Rotation error for all estimation methods **Essential Matrix** 3.0 Kabsch Kabsch (EM inliers) Kabsch (PnP inliers) 2.5 Magnitude of rotation (radians) iterative PnP **EPnP** 2.0 1.5 1.0 0.5 0.0 20 60 10 30 40 50 70 +1.5337937e9 Time