# A deeper dive into loading data

INTRODUCTION TO DEEP LEARNING WITH PYTORCH



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#### Back to our animals dataset

```
import pandas as pd
pd.read_csv('animals.csv')
```

animal_name	hair	feathers	eggs	milk	predator	fins	legs	tail	type
skimmer	0	1	1	0	1	0	2	1	2
gull	0	1	1	0	1	0	2	1	2
seahorse	0	0	1	0	0	1	0	1	4
tuatara	0	0	1	0	1	0	4	1	3
squirrel	1	0	0	1	0	0	2	1	1

Type key: mammal (1), bird (2), reptile (3), fish (4), amphibian (5), bug (6), invertebrate (7).

### Back to our animals dataset: defining features

```
import numpy as np
# Define input features
features = animals.iloc[:, 1:-1]
X = features.to_numpy()
print(X)
array([[0, 1, 1, 0, 1, 0, 2, 1],
       [0, 1, 1, 0, 1, 0, 2, 1],
       [0, 0, 1, 0, 0, 1, 0, 1],
```

[0, 0, 1, 0, 1, 0, 4, 1],

[1, 0, 0, 1, 0, 0, 2, 1]])

### Back to our animals dataset: defining target values

```
# Define target features (ground truth)
target = animals.iloc[:, -1]
y = target.to_numpy()
```

```
array([2, 2, 4, 3, 1])
```

## Recalling TensorDataset

```
import torch
from torch.utils.data import TensorDataset
# Instantiate dataset class
dataset = TensorDataset(torch.tensor(X).float(), torch.tensor(y).float())
# Access an individual sample
sample = dataset[0]
input_sample, label_sample = sample
print('input sample:', input_sample)
print('label_sample:', label_sample)
input sample: tensor([0., 1., 1., 0., 1., 0., 2., 1.])
label_sample: tensor(2.)
```



### Recalling DataLoader

from torch.utils.data import DataLoader

```
batch_size = 2
shuffle = True

# Create a DataLoader
dataloader = DataLoader(dataset, batch_size=batch_size, shuffle=shuffle)
```

#### Recalling DataLoader

```
# Iterate over the dataloader
for batch_inputs, batch_labels in dataloader:
    print('batch inputs', batch_inputs)
    print('batch labels', batch_labels)
```

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# Evaluating model performance

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### Training, validation and testing

• Raw dataset is usually split in three subsets:

	Percent of data	Role
Training	80-90%	Used to adjust the model's parameters
Validation	10-20%	Used for hyperparameter tuning
Testing	5-10%	Only used once to calculate final metrics

#### Model evaluation metrics

- In this video, we'll focus on evaluating:
  - Loss
    - Training
    - Validation
  - Accuracy
    - Training
    - Validation

 In classification, accuracy measures how well model correctly predicts ground truth labels

#### Calculating training loss

- For each epoch:
  - we sum up the loss for each iteration of the training set dataloader
  - at the end of the epoch, we calculate the mean training loss

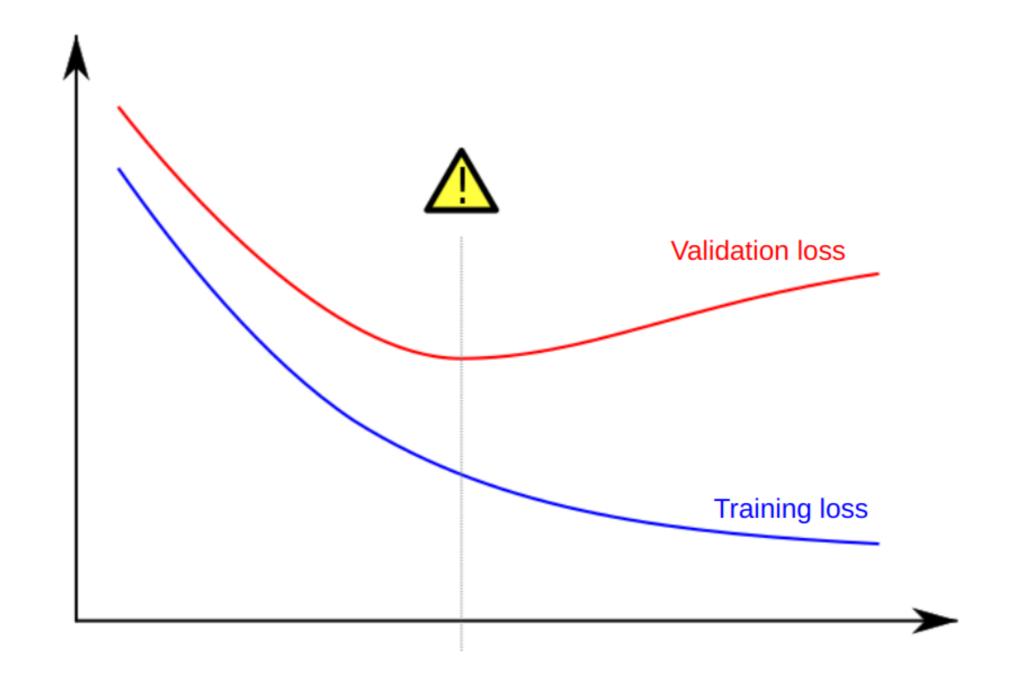
```
training_loss = 0.0
for i, data in enumerate(trainloader, 0):
   # Run the forward pass
   # Calculate the loss
    loss = criterion(outputs, labels)
   # Calculate the gradients
   # Calculate and sum the loss
   training_loss += loss.item()
epoch_loss = training_loss / len(trainloader)
```

