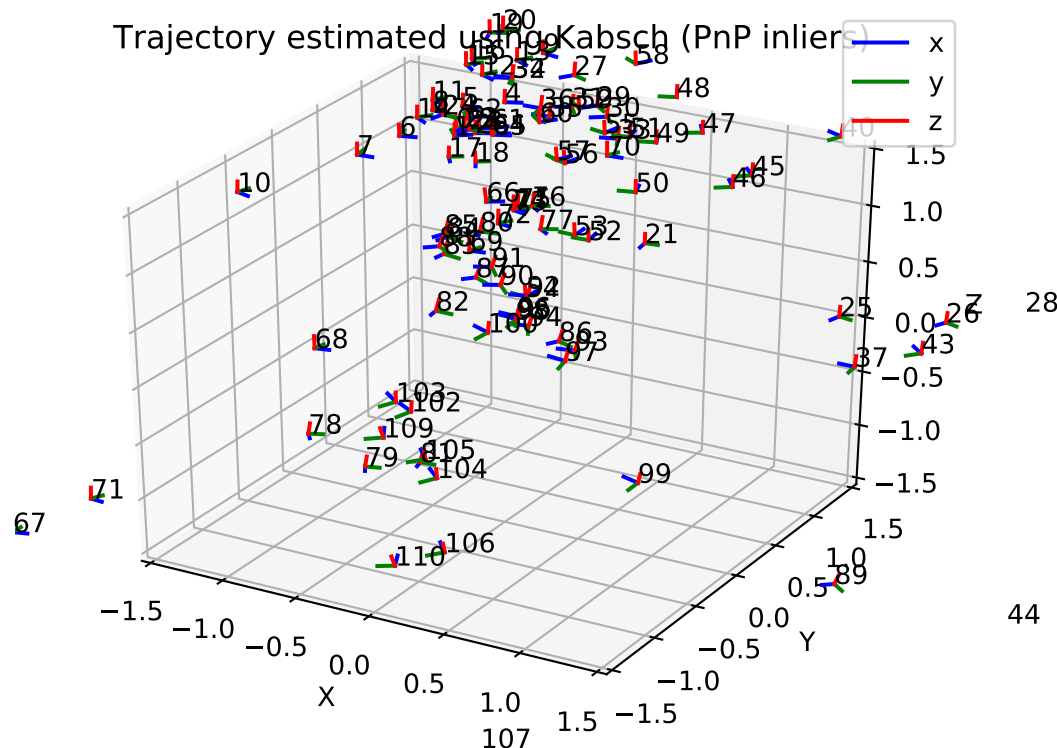


Trajectory estimated using Kabsch (PnP inlier)



63

108

101

42 41

39

44

38

28