

14

18

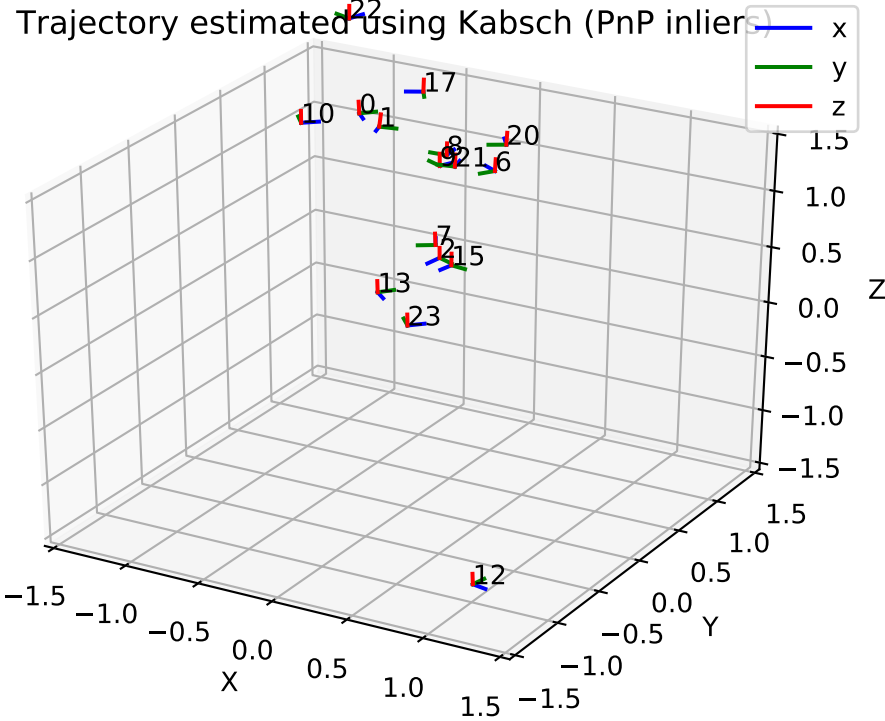
3

11

24

4

Trajectory estimated using Kabsch (PnP inliers)



19

16

5