#### Calculating validation loss

 After the training epoch, we iterate over the validation set and calculate the average validation loss

```
validation loss = 0.0
model.eval() # Put model in evaluation mode
with torch.no_grad(): # Speed up the forward pass
 for i, data in enumerate(validationloader, 0):
     # Run the forward pass
     # Calculate the loss
      loss = criterion(outputs, labels)
      validation_loss += loss.item()
epoch_loss = validation_loss / len(validationloader)
model.train()
```

## Overfitting





## Calculating accuracy with torchmetrics

```
import torchmetrics
# Create accuracy metric using torch metrics
metric = torchmetrics.Accuracy(task="multiclass", num_classes=3)
for i, data in enumerate(dataloader, 0):
   features, labels = data
    outputs = model(features)
   # Calculate accuracy over the batch
    acc = metric(outputs, labels.argmax(dim=-1))
# Calculate accuracy over the whole epoch
acc = metric.compute()
print(f"Accuracy on all data: {acc}")
# Reset the metric for the next epoch (training or validation)
metric.reset()
```

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# Fighting overfitting

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#### Reasons for overfitting

- Overfitting: the model does not generalize to unseen data.
  - model memorizes training data
  - good performances on the training set / poor performances on the validation set
- Possible causes:

Problem	Solutions			
Dataset is not large enough	Get more data / use data augmentation			
Model has too much capacity	Reduce model size / add dropout			
Weights are too large	Weight decay			

## Fighting overfitting

#### Strategies:

- Reducing model size or adding dropout layer
- Using weight decay to force parameters to remain small
- Obtaining new data or augmenting data

#### "Regularization" using a dropout layer

Randomly zeroes out elements of the input tensor during training

```
tensor([[1.4655, 0.0000, 0.0000, 0.8456]], grad_fn=<MulBackward0>)
```

- Dropout is added **after** the activation function
- Behaves differently during training and evaluation; we must remember to switch modes using model.train() and model.eval()

