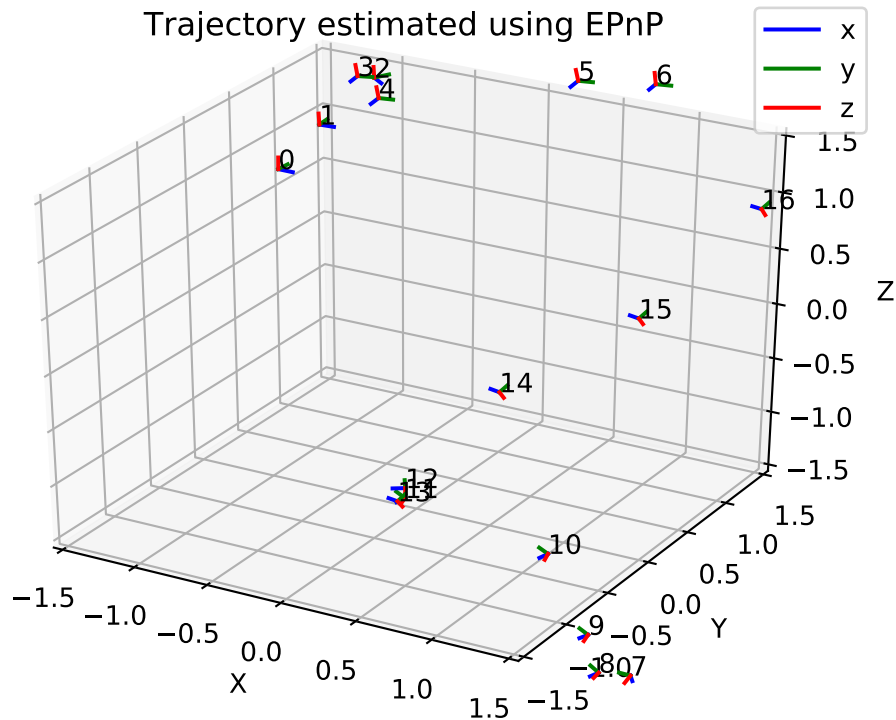


Trajectory estimated using EPnP



170

20

22123