# Parallel Sorting

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# Logistics

# Today

- Parallel Sorting: Quicksort
- ▶ Wed: Mini-exam 2

### Reading: Grama Ch 9

- Sorting
- ► Focus on 9.4: Quicksort

## **Quick Review**

- What is Amdahl's law? What does it say about the speedup achievable by parallel programs?
- ► How does one calculate the following for a parallel algorithm
  - ► *S*: Speedup
  - ► *E*: Efficiency
  - ► *C*: Cost
- ▶ How does the Efficiency of a parallel usually change if the number of processors P increases but the problem size stays the same? If number of procs stays the same but problem size increases?
- ► What was the major benefit that Cannon's Algorithm provided over a naive implementation of parallel matrix multiply?
- ▶ In broad strokes, how was the LU factorization parallelized?

# Sorting

- Much loved computation problem
- What is the best complexity of general purpose (comparison-based) sorting algorithms?
- What are some algorithms which have this complexity?
- What are some other sorting algorithms which aren't so hot?
- What issues need to be addressed to parallelize any sorting algorithm?

## Partition and Quicksort

- ▶ Quicksort has  $O(N \log N)$  average complexity
- In-place, low overhead sorting, recursive

#### **Partition**

- ► Partition: select pivot value
- Rearrange elements so
  - ▶ Left array is ≤ pivot
  - ► Right array is > pivot
  - pivot is in "middle"

```
// A is an array, lo/hi are
// inclusive boundaries
algorithm partition(A, lo, hi) is
pivot := A[hi]
boundary := lo
for j := lo to hi do
  if A[j] <= pivot then
    swap A[boundary] with A[j]
  boundary++
swap A[boundary] with A[hi]
return boundary</pre>
```

### Quicksort

- Partition into two parts
- Recurse on both halves
- ▶ Bail out when boundaries lo/hi cross

```
algorithm quicksort(A, lo, hi) is
if lo < hi then
  p := partition(A, lo, hi)
  quicksort(A, lo, p - 1)
  quicksort(A, p + 1, hi)</pre>
```

## Practical Parallel Sorting Setup

 Input array A of size N is already spread across P processors (no need to scatter)

```
P0: A[] = { 84 31 21 28 }
P1: A[] = { 17 20 24 84 }
P2: A[] = { 24 11 31 99 }
P3: A[] = { 13 32 26 75 }
```

Goal: Numbers sorted across processors. Smallest on P0, next smallest on P1, etc.

```
P0: A[] = { 11 13 17 20 }
P1: A[] = { 21 24 24 26 }
P2: A[] = { 28 31 32 33 }
P3: A[] = { 75 84 84 99 }
```

- ▶ Want to use *P* processors as effectively as possible
- Favor bulk communication over many small messages

## Exercise: Parallel Quicksort

- Find a way to parallelize quicksort
- ▶ **Hint:** The last step is each processor sorting its own data using a serial algorithm. Try to arrange data so this is possible.

```
START:
                                             SERTAL ALGORITHM
P0: A[] = \{ 84 \ 32 \ 21 \ 28 \}
                                             algorithm quicksort(A, lo, hi) is
P1: A[] = \{ 17 20 25 85 \}
                                              if lo < hi then
P2: A[] = \{ 24 \ 11 \ 31 \ 99 \}
                                                p := partition(A, lo, hi)
                                                quicksort(A, lo, p - 1)
P3: A[] = \{ 13 32 26 75 \}
                                                quicksort(A, p + 1, hi)
GOAL
P0: A[] = \{ 11 \ 13 \ 17 \ 20 \}
                                             algorithm partition(A, lo, hi) is
P1: A[] = \{ 21 \ 24 \ 25 \ 26 \}
                                               pivot := A[hi]
P2: A[] = \{ 28 \ 31 \ 32 \ 33 \}
                                               boundary := lo
P3: A[] = \{ 75 84 85 99 \}
                                               for j := lo to hi - 1 do
                                                 if A[j] <= pivot then
                                                    swap A[boundary] with A[j]
                                                    boundary++
                                               swap A[i] with A[hi]
                                               return boundary
```

# **Answers**: Parallel Quicksort Ideas 1 / 2

```
A[] = \{ 84 \ 32 \ 21 \ 11 \ | \ 17 \ 20 \ 25 \ 85 \ | \ 24 \ 28 \ 31 \ 99 \ | \ 13 \ 33 \ 26 \ 75 \ \}
                                       P2
        PΩ
                        P1
                                                       P.3
Partition(pivot=26) on each processor
A[] = { 21 11 84 32 | 17 20 25 85 | 24 28 31 99 | 13 26 33 75 }
Boundary: ^
Counts: PO: 2
                   P1: 3
                                    P2: 1
                                                       P3: 2
Calculate which data goes where
A[] = { 21 11 84 32 | 17 20 25 85 | 24 28 31 99 | 13 26 33 75 }
        PO PO P2 P2 PO PO P1 P2 P1 P2 P3 P3 P1 P1 P3 P3
Re-arrange so values <= 26 on PO and P1, > 26 on P2 and P3
A[] = { 21 11 17 20 | 25 24 13 26 | 84 32 85 28 | 31 99 33 75 }
        PΩ
                        P1
                                       P2
                                                       P.3
Split the world: 2 groups
A[] = \{ 21 \ 11 \ 17 \ 20 \ | \ 25 \ 24 \ 13 \ 26 \} | \{ 84 \ 32 \ 85 \ 28 \ | \ 31 \ 99 \ 33 \ 75 \ \}
        P0
                        P1
                                       P2
                                                       Р3
```

# **Answers**: Parallel Quicksort Ideas 2 / 2

```
Each half partitions on different pivot value
          PO-P1: Partition(pivot=20) P2-P3: Partition(pivot=33)
A[] = \{ 11 \ 17 \ 20 \ 21 \ | \ 13 \ 25 \ 24 \ 26 \} | \{ 28 \ 32 \ 84 \ 85 \ | \ 31 \ 33 \ 99 \ 75 \ \}
Boundary:
Counts: PO: 3
                        P1: 1
                                          P2: 2
                                                            P3: 2
Calculate which data goes where
A[] = \{ 11 \ 17 \ 20 \ 21 \ | \ 13 \ 25 \ 24 \ 26 \} | \{ 28 \ 32 \ 84 \ 85 \ | \ 31 \ 33 \ 99 \ 75 \ \}
          PO PO PO P1 PO P1 P1 P1 P2 P2 P3 P3 P2 P2 P3 P3
Re-arrange values to proper processors
A [] = \{ 11 \ 17 \ 20 \ 13 \ | \ 21 \ 25 \ 24 \ 25 \} | \{ 28 \ 32 \ 31 \ 33 \ | \ 84 \ 85 \ 99 \ 75 \ \}
          PΩ
                           P1
                                             P2
                                                               P.3
Split the world: 4 groups
A[] = \{ 11 \ 17 \ 20 \ 13\} | \{21 \ 25 \ 24 \ 25\} | \{28 \ 32 \ 31 \ 33\} | \{84 \ 85 \ 99 \ 75 \ \}
          PΩ
                           P1
                                              P2
                                                                P.3
4 groups == 4 processors, all processors sort locally
A[] = \{ 11 \ 13 \ 17 \ 20\} | \{21 \ 24 \ 25 \ 25\} | \{28 \ 31 \ 32 \ 33\} | \{75 \ 84 \ 85 \ 99 \ \}
          P0
                            P1
                                              P2
                                                                P3
```

## Quicksort Difficulties

#### Communication

- Determine which data go to which processors, how many send/receives are required
- Opportunity for all-to-all communications in MPI

### Recursing

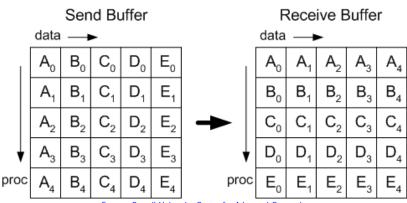
- Recursive step of algorithm requires smaller "worlds"
- Use MPI's communicator splitting capability

#### Pivot Value Selection

- In example, pivot values were cherry-picked to get even distribution of data among processors
- A bad pivot splits data unevenly, is annoying for serial Quicksort, shaves off processors in parallel quicksort destroying efficiency

#### All-to-All Personalized Communication

All-to-all personalized communication: like every processor scattering to every other processor.



Source: Cornell University Center for Advanced Computing

## MPI\_Alltoall

- Standard version: every processor gets a slice of sendbuf, same sized data
- Vector version allows different sized slices (appropriate for quicksort)

```
int MPI_Alltoall(
  void *sendbuf, int sendcount, MPI_Datatype sendtype,
  void *recvbuf, int recvcount, MPI_Datatype recvtype,
  MPI_Comm comm);

int MPI_Alltoallv(
  void *sendbuf, int sendcounts[], int sdispls[], MPI_Datatype sendtype,
  void *recvbuf, int recvcounts[], int rdispls[], MPI_Datatype recvtype,
  MPI_Comm comm);
```

## Exercise: Redistribution during Quicksort

- ► After partition, procs must redistribute data
- Use All-Gather so that all procs have the following table

E.	lement	vs	Pivot			
1	Proc		<=	1	>	1
1.		+-		+-		1
	P0		2		2	1
	P1		3		1	1
1	P2		1	1	3	1
Τ	Р3	1	2	ı	2	1

### Want each Proc to calculate its own Count/Displ in this table:

- :	P#	•								P3	 	•		•		•		•		•	P#	
		RecvCount									SendCount							Ċ			PO I	
	P1	1	1	0		1	l	1		2			2		1	l	1		0	l	P1	
	P2	1	1	2	1	1	ı	1		0			0		1	l	1		2	l	P2	
	РЗ	1		0	ı	0	ı	2	1	2			0	I	2	ı	0	I	2	ı	P3	
		1	1		1		ı									l				l	- 1	
	P0	RecvDispl		0	ı	2	ı	4	1	4	SendDispl		0	ı	0	ı	2	I	0	ı	P0	
	P1	I		0	ı	0	ı	1	1	2			0	I	2	ı	3	I	4	ı	P1	
	P2	1	1	0	ı	2	ı	3	1	4		1	0	I	0	I	1	Ī	2	I	P2	
- 1	РЗ	I	1	0	l	0	I	0	1	2		1	0	I	0	I	2	١	2	I	P3	

- Describe the process of calculating RecvCount
- Given RecvCount, how can one calculate RecvDispl

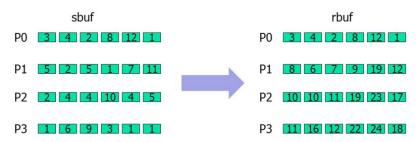
# **Answers**: Redistribution during Quicksort

- ▶ RecvCount can be calculate through an iterative process
- Compute the prefix sum of for the table

- Know each proc must send/receive N / P = 4 elements
- Procs receiving <= pivot, proc # i, scan column 0 for</p>
  - First partner is proc F where PS[F,0] <= 4\*i</p>
  - ► Last partner is proc L where PS[L,0] >= 4\*(i+1)
- ▶ Procs receiving > pivot, proc # i, scan column 1 for
  - ► First partner is proc F where PS[F,1] <= 4\*(i-2)
  - ► Last partner is proc L where PS[L,1] >= 4\*(i-2+1)
- ► Actual code will need to do some arithmetic (e.g. P1 receives 1 element from itself)
- RecvDispl is the prefix sum of RecvCount

# Prefix Sums / Scan

Prefix Sums or Prefix Scans are supported in parallel via MPI



- Similar to reduction but only add on values from procs <= proc\_id</p>
- op can be sum/max/min/etc.
- In simple Quicksort implementations, don't use parallel prefix scan as this does not yield enough info to calculate send/receive partners

### Overall Flow

- 1. Pivot selection (open question how to do this right)
- 2. Broadcast of pivot value
- 3. Each processor partition's its data
- 4. All-gather to get element/pivot counts
- 5. Calculate send/receives
- Redistribute data via MPI\_Alltoallv()
- 7. And then...

# Splitting the World

- comm is the old communicator (start with MPI\_COMM\_WORLD)
- color is which sub-comm to go into
  - Colors 0,1 splits into 2 communicators
  - Colors 0,1,2,3 splits into 4 communicators
  - Etc.
- key establishes rank in new sub-comm, usually proc\_id
- newcomm is filled in with a new communicator
- Examine 04-mpi-code/comm\_split.c
- ▶ In Quicksort, new comm is different for lower/upper procs

#### Exercise: Pivot Selection

- ▶ So far have assumed a "good" pivot can be found
- Pivot evenly splits N/2 data, half to lower # processors, half to upper

Discuss the following questions with a neighbor

- 1. What if the pivot is poorly selected? E.g. 1/4 below pivot, 3/4 above? Could the algorithm adapt?
- 2. How could one avoid a bad pivot? Discuss a some strategies
- 3. Is there a way to avoid recusing entirely?

# **Answers**: Pivot Selection 1/2

Discuss the following questions with a neighbor

- 1. What if the pivot is poorly selected? E.g. 1/4 below pivot, 3/4 above? Could the algorithm adapt?

