

LECTURE 19

▣ Recap :- Oscillatory motion.

- Simple harmonic motion with/without small θ -approximation.
- Two-dimensional harmonic oscillator :- equ. of path.

▣ Damped oscillations.

$$m\ddot{x} + b\dot{x} + kx = 0$$

→ resistive force \propto velocity.

$$\Rightarrow \ddot{x} + 2\beta\dot{x} + \omega_0^2 x = 0$$

$$\ddot{x} + 2\beta \dot{x} + \omega_0^2 x = 0 \rightarrow \text{homogeneous linear ODE.}$$

Trial soln :- $x(t) = e^{rt}$

$$(r^2 + 2\beta r + \omega_0^2) e^{rt} = 0$$

$$r^2 + 2\beta r + \omega_0^2 = 0$$

$$r_1 = -\beta + \sqrt{\beta^2 - \omega_0^2}$$

$$r_2 = -\beta - \sqrt{\beta^2 - \omega_0^2}$$

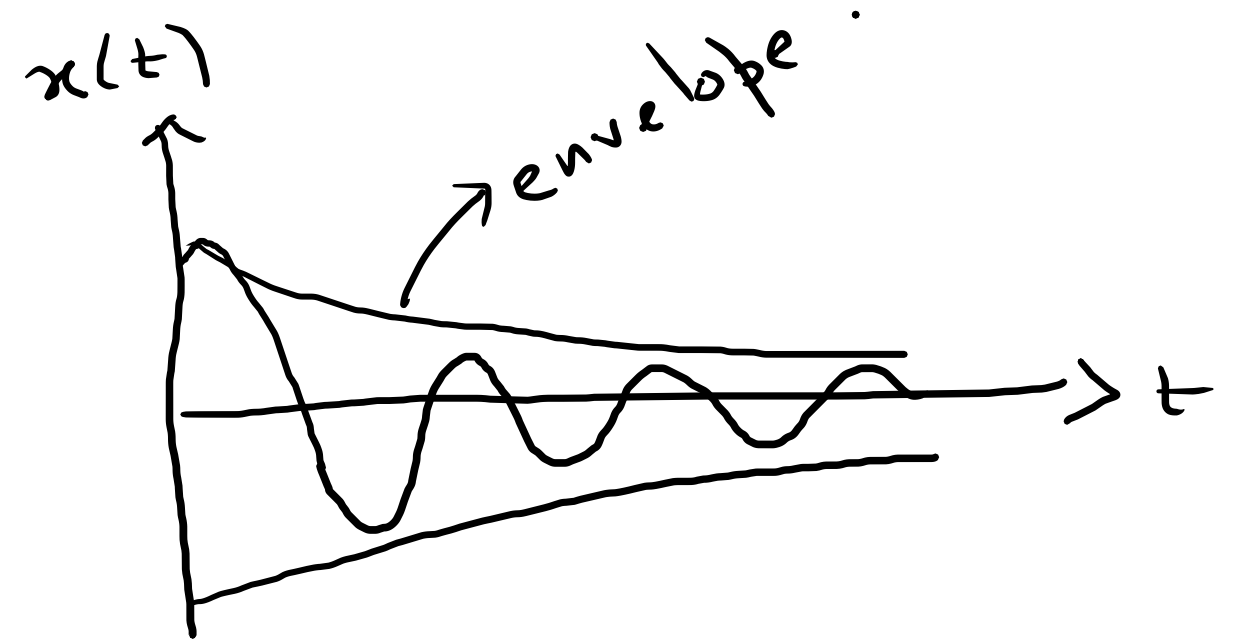
$$x(t) = A e^{(\beta + \sqrt{\beta^2 - \omega_0^2})t} + B e^{(\beta - \sqrt{\beta^2 - \omega_0^2})t}.$$

So, far, nothing has been assumed regarding relative magnitudes of β and ω_0 .

