Rotation error for all estimation methods **Essential Matrix** 3.0 Kabsch Kabsch (EM inliers) Kabsch (PnP inliers) Magnitude of rotation (radians) 2.5 iterative PnP **EPnP** 2.0 1.5 1.0 0.5 0.0 220 280 180 200 240 260 300 320 +1.455208e9 Time