Rotation error for all estimation methods **Essential Matrix** 3.0 Kabsch Kabsch (EM inliers) 2.5 Kabsch (PnP inliers) Magnitude of rotation (radians) iterative PnP **EPnP** 2.0 1.5 1.0 0.5 0.0 20 30 60 10 40 50 70 +1.5337937e9 Time