Rotation error for all estimation methods **Essential Matrix** 3.0 Kabsch Kabsch (EM inliers) Kabsch (PnP inliers) 2.5 Magnitude of rotation (radians) iterative PnP **EPnP** 2.0 1.5 1.0 0.5 0.0 360 380 400 420 440 460 +1.455208e9 Time