

Assignment-2

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Assumption

- Polytope is non-degenerate.
- Rank of A is n
- Initial feasible point is given

Instructions to execute code: -

- Kindly re-start the kernel every-time before running the code

```
In [1]: # importing Libraries
import numpy as np
import numpy.linalg as la
import csv

class LO_Assignment_2:
    def __init__(self, m, n, A, B, C):
        self.epsilon = 1e-8

        self.A = A
        self.B = B
        self.C = C
        self.X = np.empty([n])
        self.n = n
        self.m = m
        self.assert_input_dimesions()

    # Verifying that input has correct dimensions
    def assert_input_dimesions(self):

        assert(self.B.shape == (self.m,))
        assert(self.C.shape == (self.n,))
        assert(self.X.shape == (self.n,))

        self.execute_simplex_algorithm()

    #method to extract linearly independent rows
    def get_linearly_independ_rows(self, A, B, X):
        indices = np.where(np.abs((A @ X) - B) < self.epsilon)[0]
        return A[indices], indices

    # calculating min ratio to calculate beta value
    def get_min_ratio(self, A_non_tight, B_non_tight, v):
        return (B_non_tight - np.dot(A_non_tight, self.X)) / ((A_non_tight @ v) + 1)
```

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#extracting non tight rows to calculate beta value
def extract_non_tight_rows(self, matrix, indices):
    return matrix[~np.isin(np.arange(len(matrix)), indices)]

# Method used to move towards vertex
def move_towards_vertex(self, negative_alphas_list, A_tight_row_matrix_inv, inc):
    if len(negative_alphas_list) == 0:
        return None
    else:
        negative_alphas_list = negative_alphas_list[0]
        v = -A_tight_row_matrix_inv[negative_alphas_list]

        # Checking for un-boundedness
        if len(np.where((self.A @ v) > 0)[0]) == 0:
            return np.array(["Unbounded"])

        B_non_tight = self.extract_non_tight_rows(B, indices)
        A_non_tight = self.extract_non_tight_rows(A, indices)
        min_ratio = self.get_min_ratio(A_non_tight, B_non_tight, v)
        beta = np.min(min_ratio[min_ratio >= 0])
        return beta * v

# Method to calculate direction vectos using linearly independent rows which is
def get_direction_vector(self):
    A_tight_row_matrix, indices = self.get_linearly_independ_rows(self.A, self.C)
    A_tight_row_matrix_inv = la.inv(A_tight_row_matrix.T)
    alphas = (A_tight_row_matrix_inv @ self.C)
    negative_alphas_list = np.where(alphas < 0)[0]
    return self.move_towards_vertex(negative_alphas_list, A_tight_row_matrix_inv, 1)

# Method to run simplex algorithm
def execute_simplex_algorithm(self) -> None:
    while True:
        direction_vector = self.get_direction_vector()
        if direction_vector is not None:
            if np.array_equal(direction_vector, np.array(["Unbounded"])):
                print("Polytope is Unbounded")
                return
            else:
                self.X = self.X + direction_vector
                print(f"Arrived at new point Z': {self.X}\tCost at this Z': {self.C @ self.X}")
                print('-----')
        else:
            break

    print(f"Optimal Value (C.X) :{np.dot(self.C, self.X)}\tOptimal vertex (X) :{self.X}")

if __name__ == '__main__':
    file_path = 'Assignment2.csv'
    with open(file_path, 'r') as file:
        reader = csv.reader(file)
        data = list(reader)

    # Extracting data
    X = np.array([float(x) for x in data[0][:-1]])
    C = np.array([float(x) for x in data[1][:-1]])
    B = np.array([float(x) for x in [row[-1] for row in data[2:]]])
    A = np.array([[float(x) for x in row[:-1]] for row in data[2:]]])
    m = A.shape[0]
    n = A.shape[1]
    print('A:')
    print(A)
    print(f'B: {B}')
    print(f'C: {C}')

```

```
print(f'X: {X}\n')  
LO_Assignment_2(m, n, A, B, C)
```

```
A:  
[[ 1. -1.]  
 [ 2. -1.]  
 [-1.  0.]  
 [ 0. -1.]]  
B: [10. 40.  0.  0.]  
C: [2. 1.]  
X: [10.  0.]
```

Arrived at new point Z': [30. 20.] Cost at this Z': 79.99999999994

Polytope is Unbounded

In []: