Thesis Proposal

O. Tate Kernell¹

¹Department of Mathematics, Baylor University

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- Robert Kirby
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Linearized Rotating Shallow-Water Equations with Damping

Tide Model

$$u_{t} + \frac{f}{\epsilon} u^{\perp} + \frac{\beta}{\epsilon^{2}} \nabla (\eta - \eta') + g(u) = F$$
$$\eta_{t} + \nabla \cdot (Hu) = 0,$$

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- u: nondimensional two dimensional velocity field tangent to Ω
- u^{\perp} : $(-u_2, u_1)$ velocity rotated by $\pi/2$
- η: nondimensional free surface elevation above the height at a state of rest
- $\nabla \eta'$: spatially varying tidal forcing

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- $ightharpoonup \epsilon$: Rossby number (small)
- f: spatially-dependent non-dimensional Coriolis parameter
- \triangleright β : Burger number (small)
- H: spatially varying non-dimensional fluid depth at rest
- g(u): monotonic damping function



First-Order Equation

$$qu_t + \nabla p = 0,$$

$$k^{-1}p_t + \nabla \cdot u = 0,$$

on some domain $\Omega \times [0,T] \subset \mathbb{R}^d \times \mathbb{R}$ with d=2,3 and Ω assumed to be polyhedral

Boundary and Initial Conditions

We impose the initial conditions:

$$p(x,0)=p_0(x)$$

$$u(x,0)=u_0(x)$$

with the boundary condition $u*\nu=0$ on $\partial\Omega$ where ν is the unit outward normal to Ω

Weak Form

Multiplying and integrating by parts gives

$$(u_t, v) + (\nabla p, v) = (f, v), v \in H_0(div)$$

 $(p_t, w) + (\nabla \cdot u, w) = (g, w), w \in L_0^2$

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 \downarrow
 $(u_t, v) - (p, \nabla \cdot v) + \underbrace{\langle p, v \cdot \nu \rangle_{\partial\Omega}}_{=0} = (f, v),$
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where $u:[0,T]\to V\equiv H_0({\rm div})$ and $p:[0,T]\to W\equiv L_0^2$

Semidiscrete Mixed Form

The semidiscrete mixed formulation is to find $u_h:[0,T]\to V_h$ and $p_h:[0,T]\to W_h$ such that

$$(u_{h,t},v_h)-(p_h,\nabla\cdot v_h)=(f,v_h),(p_{h,t},w_h)+(\nabla\cdot u_h,w_h)=(g,w_h),$$

 $\forall v_h \in V_h \text{ and } w_h \in W_h \text{ where } V_h \subset V \text{ and } W_h \subset W$

Crank Nicolson

Partitioning [0, T] into timesteps $0 \equiv t_0 < t_1 < \cdots < t_N$ where $t_i = i\Delta t$ and applying Crank Nicolson leads to

$$\begin{split} &\left(\frac{u_h^{n+1}-u_h^n}{\Delta t},v_h\right)-\left(\frac{p_h^{n+1}+p_h^n}{2},\nabla\cdot v_h\right)=\left(f^{n+\frac{1}{2}},v_h\right),\\ &\left(\frac{p_h^{n+1}-p_h^n}{\Delta t},w_h\right)+\left(\nabla\cdot\frac{u_h^{n+1}+u_h^n}{2},w_h\right)=\left(g^{n+\frac{1}{2}},w_h\right), \end{split}$$

where $u_h(t_n) \approx u_h^n \in V_h$, $p_h(t_n) \approx p_h^n \in W_h$, $f^{n+\frac{1}{2}} = \frac{f(t_{n+1}) + f(t_n)}{2}$, and similarly for g.

