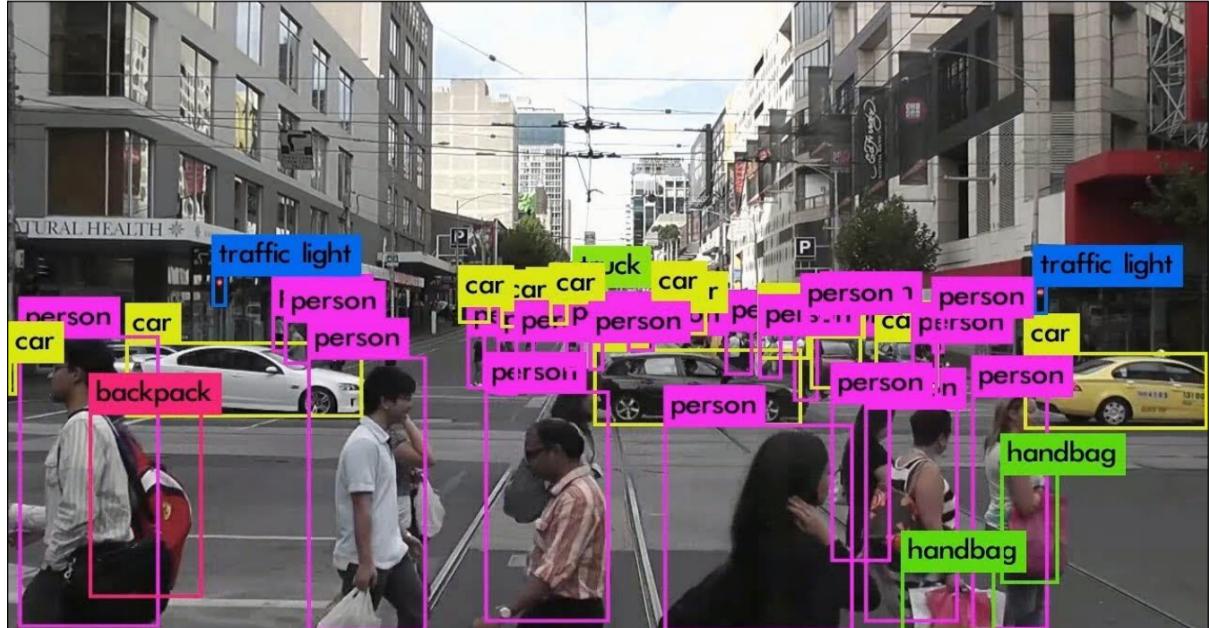


YOLO 교안

1. Object Detection



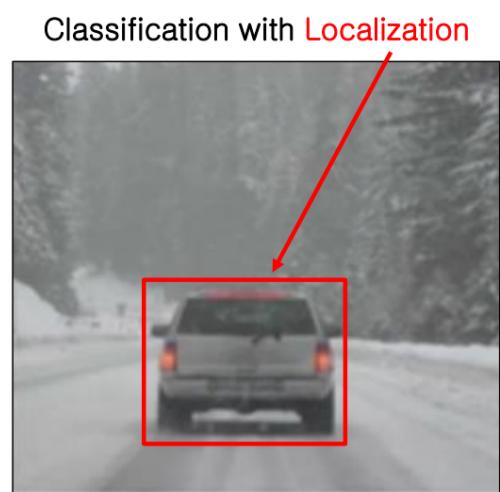
Object Detection = Object Classification + Object Localization
= Object Classification with Localization



