Rotation error for all estimation methods 2.5 **Essential Matrix** Kabsch Kabsch (EM inliers) 2.0 Kabsch (PnP inliers) Magnitude of rotation (radians) iterative PnP **EPnP** 1.5 1.0 0.5 0.0 20 50 60 10 30 40 70 +1.5337937e9 Time