,6

 $^{-1.5}_{-1.0}$ $^{-0.5}_{-0.0}$ $^{0.0}_{0.5}$ $^{0.5}_{1.0}$

1.5

1.0

0.5 0.0 Z

-0.5

-1.0

1.5 1.0 0.5 0.0 -0.5 -1.0 1.5 -1.5

30 21

8 19 1 29 ₂27 15 20

33 ₃₂ ₃₁ ₁₁ ₇

10 2 24 25²³ 22 Trajectory estimated using Kabsch