Object Classification with Localization - concept

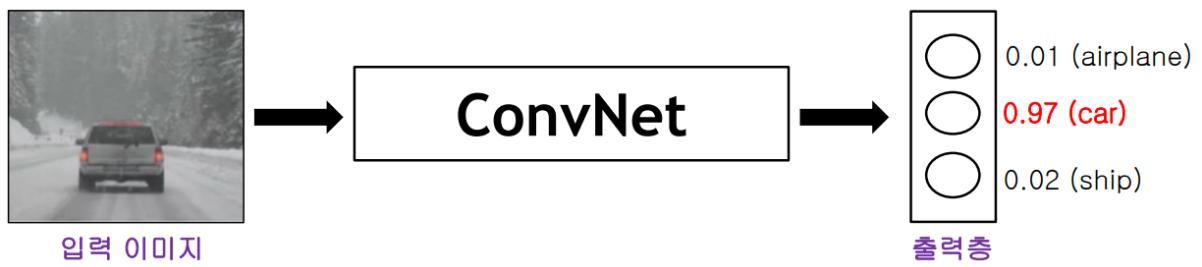


car

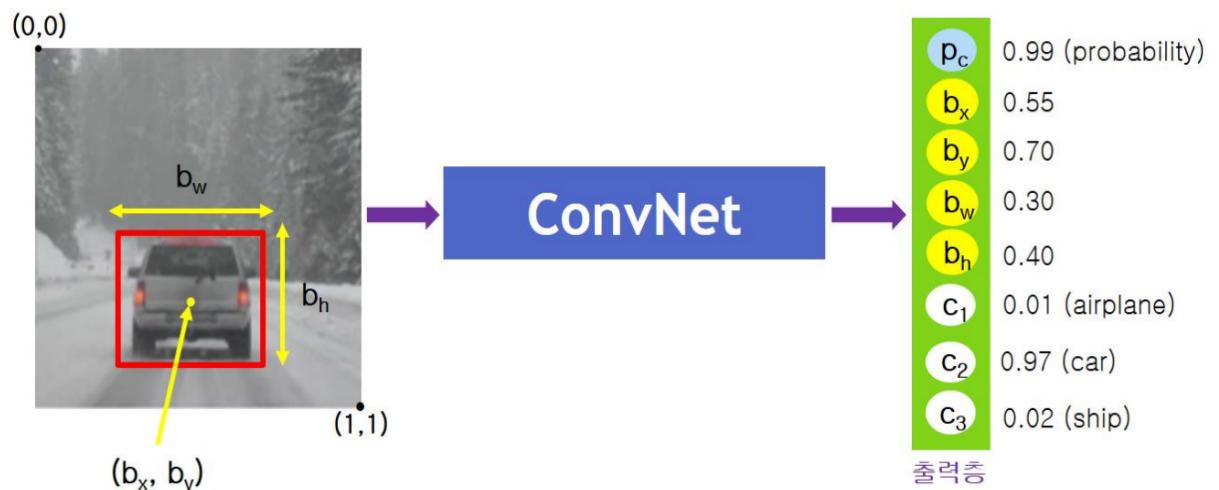


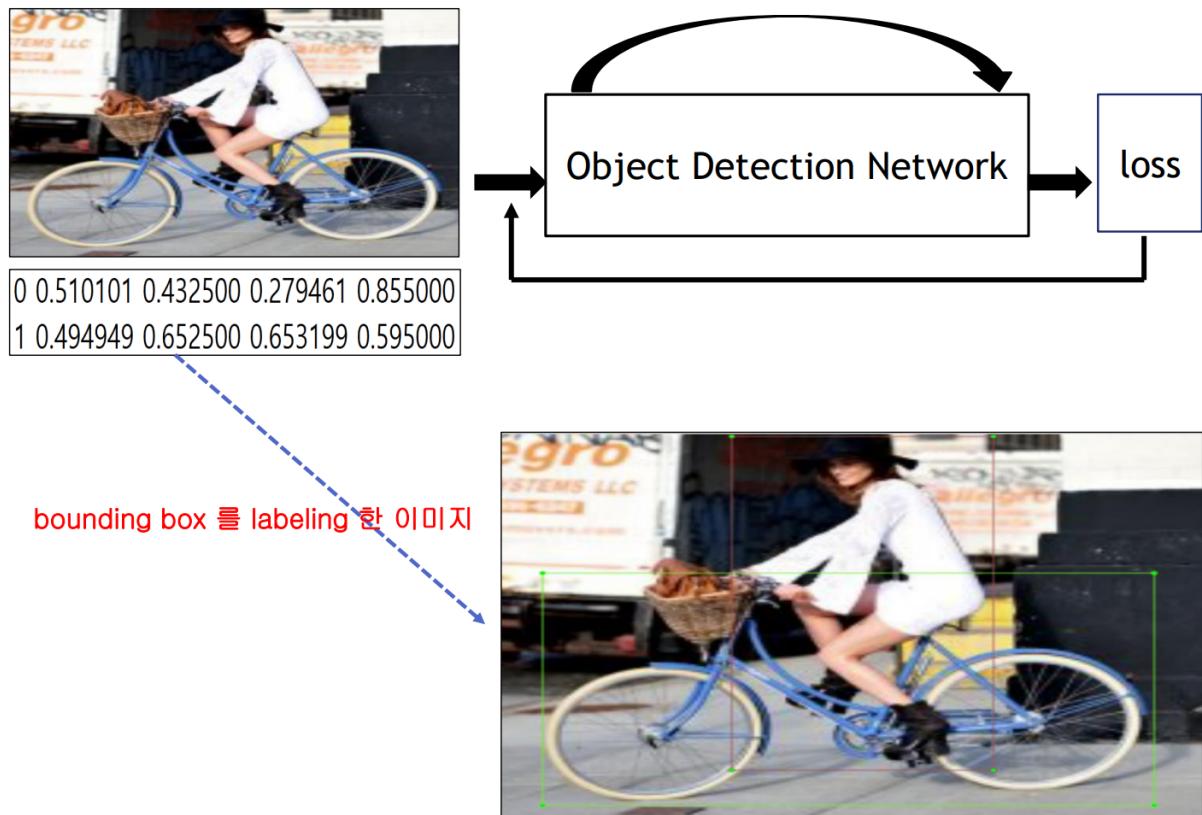
car with bounding box

Object Classification using Softmax



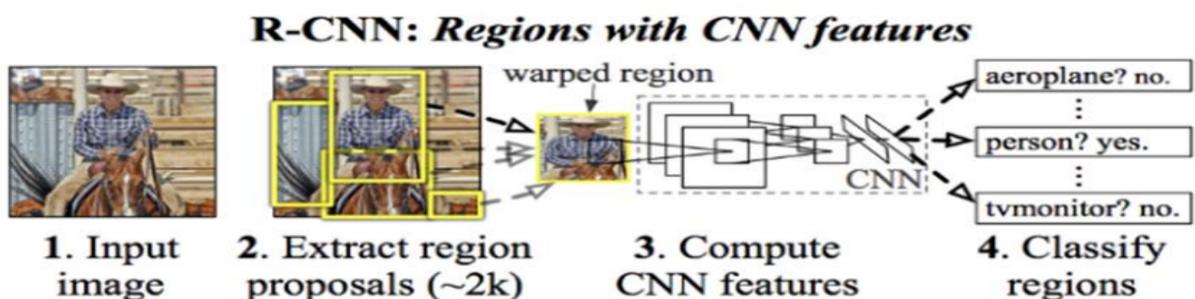
