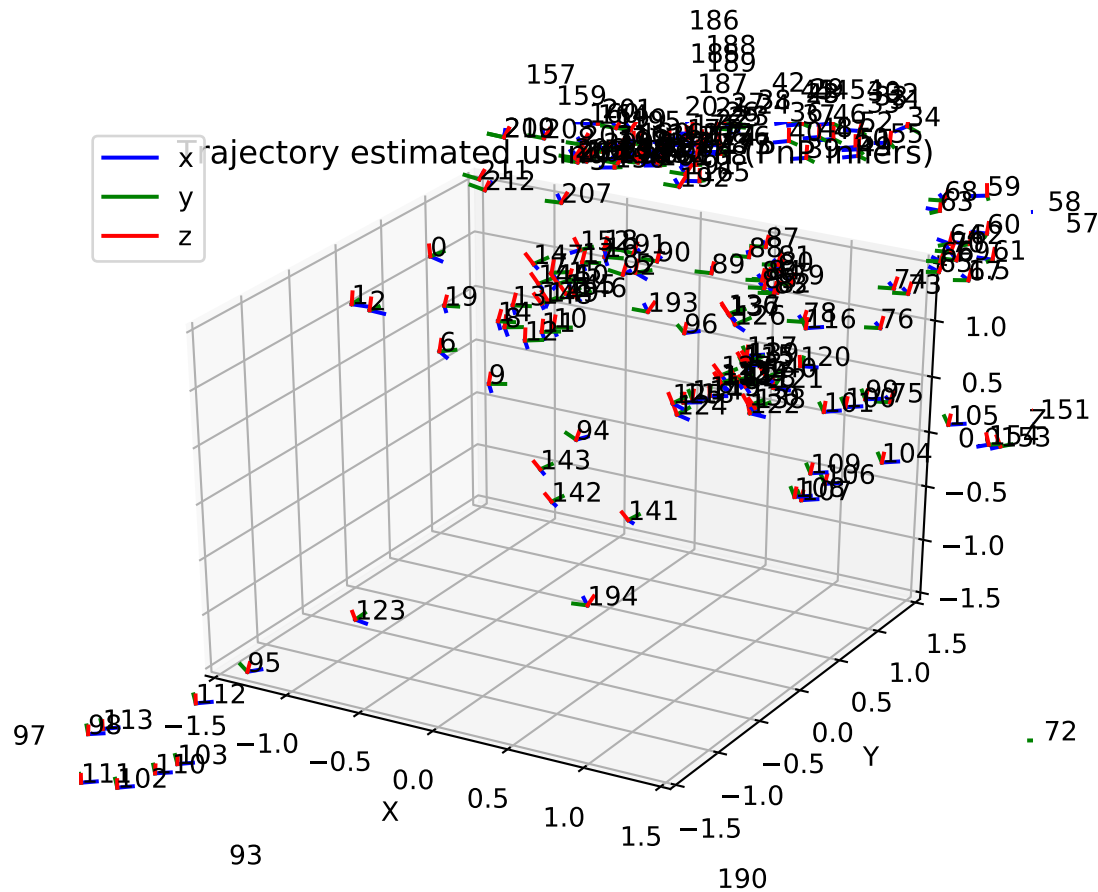


trajectory estimated using



53

41 56

71

77

184

190

93

97

4 3