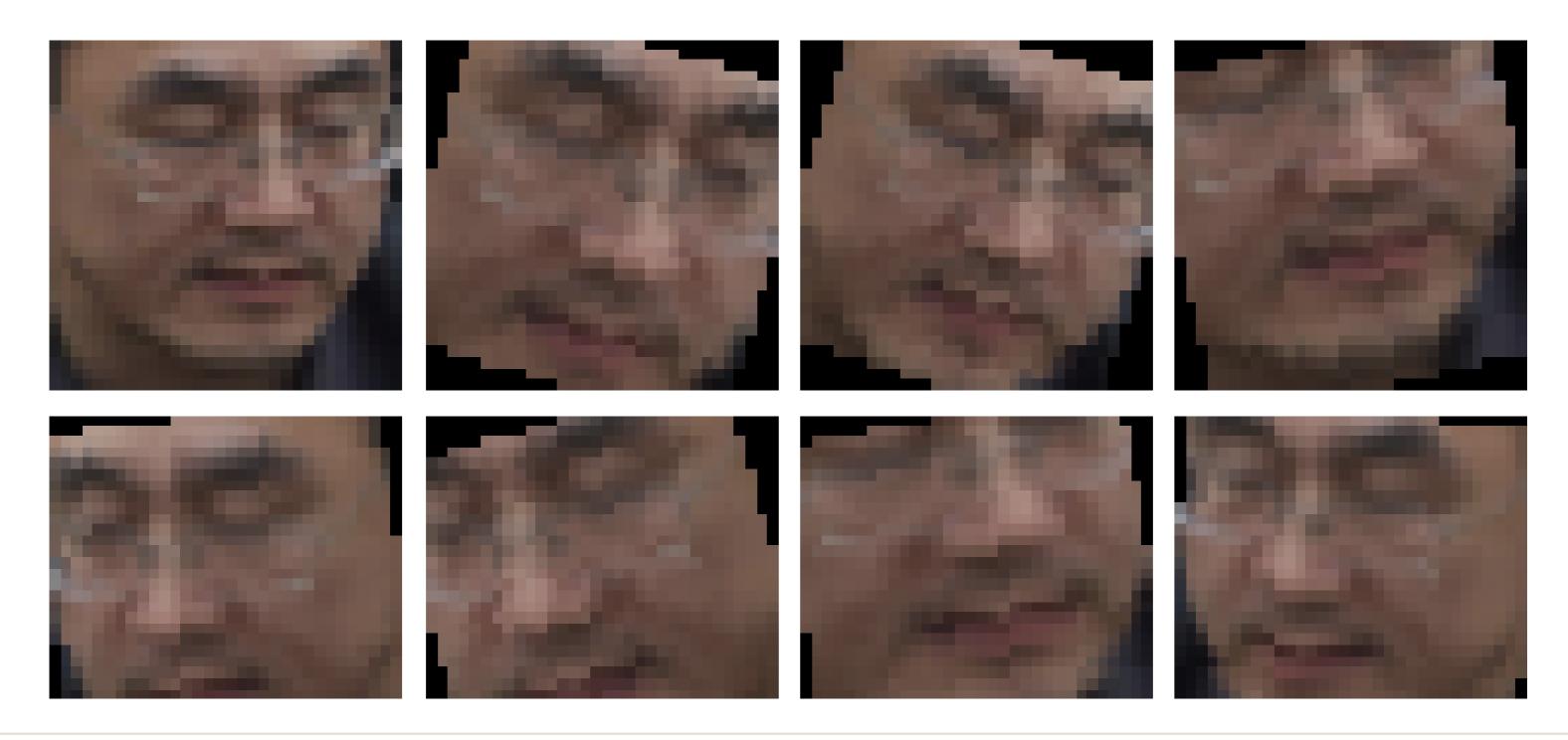
### Regularization with weight decay

```
optimizer = optim.SGD(model.parameters(), lr=1e-3, weight_decay=1e-4)
```

- Optimizer's weight\_decay parameter takes values between zero and one
  - Typically small value, e.g. 1e-3
- Weight decay adds penalty to loss function to discourage large weights and biases
- The higher the parameter, the less likely the model is to overfit



## Data augmentation



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# Improving model performance

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#### Steps to maximize performance

- Overfit the training set
  - o can we solve the problem?
  - sets a performance baseline
- Reduce overfitting
  - improve performances on the validation set
- Fine-tune hyperparameters

#### Step 1:

Overfit the training set

#### Step 2:

Reduce overfitting

#### Step 3:

Fine-tune the hyperparameters



#### Step 1: overfit the training set

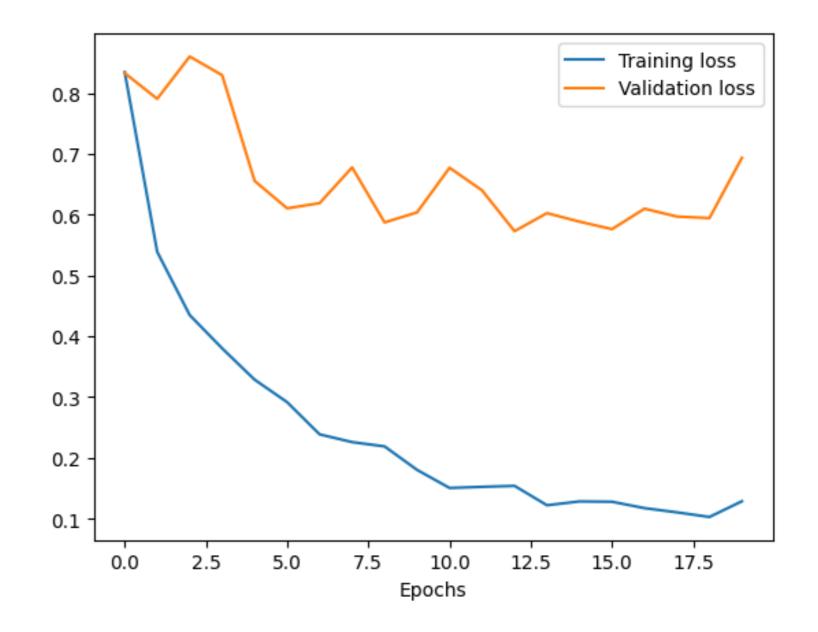
Modify the training loop to overfit a single data point (batch size of 1)

```
features, labels = next(iter(trainloader))
for i in range(1e3):
   outputs = model(features)
   loss = criterion(outputs, labels)
   loss.backward()
   optimizer.step()
```