Object Localization using Bounding Box



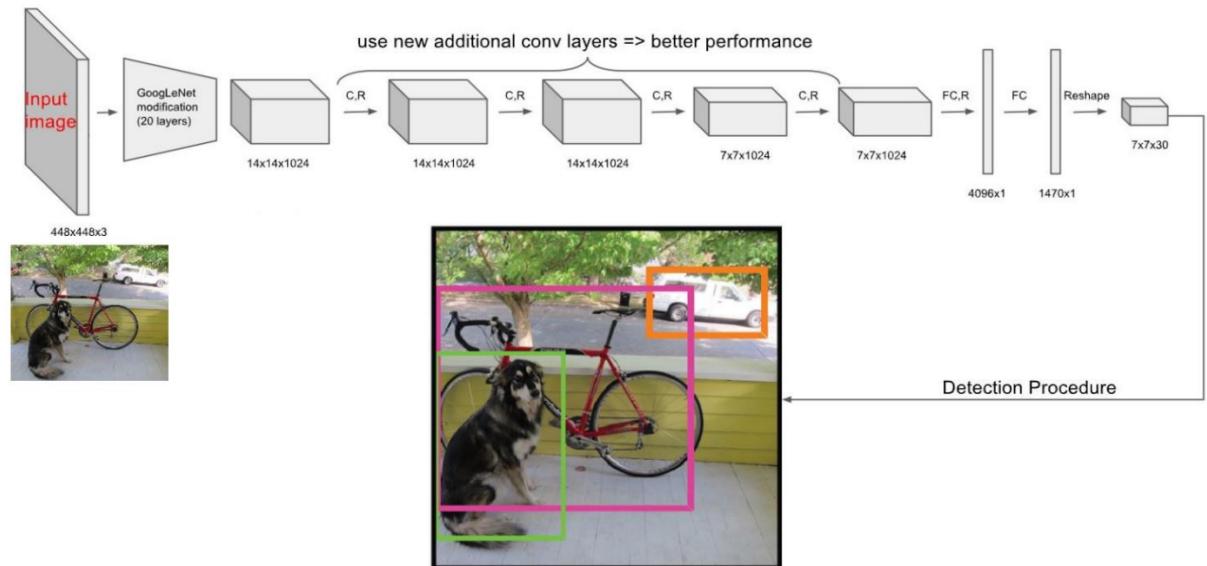


2. YOLO (You Only Look Once)

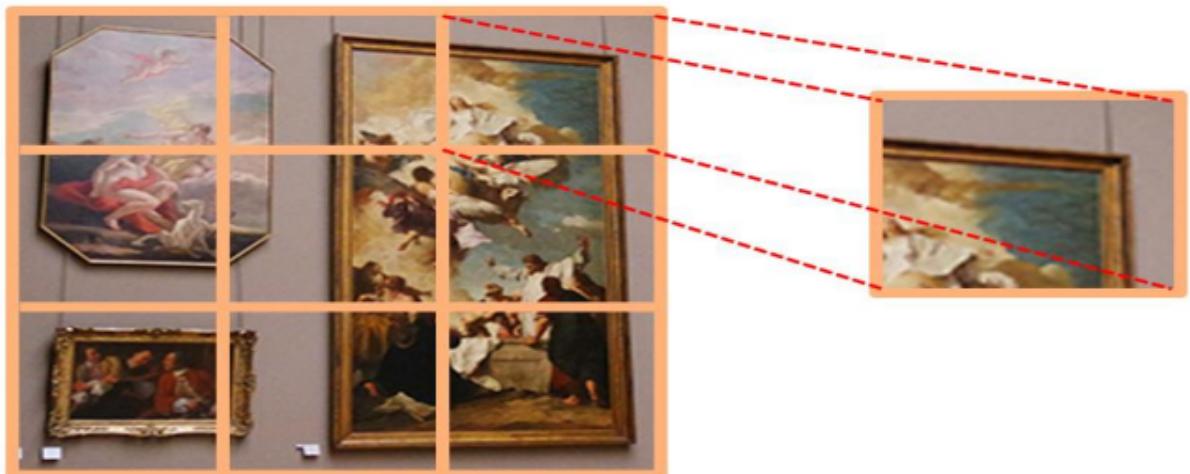
(1) two-shot-detection 개요

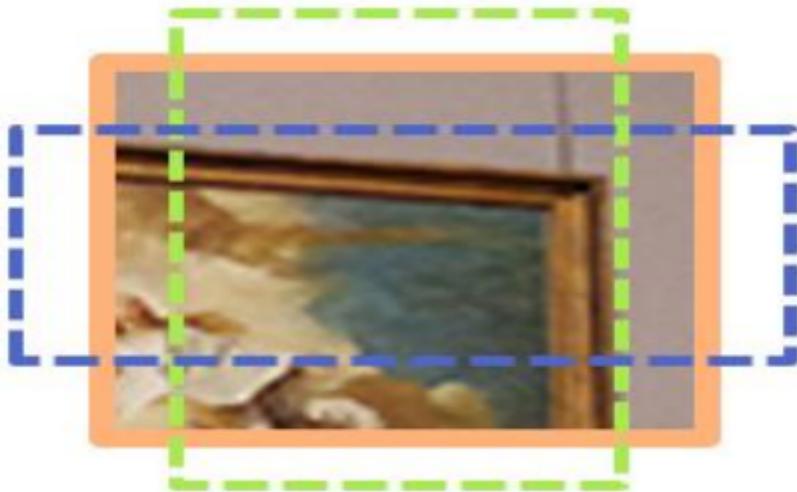


(2) one-shot-detection 개요(YOLO)



