

Modelling and quantifying mortality and longevity risk

Module C.2 on Statistical and machine learning methods for fine-grained mortality data

Katrien Antonio & Michel Vellekoop

September 18-19, 2025



UNIVERSITY
OF AMSTERDAM



In this module you will learn:

- pros and cons of using machine and deep learning methods for modelling mortality data
- how to specify a baseline model (of type Serfling) for short-term mortality
- how to use gradient boosting as a learning method to explore associations between short term mortality and a high-dimensional set of weather and pollution features.

Outline

Use of machine learning techniques in mortality modelling

Short-term mortality and environmental variables

Short-term association between environmental variables and mortality rates

Data

Model specification

Model calibration

Feature engineering

Calibration results

Insights in the machine-learning model

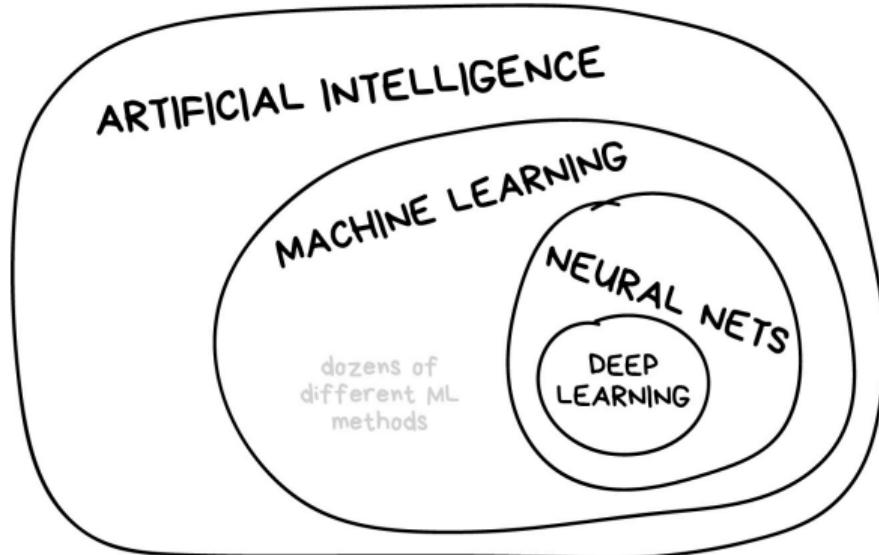
Wrap up

Use of machine learning techniques in mortality modelling

ML, DL and mortality modelling

In Module 6 on portfolio data we reflected on the use of machine or deep learning methods:

- for death counts $D_{x,t,g,\ell}$ under Poisson assumption, in the presence of risk factors or covariates \mathbf{x}_ℓ
- with techniques such as:
 - Random Forests (RFs)
 - Gradient Boosting Machines (GBMs)
 - Combined Actuarial Neural Networks (CANNs) with Artificial Neural Networks (ANNs) on top of e.g. GLM baseline.

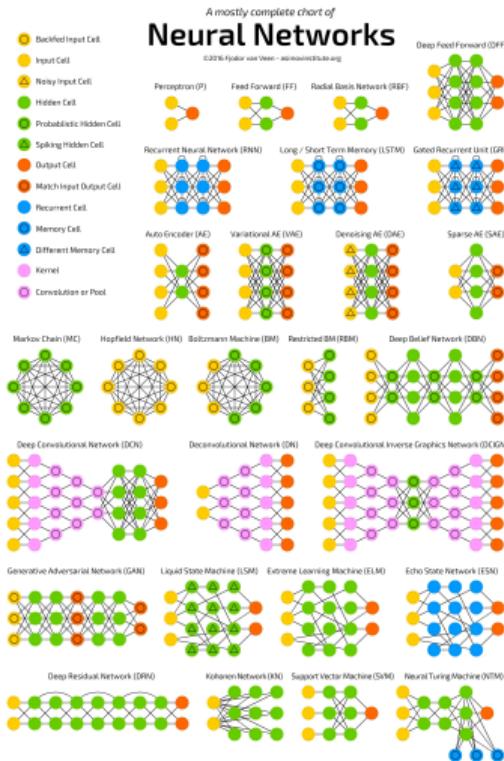


Picture taken from [Machine learning for everyone. In simple words. With real-world examples. Yes, again.](#)

Neural nets, DL and mortality modelling

(Deep) Feed-forward neural nets:

- as in Richman and Wüthrich [2021]
- with country, gender, age and year as input features
- Lee & Carter and Li & Lee revisited with a network version + its calibration (no hidden layers)
- deep feed-forward neural nets are explored as well
- focus on improving a loss function, residual plots, ...



Neural nets, DL and mortality modelling

(Deep) Recurrent neural nets (RNNs), Long short-term memory nets (LSTMs)

- as in [Lindholm and Palmborg \[2022\]](#), with focus on LSTM for the $\hat{\kappa}_t$'s
- as in [Perla et al. \[2021\]](#) where the $\mu_{x,t}^{(i)}$'s are modelled with (deep) RNNs and LSTMs for different populations (i) (i.e., genders and countries)
- as in [Euthum et al. \[2024\]](#) where the $\mu_{x,t}^{(i)}$'s are modelled with (deep) RNNs and LSTMs using inputs age, gender, year and deprivation group.

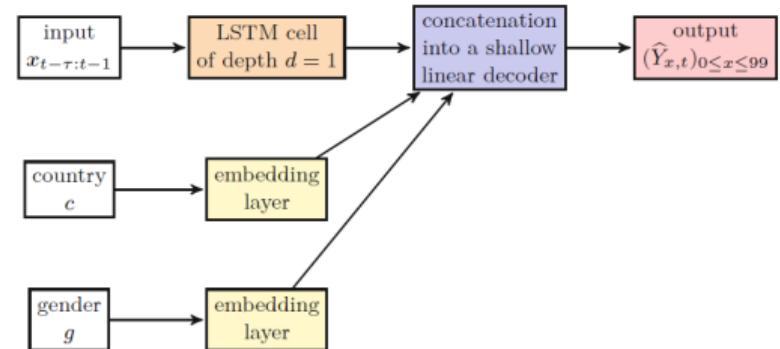


Fig. 8.13 LSTM architecture used to process the raw mortality rates $(M_{x,t})_{x,t}$

Picture from [Wüthrich and Merz \[2023\]](#).

Neural nets, DL and mortality modelling

(Deep) Convolutional neural nets (CNNs):

- as in Perla et al. [2021] where the $\mu_{x,t}^{(i)}$'s are modelled with CNN-type layers for the $\mu_{x,t}^{(i)}$'s, combined with input features gender and region for population (i)
- as in Wang et al. [2021] who use CNNs with as input a 2-dimensional 'image' around $\mu_{x,t}$ with mortality information for ages in $[x - x_1, x + x_2]$, lagging k years $1 \leq k \leq s$.

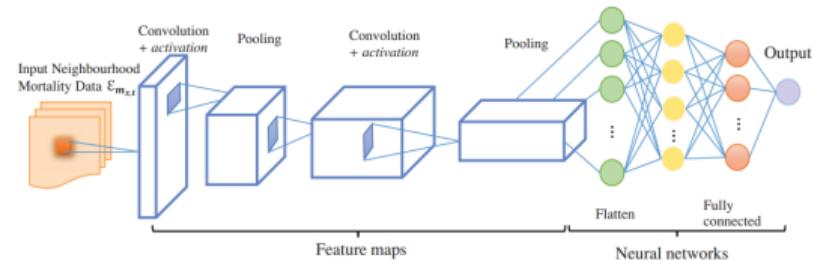


FIGURE 6: An illustrative CNN architecture in constructing neighbouring prediction models.

Today's approach

For details on analyzing mortality data with neural networks, we refer to:

- Lee and Carter go Machine Learning: Recurrent Neural Networks, a tutorial by the Swiss Actuarial Data Science working group
- the chapters on neural nets in Wüthrich and Merz [2023].

Today, we take a deep dive into a recent working paper by Jens, Katrien and Torsten:

- try to explain weekly death counts across European regions
- with a baseline Serfling model (e.g., alike EuroMoMo)
- combined with a (high-dimensional) set of weather and pollution features.

Short-term mortality and environmental variables

I will present today our JRSS A paper:

The association between environmental variables and short-term mortality: evidence from Europe

working paper on [arxiv](#), code on [GitHub](#), by Jens Robben (UvA, RCLR), Katrien Antonio and Torsten Kleinow (UvA, RCLR).

1. Identify the primary environmental factors contributing to the estimation of mortality deviations from a pre-defined baseline level.

1. Identify the primary environmental factors contributing to the estimation of mortality deviations from a pre-defined baseline level.
2. Investigate the marginal impact of an environmental factor on deviations from the mortality baseline level.

1. Identify the primary environmental factors contributing to the estimation of mortality deviations from a pre-defined baseline level.
2. Investigate the marginal impact of an environmental factor on deviations from the mortality baseline level.
3. Investigate how environmental factors interact when modelling mortality rates. Are there harvesting effects present?

1. Identify the primary environmental factors contributing to the estimation of mortality deviations from a pre-defined baseline level.
2. Investigate the marginal impact of an environmental factor on deviations from the mortality baseline level.
3. Investigate how environmental factors interact when modelling mortality rates. Are there harvesting effects present?
4. Quantify the added contribution of environmental factors when aggregating the resulting estimated weekly mortality rates on an annual or country-level basis.

Short-term association between environmental variables and mortality rates

Introduction

Plan of attack

Using fine-grained [open data](#), study the association between [environmental factors](#) and [weekly mortality rates](#) in European regions.

Introduction

Plan of attack

Using fine-grained [open data](#), study the association between [environmental factors](#) and [weekly mortality rates](#) in European regions.

Proposed framework:

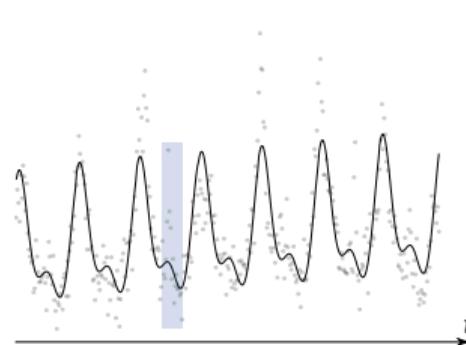
Introduction

Plan of attack

Using fine-grained [open data](#), study the association between [environmental factors](#) and [weekly mortality rates](#) in European regions.

Proposed framework:

1. a weekly, region-specific [baseline](#) mortality model to capture overall [seasonal](#) trends.



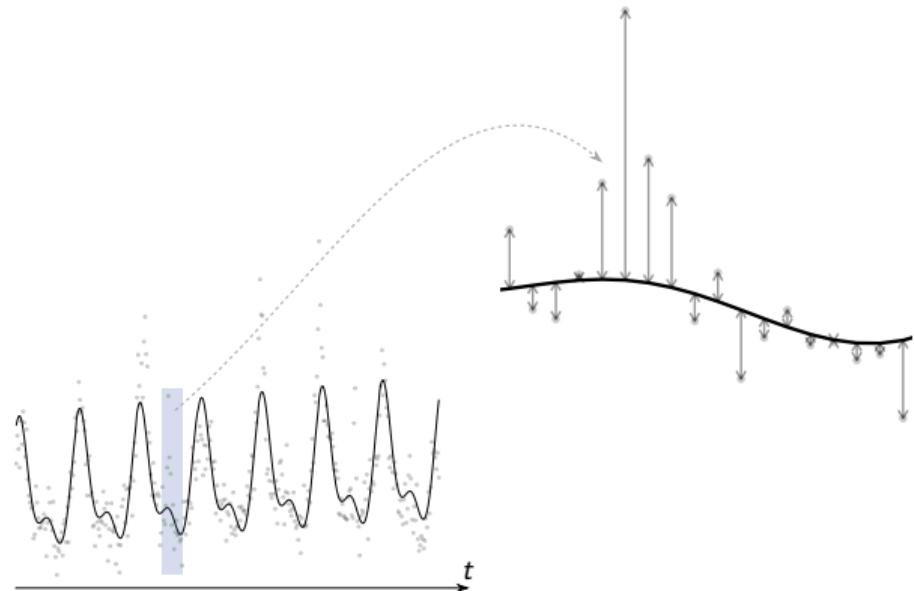
Introduction

Plan of attack

Using fine-grained **open data**, study the association between **environmental factors** and **weekly mortality rates** in European regions.

Proposed framework:

1. a weekly, region-specific **baseline** mortality model to capture overall **seasonal** trends.
2. a predictive model to analyze **mortality deviations** from the baseline model using region-specific environmental factors.



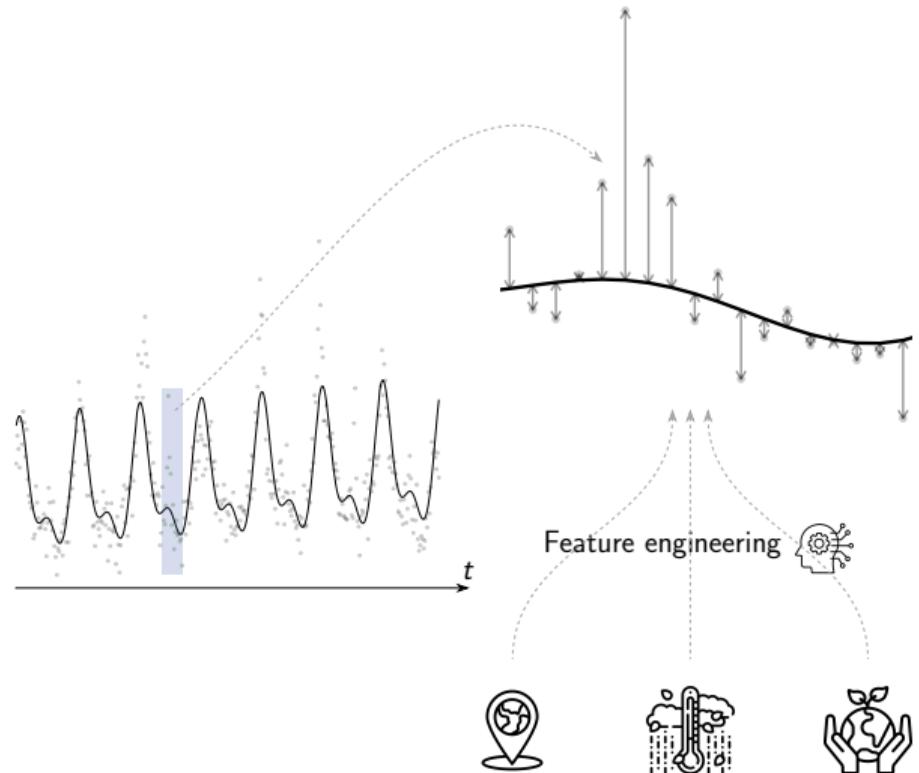
Introduction

Plan of attack

Using fine-grained **open data**, study the association between **environmental factors** and **weekly mortality rates** in European regions.

Proposed framework:

1. a weekly, region-specific **baseline** mortality model to capture overall **seasonal** trends.
2. a predictive model to analyze **mortality deviations** from the baseline model using region-specific environmental factors.



Data

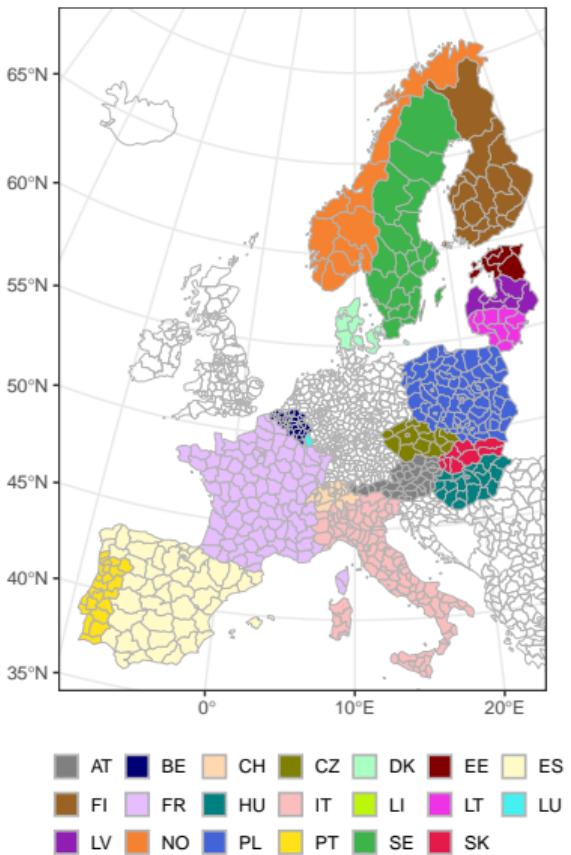
Death counts

Eurostat: deaths by week, gender, 5-year age group and NUTS 3 region from 20 European countries throughout the years 2013-2019 (> 500 regions).

Death counts

Eurostat: deaths by week, gender, 5-year age group and NUTS 3 region from 20 European countries throughout the years 2013-2019 (> 500 regions).

NUTS 3 regions

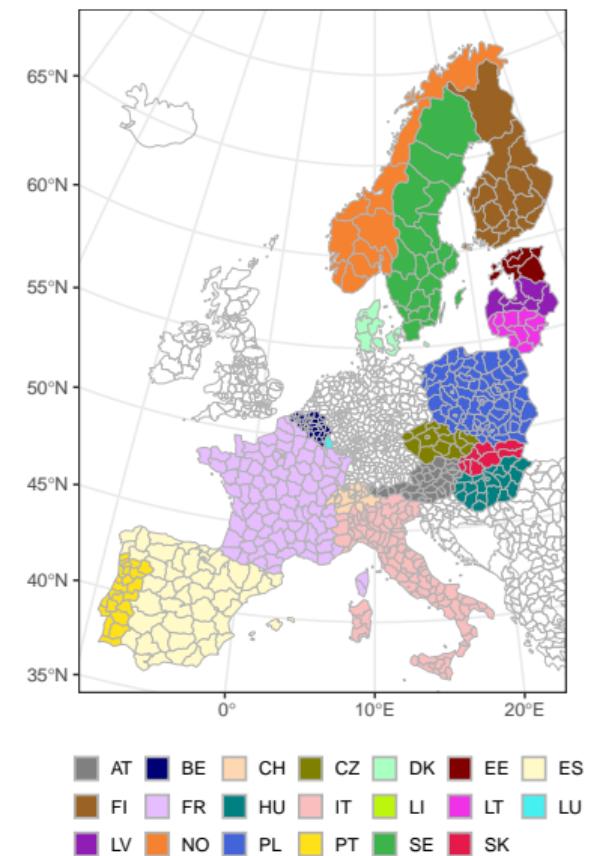


Death counts

Eurostat: deaths by week, gender, 5-year age group and NUTS 3 region from 20 European countries throughout the years 2013-2019 (> 500 regions).

