

75

46

58

20

6

8

51

54

15

39

17

3

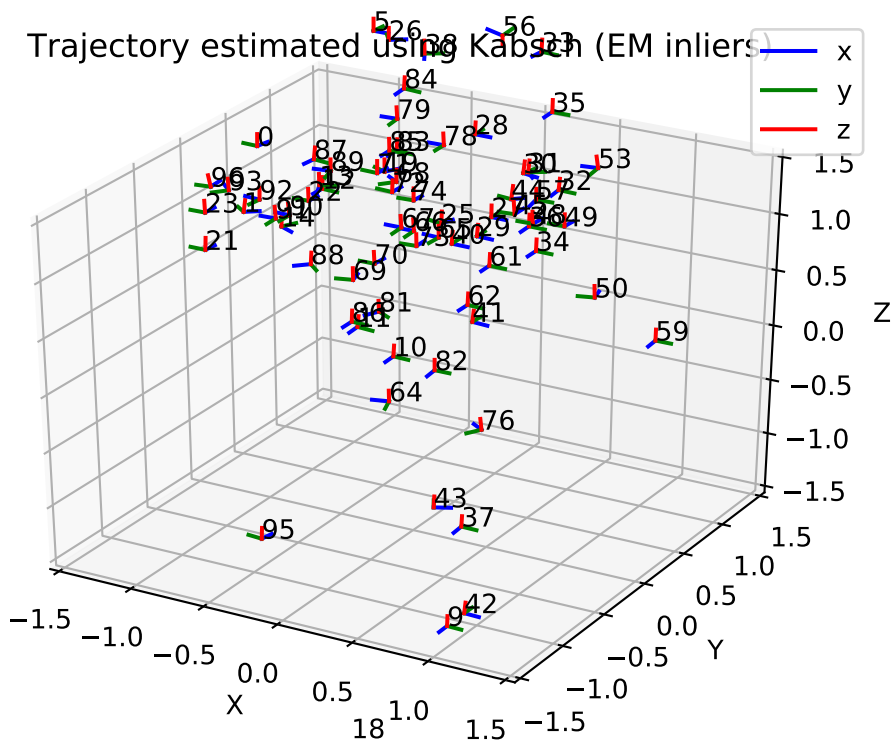
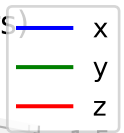
94

80

2

63

Trajectory estimated using Kalman (EM inliers)



77

16⁴

69

7

52

47

24