(3) grid cell, bounding box

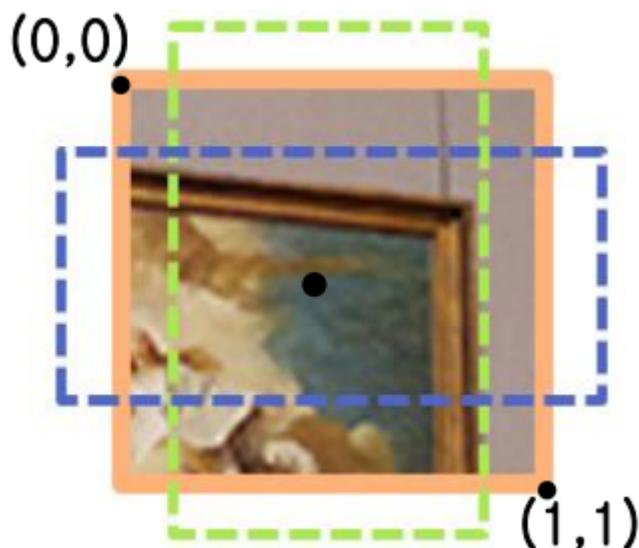




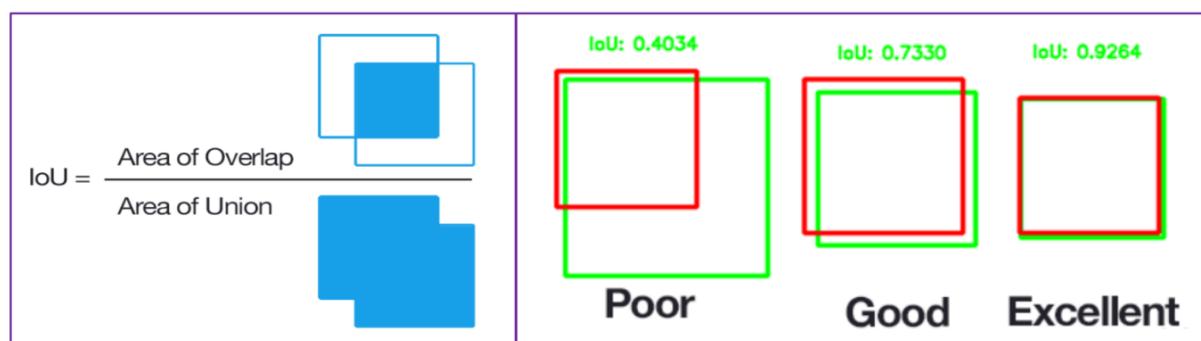
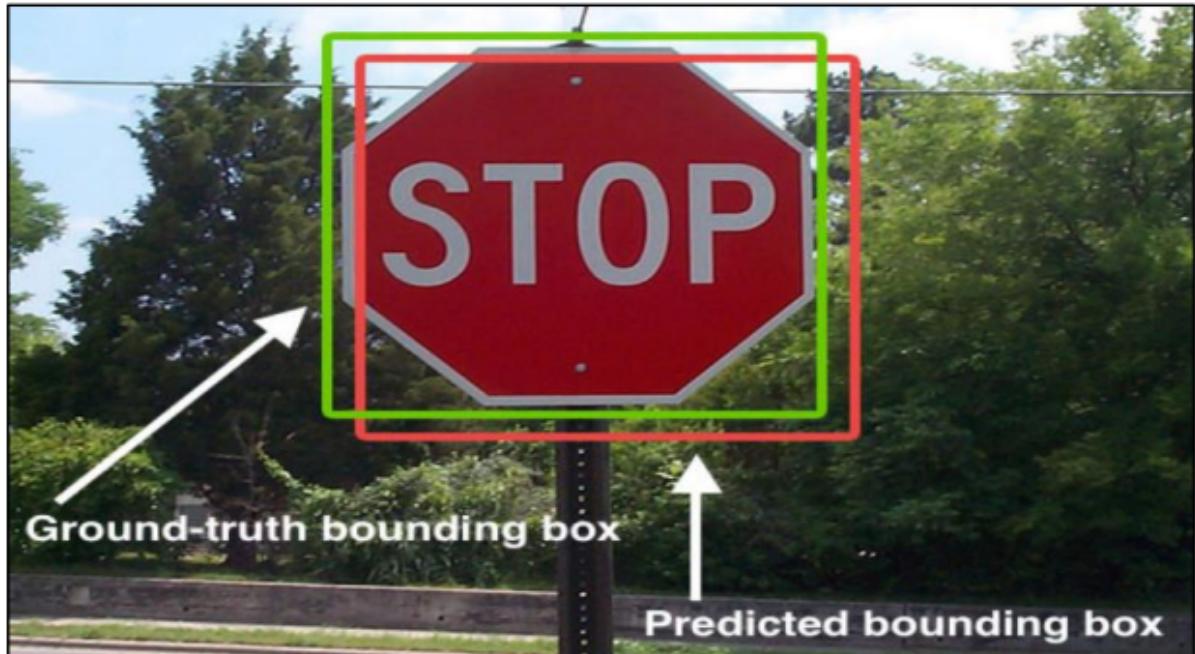
해당 그리드 셀에 물체가 존재할 확률

$$\text{confidence score} = \Pr(\text{Object}) * \text{IoU}_{\text{pred}}^{\text{truth}}$$

