SC223 - Linear Algebra

Aditya Tatu

Lecture 31



October 20, 2023

Summary of Lecture 30

- **Definition:** Let $T \in \mathcal{L}(U)$. If V is a subspace of U such that $\forall u \in V, Tu \in V$, then V is said to be an *invariant subspace* of T, or T-invariant subspace.
- If $U = V_1 \oplus V_2$, where V_1, V_2 are T-invariant, then with $B = B_{V_1} \cup B_{V_2}$ as the basis of U, $[T]_B^B$ becomes block-diagonal.
- If V is a 1-dimensional T- invariant subspace,

 $\forall u \in V, u \neq \theta, Tu = \lambda u. \lambda$ is the eigenvalue associated with eigenvector и.

$$V = \{ ku \mid \forall k \in F \}, u \neq 0$$

 $\forall x \neq 0, z \in V, z = a_1 \cdot u -, a_1 \neq 0$
 $Tz = a_2 \cdot u$

$$T(k \cdot u) = \lambda(k \cdot u) T(a_1 \cdot u) = a_2 \cdot u$$

$$T(k \cdot u) = \lambda(k \cdot u) T(a_1 \cdot u) = a_2 \cdot u = \lambda u$$

eigenvectors: (eigenspace) \Rightarrow Tu = $\frac{a_2}{a_1}u = \lambda u$.

1 dimensional Invariant Subspaces

• If $U = \bigoplus_{i=1}^n V_i$, where V_i are 1-dimensional T-invariant subspaces, then with basis $e = \{u_i, i = 1, \dots, n \mid u_i \in V_i, u_i \neq \theta\}$ $[T]^e = diag(\lambda_1, \dots, \lambda_n)$

$$[T]_{e}^{e} = diag(\lambda_{1}, \dots, \lambda_{n}).$$

$$dim(V) = \eta.$$

$$\forall_{1}, --, \forall_{n}.$$

$$\downarrow$$

$$U_{1} \qquad U_{n}$$

$$\neq \theta \qquad \neq \theta$$

$$v = \{U_{1}, \dots, U_{n}\}.$$

$$U_{i} \in V_{i}$$

$$Tu_{i} = \lambda_{i} U_{i}$$

$$[T]_{e}^{e} = \begin{bmatrix} \lambda_{1} & 0 & 0 \\ 0 & \lambda_{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

1 dimensional Invariant Subspaces

- If $U = \bigoplus_{i=1}^n V_i$, where V_i are 1-dimensional T-invariant subspaces, then with basis $e = \{u_i, i = 1, \dots, n \mid u_i \in V_i, u_i \neq \theta\}$, $[T]_e^e = diag(\lambda_1, \dots, \lambda_n)$.
- Note that if $Tu = \lambda u$, then $(T \lambda I)u = \theta$.
- Thus $(T \lambda I)$ is not invertible, and $det([T]^{\beta}_{\beta} \lambda I_n) = 0$.

$$\int u \neq 0, \quad (T - \lambda I) u = 0$$

$$\begin{bmatrix} T - \lambda I \end{bmatrix}_{\mathcal{B}} \begin{bmatrix} u \end{bmatrix}_{\mathcal{B}} = \vec{0} = [0]_{\mathcal{B}}$$

$$A n_2 = y \quad det ([T - \lambda I]_{\mathcal{B}}) = 0$$

$$A(x_1 - x_2) = \vec{0} \quad det ([T]_{\mathcal{B}} - \lambda I_{\mathcal{B}}) = 0$$

1 dimensional Invariant Subspaces

- If $U=\oplus_{i=1}^n V_i$, where V_i are 1-dimensional T-invariant subspaces, then with basis $e=\{u_i,i=1,\ldots,n\mid u_i\in V_i,u_i\neq\theta\}$, $[T]_e^e=diag(\lambda_1,\ldots,\lambda_n)$.
- Note that if $Tu = \lambda u$, then $(T \lambda I)u = \theta$.
- Thus $(T \lambda I)$ is not invertible, and $det([T]^{\beta}_{\beta} \lambda I_n) = 0$.
- Characteristic polynomial of T: $c(\lambda) = det([T]_{\beta}^{\beta} \lambda I_n)$. Eigenvalues of T are roots of the polynomial $c(\lambda)$, and the eigenvector is a non-zero vector belonging to $\mathcal{N}(T \lambda I)$.

$$C(\lambda) = \det(\lambda I_n - (7)_B^B)$$

$$C_1(\lambda) = \det([7]_B^B - \lambda I_n)$$

$$C_2(\lambda) = \det([7]_A^B - \lambda I_n)$$

$$\det(ABC) = \det(CAB) = \det(BCA)$$

 $det (TT_{k}^{2} - \lambda I_{n}) = det (S^{1}T_{k}^{3}S - \lambda I_{n})$ $= det (S^{1}(T_{k}^{3} - \lambda S^{1}T_{k}^{3})$ $= det (S^{1}(T_{k}^{3} - \lambda I_{n})S)$ $= det (S \cdot S^{1}(T_{k}^{3} - \lambda I_{n}))$ $= det (TT_{k}^{3} - \lambda I_{n})$

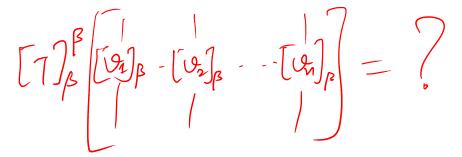
• For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.

