

LECTURE 11

(Ref: Gregory :- Classical mechanics).

▣ Recap.

- EOM for central force fields. $\vec{F} = f(r) \hat{r}$

(i) Moving to (r, θ) coordinates and deriving expressions for \vec{v} and \vec{a} . In this approach, conservation of energy and angular momentum emerge automatically.

(ii) Using the fact that central force is conservative and thus preserves energy along with angular momentum, EOM can be derived.

$$L = m r^2 \dot{\theta} = m h = \text{const.}$$

$$E = \text{const.}$$

Using 2nd approach,

$$\vec{v} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

$$K.E = T = \frac{1}{2} m \vec{v} \cdot \vec{v} = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2)$$

$$T + V = E = \text{const.}$$

$$\Rightarrow \dot{r}^2 + r^2 \dot{\theta}^2 = \frac{2(E - V)}{m}$$

$$\Rightarrow \dot{r}^2 + r^2 \frac{L^2}{m^2 r^4} = \frac{2(E - V)}{m}$$

$$r(t)$$

$$\theta(t)$$

$$V(r) = - \int \vec{F} \cdot d\vec{r}$$

$$\dot{r}^2 + \frac{L^2}{m^2 r^2} = \frac{2(E - V)}{m}$$

Non-trivial to solve for $r(t)$.

— Easier to determine $r \equiv r(\theta)$

$$r \equiv r(t)$$

$$\theta \equiv \theta(t).$$



$$- \frac{dr}{dt} = \frac{dr}{d\theta} \frac{d\theta}{dt} = \frac{dr}{d\theta} \dot{\theta} = \frac{L}{mr^2} \left(\frac{dr}{d\theta} \right).$$

Substituting,

$$\frac{L^2}{m^2 r^4} \left(\frac{dr}{d\theta} \right)^2 + \frac{L^2}{m^2 r^2} = \frac{2(E - V)}{m}$$

$$\Rightarrow \frac{L^2}{m^2 r^4} \left[\left(\frac{dr}{d\theta} \right)^2 + r^2 \right] = \frac{2(E - V)}{m}$$

Qualitative features about orbit.

$$\frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2) + V = E$$

$$\Rightarrow \frac{m \dot{r}^2}{2} + \frac{L^2}{2mr^2} + V(r) = E$$

Resembles the corr. eqn. for 1d motion with extra term $L^2/(2mr^2)$

$$V_{\text{eff}}(r) = \frac{L^2}{2mr^2} + V(r).$$

$\frac{L^2}{2mr^2} \equiv$ angular momentum barrier.

$$\frac{1}{2} m \dot{r}^2 + V_{\text{eff}}(r) = E$$

— From EOM, (CROSS-CHECK)

$$m\ddot{r} - mr\dot{\theta}^2 = f(r)$$

$$\Rightarrow m\ddot{r} - mr \cdot \frac{L^2}{m^2 r^4} = f(r)$$

$$V(r) = - \int dr f(r)$$

$$\Rightarrow m\ddot{r} = \underbrace{\frac{L^2}{mr^3} + f(r)}_{\text{effective force}}$$

$$V_{\text{eff}}(r) = \frac{L^2}{2mr^2} + V(r)$$

$$F_{\text{eff}} = - \frac{dV_{\text{eff}}(r)}{dr} = - \left(- \frac{L^2}{mr^3} - f(r) \right) \\ = \frac{L^2}{mr^3} + f(r)$$