$$\text{conditional class probabilities} = \Pr(\text{Class}_i | \text{Object})$$



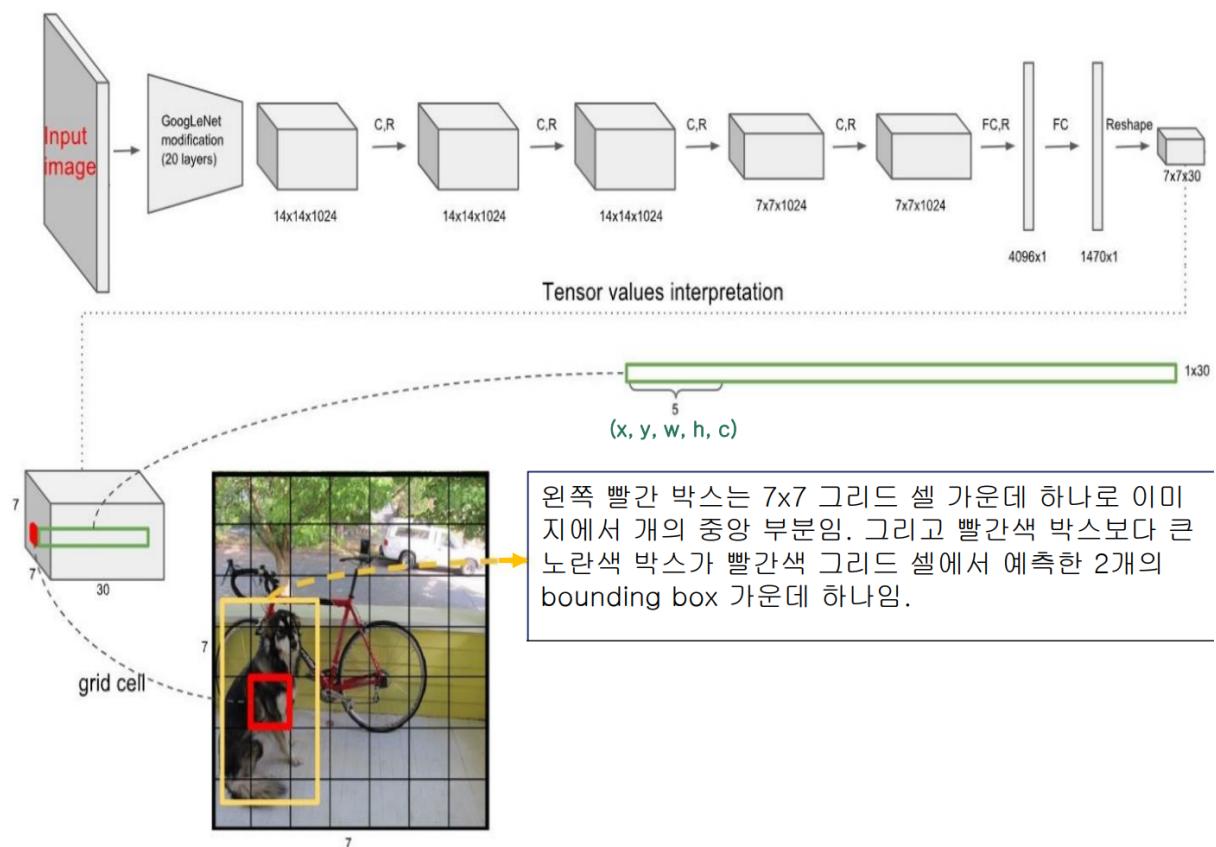
(4) ground-truth, IoU



