Rotation error for all estimation methods **Essential Matrix** Kabsch 2.5 Kabsch (EM inliers) Kabsch (PnP inliers) Magnitude of rotation (radians) iterative PnP 2.0 **EPnP** 1.5 1.0 0.5 0.0 160 170 180 200 210 220 230 190 +1.455208e9 Time