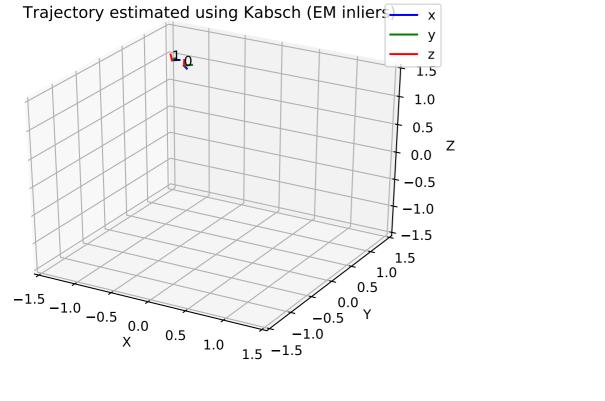
2 3



Trajectory estimated using Kabsch (EM inliers)— $_{x}$