- should reach 1.0 accuracy and 0 loss
- helps findings bugs in the code
- Goal: minimize the training loss
  - create large enough model
  - use a default learning rate

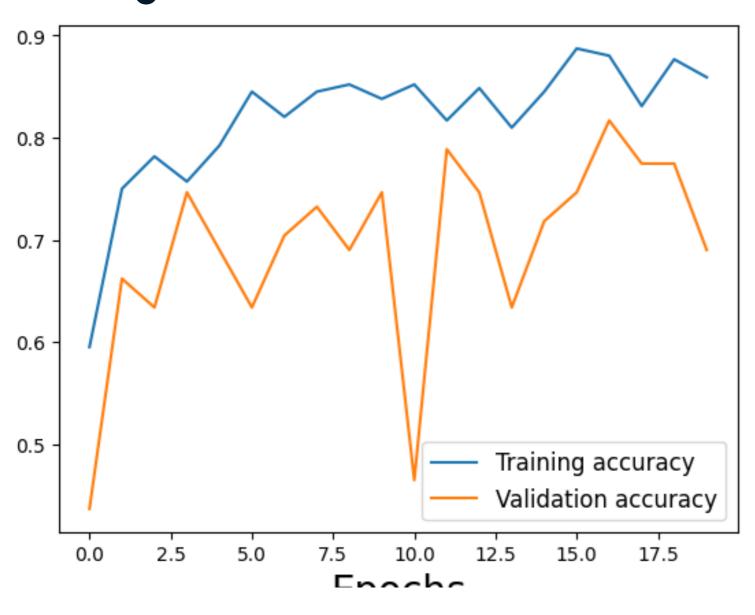
#### Step 2: reduce overfitting

- Goal: maximize the validation accuracy
- Experiment with:
  - Dropout
  - Data augmentation
  - Weight decay
  - Reducing model capacity
- Keep track of each hyperparameter and report maximum validation accuracy