- For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.
- Since $Tv_i = \lambda_i v_i$, $[T]_e^e =$

- For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.
- Since $Tv_i = \lambda_i v_i$, $[T]_e^e = diag(\lambda_1, \dots, \lambda_n)$.

- For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.
- Since $Tv_i = \lambda_i v_i$, $[T]_e^e = diag(\lambda_1, \dots, \lambda_n)$.
- Note that for any other basis β , $[T]^{\beta}_{\beta}[v_i]_{\beta} =$

- For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.
- Since $Tv_i = \lambda_i v_i$, $[T]_e^e = diag(\lambda_1, \dots, \lambda_n)$.
- Note that for any other basis β , $[T]^{\beta}_{\beta}[v_i]_{\beta} = \lambda_i [v_i]_{\beta}$.



- For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.
- Since $Tv_i = \lambda_i v_i$, $[T]_e^e = diag(\lambda_1, \dots, \lambda_n)$.
- Note that for any other basis β , $[T]^{\beta}_{\beta}[v_i]_{\beta} = \lambda_i [v_1]_{\beta}$.
- Thus,

$$[T]_{\beta}^{\beta} \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ [v_{1}]_{\beta} & [v_{2}]_{\beta} & \dots & [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \lambda_{1} [v_{1}]_{\beta} & \lambda_{2} [v_{2}]_{\beta} & \dots & \lambda_{n} [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

$$= \begin{bmatrix} \vdots & \vdots & \vdots & \vdots & \vdots \\ \lambda_{1} [v_{1}]_{\beta} & \lambda_{2} [v_{2}]_{\beta} & \dots & \lambda_{n} [v_{n}]_{\beta} \end{bmatrix}$$

- For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.
- Since $Tv_i = \lambda_i v_i$, $[T]_e^e = diag(\lambda_1, \dots, \lambda_n)$.
- Note that for any other basis β , $[T]^{\beta}_{\beta}[v_i]_{\beta} = \lambda_i [v_1]_{\beta}$.
- Thus,

$$[T]_{\beta}^{\beta} \begin{bmatrix} \vdots & \vdots & \vdots & \vdots & \vdots \\ [v_{1}]_{\beta} & [v_{2}]_{\beta} & \dots & [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots & \vdots \\ \lambda_{1} [v_{1}]_{\beta} & \lambda_{2} [v_{2}]_{\beta} & \dots & \lambda_{n} [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

$$= \begin{bmatrix} \vdots & \vdots & \vdots & \vdots & \vdots \\ [v_{1}]_{\beta} & [v_{2}]_{\beta} & \dots & [v_{n}]_{\beta} \end{bmatrix} \begin{bmatrix} \lambda_{1} & 0 & \dots & \vdots \\ 0 & \lambda_{2} & \dots & 0 \\ 0 & \dots & \vdots & \lambda_{n} \end{bmatrix}$$

$$[T]_{\beta}^{\beta} \begin{bmatrix} \vdots & \vdots & \vdots & \vdots & \vdots \\ [v_{1}]_{\beta} & [v_{2}]_{\beta} & \dots & [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} \lambda_{1} & 0 & \dots & \vdots \\ 0 & \lambda_{2} & \dots & 0 \\ 0 & \dots & \vdots & \lambda_{n} \end{bmatrix}$$

- For $T \in \mathcal{L}(U)$, dim(U) = n, if a diagonal matrix representation is preferred, we need an *eigenbasis* of the linear operator: $e = \{v_1, \dots, v_n\}$.
- Since $Tv_i = \lambda_i v_i$, $[T]_e^e = diag(\lambda_1, \dots, \lambda_n)$.
- Note that for any other basis β , $[T]^{\beta}_{\beta}[v_i]_{\beta} = \lambda_i [v_1]_{\beta}$.
- Thus,

$$[T]_{\beta}^{\beta} \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ [v_{1}]_{\beta} & [v_{2}]_{\beta} & \dots & [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \lambda_{1} [v_{1}]_{\beta} & \lambda_{2} [v_{2}]_{\beta} & \dots & \lambda_{n} [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ [v_{1}]_{\beta} & [v_{2}]_{\beta} & \dots & [v_{n}]_{\beta} \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}}_{E} \underbrace{\begin{bmatrix} \lambda_{1} & 0 & \dots & \vdots \\ 0 & \lambda_{2} & \dots & 0 \\ 0 & \dots & \vdots & \lambda_{n} \end{bmatrix}}_{\Lambda}$$

$$[T]_{\beta}^{\beta} E = E\Lambda \Rightarrow \Lambda = [T]_{\alpha}^{e} = E^{-1}[T]_{\beta}^{\beta} E$$

• Eigenvalues of T are roots of $det([T]^{\beta}_{\beta} - \lambda I_n)$, and corresponding eigenvectors are linearly independent vectors in $\mathcal{N}(T - \lambda I)$.



Examples

 $R_{\theta}: \mathbb{R}^2 \to \mathbb{R}^2$

Results on Eigenvectors and Eigenvalues

Proposition 20: Let $\lambda_1, \ldots, \lambda_m$ be distinct eigenvalues of $T \in \mathcal{L}(U)$. Then the eigenvectors v_1, \ldots, v_m associated with these eigenvalues are linearly independent.