

18

11

5

8

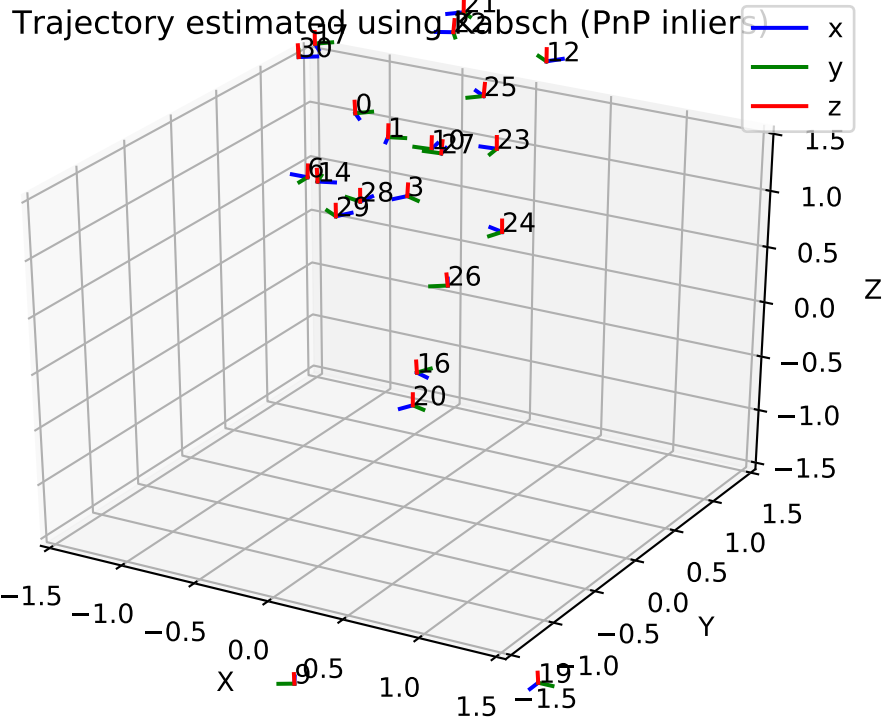
15

31

2

4

Trajectory estimated using Kabsch (PnP inlier)



7

13