Focus on old age group 65+, unisex.

NUTS 3 regions

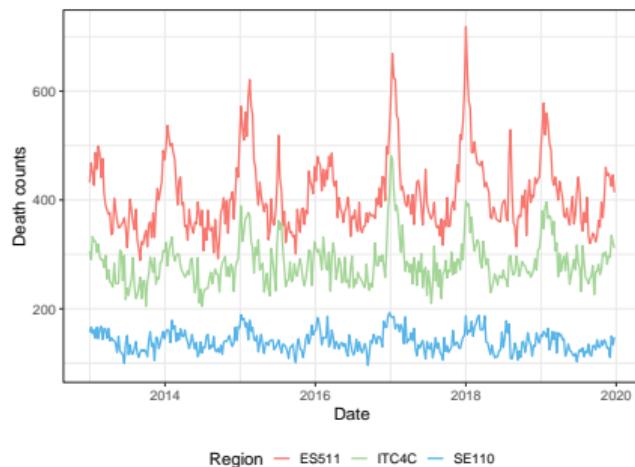


Death counts

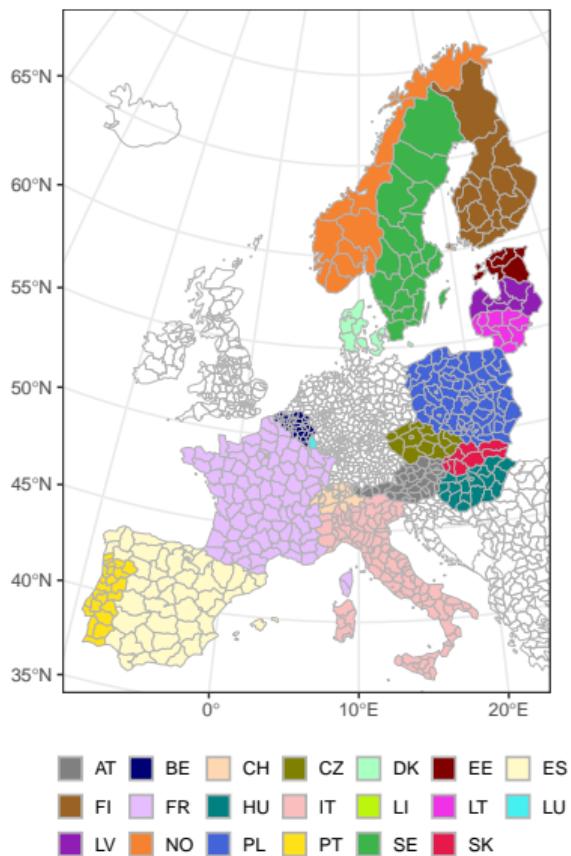
Eurostat: deaths by week, gender, 5-year age group and NUTS 3 region from 20 European countries throughout the years 2013-2019 (> 500 regions).

Focus on old age group 65+, unisex.

Seasonal trend:



NUTS 3 regions



Weather data

E-OBS land-only, gridded meteorological data for Europe from the Copernicus Climate Data Store.

Weather data

E-OBS land-only, gridded meteorological data for Europe from the Copernicus Climate Data Store.

Daily, high-resolution gridded dataset, defined on a grid with a spatial resolution of 0.10° (≈ 9 km).

Weather data

E-OBS land-only, gridded meteorological data for Europe from the Copernicus Climate Data Store.

Daily, high-resolution gridded dataset, defined on a grid with a spatial resolution of 0.10° (≈ 9 km).

Weather factors:

Tmax: daily maximum temperature

Tmin: daily minimum temperature

Hum: daily average relative humidity

Rain: total daily precipitation

Wind: daily average wind speed

Weather data

E-OBS land-only, gridded meteorological data for Europe from the Copernicus Climate Data Store.

Daily, high-resolution gridded dataset, defined on a grid with a spatial resolution of 0.10° (≈ 9 km).

Weather factors:

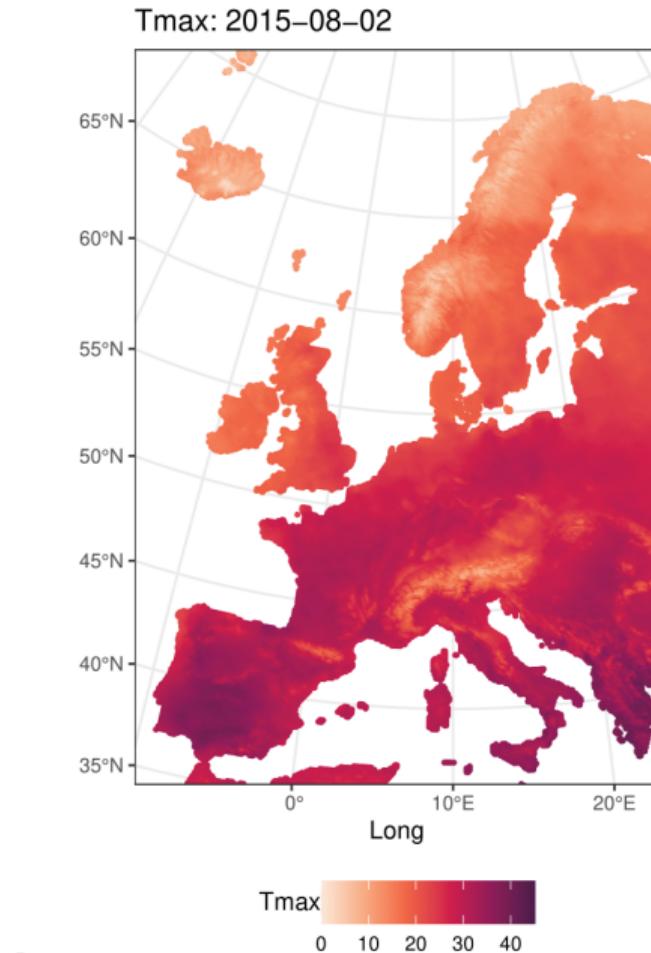
Tmax: daily maximum temperature

Tmin: daily minimum temperature

Hum: daily average relative humidity

Rain: total daily precipitation

Wind: daily average wind speed



Weather data

E-OBS land-only, gridded meteorological data for Europe from the Copernicus Climate Data Store.

Daily, high-resolution gridded dataset, defined on a grid with a spatial resolution of 0.10° (≈ 9 km).

Weather factors:

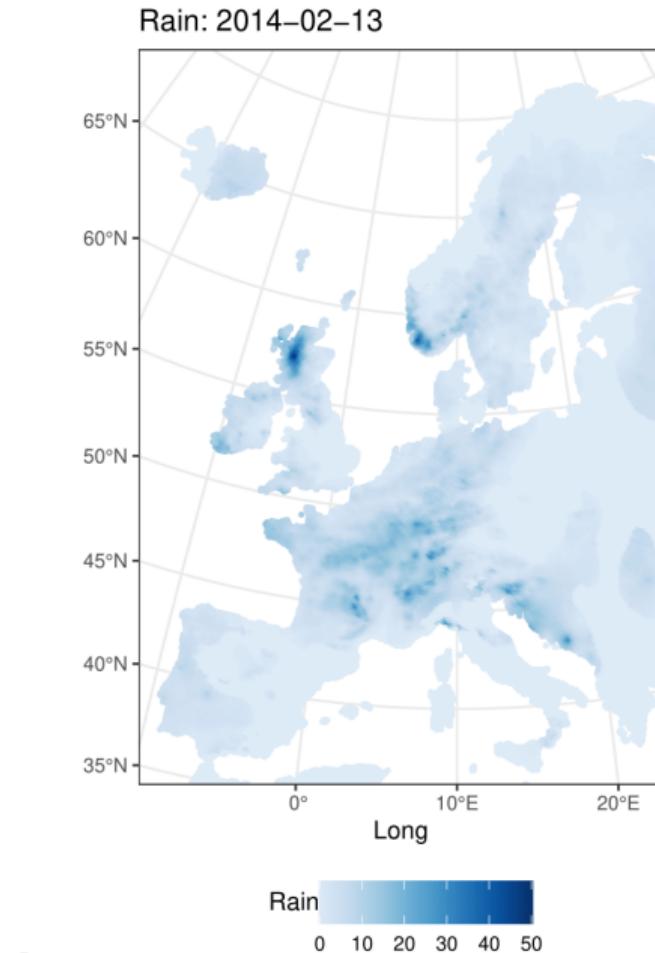
Tmax: daily maximum temperature

Tmin: daily minimum temperature

Hum: daily average relative humidity

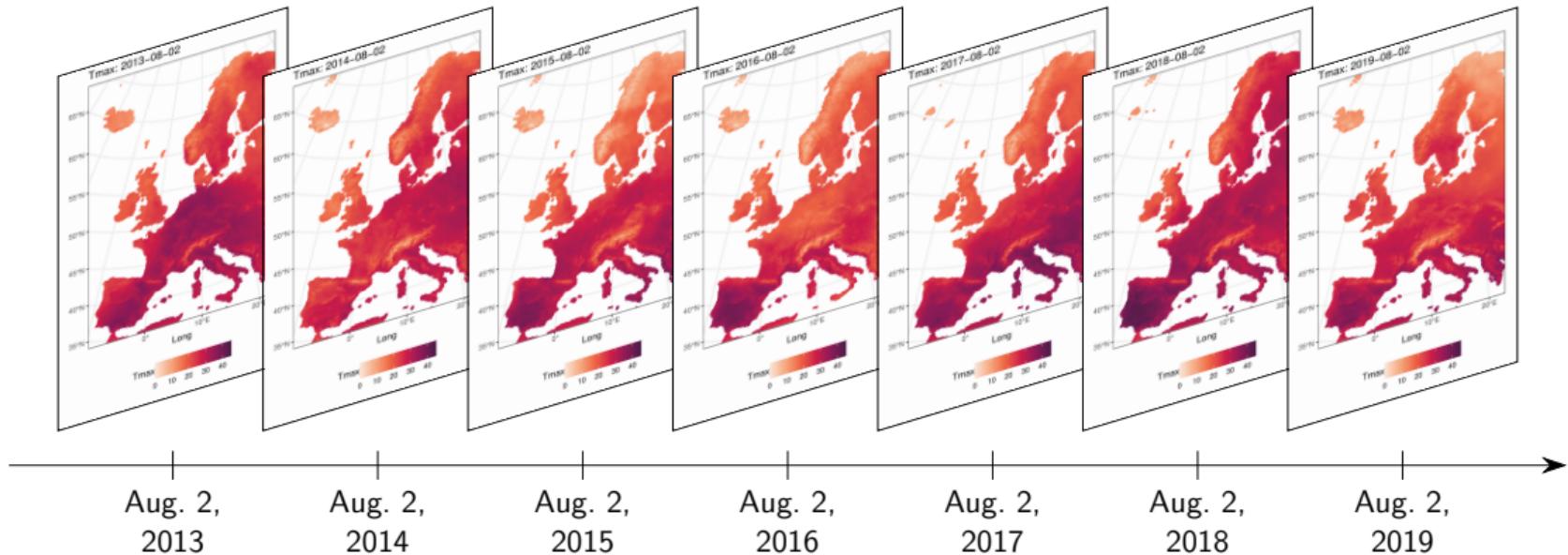
Rain: total daily precipitation

Wind: daily average wind speed



Weather data

14



Air pollution data

CAMS [European air quality reanalyses](#) dataset from the Copernicus Atmosphere Monitoring Service (land + sea).

Air pollution data

CAMS [European air quality reanalyses](#) dataset from the Copernicus Atmosphere Monitoring Service (land + sea).

[Hourly](#), high-resolution air quality reanalyses, defined on a grid with a [spatial resolution of \$0.10^\circ\$](#) (≈ 9 km).

Air pollution data

CAMS European air quality reanalyses dataset from the Copernicus Atmosphere Monitoring Service (land + sea).

Hourly, high-resolution air quality reanalyses, defined on a grid with a spatial resolution of 0.10° (≈ 9 km).

Air pollutants ($\mu\text{g}/\text{m}^3$):

O₃: hourly ozone levels.

N_O2: hourly nitrogen dioxide levels.

PM10: hourly particular matter (10 microns wide).

PM2.5: hourly particular matter (2.5 microns wide).

Air pollution data

CAMS [European air quality reanalyses](#) dataset from the Copernicus Atmosphere Monitoring Service (land + sea).

[Hourly](#), high-resolution air quality reanalyses, defined on a grid with a [spatial resolution of \$0.10^\circ\$](#) ($\approx 9 \text{ km}$).

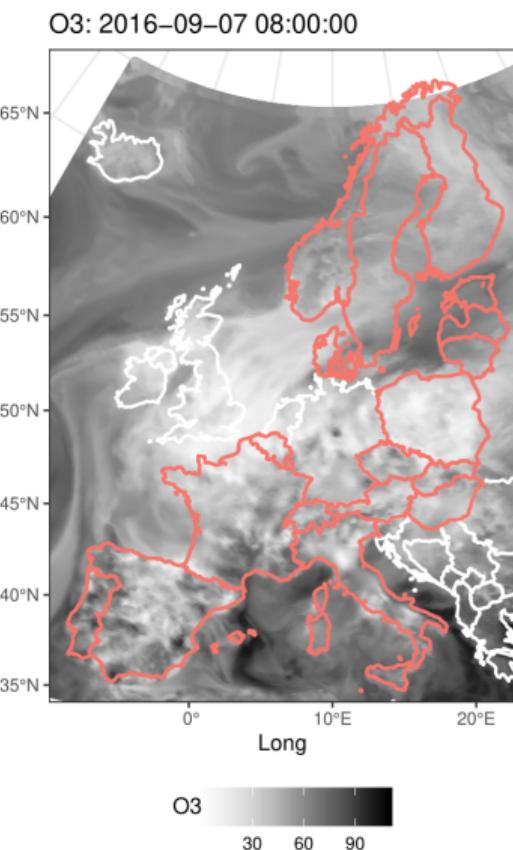
Air pollutants ($\mu\text{g}/\text{m}^3$):

O3: hourly ozone levels.

N02: hourly nitrogen dioxide levels.

PM10: hourly particular matter (10 microns wide).

PM2.5: hourly particular matter (2.5 microns wide).



Air pollution data

CAMS [European air quality reanalyses](#) dataset from the Copernicus Atmosphere Monitoring Service (land + sea).

[Hourly](#), high-resolution air quality reanalyses, defined on a grid with a [spatial resolution of \$0.10^\circ\$](#) ($\approx 9 \text{ km}$).

Air pollutants ($\mu\text{g}/\text{m}^3$):

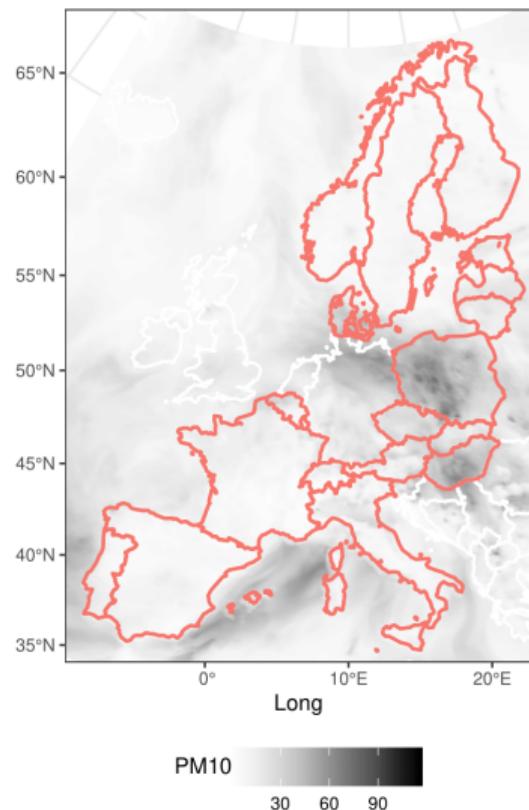
O3: hourly ozone levels.

NO2: hourly nitrogen dioxide levels.

PM10: hourly particular matter (10 microns wide).

PM2.5: hourly particular matter (2.5 microns wide).

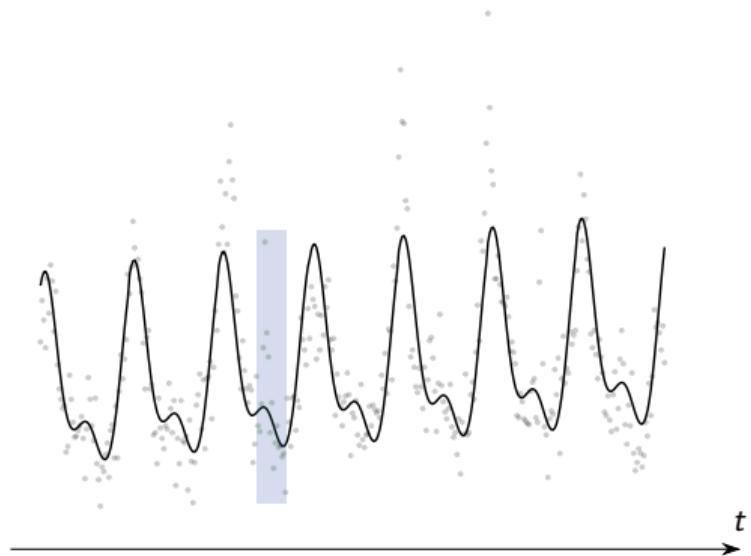
PM10: 2019-02-01 10:00:00



Model specification

Weekly, region-specific baseline mortality model

A weekly, region-specific baseline mortality model to capture the overall seasonal trends in the considered regions.



