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Trajectory estimated using Essential Matrix — 22 У 2 <u>A</u> 21 Z 0 13 1.5 5 6 1.0 20 0.5 **1**9 8 0.0 1 Z \_0.5 **1**8 **\_1**2 **\_1**0.0 <u>\_1</u>11 **1**7 -1.51.5 0.5 0.0 -0.5 0 **\_1**13 <u> 1</u>4 **1**6 -1.5 <sub>-1.0</sub> <sub>-0.5</sub> <sub>0.0</sub> X

0.5

1.0

-1.0

1.5 -1.5