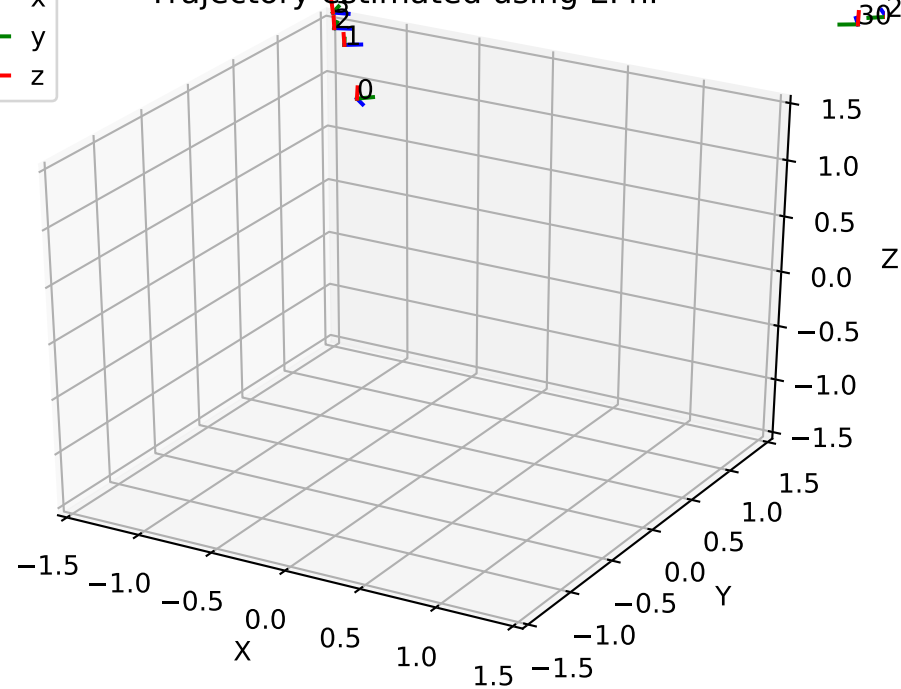


Trajectory estimated using EPnP



Z

Y

X

38

36

39

40

43
42
41

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