Weekly, region-specific baseline mortality model

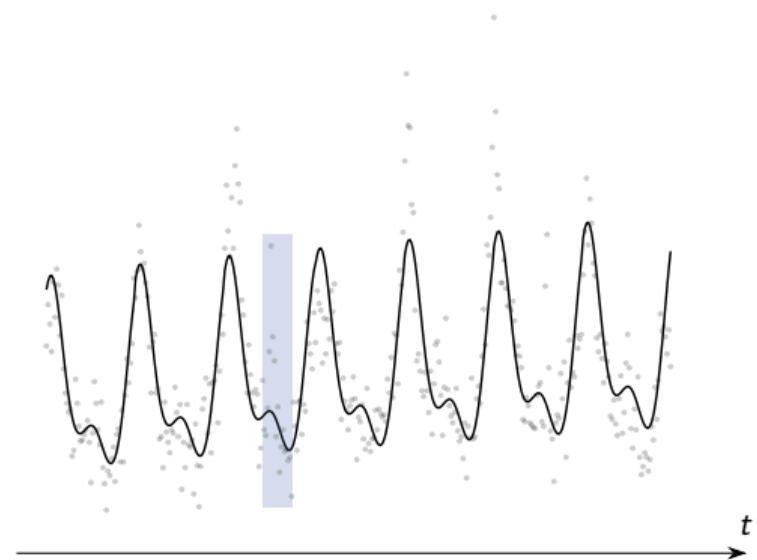
A weekly, region-specific baseline mortality model to capture the overall seasonal trends in the considered regions.

Incorporate seasonality through Fourier terms

Serfling [1963]:

$$D_{t,w}^{(r)} \sim \text{Poisson} \left(E_{t,w}^{(r)} \cdot \mu_{t,w}^{(r)} \right),$$

$$\log \mu_{t,w}^{(r)} = \beta_0^{(r)} + \beta_1^{(r)} t + \beta_2^{(r)} \sin \left(\frac{2\pi w}{52} \right) + \beta_3^{(r)} \cos \left(\frac{2\pi w}{52} \right) + \\ \beta_4^{(r)} \sin \left(\frac{2\pi w}{26} \right) + \beta_5^{(r)} \cos \left(\frac{2\pi w}{26} \right).$$



Weekly, region-specific baseline mortality model

A weekly, region-specific baseline mortality model to capture the overall seasonal trends in the considered regions.

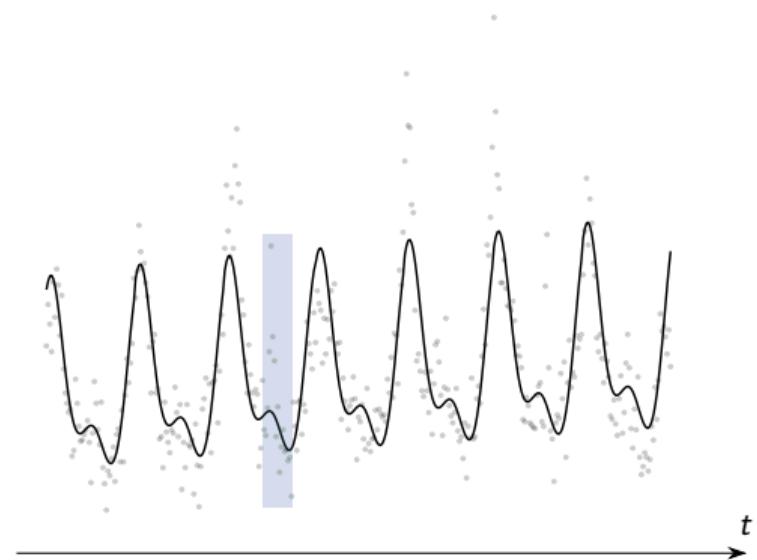
Incorporate seasonality through Fourier terms

Serfling [1963]:

$$D_{t,w}^{(r)} \sim \text{Poisson} \left(E_{t,w}^{(r)} \cdot \mu_{t,w}^{(r)} \right),$$

$$\log \mu_{t,w}^{(r)} = \beta_0^{(r)} + \beta_1^{(r)} t + \beta_2^{(r)} \sin \left(\frac{2\pi w}{52} \right) + \beta_3^{(r)} \cos \left(\frac{2\pi w}{52} \right) + \\ \beta_4^{(r)} \sin \left(\frac{2\pi w}{26} \right) + \beta_5^{(r)} \cos \left(\frac{2\pi w}{26} \right).$$

Region-specific population exposures $E_{t,w}^{(r)}$ from Eurostat.



Weekly, region-specific baseline mortality model

A weekly, region-specific baseline mortality model to capture the overall seasonal trends in the considered regions.

Incorporate seasonality through Fourier terms

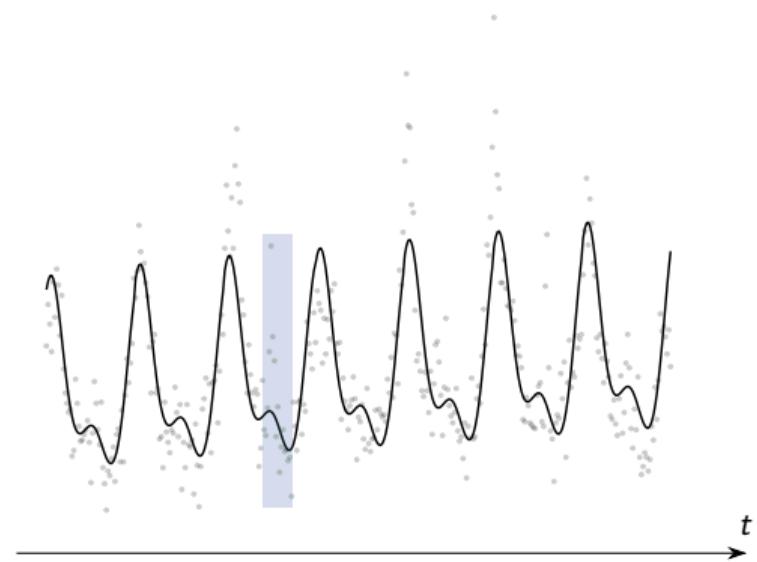
Serfling [1963]:

$$D_{t,w}^{(r)} \sim \text{Poisson} \left(E_{t,w}^{(r)} \cdot \mu_{t,w}^{(r)} \right),$$

$$\log \mu_{t,w}^{(r)} = \beta_0^{(r)} + \beta_1^{(r)} t + \beta_2^{(r)} \sin \left(\frac{2\pi w}{52} \right) + \beta_3^{(r)} \cos \left(\frac{2\pi w}{52} \right) + \\ \beta_4^{(r)} \sin \left(\frac{2\pi w}{26} \right) + \beta_5^{(r)} \cos \left(\frac{2\pi w}{26} \right).$$

Region-specific population exposures $E_{t,w}^{(r)}$ from Eurostat.

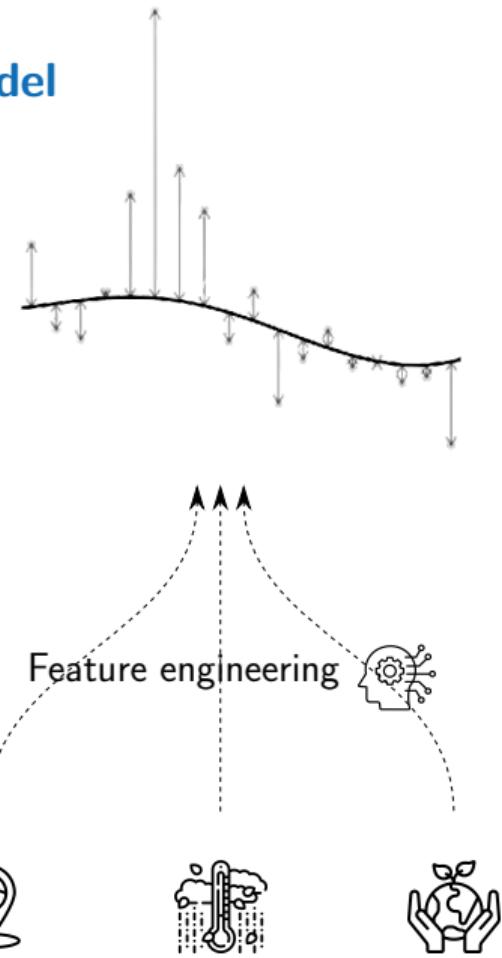
Estimated baseline death counts: $\hat{b}_{t,w}^{(r)} := E_{t,w}^{(r)} \cdot \hat{\mu}_{t,w}^{(r)}$.



Modelling mortality deviations from the baseline model

17

Explain observed deviations from the baseline deaths using region-specific environmental features.



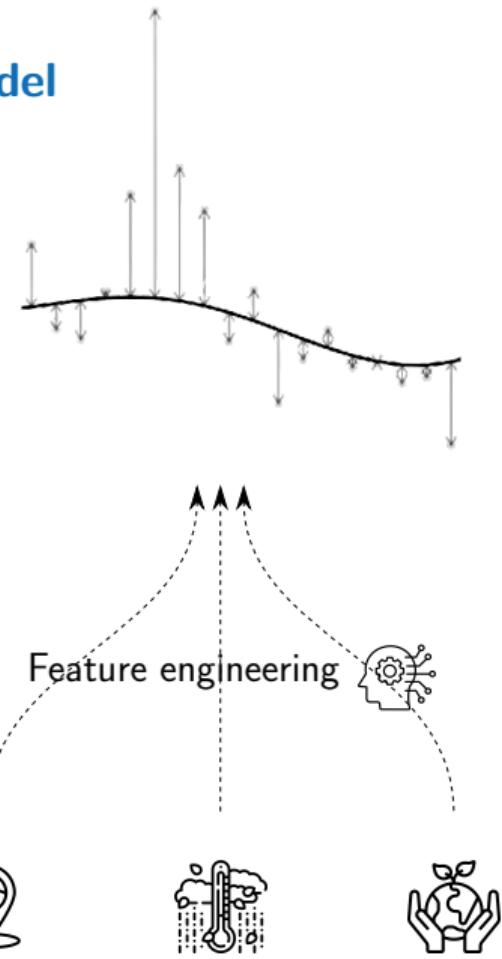
Modelling mortality deviations from the baseline model

Explain observed deviations from the baseline deaths using region-specific environmental features.

Fix estimated baseline deaths and impose distributional assumption:

$$D_{t,w}^{(r)} \sim \text{Poisson} \left(\hat{b}_{t,w}^{(r)} \phi_{t,w}^{(r)} \right),$$

$$\phi_{t,w}^{(r)} = f \left(\text{long}^{(r)}, \text{lat}^{(r)}, \text{season}_{t,w}, \mathbf{c}_{t,w}^{(r)}, \mathbf{e}_{t,w}^{(r)}, I^1 \left(\mathbf{c}_{t,w}^{(r)} \right), I^1 \left(\mathbf{e}_{t,w}^{(r)} \right), \dots, I^s \left(\mathbf{c}_{t,w}^{(r)} \right), I^s \left(\mathbf{e}_{t,w}^{(r)} \right) \right).$$



Modelling mortality deviations from the baseline model

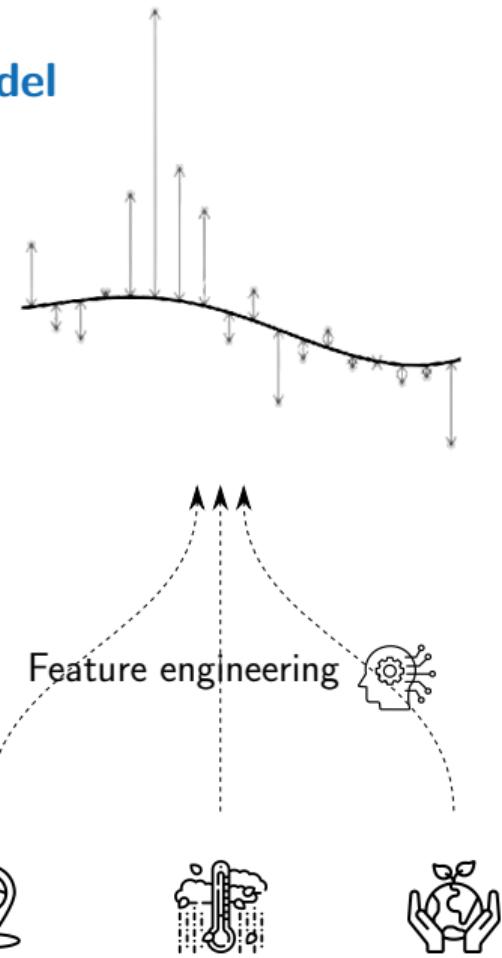
Explain observed deviations from the baseline deaths using region-specific environmental features.

Fix estimated baseline deaths and impose distributional assumption:

$$D_{t,w}^{(r)} \sim \text{Poisson} \left(\hat{b}_{t,w}^{(r)} \phi_{t,w}^{(r)} \right),$$

$$\phi_{t,w}^{(r)} = f \left(\text{long}^{(r)}, \text{lat}^{(r)}, \text{season}_{t,w}, \mathbf{c}_{t,w}^{(r)}, \mathbf{e}_{t,w}^{(r)}, I^1 \left(\mathbf{c}_{t,w}^{(r)} \right), I^1 \left(\mathbf{e}_{t,w}^{(r)} \right), \dots, I^s \left(\mathbf{c}_{t,w}^{(r)} \right), I^s \left(\mathbf{e}_{t,w}^{(r)} \right) \right).$$

$f(\cdot)$ is a selected predictive modelling technique.



Modelling mortality deviations from the baseline model

Explain observed deviations from the baseline deaths using region-specific environmental features.

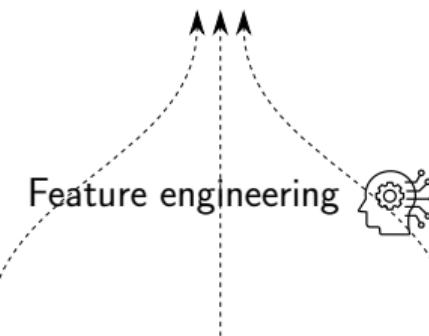
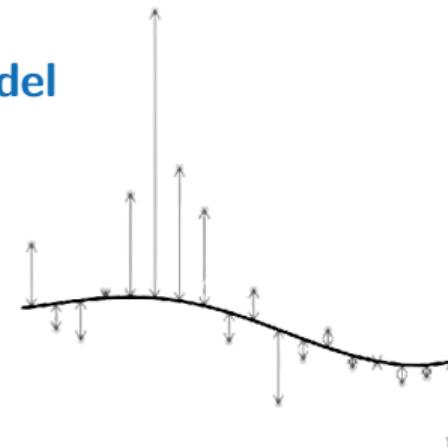
Fix estimated baseline deaths and impose distributional assumption:

$$D_{t,w}^{(r)} \sim \text{Poisson} \left(\hat{b}_{t,w}^{(r)} \phi_{t,w}^{(r)} \right),$$

$$\phi_{t,w}^{(r)} = f \left(\text{long}^{(r)}, \text{lat}^{(r)}, \text{season}_{t,w}, \mathbf{c}_{t,w}^{(r)}, \mathbf{e}_{t,w}^{(r)}, I^1 \left(\mathbf{c}_{t,w}^{(r)} \right), I^1 \left(\mathbf{e}_{t,w}^{(r)} \right), \dots, I^s \left(\mathbf{c}_{t,w}^{(r)} \right), I^s \left(\mathbf{e}_{t,w}^{(r)} \right) \right).$$

$f(\cdot)$ is a selected predictive modelling technique.

We opt for a machine learning model.



Model calibration

Fit a [Poisson GLM](#) jointly across all regions,
add a smoothness penalty:

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \left(-\log \mathcal{L}_P(\boldsymbol{\beta}) + \sum_{p=0}^5 \lambda_p \boldsymbol{\beta}_p^T \mathbf{S} \boldsymbol{\beta}_p \right),$$

Fit a Poisson GLM jointly across all regions,
add a smoothness penalty:

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \left(-\log \mathcal{L}_P(\beta) + \sum_{p=0}^5 \lambda_p \beta_p^T \mathbf{S} \beta_p \right),$$

where:

β : parameter vector

$\log \mathcal{L}_P(\beta)$: Poisson log-likelihood

$\beta_p^T \mathbf{S} \beta_p$: penalizes sum of squared differences
between coefs of adjacent regions

λ_p : smoothing or penalty parameter.

Calibrating the baseline model

Fit a [Poisson GLM](#) jointly across all regions, add a smoothness penalty:

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \left(-\log \mathcal{L}_P(\beta) + \sum_{p=0}^5 \lambda_p \beta_p^T \mathbf{S} \beta_p \right),$$

where:

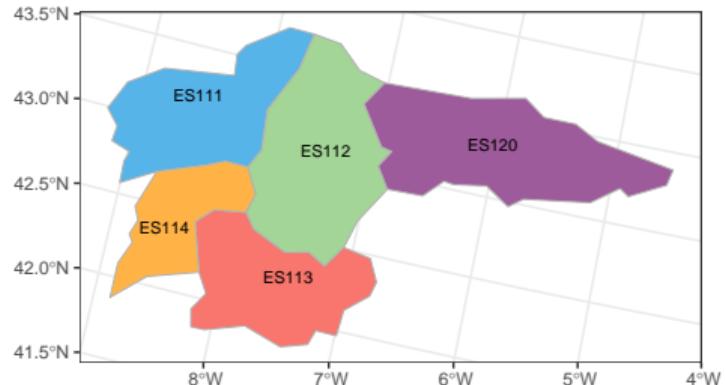
β : parameter vector

$\log \mathcal{L}_P(\beta)$: Poisson log-likelihood

$\beta_p^T \mathbf{S} \beta_p$: penalizes sum of squared differences between coefs of adjacent regions

λ_p : smoothing or penalty parameter.

Example (5 Spanish NUTS 3 regions):



Calibrating the baseline model

Fit a [Poisson GLM](#) jointly across all regions, add a smoothness penalty:

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \left(-\log \mathcal{L}_P(\beta) + \sum_{p=0}^5 \lambda_p \beta_p^T S \beta_p \right),$$

where:

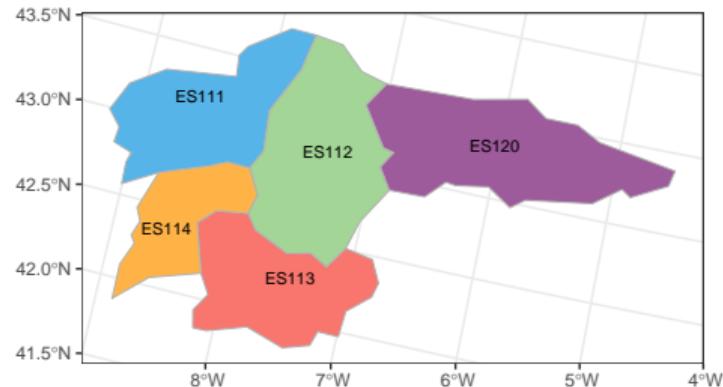
β : parameter vector

$\log \mathcal{L}_P(\beta)$: Poisson log-likelihood

$\beta_p^T S \beta_p$: penalizes sum of squared differences between coefs of adjacent regions

λ_p : smoothing or penalty parameter.

