

LECTURE 25

Recap:

- Solving inhomogeneous ^{linear} differential eqns
- Motivation:- in this context, obtaining solutions for oscillators subject to generic driving forces.

Ex. $\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = F(t) = F_0 \cos \omega t$.

$$\ddot{z} + 2\beta\dot{z} + \omega_0^2 z = F_0 e^{i\omega t}$$

Trial soln: $z = () e^{i\omega t}$

$$F(t) = t \cos \omega t$$

$\boxed{\frac{dx}{dt} + P(t)x(t) = Q(t)}$ \rightarrow inhomogeneous eqn.

$$M(t) \frac{dx}{dt} + M P x = Q M.$$

$$\Rightarrow \frac{d}{dt}(Mx) = Q M \quad (\text{demand}).$$

$$\frac{dM}{dt} = M P.$$

$$\Rightarrow M = \exp \left[\int dt P(t) \right]$$

$$x(t) = M^{-1} \int dt M Q.$$

— IF method is applicable for 1st order ODEs.

— How to solve higher order ODEs?

Ex: $y'' + y' - 2y = e^x$. $D \equiv \frac{d}{dx}$.

$$\Rightarrow (D-1)(D+2)y = e^x \longrightarrow D^2 y + 2Dy - Dy - 2y = e^x.$$

Let $u = (D+2)y$.

$$(D-1)u = e^x.$$

$$\Rightarrow \underline{u' - u = e^x}.$$

$$\left[\begin{array}{l} P = -1 \\ Q = e^x \\ M = e^{+\int dx P(x)} = e^{-x} + C_1 \end{array} \right] \Rightarrow \frac{d^2 y}{dx^2} + \frac{dy}{dx} - 2y = e^x.$$

Now, reduced to 1st order ODE, so, IF method can be used now.

$$u = M^{-1} \int dx M Q.$$

$$\Rightarrow u = x e^x + c_1 e^x$$

$$(D+2)y = x e^x + c_1 e^x.$$

$$\Rightarrow y' + 2y = x e^x + c_1 e^x.$$

$$y = e^{-2x} \int dx e^{3x} (x + c_1) + c_2.$$

Exercise: Arrive at the same result, in the form of complementary functions and particular integrals.

- Motivation for using D-notation.

$$y'' + y - 2y = 0.$$

$$\Rightarrow (D+2)(D-1)y = 0.$$

$$y = e^{rx}.$$

$$r^2 + r - 2 = 0.$$

$$\Rightarrow (r+2)(r-1) = 0.$$

Ex:- $(D-1)(D+5)y = 7e^{2x}.$

Guess a trial solⁿ: $y_p = C e^{2x}.$

$$y_p'' + 4y_p' - 5y_p = C(4e^{2x} + 8e^{2x} - 5e^{2x}) = \underline{7e^{2x}}.$$

$$\Rightarrow \underline{7C e^{2x}} = e^{2x}$$

$$\Rightarrow C = 1. \quad (\text{method of undetermined coefficients}).$$

Prob. $\ddot{x}_1 + 2\omega^2 x_1 - \omega^2 x_2 = 0$

$$2\ddot{x}_2 + 2\omega^2 x_2 - \omega^2 x_1 = 0$$

Method 1:- Let $x_1 = A_1 e^{i\alpha t}$
 $x_2 = A_2 e^{i\alpha t}$

} Trial solⁿ.

Sub: solve for α .

Method 2:- $M\ddot{x} = -Kx$

$$M = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$$

$$K = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

$$M^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1/2 \end{pmatrix}$$

$$K = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

Eigenvalues of $M^{-1}K$:-

$$\underline{\underline{M^{-1}K = \begin{pmatrix} 2 & -1 \\ -1/2 & 1 \end{pmatrix}}}$$

$$\underline{\lambda = \frac{1}{2}(3 \pm \sqrt{3})}$$

$$m\ddot{x} + kx = 0$$

$$\Rightarrow \ddot{x} + \omega^2 x = 0.$$

(check ::) $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \sqrt{3} + 1 \\ -1 \end{pmatrix} \cos(\alpha_1 t + \delta_1) \rightarrow \text{1st normal mode}$

$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \sqrt{3} - 1 \\ 1 \end{pmatrix} \cos(\alpha_2 t + \delta_2) \rightarrow \text{2nd normal mode}$

General solⁿ is:-

$$x(t) = B_1 \begin{pmatrix} \sqrt{3} + 1 \\ -1 \end{pmatrix} \cos(\alpha_1 t + \delta_1) + B_2 \begin{pmatrix} \sqrt{3} - 1 \\ 1 \end{pmatrix} \cos(\alpha_2 t + \delta_2) .$$

$$\ddot{x}_1 + \omega_1^2 x_1 = 0$$

$$\ddot{x}_2 + \omega_2^2 x_2 = 0 .$$

- How to guess normal coord.s from above
- Recall, normal coords. exhibit "pure" freq.
- So, procedure should be to find linear combinations which show either no α_1 -dependence or no α_2 -dependence.

$$\begin{aligned} B_1 (\sqrt{3} + 1) + B_2 (\sqrt{3} - 1) &= x_1 \\ -B_1 + B_2 &= x_2 \end{aligned} \quad \left\{ \begin{array}{l} \xrightarrow{\text{solving,}} x_1 + (\sqrt{3} + 1) x_2 \\ x_1 - (\sqrt{3} - 1) x_2 \end{array} \right\} \parallel$$

$$- \quad M^{-1}K = \begin{pmatrix} 2 & -1 \\ -1/2 & 1 \end{pmatrix}.$$

$$O = \begin{pmatrix} -(1+\sqrt{3}) & -(1-\sqrt{3}) \\ 1 & 1 \end{pmatrix}$$

\downarrow
 eig 1

\downarrow
 eig 2.