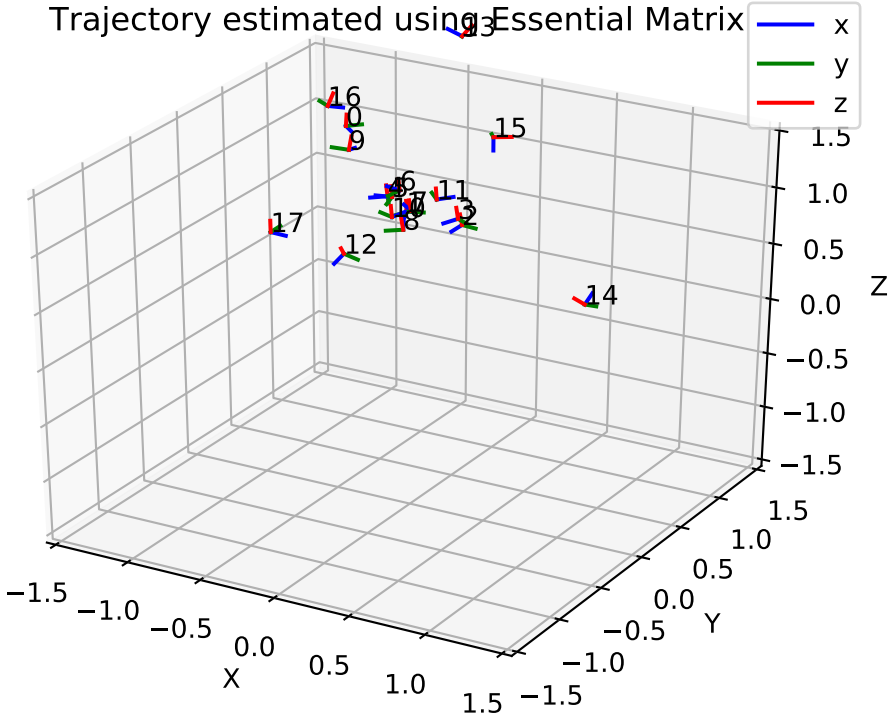
Trajectory estimated using Essential Matrix
x
y
z
X
Y
Z
−1.5
−1.0
−0.5
0.0
0.5
1.0
1.5
0
2
3
4
5
6
7
8
9
11
12
13
14
15
16
17