

9

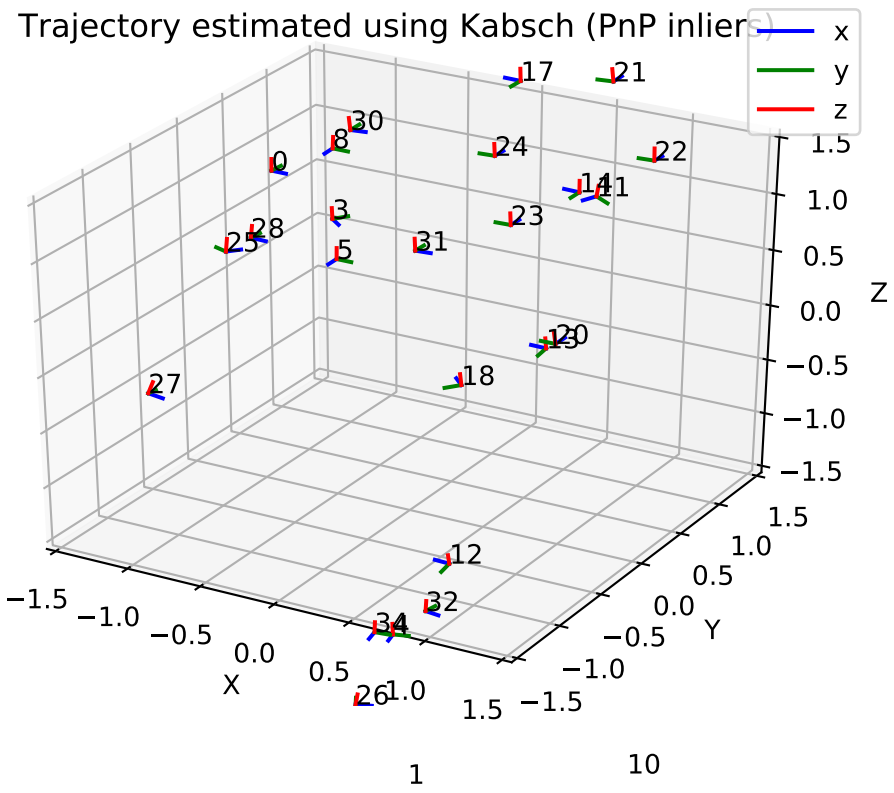
6

29 2

33

19

Trajectory estimated using Kabsch (PnP inlier)



7