

SC223 - Linear Algebra

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Lecture 26

1. Is $V = W_1 \oplus W_2$

2. Is $W_1 + W_2$ a direct sum?



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$$U = \left\{ (x_i)_{i=0}^{\infty} \mid x_0 = a, x_1 = b, x_n = x_{n-1} + x_{n-2}, n \geq 2 \right\}.$$

$$\dim(U) = 2 \qquad V = \mathbb{R}^2.$$

$$b_1 = (\underline{1}, 0, 1, 1, 2, 3, \dots) \in U$$

$$b_2 = (0, 1, 1, 2, 3, 5, \dots) \in U.$$

$$T: U \rightarrow V$$

$$T(b_1) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad T(b_2) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Summary of Lecture 25

- We say that two vector spaces over \mathbb{F} , U and V are **homomorphic** if there exists a linear transformation between them.
- We say that two vector spaces over \mathbb{F} , U and V are **isomorphic** if there exists an **invertible** linear transformation between them.
- If T is an invertible linear transformation between U and V , then we say that T is an **isomorphism** between U and V .
- **Proposition 19:** Show that two vector spaces U and V over \mathbb{F} are isomorphic iff they have the same dimensions.

Representation of Linear Transformations between FDVS

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- Now, $T(u_i) \in V$, thus $T(u_i) = \sum_{j=1}^m c_{ji} v_j$.

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$$y = \sum_{i=1}^n \sum_{j=1}^m a_i c_{ji} v_j = \sum_{j=1}^m b_j v_j$$

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- Also, since $y \in V$, $y = \sum_{j=1}^m b_j v_j$.

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- Then, $y = \sum_{i=1}^n a_i (\sum_{j=1}^m c_{ji} v_j) = \sum_{i=1}^n \sum_{j=1}^m a_i c_{ji} v_j$.
- Also, since $y \in V$, $y = \sum_{j=1}^m b_j v_j$.
- Thus, $\sum_{j=1}^m b_j v_j = \sum_{j=1}^m \sum_{i=1}^n c_{ji} a_i v_j$.

$$\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1n} \\ c_{21} & c_{22} & \cdots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mn} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$$

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- For $k \in \{1, \dots, m\}$, $b_k = \sum_{i=1}^n c_{ki} a_i$, or,

$$\underbrace{\begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}}_{[y]_{\beta_V}} = \underbrace{\begin{bmatrix} c_{11} & \dots & c_{1n} \\ \vdots & \vdots & \vdots \\ c_{m1} & \dots & c_{mn} \end{bmatrix}}_{\underbrace{[T]_{\beta_V}^{\beta_U}}_{\text{domain}}} \underbrace{\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}}_{[x]_{\beta_U}} \rightarrow \text{co-domain}$$

- The matrix $[T]_{\beta_V}^{\beta_U}$ is called the matrix representation of the linear tranformation T with respect to the basis β_U and β_V .

$$[y]_{\beta_V} = [T]_{\beta_V}^{\beta_U} [x]_{\beta_U}$$

Examples

• $\frac{d}{dx} : \mathcal{P}_2(\mathbb{R}) \rightarrow \mathcal{P}_2(\mathbb{R})$.

$$\beta^1 = \{1, x, x^2\}$$

$$\mathcal{P}_2(\mathbb{R})$$

$$\left[\frac{d}{dx} \right]_{\beta^1}^{\beta^1} = ?$$

$$\mathcal{P}_2(\mathbb{R})$$

$$p(x) = x^2 + 2x + 1$$

$$[p]_{\beta^2}^{\beta^2} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 2 \end{bmatrix}$$

$$u_3 = x. \quad \frac{d}{dx}(x) = 1$$

$$= 1 \cdot 1 + 0 \cdot x^2 + 0 \cdot x$$

$$\beta^2 = \{1, x^2, x\}$$

$$\mathcal{P}_3(\mathbb{R})$$

$$\left[\frac{d}{dx} \right]_{\beta^2}^{\beta^2} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 2 & 0 \end{bmatrix}$$

$$u_1 = 1 \quad \frac{d}{dx}(1) = 0$$

$$= 0 \cdot 1 + 0 \cdot x^2 + 0 \cdot x$$

$$\frac{d}{dx}(x^2) = 2x$$

$$= 0 \cdot 1 + 0 \cdot x^2 + 2 \cdot x$$

$$u_2 = x^2$$

Examples

- $\frac{d}{dx} : \mathcal{P}_3(\mathbb{R}) \rightarrow \mathcal{P}_3(\mathbb{R})$.
- $R_\theta : \mathbb{R}^2 \rightarrow \mathbb{R}^2$.

End of class.

Examples

- $\frac{d}{dx} : \mathcal{P}_3(\mathbb{R}) \rightarrow \mathcal{P}_3(\mathbb{R})$.
- $R_\theta : \mathbb{R}^2 \rightarrow \mathbb{R}^2$.
- Let $p \in \mathcal{P}_3(\mathbb{R})$ be such that $p(x) = p_0 + p_1x + p_2x^2 + p_3x^3$. Define $T_p : \mathcal{P}_3(\mathbb{R}) \rightarrow \mathcal{P}_6(\mathbb{R})$ by $T_p(q) = p \cdot q, \forall q \in \mathcal{P}_3(\mathbb{R})$, where \cdot represents multiplication between polynomials.

$$\mathcal{L}(U, V)$$