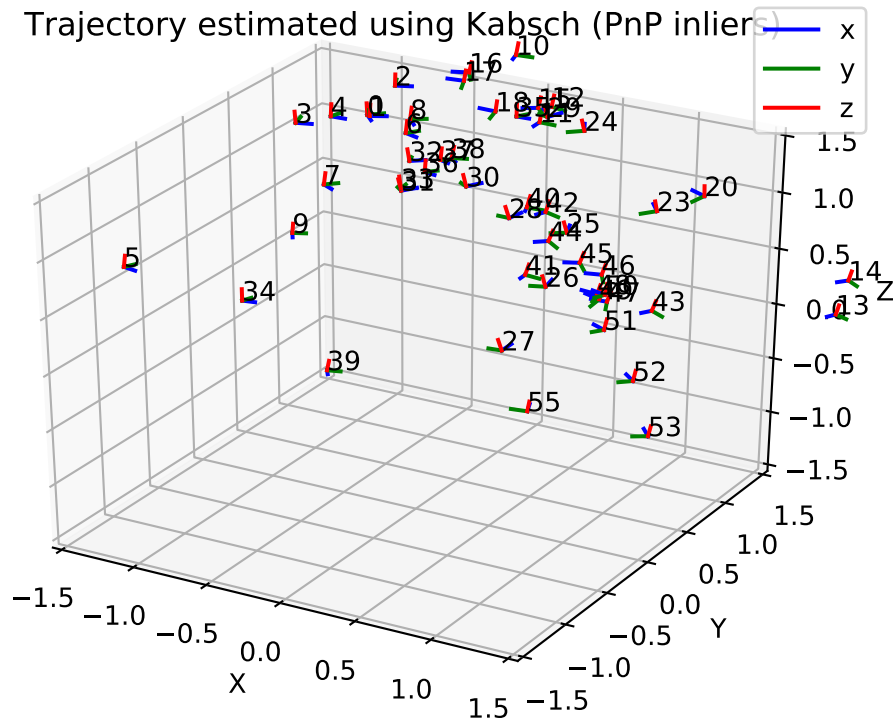


Trajectory estimated using Kabsch (PnP inlier)



19

22