— Case 1 :- $\boxed{\beta < \omega_0}$ Underdamped oscillation.

$$\sqrt{\beta^2 - \omega_0^2} = i \sqrt{\omega_0^2 - \beta^2} = i \omega_1$$

$$x(t) = e^{-\beta t} (A e^{i \omega_1 t} + B e^{-i \omega_1 t})$$
$$= A e^{-\beta t} \cos(\omega_1 t - \delta)$$



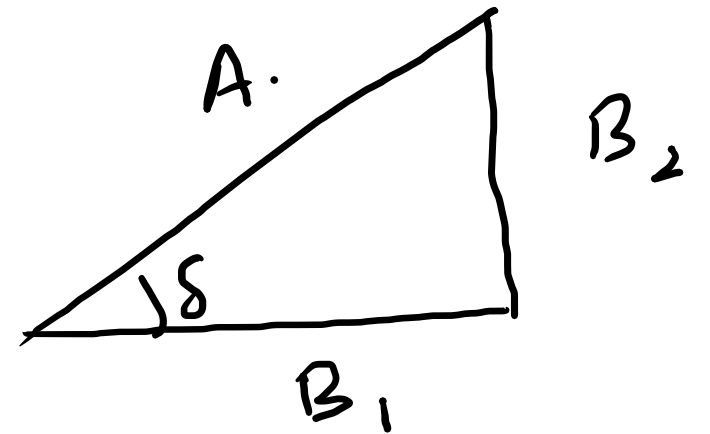
— Oscillations $(\cos(\omega_1 t - \delta))$ decay over time, but exhibit periodic behaviour.

$$\begin{aligned}
 - \quad x(t) &= C_1 e^{i\omega_1 t} + C_2 e^{-i\omega_1 t} \\
 &= C_1 (\cos \omega_1 t + i \sin \omega_1 t) + C_2 (\cos \omega_1 t - i \sin \omega_1 t) \\
 &= B_1 \cos \omega t + B_2 \sin \omega t.
 \end{aligned}$$

$$= A \left[\frac{B_1}{A} \cos \omega t + \frac{B_2}{A} \sin \omega t \right]$$

$$= A \left[\cos \delta \cos \omega t + \sin \delta \sin \omega t \right]$$

$$= A \cos(\omega t - \delta)$$

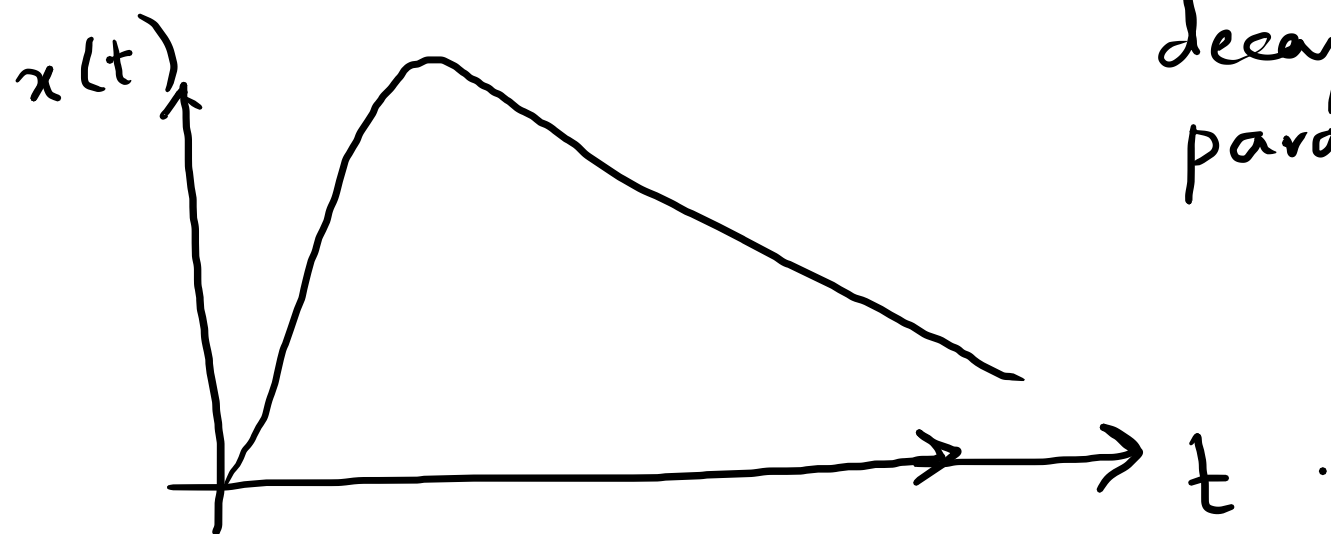


— $\beta > \omega_0$ Overdamped oscillations.

