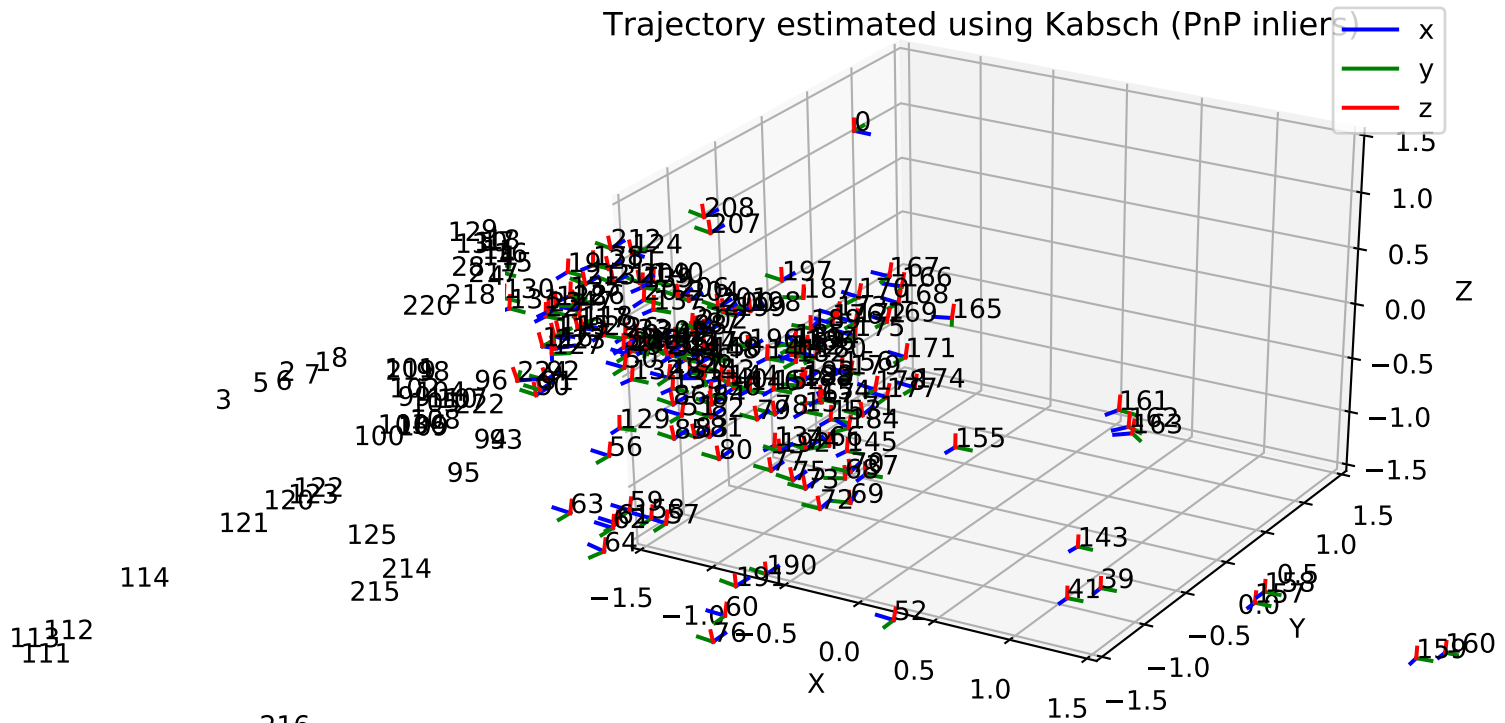


Trajectory estimated using Kabsch (PnP inlier)



164

55

97

221

89

54

53

65