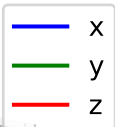


Trajectory estimated using Essential Matrix



Z

1.5

1.0

0.5

0.0

-0.5

-1.0

-1.5

1.5

1.0

0.5

0.0

-0.5

Y

-1.0

-1.5

1.0

0.5

0.0

-0.5

-1.0

-1.5

X