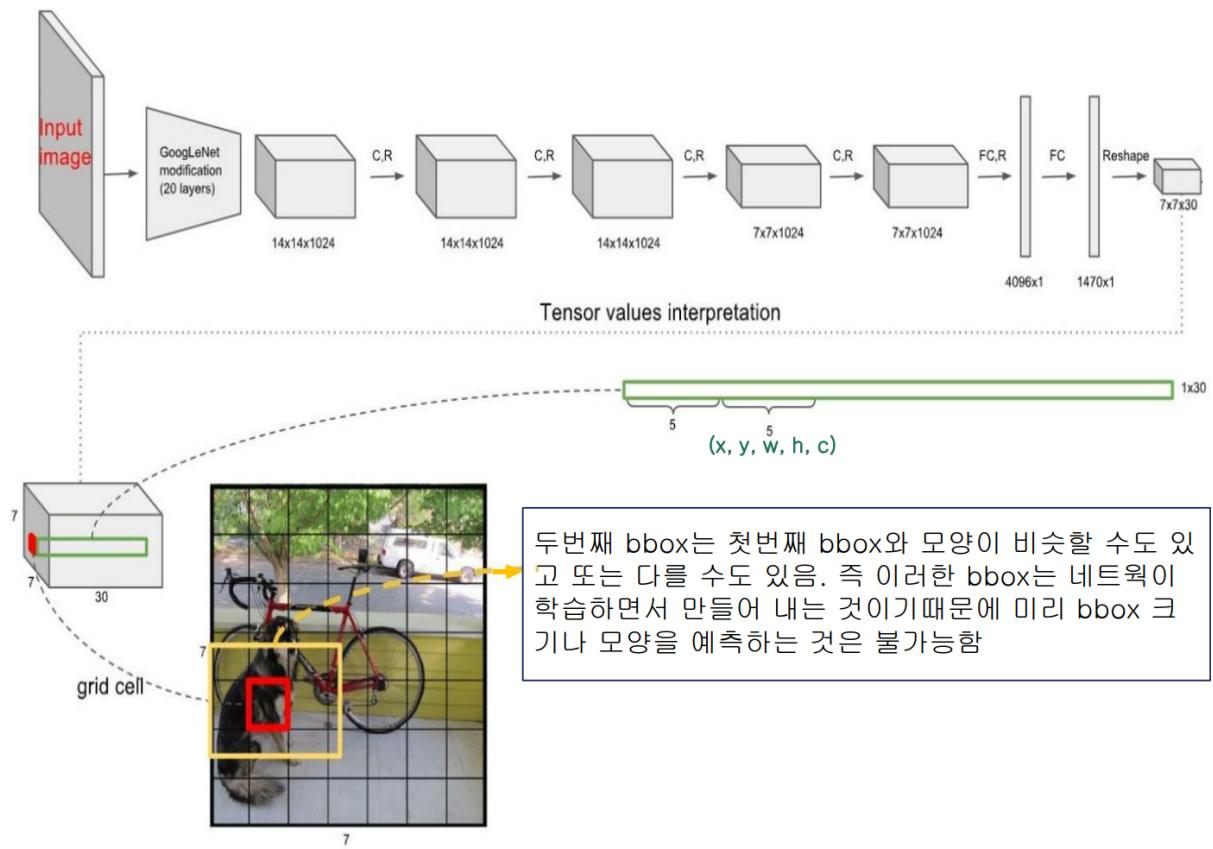
(5) YOLO Inference Process



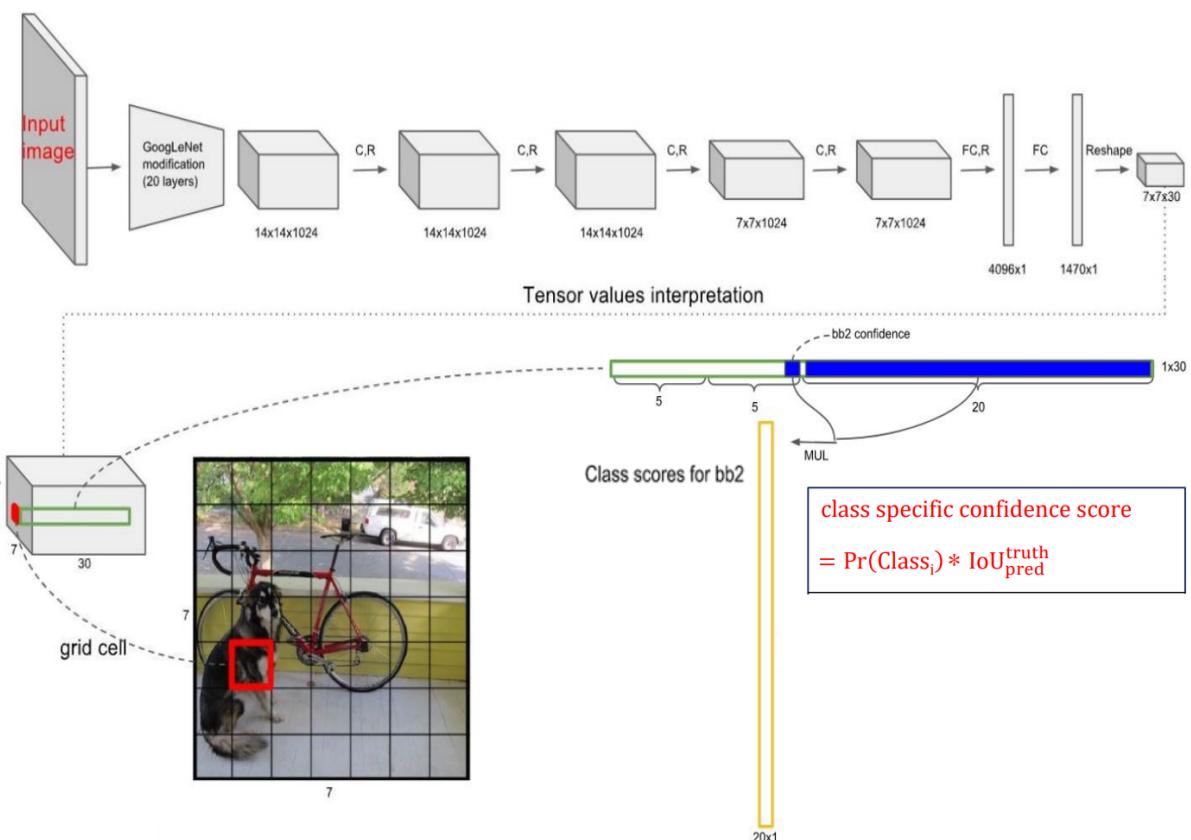
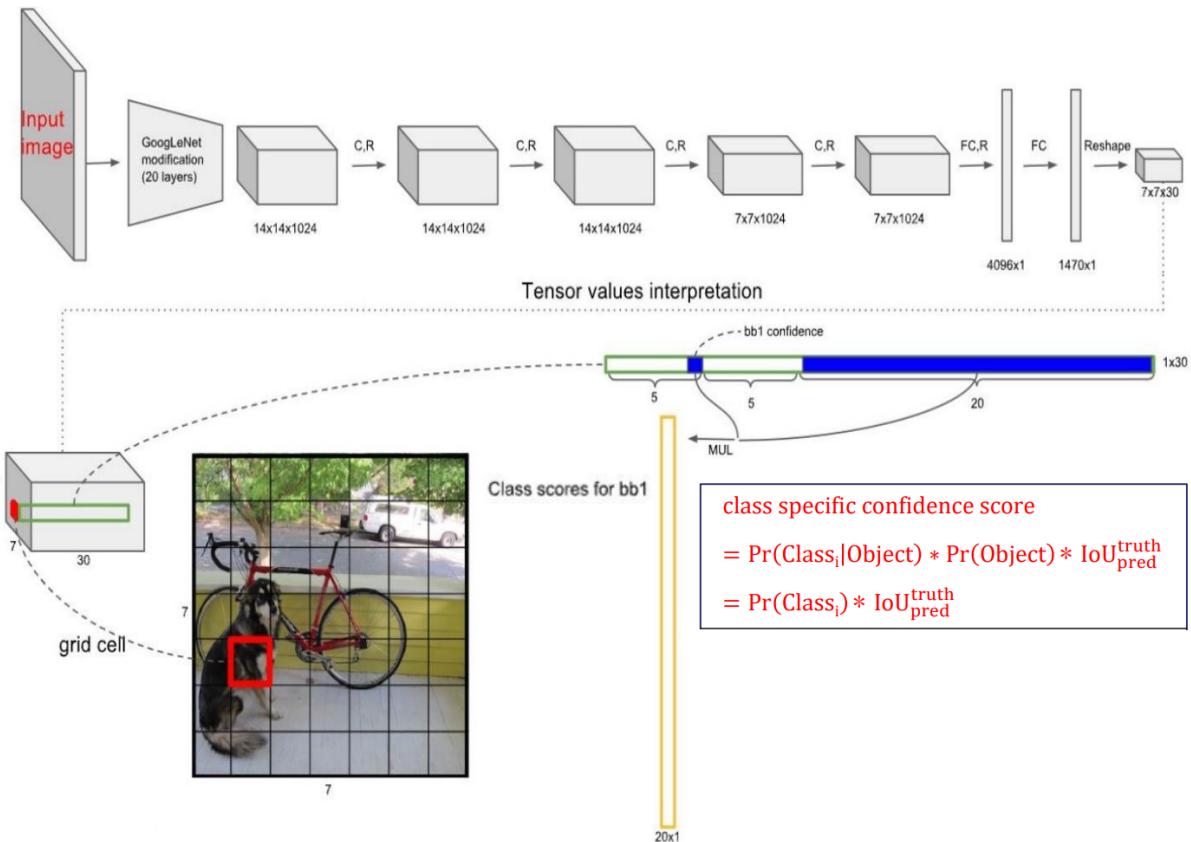
1) 1st bounding box of a grid cell