Example (5 Spanish NUTS 3 regions):



Penalty matrix S :

	ES111	ES112	ES113	ES114	ES120
ES111	2	-1	0	-1	0
ES112	-1	4	-1	-1	-1
ES113	0	-1	2	-1	0
ES114	-1	-1	-1	3	0
ES120	0	-1	0	0	1

Calibrating the mortality deviations model

XGBoost: flexible and efficient implementation of gradient boosting.

Calibrating the mortality deviations model

XGBoost: flexible and efficient implementation of gradient boosting.

Tuning parameters:

`nrounds`: number of boosting iterations.

`eta`: learning rate.

`max_depth`: the maximum depth of a tree.

`subsample`: subsample ratio of the training data.

`colsample_bytree`: subsample ratio of the features.

Calibrating the mortality deviations model

XGBoost: flexible and efficient implementation of gradient boosting.

Tuning parameters:

`nrounds`: number of boosting iterations.

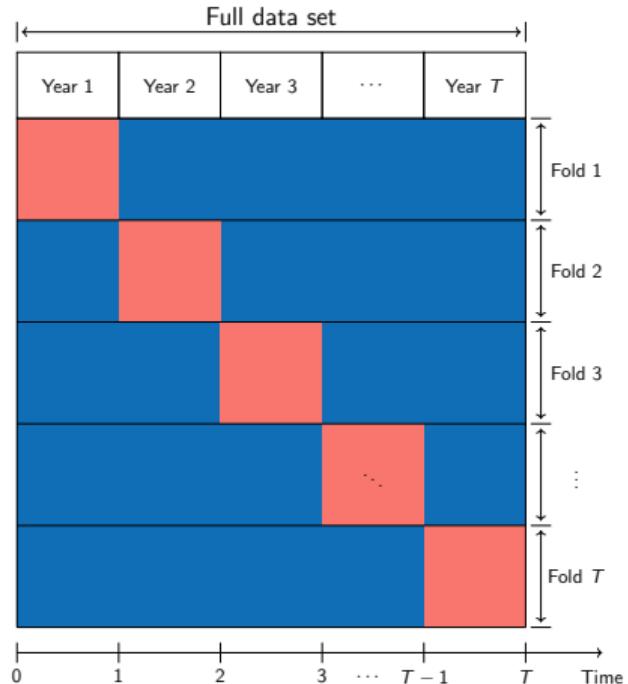
`eta`: learning rate.

`max_depth`: the maximum depth of a tree.

`subsample`: subsample ratio of the training data.

`colsample_bytree`: subsample ratio of the features.

Parameter tuning with **T-fold cross-validation**.



Calibrating the mortality deviations model

XGBoost: flexible and efficient implementation of gradient boosting.

Tuning parameters:

`nrounds`: number of boosting iterations.

`eta`: learning rate.

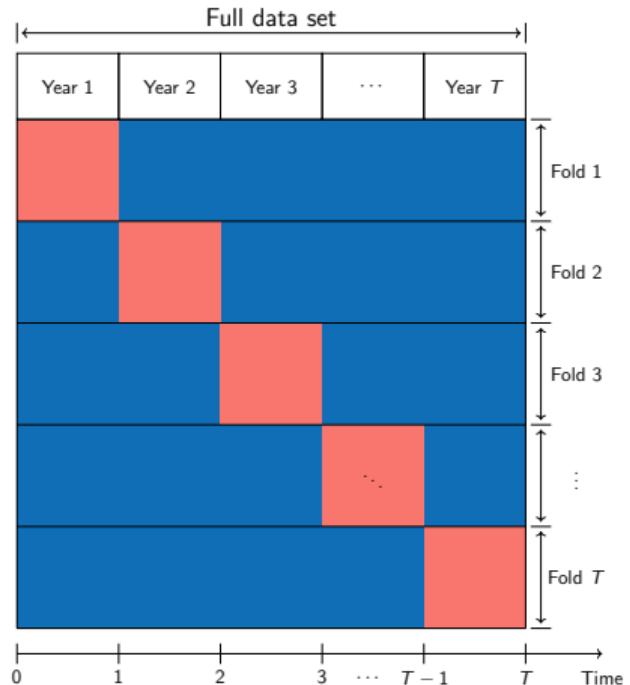
`max_depth`: the maximum depth of a tree.

`subsample`: subsample ratio of the training data.

`colsample_bytree`: subsample ratio of the features.

Parameter tuning with **T-fold cross-validation**.

Calibrate XGBoost model on entire training data with optimal parameter configuration.



Calibrating the mortality deviations model

XGBoost: flexible and efficient implementation of gradient boosting.

Tuning parameters:

`nrounds`: number of boosting iterations.

`eta`: learning rate.

`max_depth`: the maximum depth of a tree.

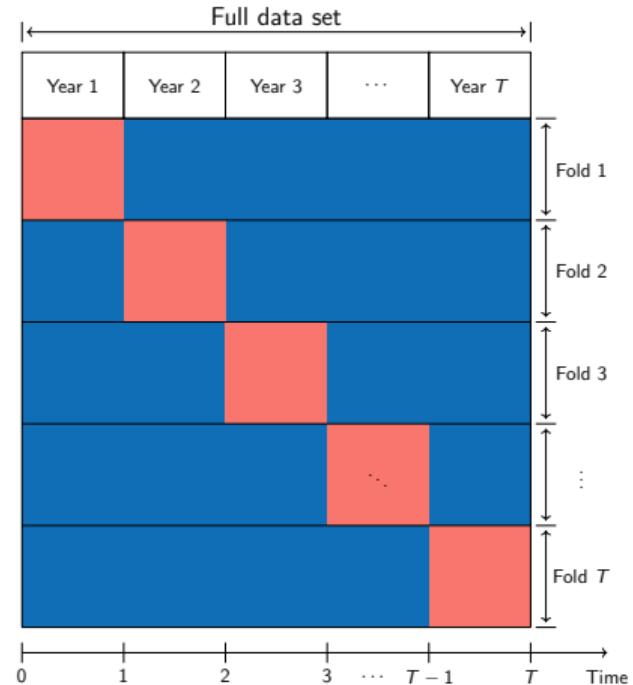
`subsample`: subsample ratio of the training data.

`colsample_bytree`: subsample ratio of the features.

Parameter tuning with [T-fold cross-validation](#).

Calibrate XGBoost model on entire training data with optimal parameter configuration.

Interpretation tools to gain insights: VIP, ALE.



Feature engineering

Motivation

Differences in spatial and temporal dimension across the data sources:

- data on death counts: weekly, NUTS 3 scale.
- environmental data: hourly or daily time scale, spatial grid.

Motivation

Differences in spatial and temporal dimension across the data sources:

- data on death counts: weekly, NUTS 3 scale.
- environmental data: hourly or daily time scale, spatial grid.

Goal of feature engineering:

- convert the temporal and spatial dimensions of the environmental data into features on a weekly, NUTS 3 scale

Feature engineering

Motivation

Differences in spatial and temporal dimension across the data sources:

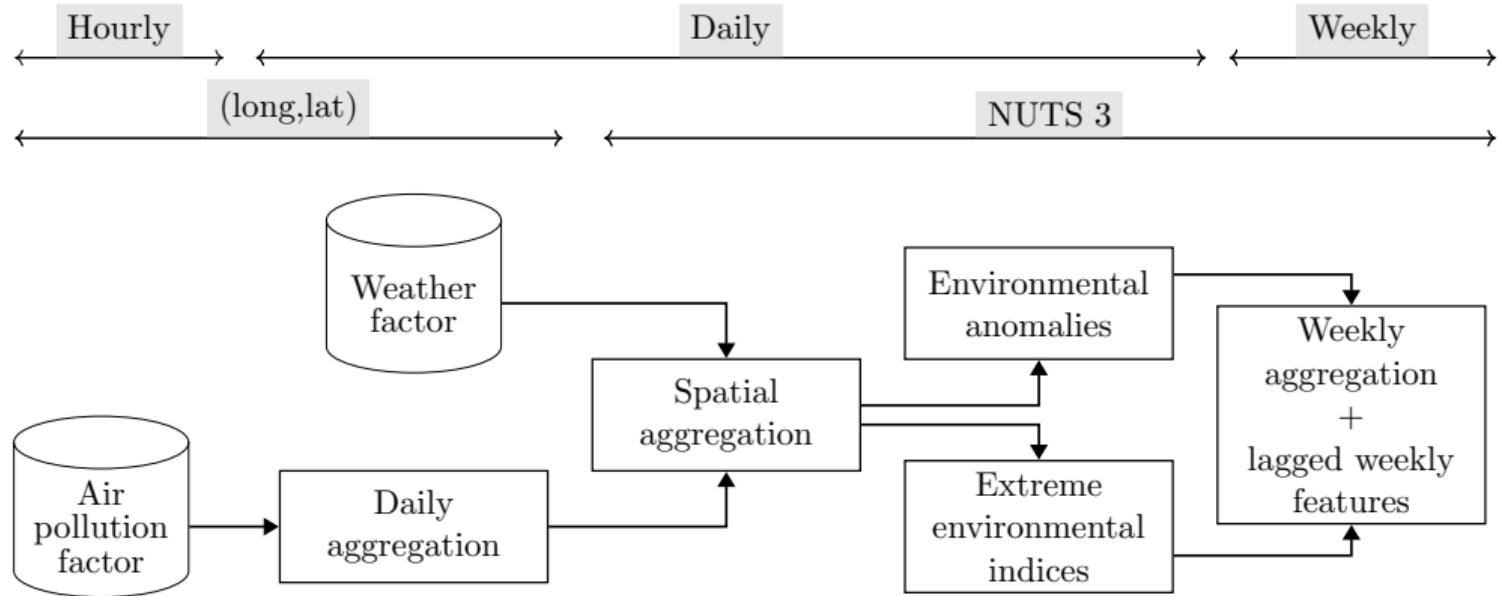
- data on death counts: weekly, NUTS 3 scale.
- environmental data: hourly or daily time scale, spatial grid.

Goal of feature engineering:

- convert the temporal and spatial dimensions of the environmental data into features on a weekly, NUTS 3 scale
- create features that measure deviations from baseline conditions from environmental data to explain excess or deficit mortality (other ideas welcome!).

Flow chart

21



Extreme environmental indices

22

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Define extreme high temperature index (hot-day index):

$$T.ind_{t,w,d}^{(r,95\%)} = \mathbb{1} \left\{ T_{\max}^{(r)}_{t,w,d} \geq q_{T_{\max}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\text{avg}}^{(r)}_{t,w,d} \geq q_{T_{\text{avg}}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\min}^{(r)}_{t,w,d} \geq q_{T_{\min}}^{(r,95\%)} \right\}.$$

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Define extreme high temperature index (hot-day index):

$$T.ind_{t,w,d}^{(r,95\%)} = \mathbb{1} \left\{ T_{\max}^{(r)}_{t,w,d} \geq q_{T_{\max}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\text{avg}}^{(r)}_{t,w,d} \geq q_{T_{\text{avg}}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\min}^{(r)}_{t,w,d} \geq q_{T_{\min}}^{(r,95\%)} \right\}.$$

Index values: 0-3, indicating the severity of hot days.

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Define extreme high temperature index (hot-day index):

$$T.ind_{t,w,d}^{(r,95\%)} = \mathbb{1} \left\{ T_{\max,t,w,d}^{(r)} \geq q_{T_{\max}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\text{avg},t,w,d}^{(r)} \geq q_{T_{\text{avg}}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\min,t,w,d}^{(r)} \geq q_{T_{\min}}^{(r,95\%)} \right\}.$$

Index values: 0-3, indicating the severity of hot days.

Similar extreme indices are created for the other daily weather and air pollution factors.

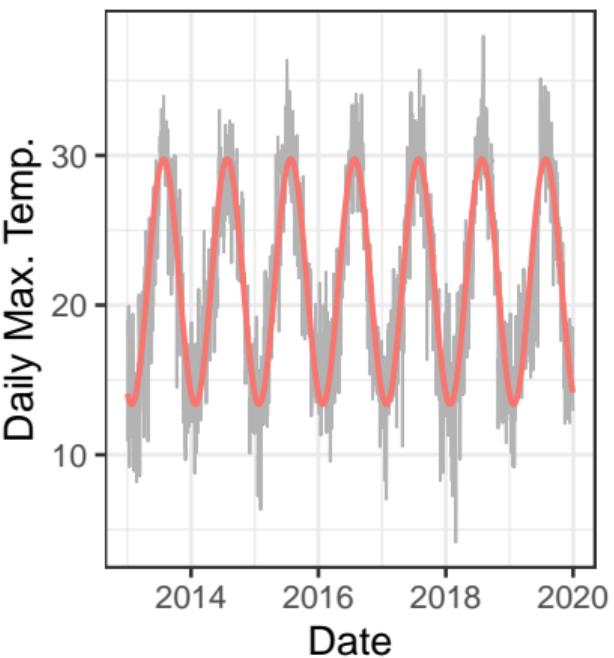
Create features that [quantify deviations from typical, baseline conditions](#) for each day throughout the year.

Create features that **quantify deviations from typical, baseline conditions** for each day throughout the year.

Robust linear regression to capture baseline:

$$\tilde{x}_{t,w,d}^{(r)} = \alpha_0^{(r)} + \alpha_1^{(r)} \sin\left(\frac{2\pi d}{365.25}\right) + \alpha_2^{(r)} \cos\left(\frac{2\pi d}{365.25}\right) + \epsilon_{t,w,d}^{(r)},$$

ES511: Barcelona



Environmental anomalies

Create features that **quantify deviations from typical, baseline conditions** for each day throughout the year.

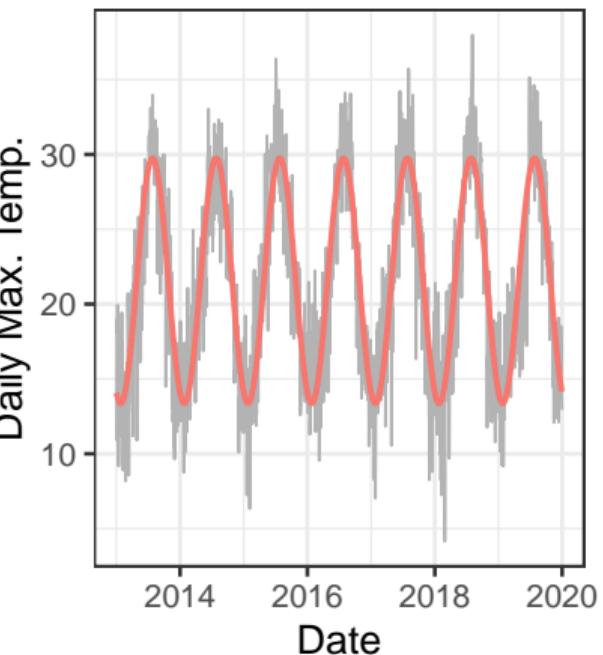
Robust linear regression to capture baseline:

$$\tilde{x}_{t,w,d}^{(r)} = \alpha_0^{(r)} + \alpha_1^{(r)} \sin\left(\frac{2\pi d}{365.25}\right) + \alpha_2^{(r)} \cos\left(\frac{2\pi d}{365.25}\right) + \epsilon_{t,w,d}^{(r)},$$

In the paper, we work with excesses or deviations from the baseline (**anomalies**):

$$\tilde{x}_{t,w,d}^{(r)} - \hat{x}_{t,w,d}^{(r)}$$

ES511: Barcelona



Create features that [quantify deviations from typical, baseline conditions](#) for each day throughout the year.

