13 15

11

25

27

17 23

3

Trajectory estimated using Kabsch (PnP inlier x y z 1.5 1.0 1.0 0.5

8

0.5 Ζ A 0.0 -0.5 929 -1.0 -1 1.5 1.0 0.5 -0.5 -1.0 5 -1.5 -1.5 <sub>-1.0</sub> <sub>-0.5 0.0</sub> 0.5 1.0 -1.51.5 5 24 26 2 16 12