  With some additional computation, can split the world unevenly: 1/4 procs assigned to "low" numbers, 3/4 to "high" numbers. Still broken if a tiny fraction of the array is lower/higher than the pivot: should just try another pivot at that point or use a scheme that prevents poor pivot selection.
- 2. How could one avoid a bad pivot? Discuss a some strategies

  Lots of these exist, some mentioned in the textbook such
  as having a randomly selected processor compute its median and broadcast it as the pivot (main text of Grama)
  or have processors sample random elements, perform AllGather, then compute a median as the common pivot
  (Grama Exercise 9.21).

# **Answers**: Pivot Selection 1/2

3. Is there a way to avoid recusing entirely, e.g. single multiway pivot?

Grama Exercise 9.20 explores this:

- lacktriangle Each proc samples elements, often around  $\log(N)$  elements, and procs perform an All-Gather
- All procs use common sample to select P-1 common pivots.
- ► Elements between pivots are sent directly to final destination procs in an All-to-All communication.
- Local sorting commences.

#### Exercise: Odd-Even Sort

- Variant of bubble sort which splits bubbling into odd/even phases
- $ightharpoonup O(N^2)$  complexity of serial algorithm
- ► There is potential for parallelism here: what is it?
  - Consider simple case where each P = N: each proc hold a single number
  - What can be parallelized and how?

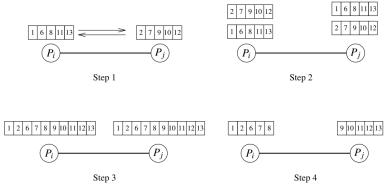
```
ODD_EVEN_SORT(A[]) {
  N = length(A[])
  for (r=0 \text{ to } N-1) {
    if(r is even){
      for(i=0; i<N-1; i+=2){
        compare_exchange(A, i, i+1);
    if(r is odd){
      for(i=1; i<N-1; i+=2){
        compare_exchange(A, i, i+1);
COMPARE_EXCHANGE(A[], i, j){
  if(A[i] > A[j]){
    temp = A[i]
    A[i] = A[j]
    A[j] = temp
```

### Answers: Odd-Even Sort

- ► There is potential for parallelism here: what is it?
- Consider simple case where each P=N: each proc hold a single number
- ▶ What can be parallelized and how?
  - The inner loops of compare\_exchange() can be executed in parallel as it involves communication between 2 procs to potentially exchange elements but only with a single partner.
  - Even iterations, lower evens exchange with higher odds
  - Odd iterations lower odds exchange with higher evens
  - ► Exchange can be done via a Send/Receive of elements and then "keeping" the appropriate element, min on lower proc, max on higher proc

#### Odd-Even Sort in Practice

- As before, unrealistic to have P=N, rather each proc holds N/P elements of the array A[]
- COMPARE\_EXCHANGE() becomes COMPARE\_SPLIT()



**Figure 9.2** A compare-split operation. Each process sends its block of size n/p to the other process. Each process merges the received block with its own block and retains only the appropriate half of the merged block. In this example, process  $P_i$  retains the smaller elements and process  $P_j$  retains the larger elements.

# Analysis of Odd-Even Sort

- ▶ Initially all procs sort their local array:  $O(\frac{N}{P}\log\frac{N}{P})$
- Conduct P Outer iterations of ODD\_EVEN\_SORT()
- Each odd/even inner loop is done in parallel by all procs communicating with a neighbor
- Neighbor procs exchange ararys:  $O(t_s + t_w \frac{N}{P})$
- **Each** proc then performs a compare/split:  $O(\frac{2N}{P})$
- Overall complexity of parallel algorithm:

$$\begin{split} T_{par} &= O\left(\frac{N}{P}\log\frac{N}{P}\right) + P \times \left(O\left(t_s + t_w \frac{N}{P}\right) + O\left(\frac{2N}{P}\right)\right) \\ &= O\left(\frac{N}{P}\log\frac{N}{P}\right) + O(N) + O(N) \end{split}$$

**Isoefficiency?** : Reported in textbook as  $O(P2^P)$ , linear increase in P requires exponential increase in problem size to maintain efficiency. Verifying this is a good exercise.

## Sorting Extras

#### Odd-Even Sort to Shell Sort

- Allowing bigger "moves" in odd-even sort can improve practical efficiency of algorithm
- Shell Sort provides a mechanism for this: neighbors selected according to a "gap" scheme, less known sort with yet mysterious complexity analysis

### Sorting Hardware

- ► Grama Ch 9.1 discusses Sorting networks, specialized hardware which can implement sorting
- ▶ With N processors, can implement Bitonic Sort in a sorting network and achieve  $T_{par} = O(\log^2 N)$
- Hardware that implements sorting networks is not common but...
- Can do this in GPUs and may revisit this algorithm when we do CUDA programming