

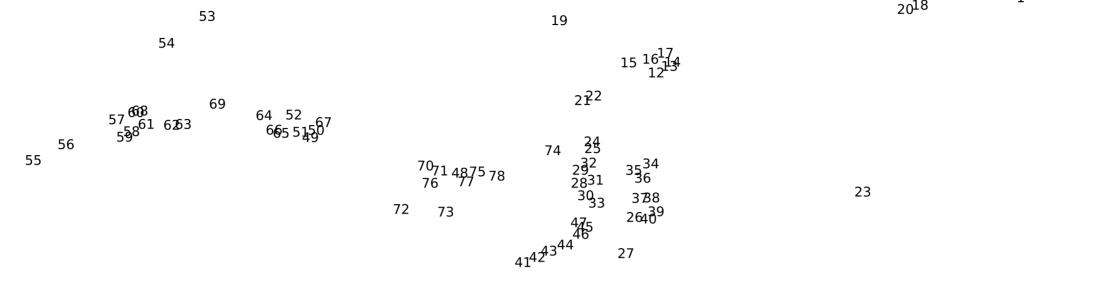
Trajectory estimated using Kabsch

— y
— z

1.0

0.5

· -0.5 · -1.0



81<mark>86</mark>289 7. 97 95 92₉94 1001

11¹211 109 105 104