Example :- $V(r) = Ar^2$

$$V_{\text{eff}}(r) = \frac{L^2}{2mr^2} + Ar^2$$

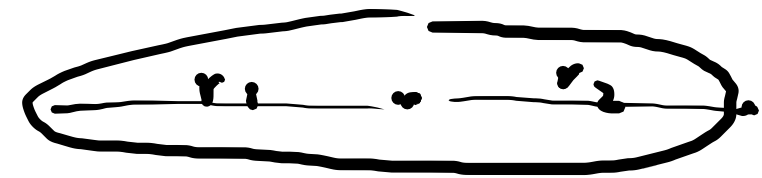
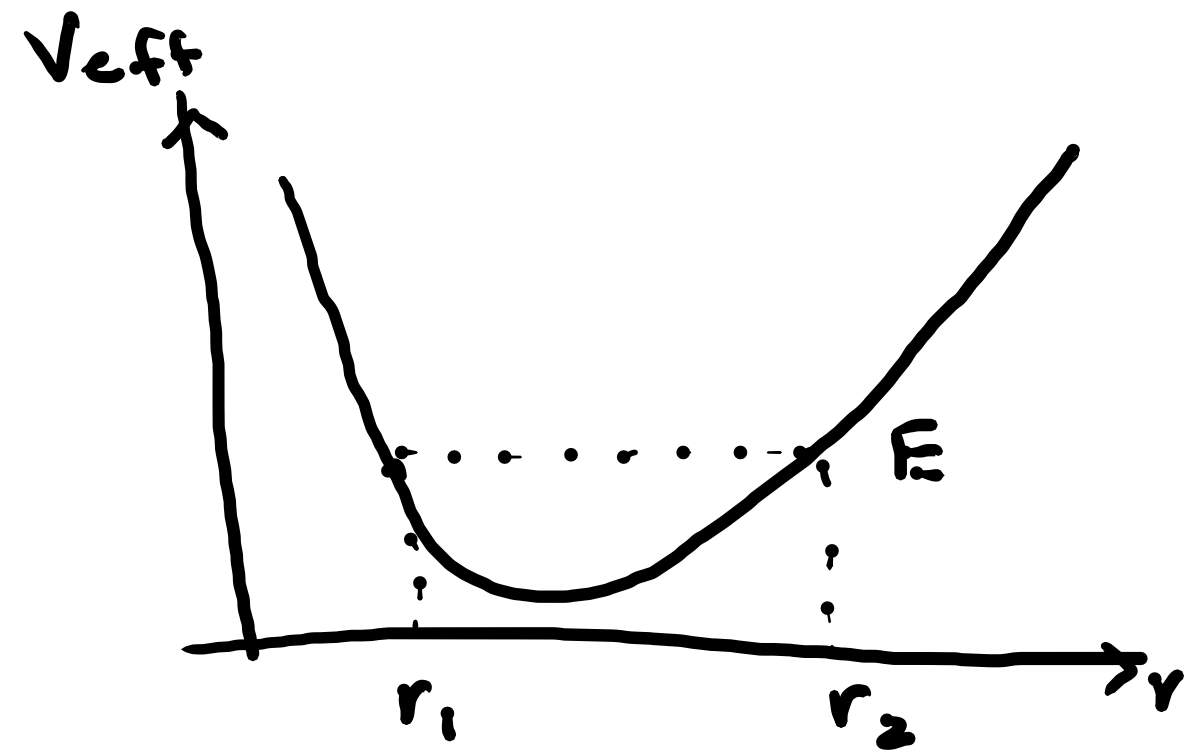
$$\frac{dV_{\text{eff}}(r)}{dr} = -\frac{L^2}{mr^3} + 2Ar = 0$$

$$\Rightarrow r^4 = \frac{L^2}{2Am}$$

Whenever, $E = V_{\text{eff}}$, $K.E. = 0$.

$(r_1, r_2) \equiv$ turning points.

\Downarrow
vel. of particle = 0



— If E is decreased, r_1 and r_2 approach each other.

— At minimum of V_{eff} , $r_1 = r_2 = r = \text{const}$.

Example 1: Potential satisfying a particular orbit $r = r_0 e^{a\theta}$
for a given energy $E = 0$

Since the EOM is written in terms of $\frac{dr}{dt}$,

$$\frac{dr}{dt} = r_0 a e^{a\theta} \dot{\theta} = a r \dot{\theta} = \frac{a L}{m r^2} \cdot r = \frac{a L}{m r}$$

$$\text{EOM: } \frac{m}{2} \dot{r}^2 + \frac{L^2}{2mr^2} + V(r) = E = 0$$

$$\Rightarrow \frac{m}{2} \left(\frac{a L}{m r} \right)^2 + \frac{L^2}{2mr^2} + V(r) = 0$$

Solve for $V(r)$.

Example 3: $V(r) = -V_0 e^{-\lambda^2 r^2}$

$$V_{\text{eff}}(r) = \frac{L^2}{2mr^2} - V_0 e^{-\lambda^2 r^2}$$

$$\frac{dV_{\text{eff}}(r)}{dr} = -\frac{L^2}{mr^3} + V_0 (2\lambda^2 r) e^{-\lambda^2 r^2}$$

$$\Rightarrow 0 = -\frac{L^2}{mr^3} + 2V_0 \lambda^2 r e^{-\lambda^2 r^2}$$

$$\Rightarrow L^2 = (2mV_0 \lambda^2) r^4 e^{-\lambda^2 r^2}$$

$$\Rightarrow \frac{L^2}{2mV_0 \lambda^2} = r^4 e^{-\lambda^2 r^2} \rightarrow \text{has maximum.}$$

