

Experiment No. 8: Binary Search Tree Operations

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Aim: Implementation of Binary Search Tree ADT using Linked List. Objective:

- 1) Understand how to implement a BST using a predefined BST ADT.
- 2) Understand the method of counting the number of nodes of a binary tree.

Theory:

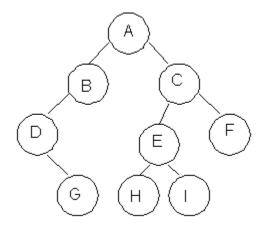
A binary tree is a finite set of elements that is either empty or partitioned into disjoint subsets. In other words node in a binary tree has at most two children and each child node is referred as left or right child.

Traversals in tree can be in one of the three ways: preorder, postorder, inorder.

Preorder Traversal

Here the following strategy is followed in sequence

- 1. Visit the root node R
- 2. Traverse the left subtree of R
- 3. Traverse the right sub tree of R





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Description	Output
Visit Root	A
Traverse left sub tree – step to B then D	ABD
Traverse right sub tree – step to G	ABDG
As left subtree is over. Visit root, which is already visited so go for right subtree	ABDGC
Traverse the left subtree	ABDGCEH
Traverse the right sub tree	ABDGCEHI F

Inorder Traversal

Here the following strategy is followed in sequence

- 1. Traverse the left subtree of R
- 2. Visit the root node R
- 3. Traverse the right sub tree of R

Description	Output
Start with root and traverse left sub tree from A-B-D	D
As D doesn't have left child visit D and go for right subtree of D which is G so visit this.	DG
Backtrack to D and then to B and visit it.	DGB
Backtract to A and visit it	DGBA
Start with right sub tree from C-E-H and visit H	DGBAH
Now traverse through parent of H which is E and then I	DGBAHEI
Backtrack to C and visit it and then right subtree of E which is F	DGBAHEICF



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Postorder Traversal

Here the following strategy is followed in sequence

- 1. Traverse the left subtree of R
- 2. Traverse the right sub tree of R
- 3. Visit the root node R

Description	Output
Start with left sub tree from A-B-D and then traverse right sub tree to get G	G
Now Backtrack to D and visit it then to B and visit it.	GD
Now as the left sub tree is over go for right sub tree	GDB
In right sub tree start with leftmost child to visit H followed by I	GDBHI
Visit its root as E and then go for right sibling of C as F	GDBHIEF
Traverse its root as C	GDBHIEFC
Finally a root of tree as A	GDBHIEFCA

Algorithm

Algorithm: PREORDER(ROOT)

Input: Root is a pointer to root node of binary tree Output: Visiting all the nodes in preorder fashion.

Description: Linked structure of binary tree

1. ptr=ROOT

2. if ptr!=NULL then

visit(ptr)

PREORDER(LSON(ptr))\

PREORDER(RSON(ptr))

End if



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3. Stop

Algorithm: INORDER(ROOT)

Input: Root is a pointer to root node of binary tree

Output: Visiting all the nodes in inorder fashion.

Description: Linked structure of binary tree

1. ptr=ROOT

2. if ptr!=NULL then

INORDER (LSON(ptr))

visit(ptr)

INORDER (RSON(ptr))

End if

3. Stop

Algorithm: POSTORDER(ROOT)

Input: Root is a pointer to root node of binary tree

Output: Visiting all the nodes in postorder fashion.

Description: Linked structure of binary tree

1. ptr=ROOT

2. if ptr!=NULL then

PREORDER(LSON(ptr))

PREORDER(RSON(ptr))

visit(ptr)

End if

3. Stop

Code:

#include <stdio.h>



```
#include <stdlib.h>
struct node {
 int data;
 struct node *leftChild, *rightChild;
};
struct node *root = NULL;
struct node *newNode(int item){
 struct node *temp = (struct node *)malloc(sizeof(struct node));
 temp->data = item;
 temp->leftChild = temp->rightChild = NULL;
 return temp;
void insert(int data){
 struct node *tempNode = (struct node*) malloc(sizeof(struct node));
 struct node *current;
 struct node *parent;
 tempNode->data = data;
 tempNode->leftChild = NULL;
 tempNode->rightChild = NULL;
 //if tree is empty
 if(root == NULL)  {
   root = tempNode;
```



```
} else {
 current = root;
 parent = NULL;
 while(1) {
   parent = current;
   //go to left of the tree
   if(data < parent->data) {
     current = current->leftChild;
     //insert to the left
     if(current == NULL) {
       parent->leftChild = tempNode;
       return;
   }//go to right of the tree
   else {
     current = current->rightChild;
     //insert to the right
     if(current == NULL) {
       parent->rightChild = tempNode;
       return;
```



```
struct node* search(int data){
 struct node *current = root;
 printf("\n\nVisiting elements: ");
 while(current->data != data) {
   if(current != NULL) {
     printf("%d ",current->data);
     //go to left tree
     if(current->data > data) {
       current = current->leftChild;
     }//else go to right tree
     else {
       current = current->rightChild;
      }
     //not found
     if(current == NULL) {
       return NULL;
```



```
return current;
}
// Inorder Traversal
void inorder(struct node *root){
 if (root != NULL) {
   inorder(root->leftChild);
   printf("%d -> ", root->data);
   inorder(root->rightChild);
// Preorder Traversal
void preorder(struct node *root){
 if (root != NULL) {
   printf("%d -> ", root->data);
   preorder(root->leftChild);
   preorder(root->rightChild);
```



```
// Postorder Traversal
void postorder(struct node *root){
 if (root != NULL) {
   printf("%d -> ", root->data);
   postorder(root->leftChild);
   postorder(root->rightChild);
}
int main(){
 insert(10);
 insert(14);
 insert(19);
 insert(26);
 insert(27);
 insert(31);
 insert(33);
 insert(35);
 insert(42);
 insert(44);
 printf("Insertion done\n");
 printf("\nPreorder Traversal: ");
 preorder(root);
```



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```
printf("\nInorder Traversal: ");
inorder(root);
printf("\nPostorder Traversal: ");
postorder(root);
struct node* k;
k = search(35);
if(k != NULL)
    printf("\nElement %d found", k->data);
else
    printf("\nElement not found");
return 0;
```

Output:

```
Insertion done

Preorder Traversal: 10 -> 14 -> 19 -> 26 -> 27 -> 31 -> 33 -> 35 -> 42 -> 44 ->
Inorder Traversal: 10 -> 14 -> 19 -> 26 -> 27 -> 31 -> 33 -> 35 -> 42 -> 44 ->
Postorder Traversal: 10 -> 14 -> 19 -> 26 -> 27 -> 31 -> 33 -> 35 -> 42 -> 44 ->

Visiting elements: 10 14 19 26 27 31 33
Element 35 found
```

Conclusion: Binary trees have many applications in computer science, including data storage and retrieval, expression evaluation, network routing, and game AI.