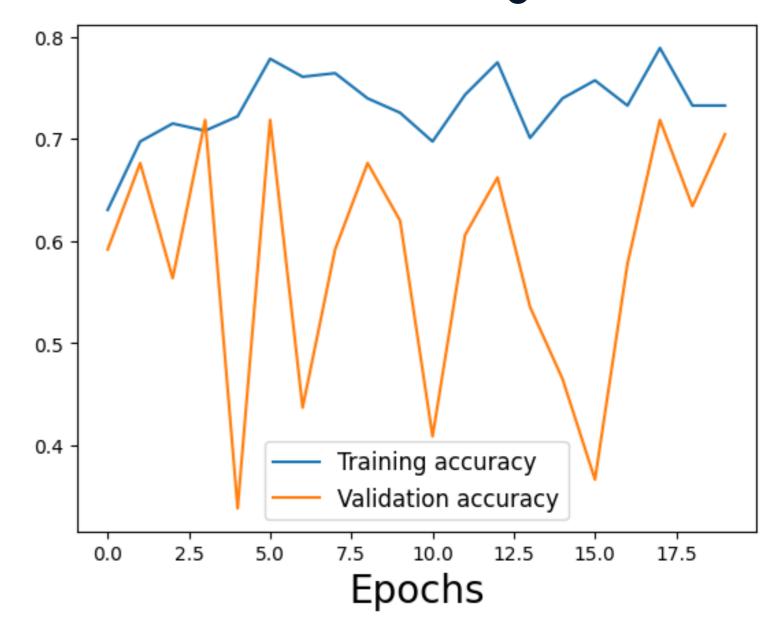


#### Step 2: reduce overfitting

# Original model overfitting the training data



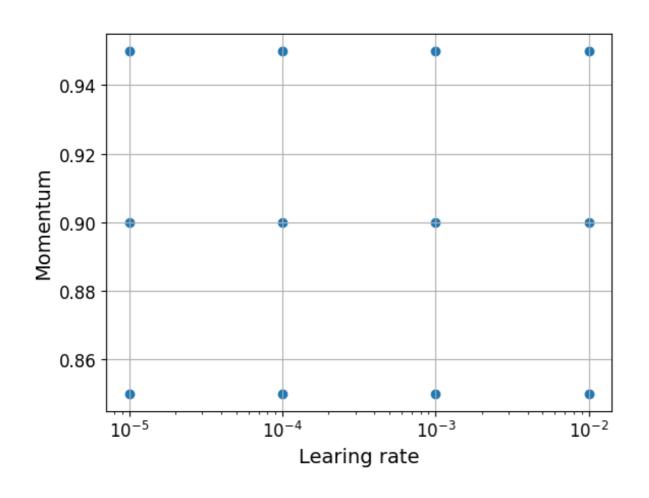
#### Model with too much regularization



#### Step 3: fine-tune hyperparameters

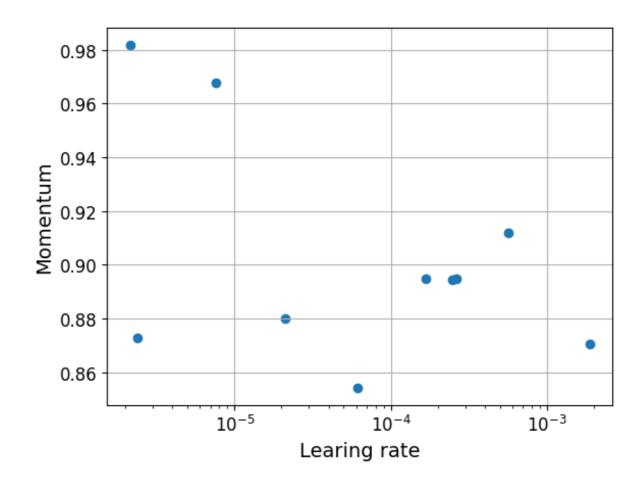
Grid search

```
for factor in range(2, 6):
    lr = 10 ** -factor
```



Random search

```
factor = np.random.uniform(2, 6)
lr = 10 ** -factor
```



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## Wrap-up video

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### Summary

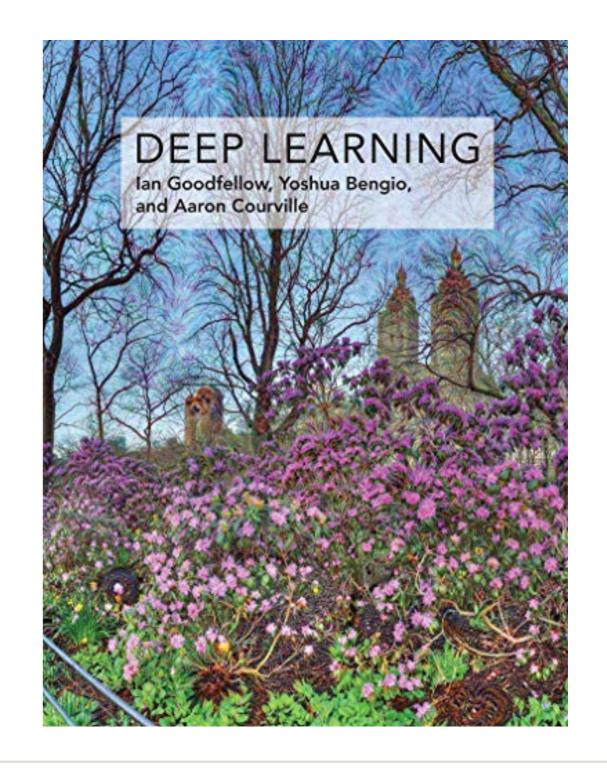
- Chapter 1
  - Discovered deep learning
  - Created small neural networks
  - Discovered linear layers and activation functions
- Chapter 2
  - Created and used loss functions
  - Calculated derivatives and use backpropagation
  - Trained a neural network

#### Chapter 3

- Manipulated the architecture of a neural network
- Played with learning rate and momentum
- Learned about transfer learning
- Chapter 4
  - Learned about dataloaders
  - Reduced overfitting
  - Evaluated model performance

#### Next steps

- Course
  - Intermediate Deep Learning with PyTorch
- Learn
  - Probability and statistics
  - Linear algebra
  - Calculus
- Practice
  - Pick a dataset on Kaggle
  - Check out DataCamp workspace
  - Train a neural network



# Let's practice!

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