Rotation error for all estimation methods **Essential Matrix** 3.0 Kabsch Kabsch (EM inliers) 2.5 Kabsch (PnP inliers) Magnitude of rotation (radians) iterative PnP **EPnP** 2.0 1.5 1.0 0.5 0.0 250 275 300 375 400 325 350 425 +1.455208e9 Time