$$x(t) = e^{-\beta t} \left(A e^{\sqrt{\beta^2 - \omega_0^2} t} + B e^{-\sqrt{\beta^2 - \omega_0^2} t} \right)$$
$$= A e^{(-\beta + \sqrt{\beta^2 - \omega_0^2}) t} + B e^{(-\beta - \sqrt{\beta^2 - \omega_0^2}) t}.$$

$$(-\beta + \sqrt{\beta^2 - \omega_0^2}) t$$

$$(-\beta - \sqrt{\beta^2 - \omega_0^2}) t.$$



decay parameter $= (\beta - \sqrt{\beta^2 - \omega_0^2})$

$$= \beta - \beta \sqrt{1 - \frac{\omega_0^2}{\beta^2}}$$
$$\approx \frac{\omega_0^2}{2\beta}.$$

— $\beta = \omega_0$ — Critical damping .

$$x_1(t) = A e^{-\beta t} \rightarrow \text{only one sol}^n \text{ survives .}$$

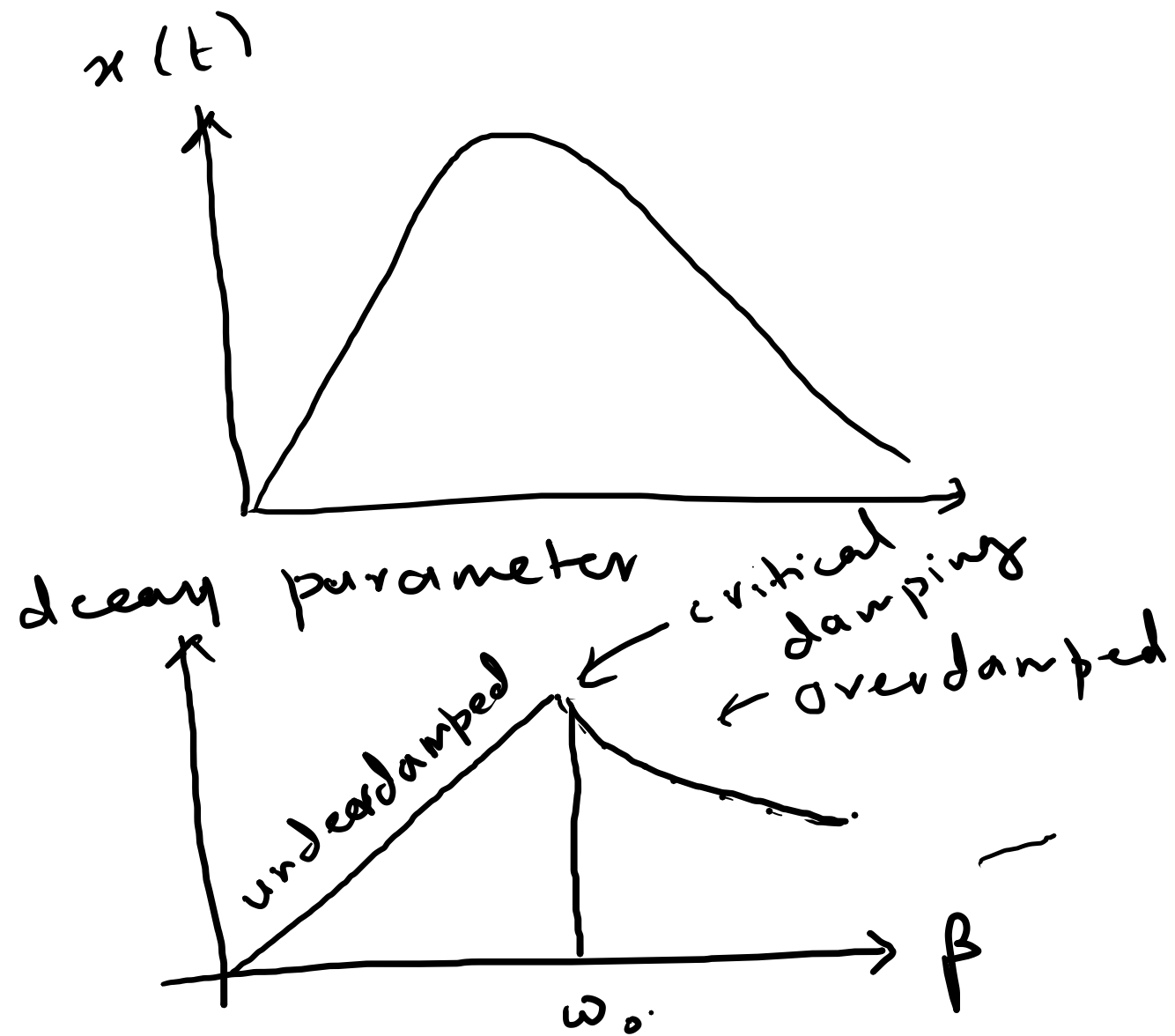
$$x_2(t) = t e^{-\beta t} .$$

$$x(t) = (A + Bt) e^{-\beta t} .$$

$$A e^{-(\text{decay parameter}) t} .$$

$$A e^{-\beta t} \rightarrow \text{underdamped}$$

$$A e^{-(\beta - \sqrt{\beta^2 - \omega_0^2}) t} \rightarrow \text{overdamped} .$$



DRIVEN DAMPED OSCILLATOR

$$\ddot{x} + 2\beta \dot{x} + \omega_0^2 x = f(t) .$$

$$D = \frac{d^2}{dt^2} + 2\beta \frac{d}{dt} + \omega_0^2$$

$$D x_p = f$$

↳ particular solution .

$$D x_h = 0 \Rightarrow x_h = C_1 e^{r_1 t} + C_2 e^{r_2 t} .$$

$$D(x_h + x_p) = D x_p + D x_h = f + 0 = f .$$

general solⁿ .

Algorithm

1. Find x_p

