6 9 5

10

13

12

16 17 11

15 14 4

3 18

21 20 24 22 Trajectory estimated using Kabsch \_ z 1.5 1.0 0.5 2 0.0 Z -0.5 -1.0-1 1.5 1.0 0.5 0.0 7 -0.5 Y -1.0 -1.5  $^{-1.5}_{-1.0}_{-0.5}_{\ \ X}^{\ \ 0.0}$ 

0.5

1.0

23