

28

40

1

54

30

2

8

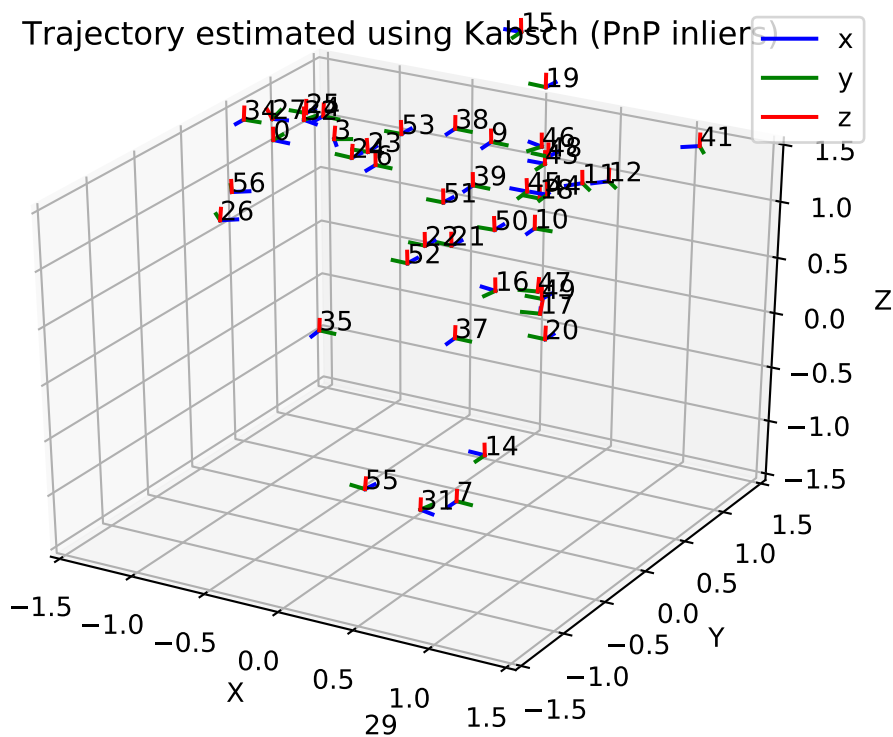
13

5

33

36

Trajectory estimated using Kabsch (PnP inliers)



42