

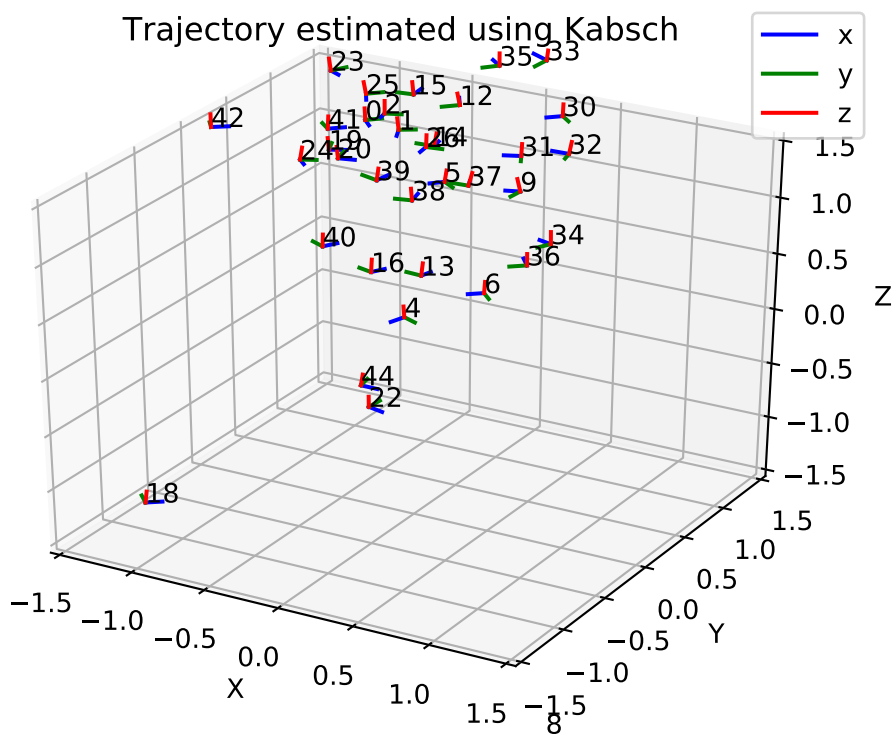
10

3

17 21  
43

29

Trajectory estimated using Kabsch



28