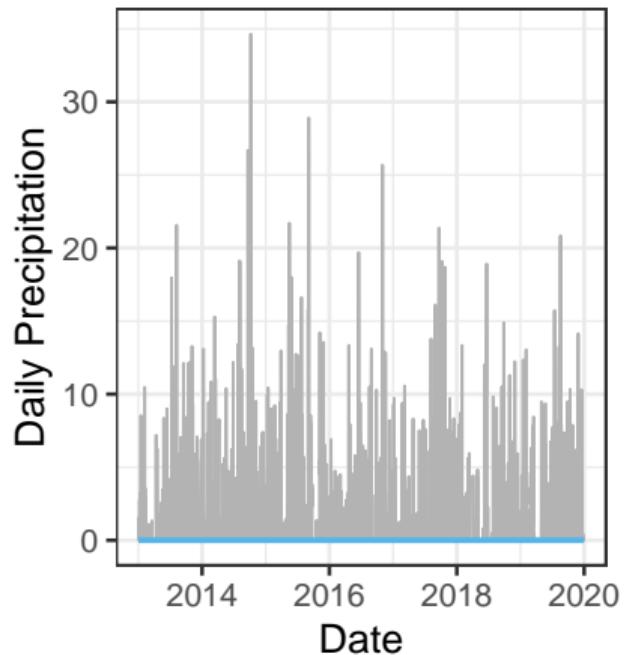
[Robust linear regression](#) to capture baseline:

$$\tilde{x}_{t,w,d}^{(r)} = \alpha_0^{(r)} + \alpha_1^{(r)} \sin\left(\frac{2\pi w}{365.25}\right) + \alpha_2^{(r)} \cos\left(\frac{2\pi w}{365.25}\right) + \epsilon_{t,w,d}^{(r)},$$

In the paper we work with excesses or deviations from the baseline ([anomalies](#)):

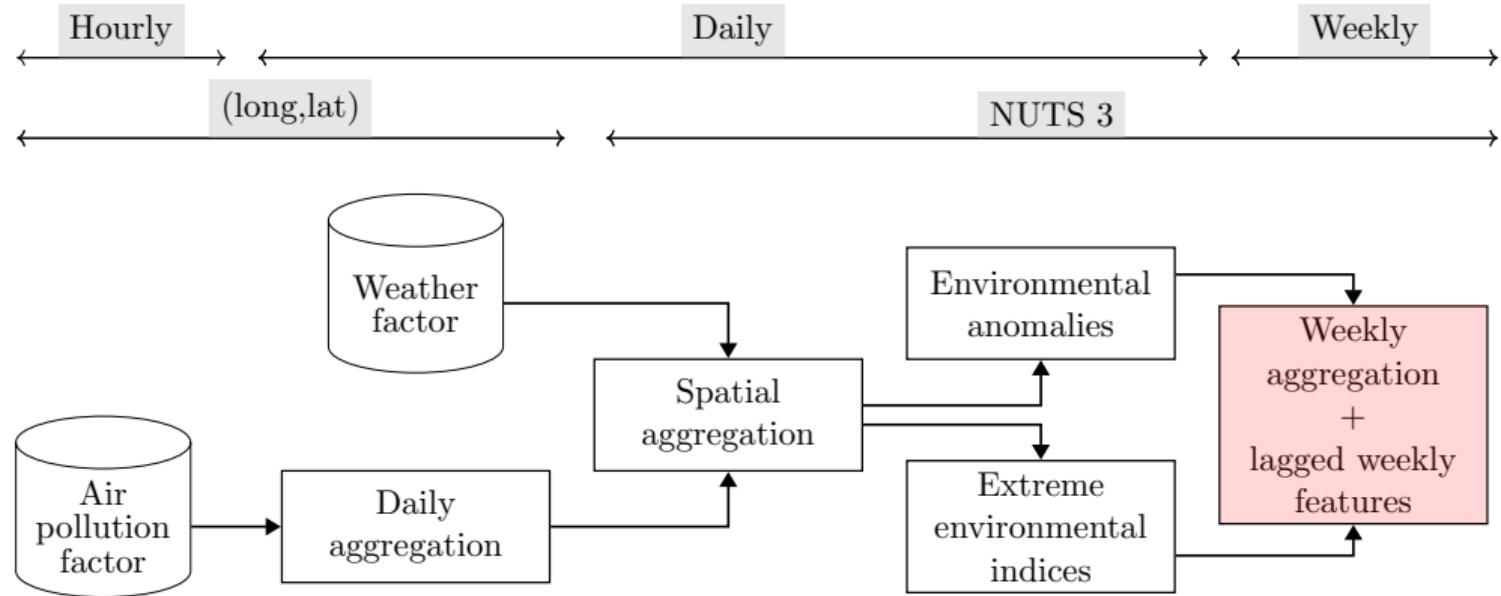
$$\tilde{x}_{t,w,d}^{(r)} - \hat{x}_{t,w,d}^{(r)}$$

SE110: Stockholms län



Flow chart

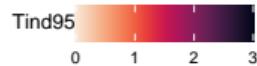
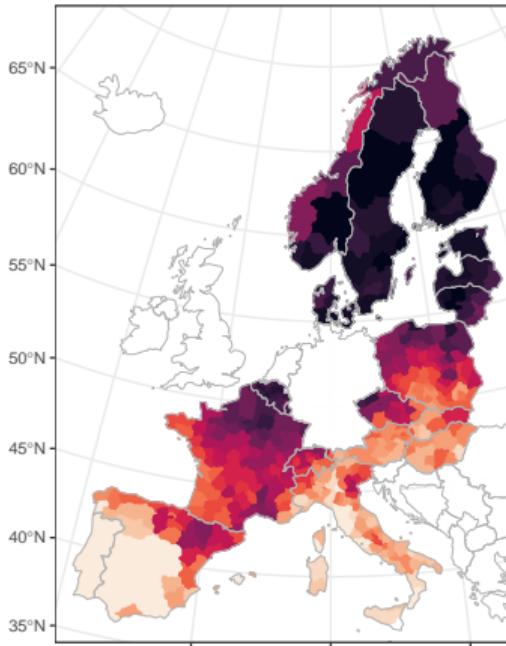
23



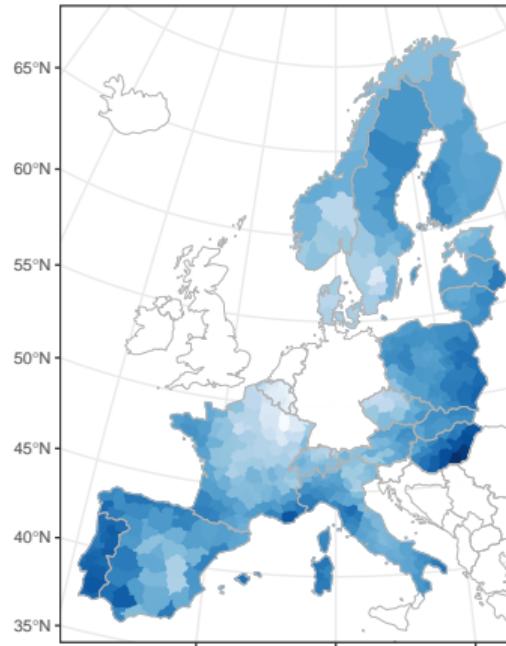
Weekly aggregation

24

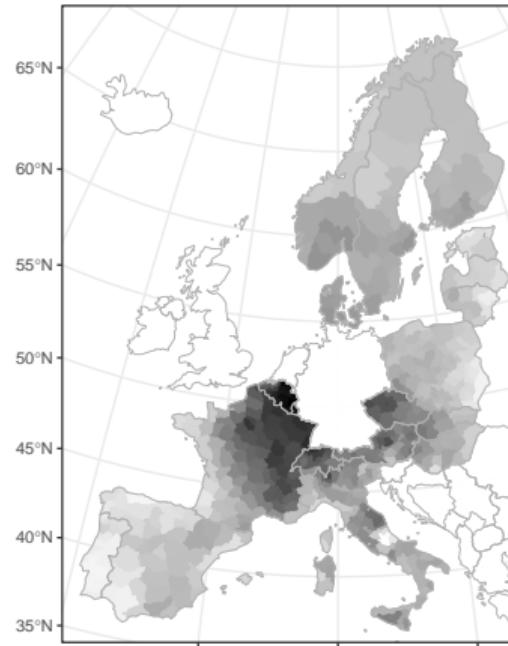
w_avg_Tind95: 2018–30



w_avg_Hum_anom: 2018–30

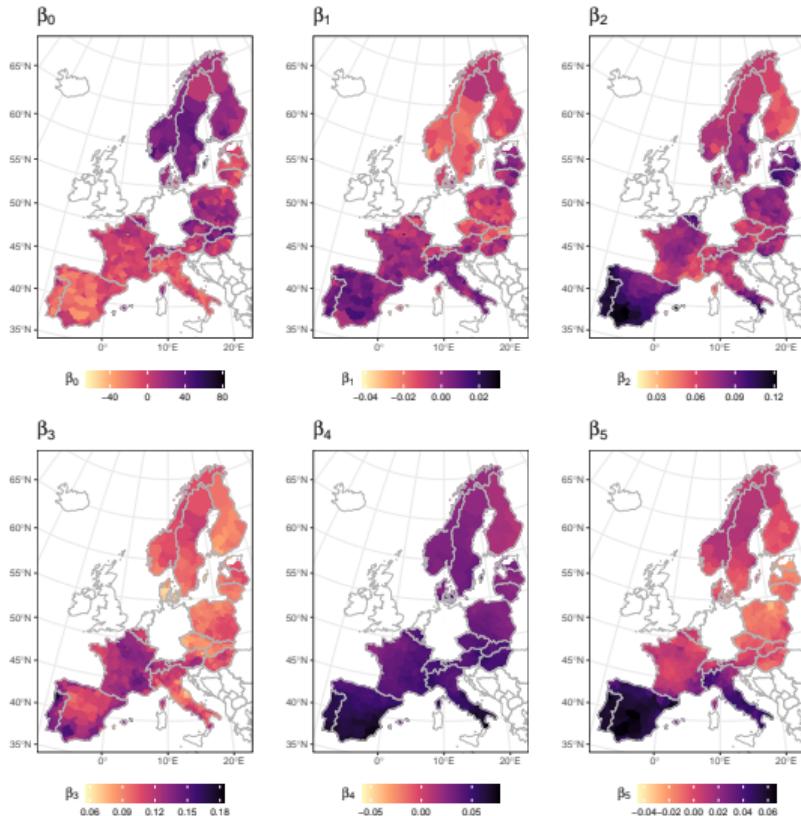


w_avg_O3_anom: 2018–30



Calibration results

Baseline model



Machine learning model

25

Input features: longitude-latitude coordinates, season, (one-week lagged) environmental anomalies and extreme indices.

Tuning by 7-fold cross validation over the years 2013-2019 using an extensive tuning grid.

Tuning parameters: `nrounds` (490), `eta` (0.01), `min_child_weight` (1000), `max.depth` (7), `subsample` (0.75), `colsample_bytree` (0.50).

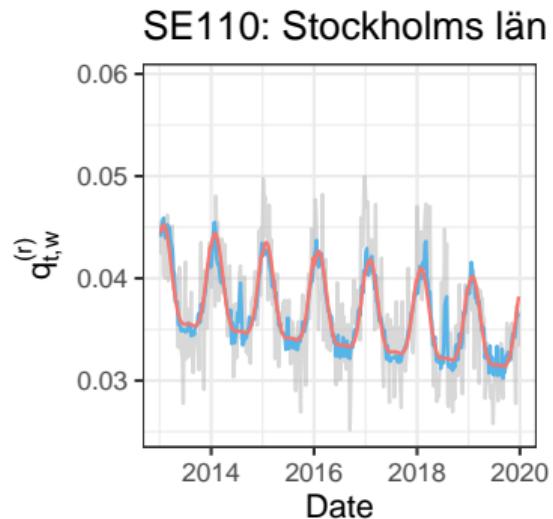
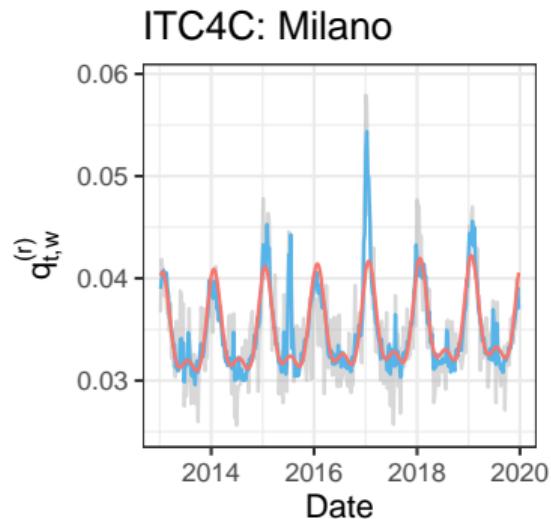
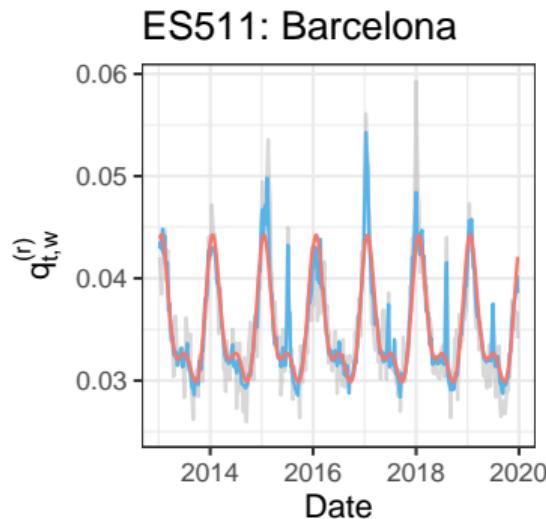
Calibration results

Insights in the machine-learning model

In-sample fit and model performance

26

Observed and estimated mortality rates (baseline + XGBoost):

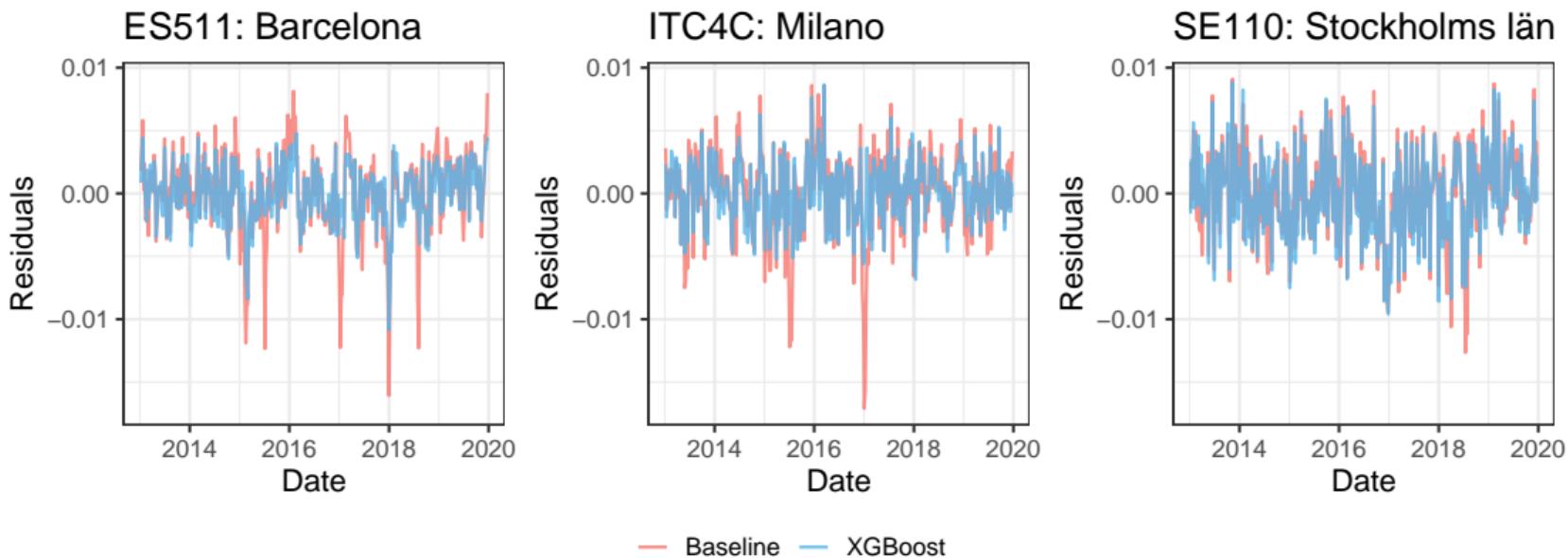


— Observed — Baseline — XGBoost

In-sample fit and model performance

27

Residuals of the estimated weekly mortality rates (baseline + XGBoost):



Machine learning techniques perform **automatic feature selection**.

Machine learning techniques perform [automatic feature selection](#).

Which features do significantly contribute to the predictions?

Machine learning techniques perform **automatic feature selection**.

Which features do significantly contribute to the predictions?

We calculate the **feature importance** of each feature X_I as:

$$\mathcal{V}_{\text{imp}}(X_I) = \frac{1}{\text{nrounds}} \sum_{n=1}^{\text{nrounds}} \Delta \mathcal{L}_n(X_I),$$

with $\Delta \mathcal{L}_n(X_I)$ the total reduction in the Poisson loss function, caused by splits associated to feature X_I in the tree built during iteration n of the XGBoost algorithm.

Machine learning techniques perform **automatic feature selection**.

Which features do significantly contribute to the predictions?

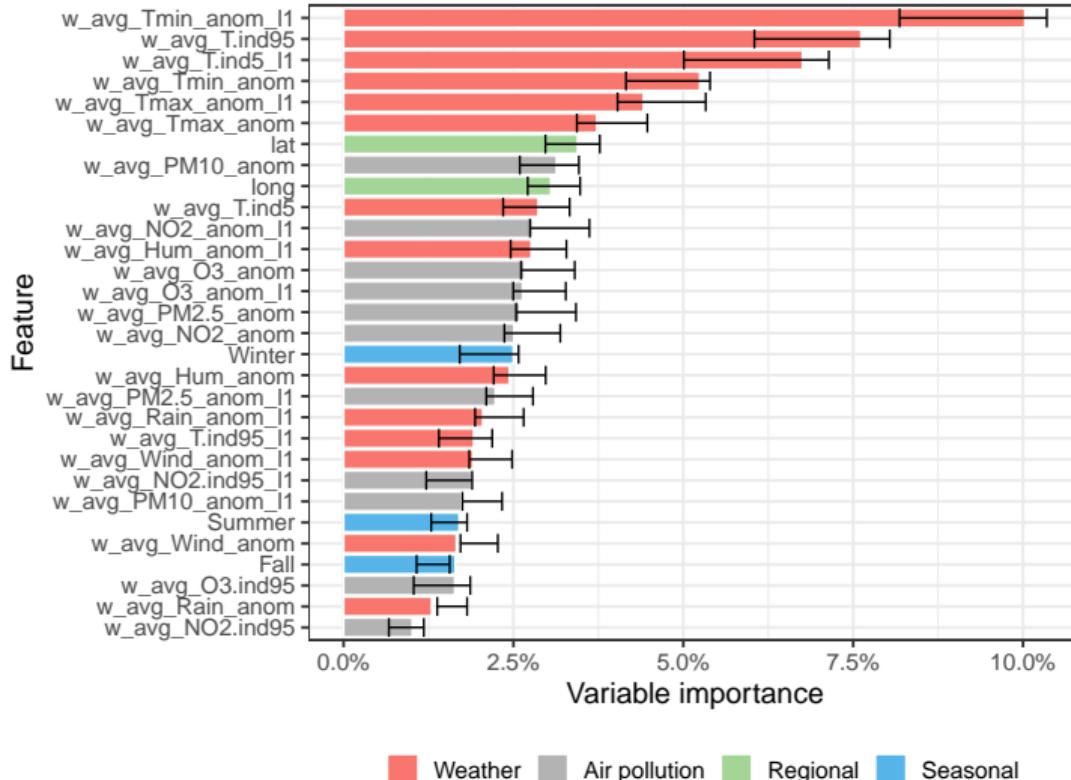
We calculate the **feature importance** of each feature X_I as:

$$V_{\text{imp}}(X_I) = \frac{1}{\text{nrounds}} \sum_{n=1}^{\text{nrounds}} \Delta \mathcal{L}_n(X_I),$$

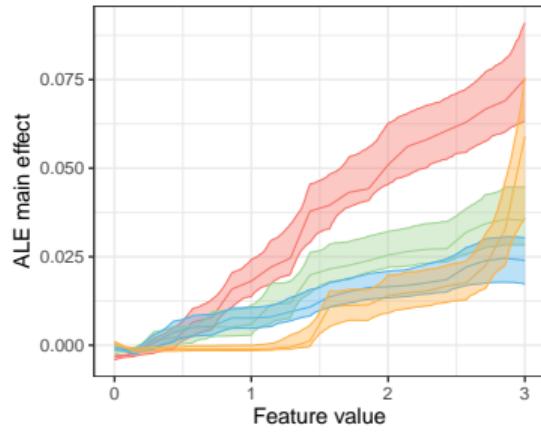
with $\Delta \mathcal{L}_n(X_I)$ the total reduction in the Poisson loss function, caused by splits associated to feature X_I in the tree built during iteration n of the XGBoost algorithm.

