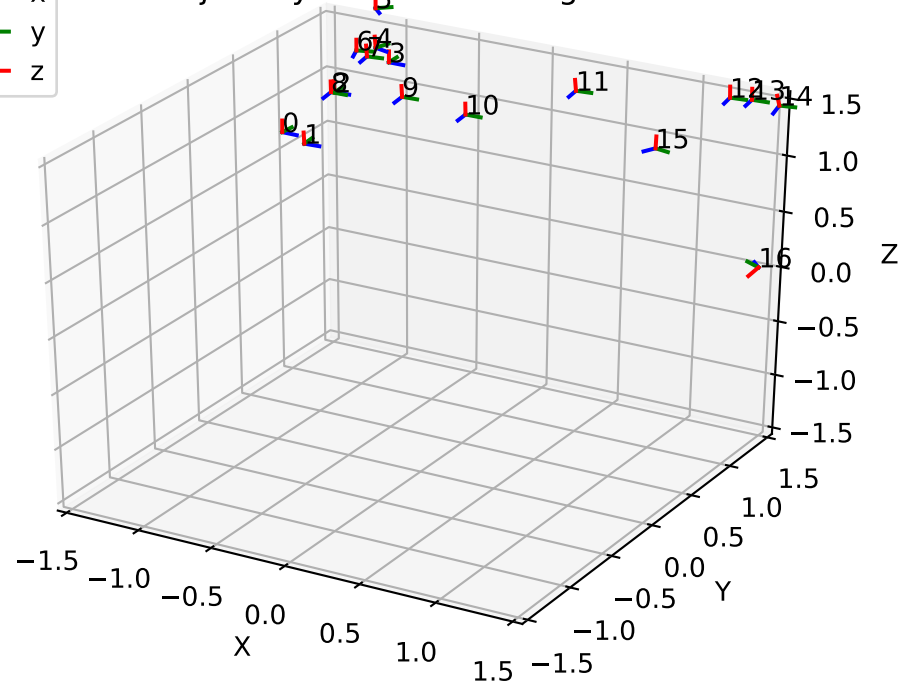


Trajectory estimated using EPnP



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21 18 20

30 31  
28 29 32  
27 25 22

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