2. Find x_h for $D x_h = 0$
and find $x = x_p + x_h$.

$$- f(t) = f_0 \cos \omega t .$$

$$\ddot{x} + 2\beta \dot{x} + \omega_0^2 x = f_0 \cos \omega t .$$

$$\ddot{z} + 2\beta \dot{z} + \omega_0^2 z = f_0 e^{i\omega t}$$

$$\left[\operatorname{Re}(\ddot{z} + 2\beta \dot{z} + \omega_0^2 z) = f_0 \cos \omega t . \right.$$

$$\rightarrow \text{Trial soln: } z(t) = C e^{i\omega t} .$$

$$(-\omega^2 + 2i\beta\omega + \omega_0^2) C e^{i\omega t} = f_0 e^{i\omega t} .$$

$$\Rightarrow C = \frac{f_0}{(\omega_0^2 - \omega^2) + 2i\beta\omega} .$$

$$C = \frac{f_0}{(\omega_0^2 - \omega^2) + 2i\beta\omega} = \frac{f_0 [(\omega_0^2 - \omega^2) - 2i\beta\omega]}{(\omega_0^2 - \omega^2)^2 + 4\beta^2\omega^2} = A e^{-i\delta} \\ = A (\cos\delta - i \sin\delta)$$

$$A^2 = C^* C = \frac{f_0^2}{(\omega_0^2 - \omega^2)^2 + 4\beta^2\omega^2}$$

$$\tan\delta = \left(\frac{2\beta\omega}{\omega_0^2 - \omega^2} \right)$$

$$C = \frac{f_0 (\omega_0^2 - \omega^2)}{(\quad)} - i \frac{2 f_0 \beta \omega}{(\quad)} = A \cos \delta - i A \sin \delta$$

$$A \cos \delta = \frac{f_0 (\omega_0^2 - \omega^2)}{(\quad)}$$

$$\tan \delta = \frac{2 \beta \omega}{\omega_0^2 - \omega^2}$$

$$A \sin \delta = \frac{2 f_0 \beta \omega}{(\quad)}$$