Crank Nicolson

Reshuffling terms leads to

$$(u_h^{n+1}, v_h) - \frac{\Delta t}{2} (p_h^{n+1}, \nabla \cdot v_h) = \tilde{F},$$

$$(p_h^{n+1}, w_h) + \frac{\Delta t}{2} (\nabla \cdot u_h^{n+1}, w_h) = \tilde{G},$$

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where

$$\tilde{F} = (u_h^n, v_h) + \frac{\Delta t}{2} (p_h^n, \nabla \cdot v_h) + \left(f^{n+\frac{1}{2}}, v_h \right),
\tilde{G} = (p_h^n, w_h) - \frac{\Delta t}{2} (\nabla \cdot u_h^n, w_h) + \left(g^{n+\frac{1}{2}}, w_h \right).$$

Discretization

Let $\{\phi_i\}_{i=1}^{|W_h|}$ and $\{\psi_i\}_{i=1}^{|V_h|}$ be bases for W_h and V_h respectively. Then we can define mass matrices

$$M_{ij} = (\phi_j, \phi_i),$$

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We can formulate the semidiscrete mixed form as

$$\begin{bmatrix} \tilde{M} & 0 \\ 0 & M \end{bmatrix} \begin{bmatrix} u_t \\ p_t \end{bmatrix} + \begin{bmatrix} 0 & -D^T \\ D & 0 \end{bmatrix} \begin{bmatrix} u \\ p \end{bmatrix} = \begin{bmatrix} F \\ G \end{bmatrix},$$

where $D_{ij} = (\operatorname{div} \psi_i, \phi_j)$, is the discrete div operator and F and G are the vectors (f, v_h) and (g, w_h) respectively.

Discretization

Then our final Crank Nicolson discretization is

$$\mathscr{A}_h \begin{bmatrix} u_h^{n+1} \\ p_h^{n+1} \end{bmatrix} = \begin{bmatrix} \tilde{F} \\ \tilde{G} \end{bmatrix},$$

where

$$\mathscr{A}_h = \begin{bmatrix} \tilde{M} & -\frac{\Delta t}{2}D^T \\ \frac{\Delta t}{2}D & M \end{bmatrix},$$

Crank Nicolson (again)

Applying Crank Nicolson again in the time derivative without discretizing in space becomes

$$u^{n+1} + \frac{\Delta t}{2} \nabla p^{n+1} = u^n - \frac{\Delta t}{2} \nabla p^n$$
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Therefore, at each timestep we have a discretization of the coefficient operator \mathscr{A} , described as

$$\mathscr{A} = \begin{pmatrix} I & \epsilon \operatorname{grad} \\ \epsilon \operatorname{div} & I \end{pmatrix}, \text{ where } \epsilon = \frac{\Delta t}{2}$$



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By discretizing in the finite element space $H_0(\text{div}) \times L_0^2$, we recover our finite dimensional coefficient operator, \mathscr{A}_h .



Mardal/Winther

We claim $\mathscr A$ is an isomorphism mapping $H(\operatorname{div}) \times L^2$ onto $H(\operatorname{div})^* \times L^2$, its dual space. Our goal is then to find a preconditioner $\mathscr B$ which maps $H(\operatorname{div})^* \times L^2$ onto $H(\operatorname{div}) \times L^2$.

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$$\mathscr{B} = \begin{bmatrix} \beta I - \alpha \operatorname{grad} \operatorname{div} & \mathbf{0} \\ \mathbf{0} & \gamma I \end{bmatrix}$$

Discrete Form

Similarly, the discrete preconditioner is of the form

$$\mathscr{B}_{h} = \begin{bmatrix} \alpha(\nabla \cdot, \nabla \cdot) + \beta(\cdot, \cdot) & 0 \\ 0 & \gamma(\cdot, \cdot) \end{bmatrix}.$$

For this preconditioner, our goal is to look at the eigenvalues of $\mathscr{B}_h^{-1}\mathscr{A}_h$ as a function of α , β , and γ . We want to choose these parameters so that our preconditioner is robust in terms of Δt and h, thus eliminating the dependence on ϵ .

Conjectures

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The operator $\mathscr{B}_h^{-1}\mathscr{A}_h$ has mesh-independent eigenvalue clustering

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Conjecture 3

The correct choice of α , β , and γ can force κ to be of order 1



Questions?

Thank you!