1 What I've done

- Got the quad to talk to the ground station via radio

- Configured the controller

- Set up the TX2 to work with the orbitty and installed librealsense

- Tested my data acquisition code on the TX2, seems to work fine (currently have a compiled version on an SD card which I am running stuff off).

- Attached the mounting to the TX2.

- Did the lab induction.

2 Parts of report to look at

- All new content is in blue

- Added information on Intel RealSense RGB-D Sensor (4.2)

- Started adding formation about the ground station (9.3)

- Copied over Jean-Luc's instructions for setting up the TX1/TX2 with Orbitty carrier

3 Questions

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4 Comments

- Quad is almost ready to fly. I think Alex mentioned he needs to make a custom cable for me to power the TX2 and pixhawk at the same time.

- I talked to Jean-Luc and Yanny on Monday. They want to fly sometime this week, probably Wednesday.