Rotation error for all estimation methods **Essential Matrix** 1.2 Kabsch Kabsch (EM inliers) Kabsch (PnP inliers) Magnitude of rotation (radians) 1.0 iterative PnP **EPnP** 8.0 0.6 0.4 0.2 0.0 10 20 30 50 60 40 70 +1.5337937e9 Time