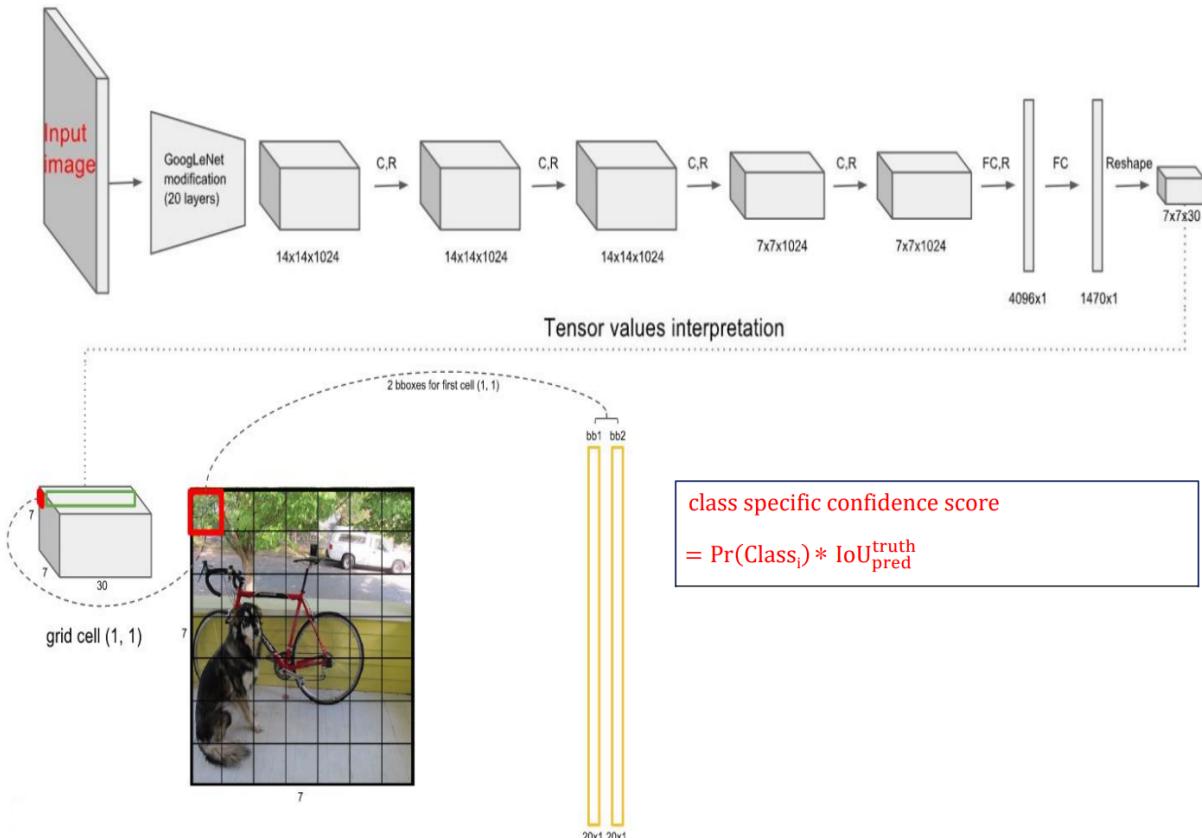


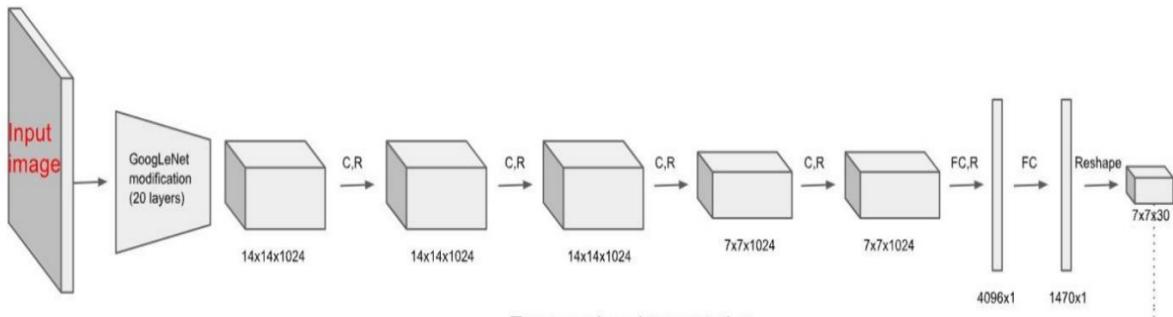
2) 2nd bounding box of a grid cell



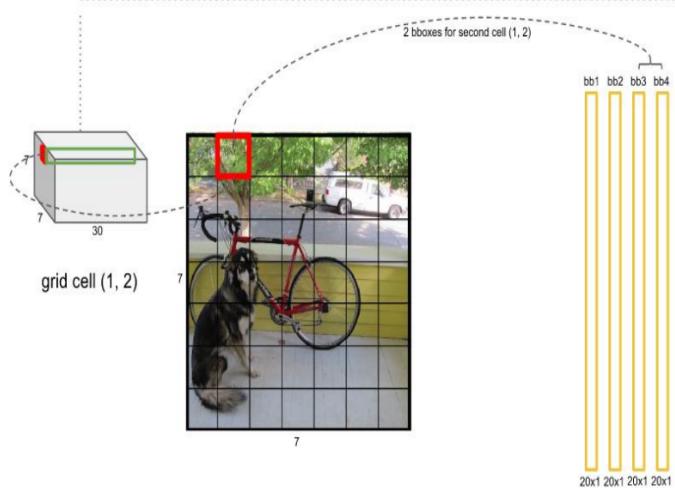
3) class specific confidence score







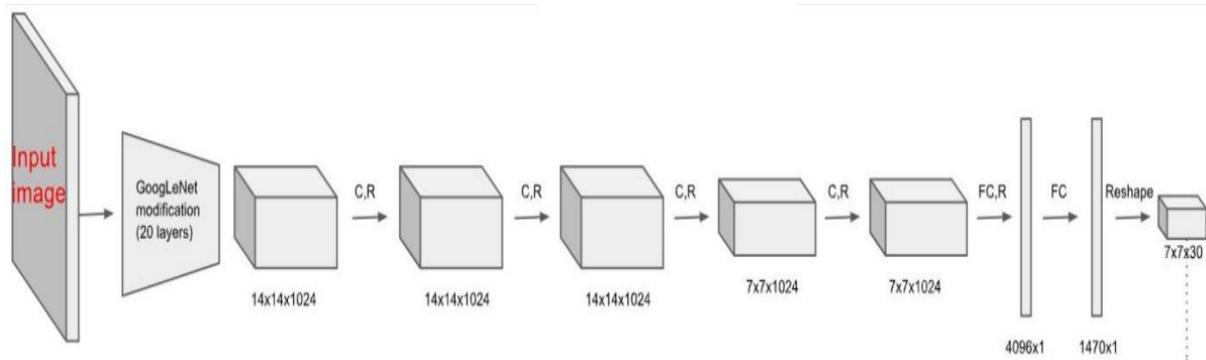
Tensor values interpretation



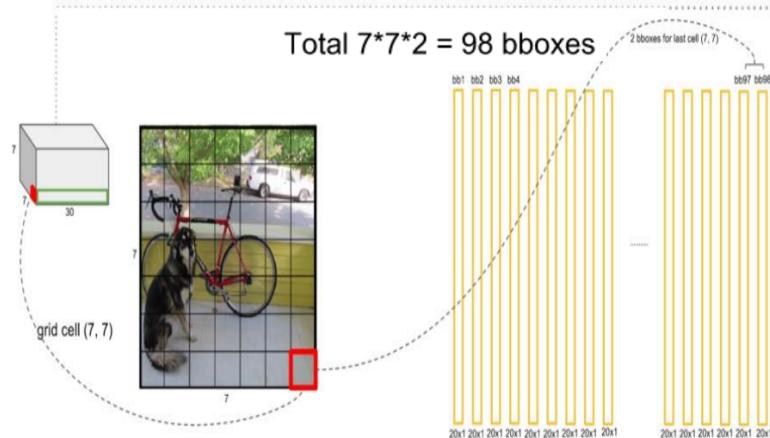
class specific confidence score

$$= \text{Pr}(\text{Class}_i) * \text{IoU}_{\text{pred}}^{\text{truth}}$$

두 번째 그리드 셀에서 두 개의 bbox에 대해서 class specific confidence score



Tensor values interpretation



98개 bbox 각각이 가지고 있는 class specific confidence score에 대해서 각 20개의 클래스, 즉 객체가 있을 확률 기준으로, 객체에 대해 신뢰도가 가장 높은 bbox만 남기고 나머지 bbox를 없애는 NMS (non-maximum suppression) 알고리즘을 이용하면, 객체에 대한 확률과 객체를 둘러싸고 있는 bbox 위치를 알아낼 수 있음.

4) NMS(Non-Maximum Suppression)