Features with a high importance appear **often** and **high** in the tree.

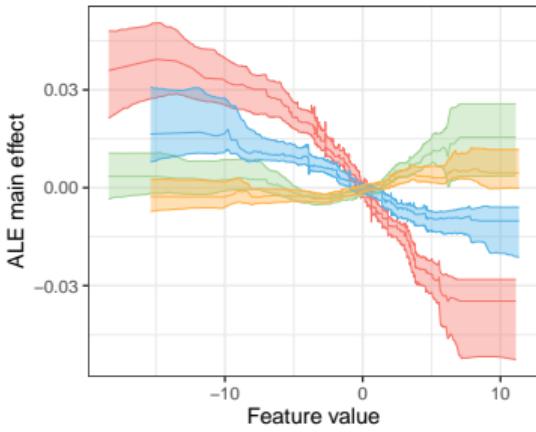
Feature importance



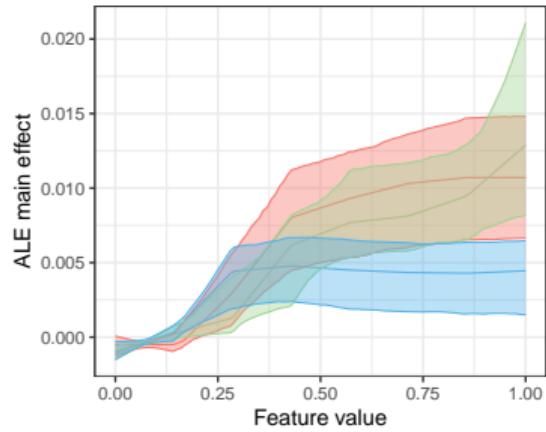
ALE main effects



T.ind95 (7.62%)	T.ind5 (2.86%)
T.ind5_I1 (6.76%)	T.ind95_I1 (1.92%)



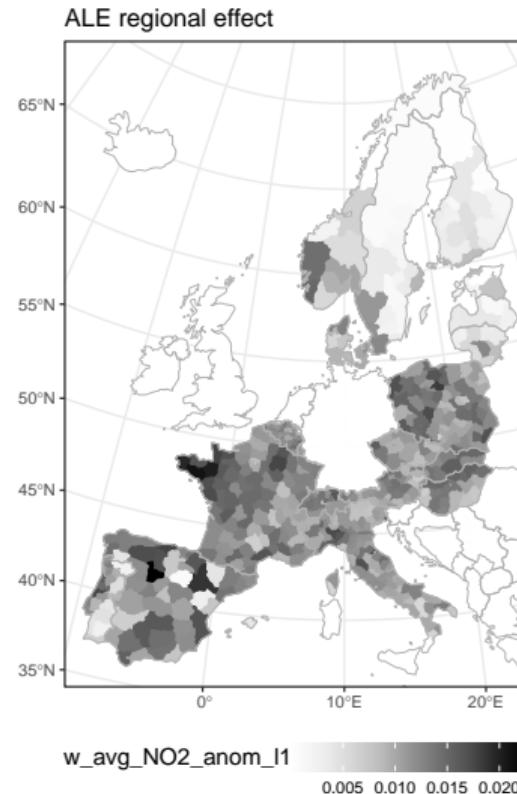
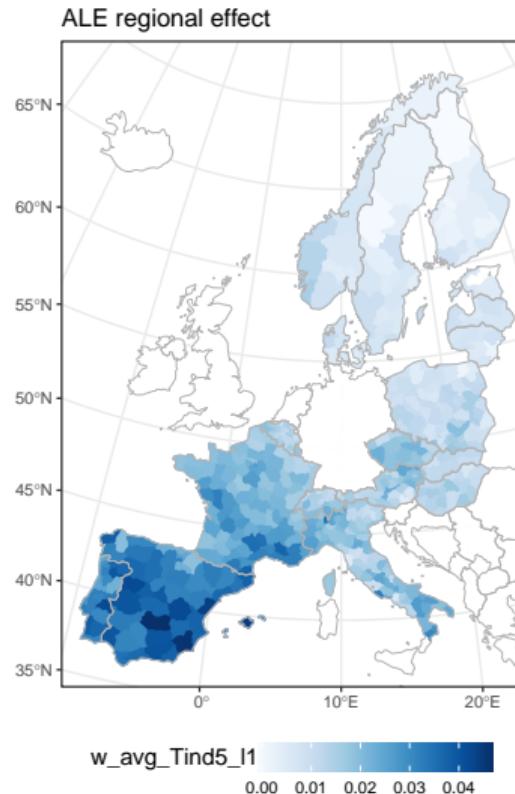
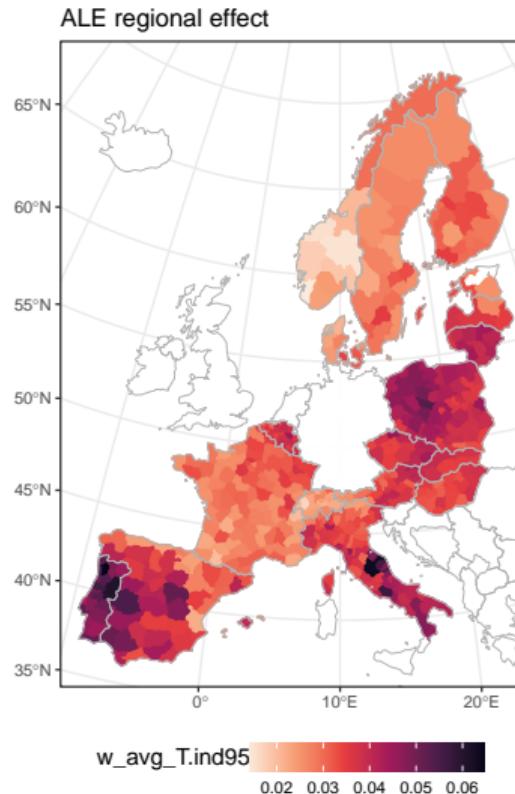
Tmin_anom_I1 (10.03%)	Tmax_anom_I1 (4.41%)
Tmin_anom (5.24%)	Tmax_anom (3.73%)



NO2.ind95_I1 (1.88%)	NO2.ind95 (1.01%)
O3.ind95 (1.64%)	

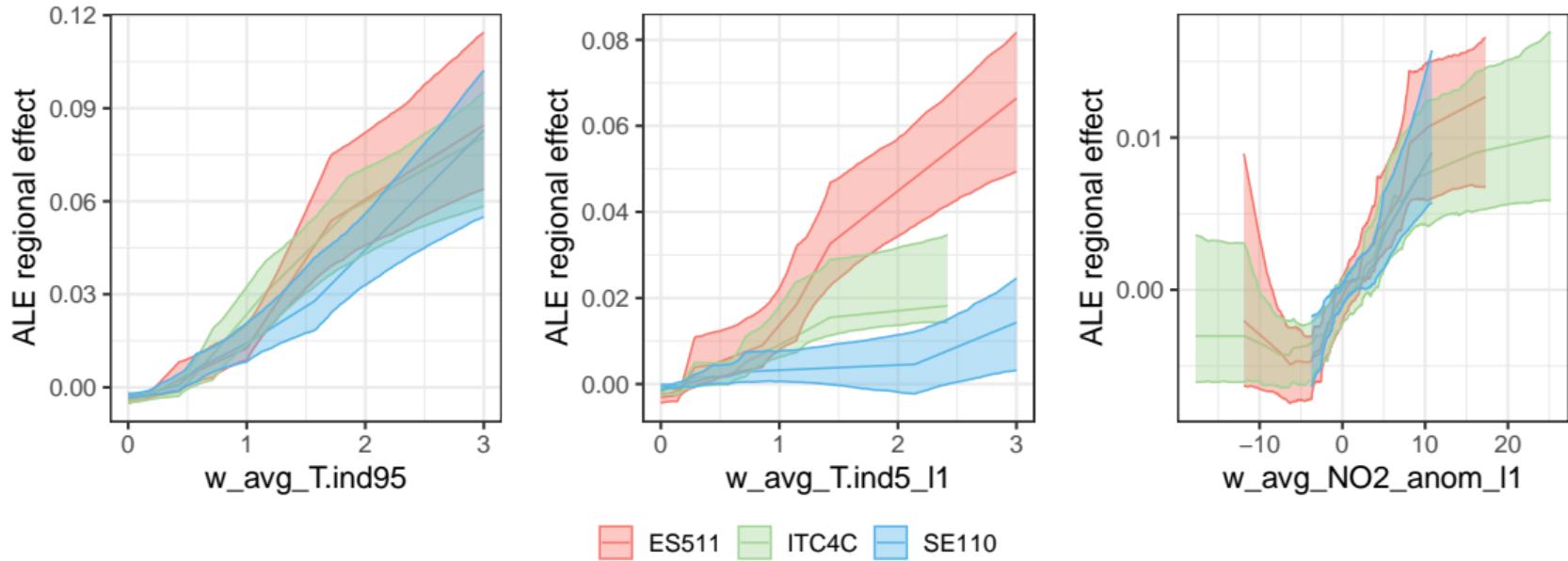
ALE regional effects

31



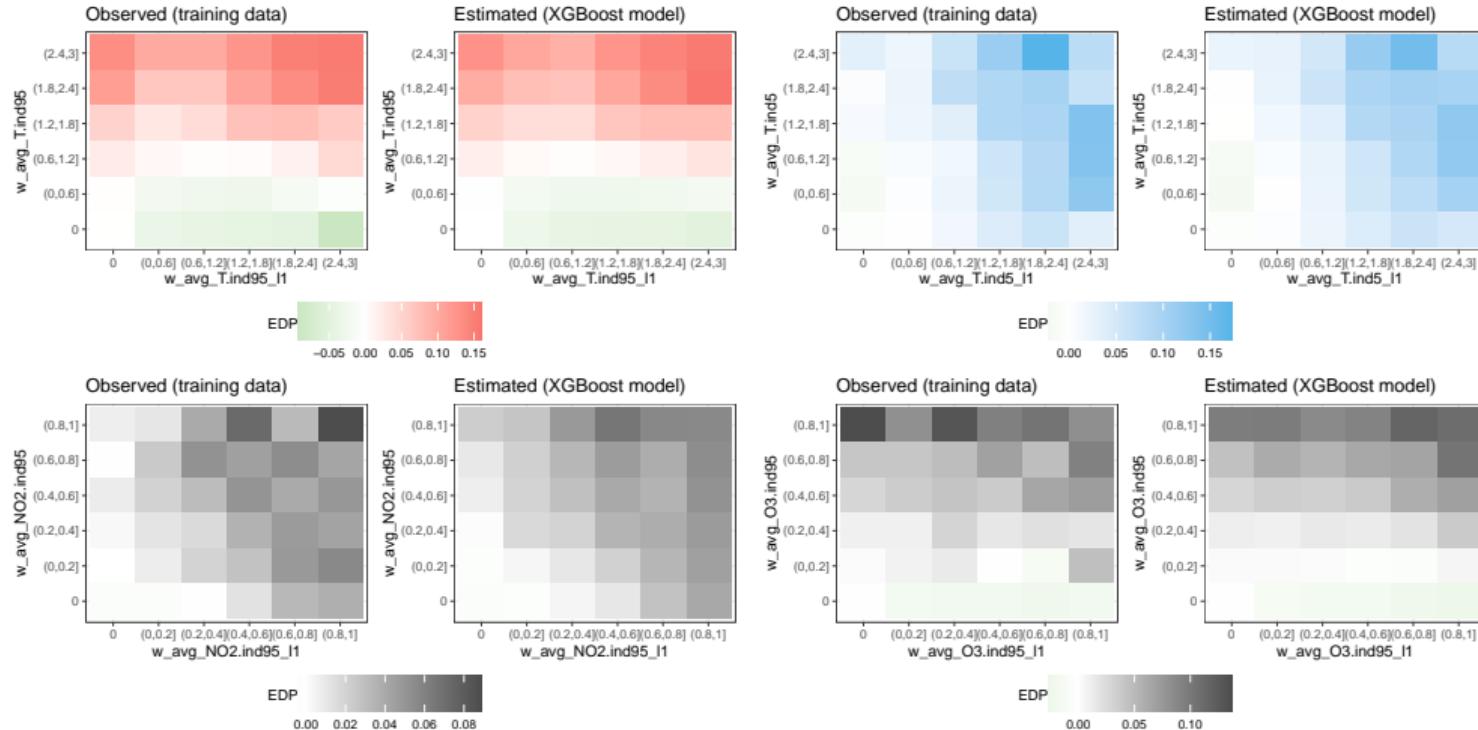
ALE regional effects

32



Harvesting effects

33



Wrap up

We have (multiple) additional visuals and analyses in the **working paper**, as well as a detailed discussion of related literature.

We have (multiple) additional visuals and analyses in the **working paper**, as well as a detailed discussion of related literature.

Limitation: focus on short-term associations only!

We have (multiple) additional visuals and analyses in the **working paper**, as well as a detailed discussion of related literature.

Limitation: focus on short-term associations only!

Exciting opportunities ahead using sophisticated learning methods and **fine-grained (open) data**.

We have (multiple) additional visuals and analyses in the **working paper**, as well as a detailed discussion of related literature.

Limitation: focus on short-term associations only!

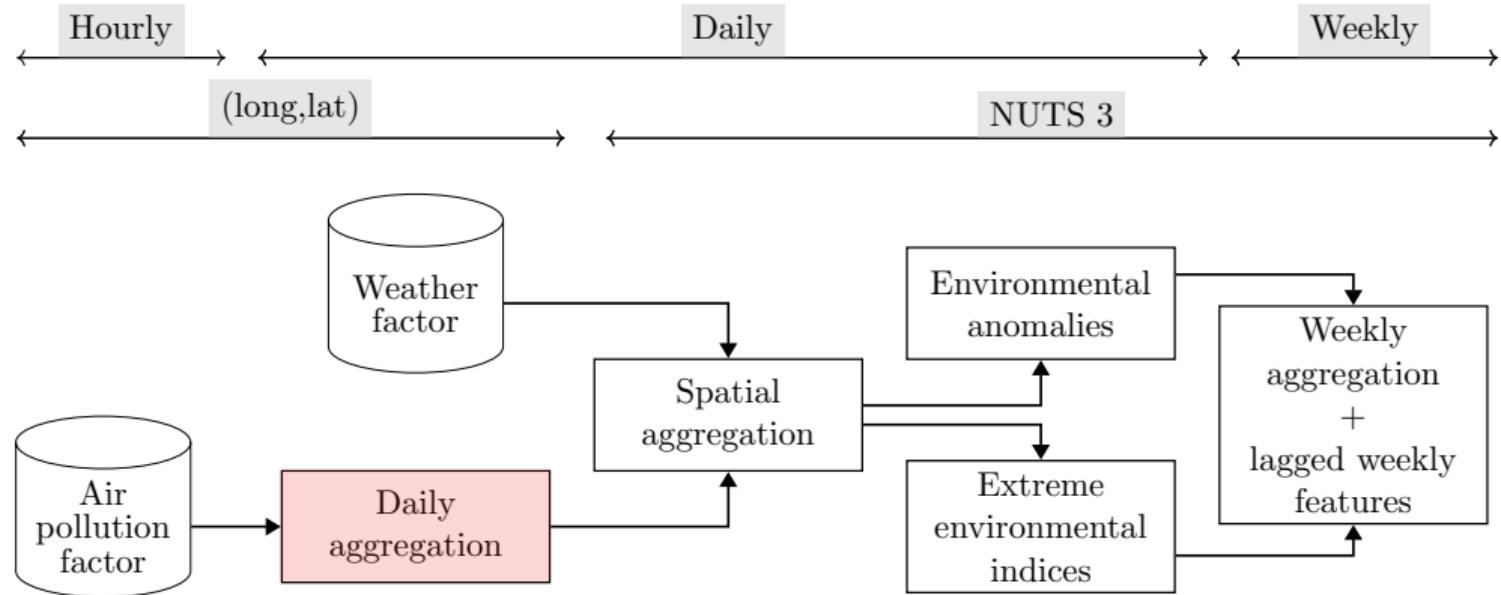
Exciting opportunities ahead using sophisticated learning methods and **fine-grained (open) data**.

However, feature engineering, (proper) interpretation tools, **interplay** of more traditional actuarial + statistical learning and sophisticated machine learning methods are key!

- M. Euthum, M. Scherer, and F. Ungolo. A neural network approach for the mortality analysis of multiple populations: a case study on data of the italian population. *European Actuarial Journal*, 2024.
- Mathias Lindholm and Lisa Palmborg. Efficient use of data for lstm mortality forecasting. *European Actuarial Journal*, 12:749–778, 2022.
- Francesca Perla, Ronald Richman, Salvatore Scognamiglio, and Mario V. Wüthrich. Time-series forecasting of mortality rates using deep learning. *Scandinavian Actuarial Journal*, 7(2): 572–598, 2021.
- Ronald Richman and Mario V. Wüthrich. A neural network extension of the lee–carter model to multiple populations. *Annals of Actuarial Science*, 15(2):346–366, 2021.
- Robert E Serfling. Methods for current statistical analysis of excess pneumonia-influenza deaths. *Public health reports*, 78(6):494, 1963.
- Chou-Wen Wang, Jinggong Zhang, and Wenjun Zhu. Neighbouring prediction for mortality. *ASTIN Bulletin*, 51(3):689–718, 2021.

Mario Wüthrich and Michael Merz. *Statistical foundations of actuarial learning and its applications*. Springer, 2023.

Flow chart



Consider an air pollution factor and denote its concentration at hour h of day d in week w of year t and located at longitude-latitude coordinates (long,lat) as $x_{t,w,d,h}^{(\text{long},\text{lat})}$.

