x Trajectory estimated using Essential Matrix
y
z 1.5 1.0 0.5 0.0 9 11 13 -0.5 -1.0 -1.5 -1.5 -1.0 -0.5 0.0 0.5 1.0 1.5 -1.5 1.0 X 1.5 -1.5 38 <sub>37</sub> 41 40 42 43 

<sup>4</sup>7<sub>6</sub>