Rotation error for all estimation methods 1.4 **Essential Matrix** Kabsch Kabsch (EM inliers) 1.2 Kabsch (PnP inliers) Magnitude of rotation (radians) iterative PnP 1.0 EPnP 8.0 0.6 0.4 0.2 0.0 30 10 50 60 20 70 40 +1.5337937e9 Time