

# SC223 - Linear Algebra

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Lecture 8



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## Why bother with $LU$ decomposition?

- Solve  $Ax = b$ .
- Given the  $LU$  decomposition of  $A$ , solve:  $LUx = b$ .
- Letting  $y := Ux$  reduces the original problem to two *simpler* linear systems:
  - ▶ Solve for  $y$  in  $Ly = b$ .
  - ▶ Solve for  $x$  in  $Ux = y$ .

$$A \cdot A^{-1} = I_n$$

$$A \begin{bmatrix} | & & | \\ u_{*1} & \dots & u_{*n} \\ | & & | \end{bmatrix} = \begin{bmatrix} e_1 & \dots & e_n \\ | & & | \end{bmatrix}$$

$$E_{n-1} \cdot E_{n-2} \cdot \dots \cdot E_1 A = U$$

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GAUSS-JORDAN

$$E_{n-1} \cdot E_{n-2} \cdots E_1 \cdot I_n = \bar{L}^{-1}$$

$$E_{n-1} \cdot E_{n-2} \cdots E_1 [A | I] = [U | \bar{L}^{-1}]$$

$$\underbrace{Q_{n-1} \cdot Q_{n-2} \cdots Q_1}_{U^{-1}} [U | \bar{L}^{-1}] = [I | A^{-1}]$$

$$U^{-1} U = I. \quad U^{-1} \bar{L}^{-1} = (LU)^{-1} = A^{-1}.$$

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- If  $b_1, b_2 \in C(A)$ ,  $\forall p, q \in \mathbb{R}$ ,  $p \cdot b_1 + q \cdot b_2$

$$\forall p, q \in \mathbb{R} \quad p \cdot b_1 + q \cdot b_2 = p(Ax_1) + q(Ax_2) = A(p \cdot x_1 + q \cdot x_2)$$

$$\begin{aligned} b_1 &\in C(A) \\ \exists x_1 \in \mathbb{R}^n, & \text{ s.t. } Ax_1 = b_1 \\ b_2 &\in C(A). \\ \exists x_2 \in \mathbb{R}^n, & \text{ s.t. } Ax_2 = b_2 \end{aligned}$$

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- Let  $Ax = b$  and  $Ay = b$ , with  $x \neq y$ .

$$A(x - y) = 0_m$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x \begin{bmatrix} 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} x+y \\ x+y \end{bmatrix}$$

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- ▶ Similarly, let  $z \in \mathbb{R}^n$  be such that  $Az = \mathbf{0}_m$ . Then, if  $Ax = b$ ,  
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$$\begin{aligned} A(p \cdot x + q \cdot y) &= p \cdot Ax + q \cdot Ay \\ &= p \cdot \mathbf{0}_m + q \cdot \mathbf{0}_m = \mathbf{0}_m. \end{aligned}$$

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- **Summary:** If  $\exists z \in N(A), z \neq \mathbf{0}_n$ , then  $Ax = b$  will have infinitely many solutions, if one exists!

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$$\Rightarrow z_k \cdot a_{*k} + \sum_{\substack{i=1 \\ i \neq k}}^n z_i a_{*i} = 0$$

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- $a_{*k} = \sum_{i=1, i \neq k}^n \frac{-z_i}{z_k} a_{*i}$ . Thus we can write column  $k$  as a *linear combination* of other columns. We say that the vectors  $\{a_{*i}, i = 1, \dots, n\}$  is a **linearly dependent** set of vectors.
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- **Beware of the notation:**  $a_{i*}$  denotes the  $i^{th}$  row of  $A$  written as a column matrix.

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- **The Column Space, Row Space, Null Space and Left Nullspace are called the Four Fundamental Subspaces associated with a matrix.**