Rotation error for all estimation methods **Essential Matrix** Kabsch 0.5 Kabsch (EM inliers) Kabsch (PnP inliers) Magnitude of rotation (radians) iterative PnP 0.4 **EPnP** 0.3 0.2 0.1 0.0 450 470 500 520 460 480 490 510 +1.455208e9 Time