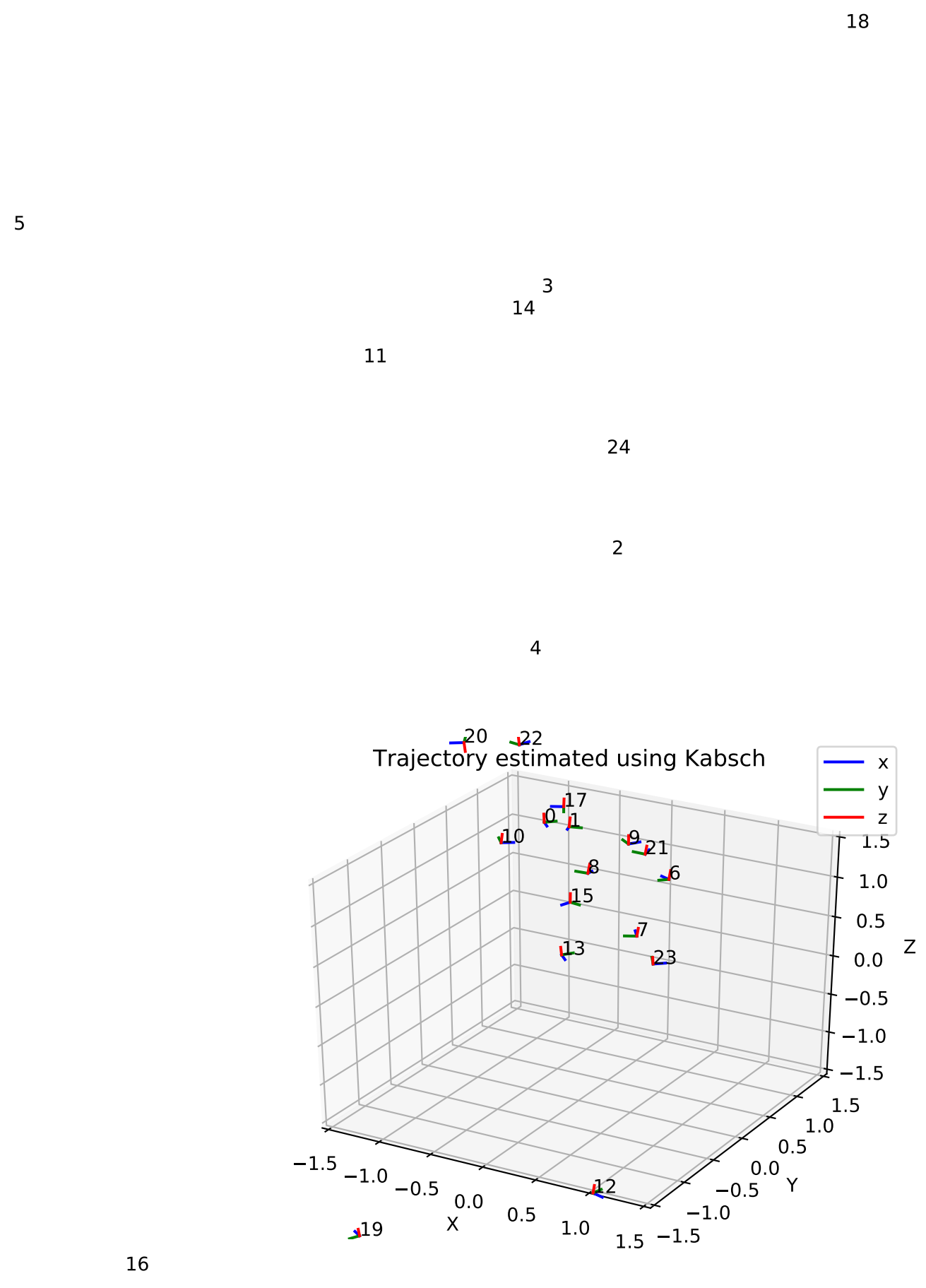
Trajectory estimated using Kabsch
x
y
z
X
Y
Z
−1.5
−1.0
−0.5
0.0
0.5
1.0
1.5
0
1
2
3
4
5
6
7
8
9
10
11
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