Rotation error for all estimation methods **Essential Matrix** 2.5 Kabsch Kabsch (EM inliers) Kabsch (PnP inliers) Magnitude of rotation (radians) 2.0 iterative PnP **EPnP** 1.5 1.0 0.5 0.0 280 180 200 220 240 260 300 320 +1.455208e9 Time