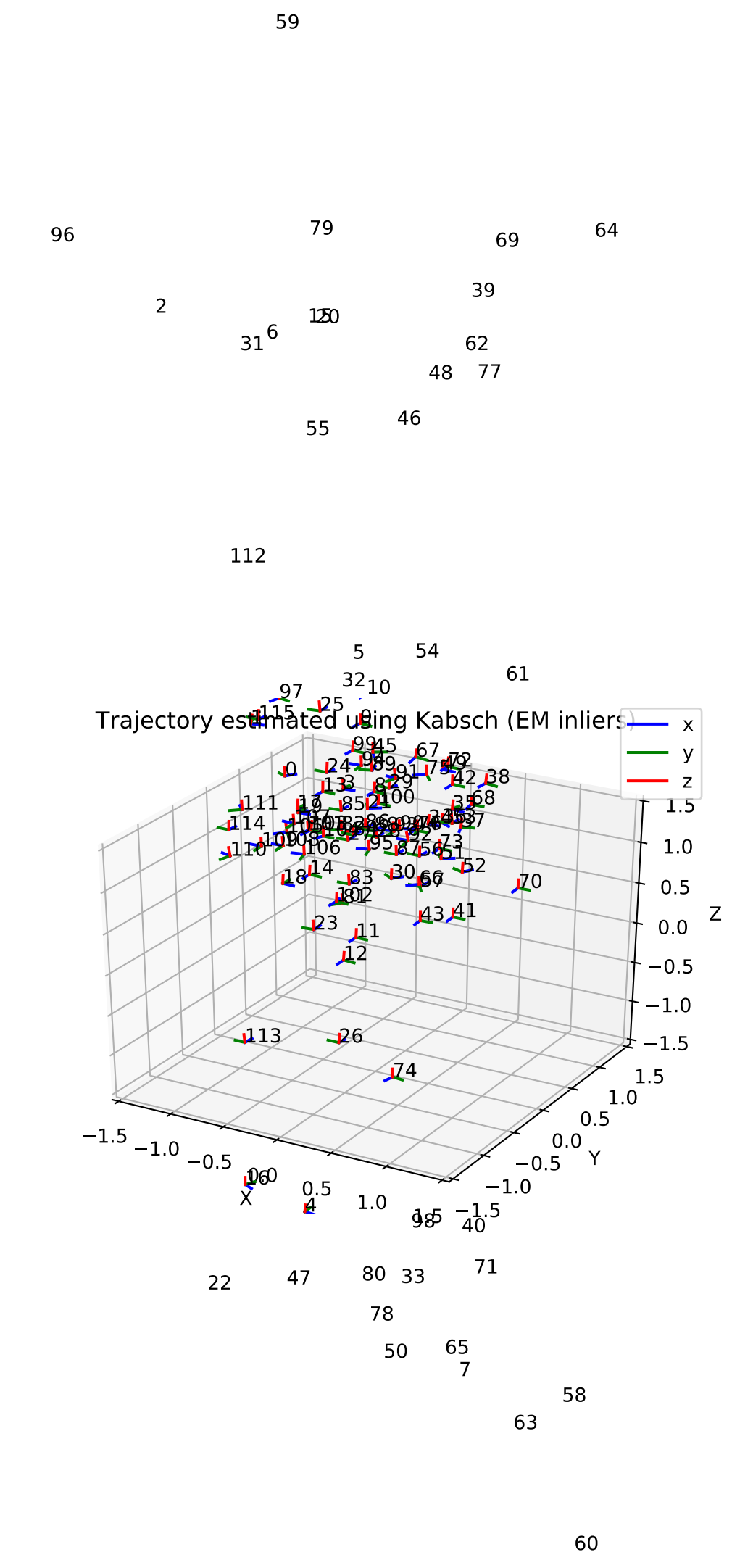
Trajectory estimated using Kabsch (EM inliers)
x
y
z
X
Y
Z