Consider an air pollution factor and denote its concentration at hour h of day d in week w of year t and located at longitude-latitude coordinates (long,lat) as $x_{t,w,d,h}^{(\text{long},\text{lat})}$.

Compute the **daily minimum, average, and maximum concentrations** of the air pollutant, measured at the coordinates (long,lat) as:

$$\hat{x}_{t,w,d}^{(\text{long},\text{lat})} = \min \left\{ x_{t,w,d,h}^{(\text{long},\text{lat})} \mid h = 0, 1, \dots, 23 \right\}$$

$$\bar{x}_{t,w,d}^{(\text{long},\text{lat})} = \text{avg} \left\{ x_{t,w,d,h}^{(\text{long},\text{lat})} \mid h = 0, 1, \dots, 23 \right\}$$

$$\vee{x}_{t,w,d}^{(\text{long},\text{lat})} = \max \left\{ x_{t,w,d,h}^{(\text{long},\text{lat})} \mid h = 0, 1, \dots, 23 \right\}.$$

Consider an air pollution factor and denote its concentration at hour h of day d in week w of year t and located at longitude-latitude coordinates (long,lat) as $x_{t,w,d,h}^{(\text{long},\text{lat})}$.

Compute the **daily minimum, average, and maximum concentrations** of the air pollutant, measured at the coordinates (long,lat) as:

$$\hat{x}_{t,w,d}^{(\text{long},\text{lat})} = \min \left\{ x_{t,w,d,h}^{(\text{long},\text{lat})} \mid h = 0, 1, \dots, 23 \right\}$$

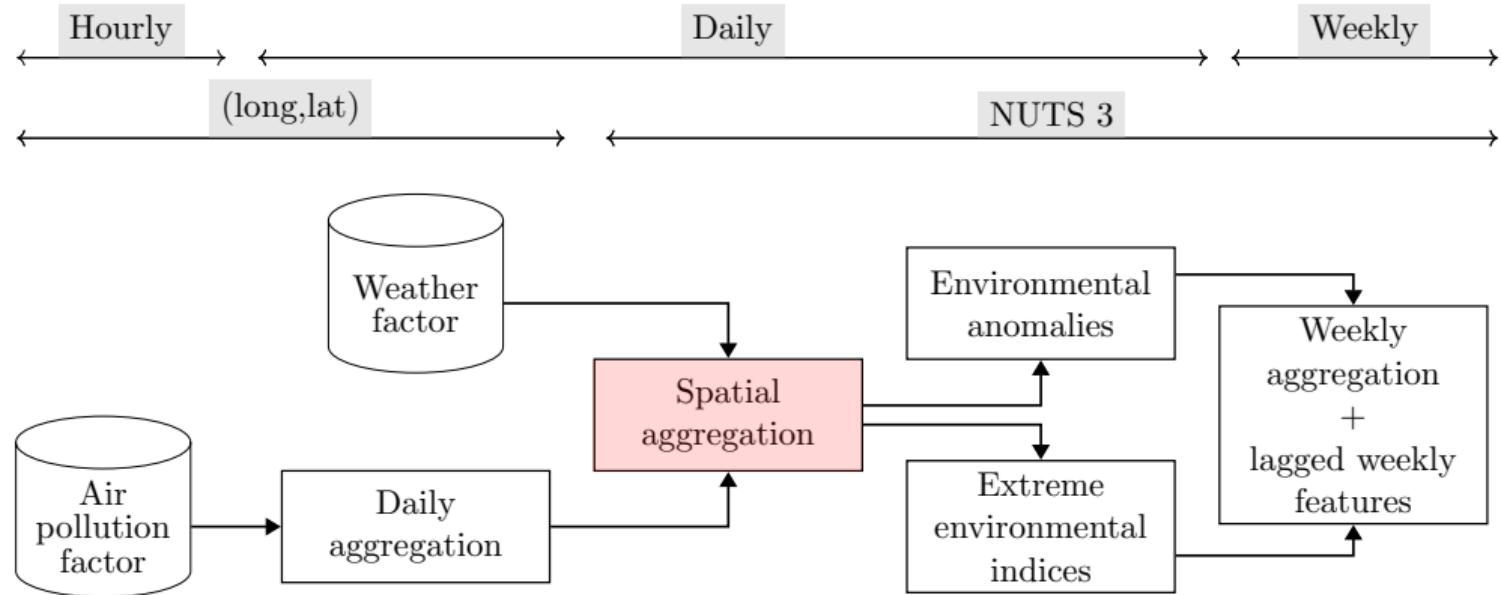
$$\bar{x}_{t,w,d}^{(\text{long},\text{lat})} = \text{avg} \left\{ x_{t,w,d,h}^{(\text{long},\text{lat})} \mid h = 0, 1, \dots, 23 \right\}$$

$$\vee_{t,w,d}^{(\text{long},\text{lat})} = \max \left\{ x_{t,w,d,h}^{(\text{long},\text{lat})} \mid h = 0, 1, \dots, 23 \right\}.$$

Weather factors already available at the daily level (no need for daily aggregation).

Flow chart

37



Spatial aggregation

$\tilde{x}_{t,w,d}^{(\text{long},\text{lat})}$: daily level of a specific environmental feature at coordinates (long, lat) for year t , week w , and day d .

Spatial aggregation

$\tilde{x}_{t,w,d}^{(\text{long},\text{lat})}$: daily level of a specific environmental feature at coordinates (long, lat) for year t , week w , and day d .

Construct feature on NUTS 3 scale:

$$\tilde{x}_{t,w,d}^{(r)} = \sum_{(\text{long},\text{lat}) \in \mathcal{I}_1(r)} \omega_{(\text{long},\text{lat})} \cdot \tilde{x}_{t,w,d}^{(\text{long},\text{lat})},$$

Spatial aggregation

$\tilde{x}_{t,w,d}^{(\text{long},\text{lat})}$: daily level of a specific environmental feature at coordinates (long, lat) for year t , week w , and day d .

Construct feature on NUTS 3 scale:

$$\tilde{x}_{t,w,d}^{(r)} = \sum_{(\text{long},\text{lat}) \in \mathcal{I}_1(r)} \omega_{(\text{long},\text{lat})} \cdot \tilde{x}_{t,w,d}^{(\text{long},\text{lat})},$$

where:

$\omega_{(\text{long},\text{lat})}$: population weights using gridded population data from the Socioeconomic Data and Applications Center (NASA's EOSDIS)

Spatial aggregation

$\tilde{x}_{t,w,d}^{(\text{long},\text{lat})}$: daily level of a specific environmental feature at coordinates (long, lat) for year t , week w , and day d .

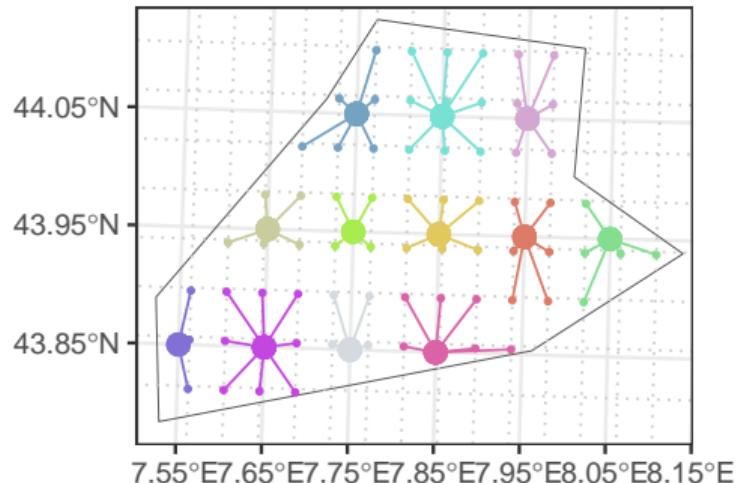
Construct feature on NUTS 3 scale:

$$\tilde{x}_{t,w,d}^{(r)} = \sum_{(\text{long},\text{lat}) \in \mathcal{I}_1(r)} \omega_{(\text{long},\text{lat})} \cdot \tilde{x}_{t,w,d}^{(\text{long},\text{lat})},$$

where:

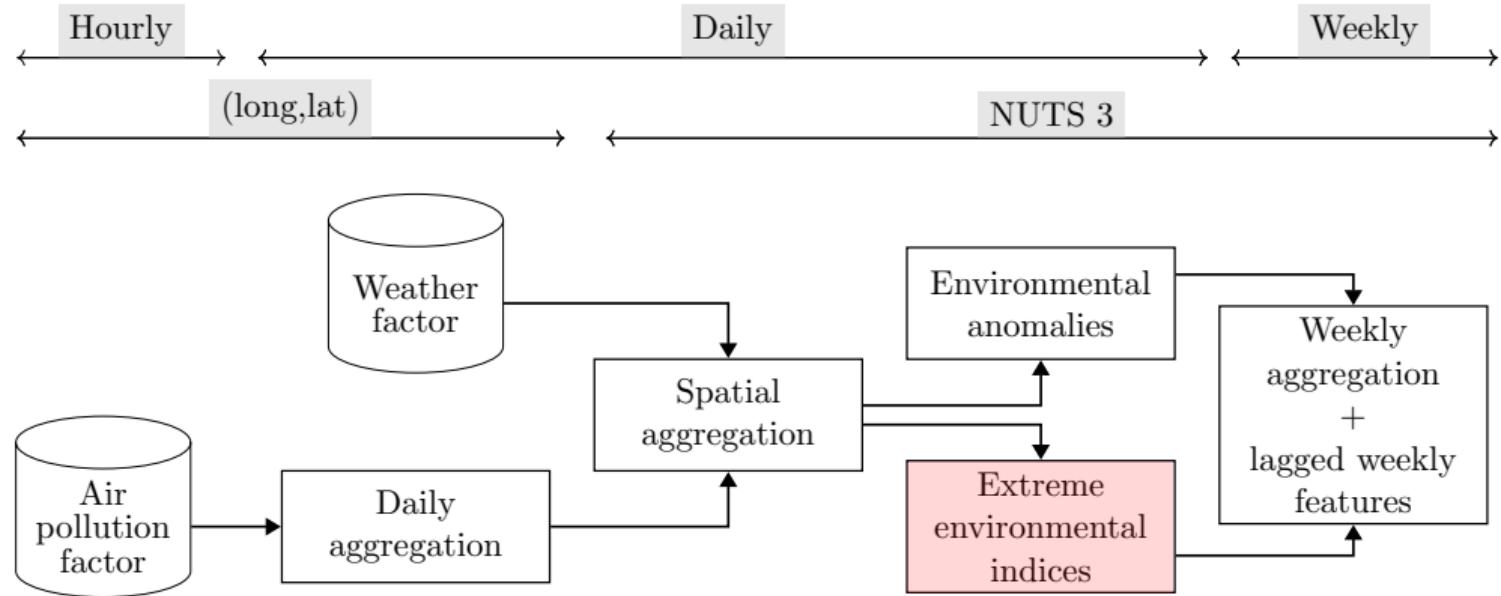
$\omega_{(\text{long},\text{lat})}$: population weights using gridded population data from the Socioeconomic Data and Applications Center (NASA's EOSDIS)

ITC31: Imperia



- Feature grid $I_1(r)$
- Population grid $I_2(r)$

Flow chart



Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Define extreme high temperature index (hot-day index):

$$T.ind_{t,w,d}^{(r,95\%)} = \mathbb{1} \left\{ T_{\max}^{(r)}_{t,w,d} \geq q_{T_{\max}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\text{avg}}^{(r)}_{t,w,d} \geq q_{T_{\text{avg}}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\min}^{(r)}_{t,w,d} \geq q_{T_{\min}}^{(r,95\%)} \right\}.$$

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Define extreme high temperature index (hot-day index):

$$T.ind_{t,w,d}^{(r,95\%)} = \mathbb{1} \left\{ T_{\max,t,w,d}^{(r)} \geq q_{T_{\max}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\text{avg},t,w,d}^{(r)} \geq q_{T_{\text{avg}}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\min,t,w,d}^{(r)} \geq q_{T_{\min}}^{(r,95\%)} \right\}.$$

Index values: 0-3, indicating the severity of hot days.

Aim: to capture the effects of extreme environmental conditions on mortality baseline deviations.

Calculate region-specific 5% and 95% quantiles of the daily historical temperature or air pollution observations over the years 2013-2019.

Define extreme high temperature index (hot-day index):

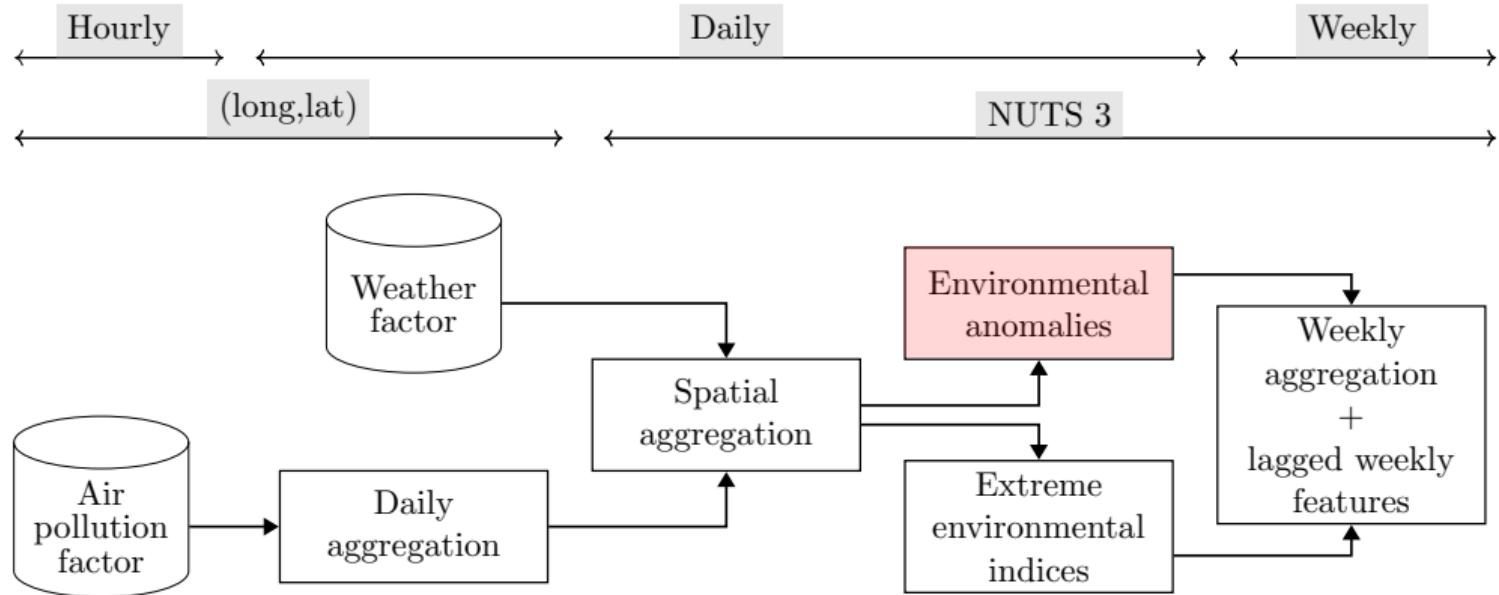
$$T.ind_{t,w,d}^{(r,95\%)} = \mathbb{1} \left\{ T_{\max,t,w,d}^{(r)} \geq q_{T_{\max}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\text{avg},t,w,d}^{(r)} \geq q_{T_{\text{avg}}}^{(r,95\%)} \right\} + \mathbb{1} \left\{ T_{\min,t,w,d}^{(r)} \geq q_{T_{\min}}^{(r,95\%)} \right\}.$$

Index values: 0-3, indicating the severity of hot days.

Similar extreme indices are created for the other daily weather and air pollution factors.

Flow chart

39



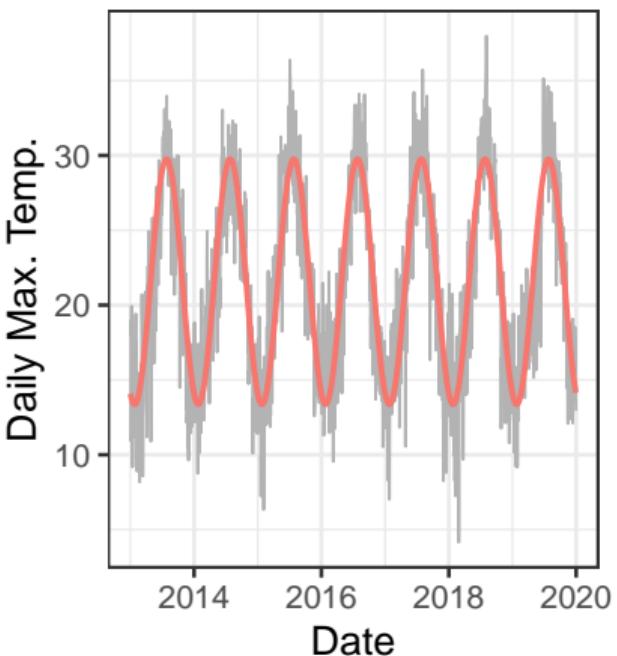
Create features that **quantify deviations from typical, baseline conditions** for each day throughout the year.

Create features that quantify deviations from typical, baseline conditions for each day throughout the year.

Robust linear regression to capture baseline:

$$\tilde{x}_{t,w,d}^{(r)} = \alpha_0^{(r)} + \alpha_1^{(r)} \sin\left(\frac{2\pi d}{365.25}\right) + \alpha_2^{(r)} \cos\left(\frac{2\pi d}{365.25}\right) + \epsilon_{t,w,d}^{(r)},$$

ES511: Barcelona



Environmental anomalies

Create features that **quantify deviations from typical, baseline conditions** for each day throughout the year.

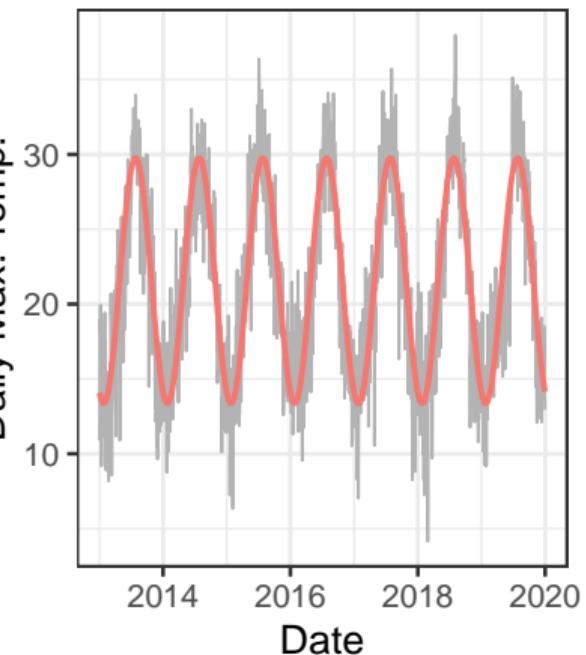
Robust linear regression to capture baseline:

$$\tilde{x}_{t,w,d}^{(r)} = \alpha_0^{(r)} + \alpha_1^{(r)} \sin\left(\frac{2\pi d}{365.25}\right) + \alpha_2^{(r)} \cos\left(\frac{2\pi d}{365.25}\right) + \epsilon_{t,w,d}^{(r)},$$

In the paper, we work with excesses or deviations from the baseline (**anomalies**):

$$\tilde{x}_{t,w,d}^{(r)} - \hat{x}_{t,w,d}^{(r)}$$

ES511: Barcelona



Create features that **quantify deviations from typical, baseline conditions** for each day throughout the year.

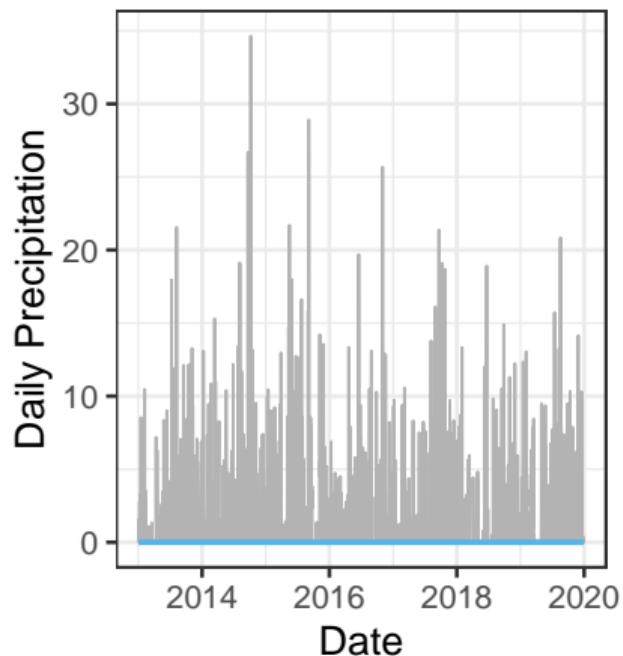
Robust linear regression to capture baseline:

$$\tilde{x}_{t,w,d}^{(r)} = \alpha_0^{(r)} + \alpha_1^{(r)} \sin\left(\frac{2\pi w}{365.25}\right) + \alpha_2^{(r)} \cos\left(\frac{2\pi w}{365.25}\right) + \epsilon_{t,w,d}^{(r)},$$

In the paper we work with excesses or deviations from the baseline (**anomalies**):

$$\tilde{x}_{t,w,d}^{(r)} - \hat{x}_{t,w,d}^{(r)}$$

SE110: Stockholms län



Accumulated local effects - motivation

How does each feature impact the predictions produced by the machine learning model?

Partial dependence plots interpret the marginal effect of a feature X_l on the model predictions as:

$$f_{l,\text{PDP}}(x) = \frac{1}{n} \sum_{j=1}^n \hat{f}(x, \mathbf{x}_j^{(-l)}),$$

where $\mathbf{x}_j^{(-l)}$ is the j -th training observation where the l -th feature is omitted.

Problem: correlated features may lead to unrealistic data points.

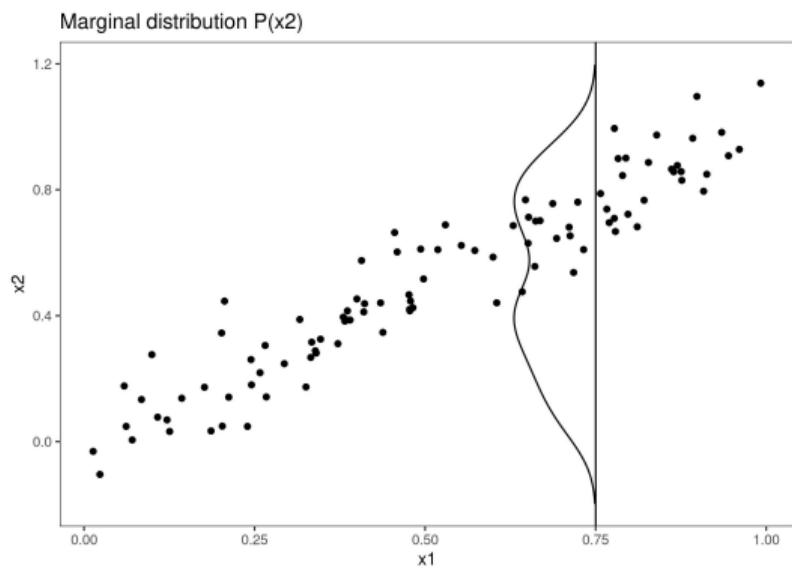


Figure: Visualisation taken from Molnar (2019).

Accumulated local effects - motivation

How does each feature impact the predictions generated by a machine learning model?

Partial dependence plots interpret the marginal effect of a feature X_l on the model predictions as:

$$f_{l,\text{PDP}}(x) = \frac{1}{n} \sum_{j=1}^n \hat{f}(x, \mathbf{x}_j^{(-l)}),$$

where $\mathbf{x}_j^{(-l)}$ is the j -th training observation where the l -th feature is omitted.

Problem: correlated features may lead to unrealistic data points.

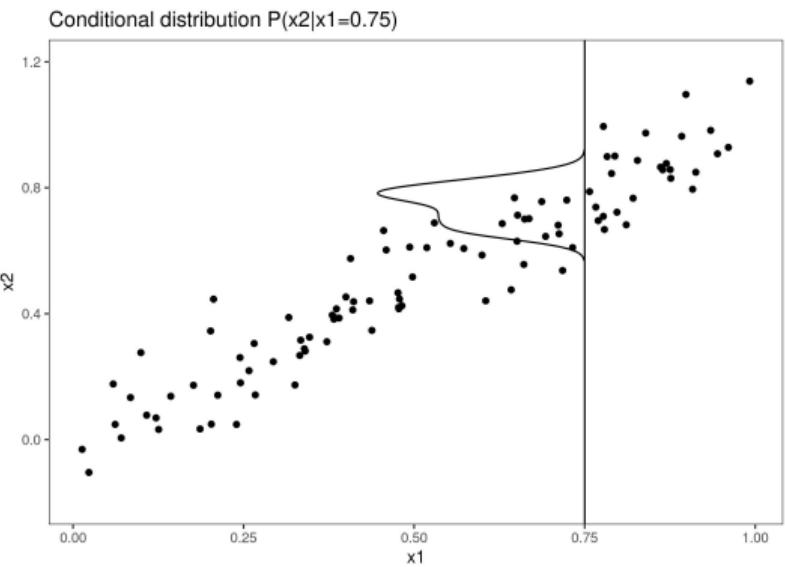


Figure: Visualisation taken from Molnar (2019).

Accumulated local effects - motivation

How does each feature impact the predictions generated by a machine learning model?

Partial dependence plots interpret the marginal effect of a feature X_l on the model predictions as:

$$f_{l,\text{PDP}}(x) = \frac{1}{n} \sum_{j=1}^n \hat{f}(x, \mathbf{x}_j^{(-l)}),$$

where $\mathbf{x}_j^{(-l)}$ is the j -th training observation where the l -th feature is omitted.

Problem: correlated features may lead to unrealistic data points.

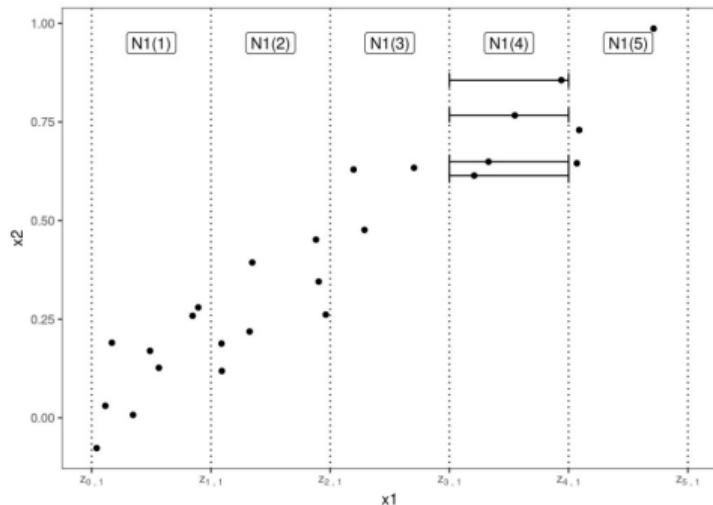


Figure: Visualisation taken from Molnar (2019).

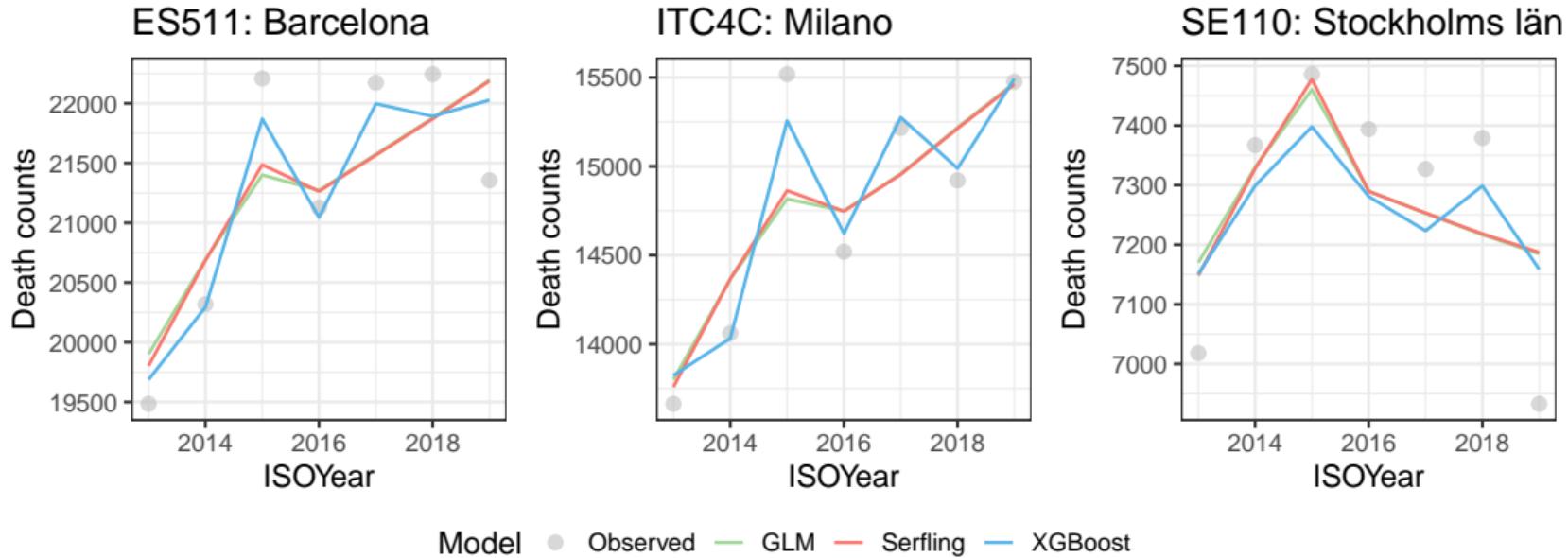
Accumulated Local Effects avoid the use of unrealistic data instances, average changes in predictions and accumulate them. For a feature X_I , the ALE effect equals:

$$f_{I,\text{ALE}}(x) = \int_{z_{0,I}}^x \mathbb{E} \left[\frac{\partial f(X_1, X_2, \dots, X_p)}{\partial X_I} \middle| X_I = z_I \right] dz_I - c_I,$$

Instead of averaging predictions, ALE average changes of predictions (via the partial derivatives). The integral over z_I accumulates the differences in the predictions when moving over the range of X_I . A constant c_I is subtracted to center the ALE plot and make sure the mean effect is zero.

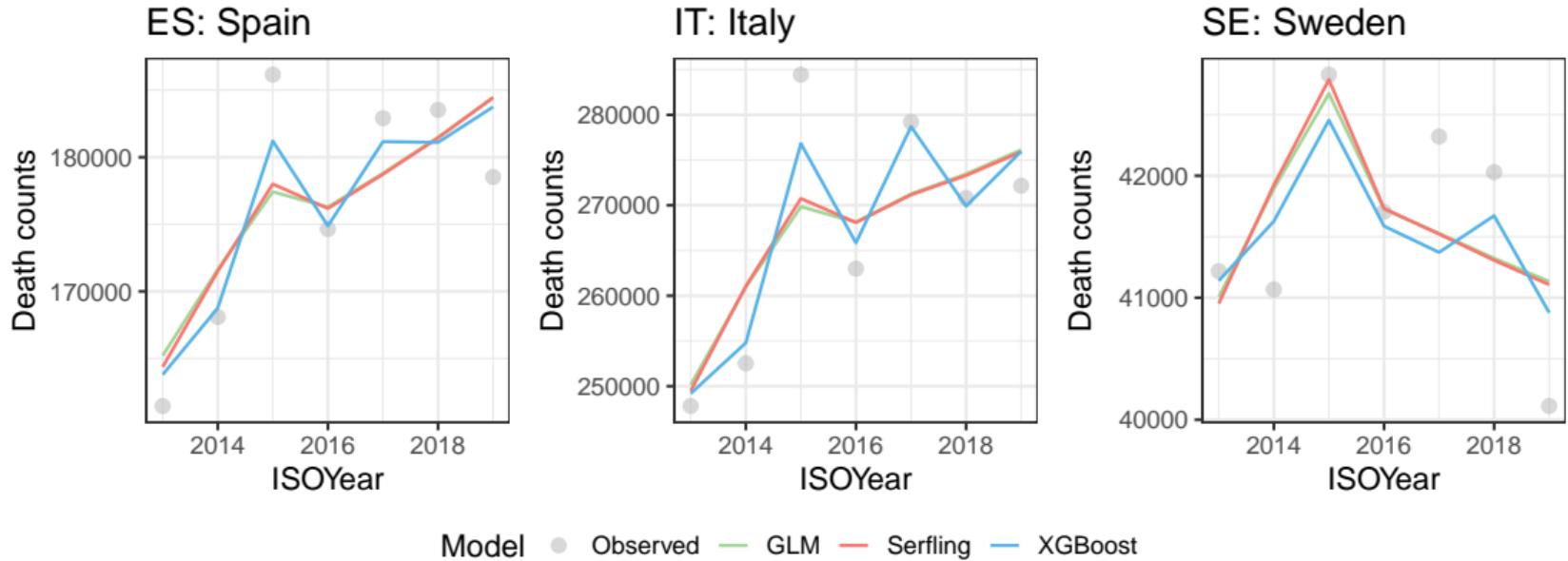
Temporal aggregation

43



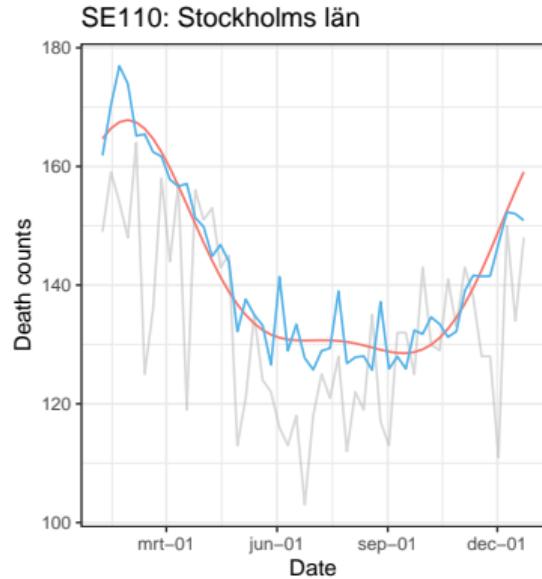
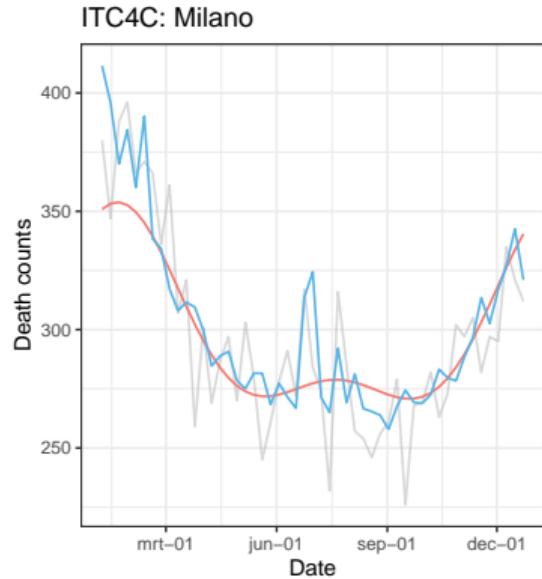
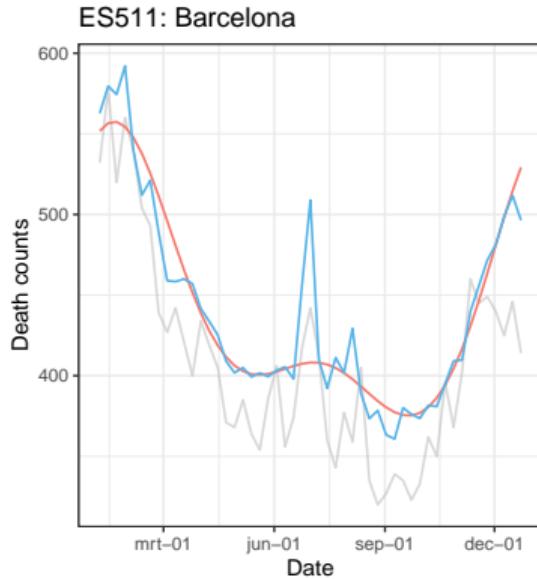
Spatial aggregation

44



Back-testing

45



Back-testing

45

