

1) a) Ideal delay system

Tutorial 04

$$y(n) = x(n-d) = \mathcal{D}\{x(n)\} \rightarrow F/O$$

$$\therefore \mathcal{D}\{x_1(n)\} = y_1(n) = x_1(n-d)$$

$$\therefore \mathcal{D}\{x_2(n)\} = y_2(n) = x_2(n-d)$$

$$\therefore \mathcal{D}\{x_1(n) + x_2(n)\} = x_1(n-d) + x_2(n-d)$$

— [A]

$$\therefore y_1(n) + y_2(n) = x_1(n-d) + x_2(n-d)$$

— [B]

$$\mathcal{D}\{x_1(n) + x_2(n)\} = y_1(n) + y_2(n)$$

\therefore Additivity property is satisfied.

$$\therefore \mathcal{D}\{a \cdot x(n)\} = a \cdot x(n-d)$$

$$\therefore a \cdot y(n) = a \cdot x(n-d)$$

$$\therefore \mathcal{D}\{a \cdot x(n)\} = a \cdot y(n)$$

\therefore Homogeneity is satisfied.

\therefore Ideal delay system is linear system

1. (b) To prove Moving Average (MA) system is linear,

$$y(n) = D\{x(n)\} = \left(\frac{1}{N_1 + N_2} \right) \sum_{k=-N_1}^{+N_2} x(n-k)$$

→
I/O

(2) (??)

1) Additivity ? → satisfied

2) Homogeneity → ?? satisfied.

∴ Moving Average system is linear.

Q-2) a) $\boxed{y(n) = D\{x(n)\} = g(n) \cdot x(n)}$ $\leftrightarrow I/O$
 $I/O \rightarrow$

i) stability. BIBO, let $|x(n)| \leq B_x < \infty$

$$|y(n)| = |g(n) \cdot x(n)|$$

$$|y(n)| \leq |g(n)| \cdot |x(n)|$$

$$\& |g(n)| < +\infty \quad \forall n \text{ then}$$

$$|y(n)| \leq k \cdot B_x$$

$$\therefore |y(n)| < +\infty \quad \forall n$$

\therefore If the number $|g(n)|$ is finite
 the given system D.F. is static

else system is D.F. is unstable.

ii) Causality:

Since the output of system depends upon only
 on the present value of input, i.e. $x(n)$,
 the given system D.F. is causal. - (3)

iii) Linearity.

Additivity. ✓

Homogeneity. ✓

∴ $D\{f\}$ is linear

iv) Time-Invariance

$$\therefore D\{x(n-n_0)\} = \underline{y(n-n_0)}$$

$$g(n, x(n-n_0)) \neq g(n-n_0, x(n-n_0))$$

∴ Given system is time-variant
OR NOT time-invariant

v) Memoryless

$$y(n) = g(n, x(n))$$

Since $y(n)$ depends only on present
i/p, the given system is memoryless.

④

$$y[n] = D\{x[n]\} = \sum_{k=n_0}^n x[k]$$

Soln i) Stability.

Unstable

ii) linearity. \rightarrow linear

$$n = n_0 + 1$$

$$n > n_0$$

iii) Causality \Rightarrow

for

$$n < n_0$$

$$n = n_0 - 1$$

$$y[n] = \sum_{k=n_0}^n x[k]$$

$$n = n_0 - 1$$

$$\therefore y[n_0 - 1] = \sum_{k=n_0}^{n_0 - 1} x[k] = x[n_0 - 1] + \underline{x[n_0]}$$



\therefore Given system is Non-causal.

(5)

iii) Linearity.

linear.

iv) Time-invariance

$$D\{x(n-n_0)\} \neq y(n-n_0).$$

$$\sum_{k=n_0}^n x(k-n_0) \stackrel{??}{\Leftrightarrow} \sum_{k=n_0}^{n-n_0} x(k)$$

\Downarrow

$$\sum_{k=0}^{n-n_0} x(k)$$

\swarrow

~~$\sum_{k=0}^n x(k)$~~

\therefore Given system is time-variant.

v) Memoryless ??

The system $D\{ \cdot \}$ is with memory.

(6)

$$c) y(n) = \mathcal{D}\{x(n)\} = \frac{x(n)}{e} \quad (??).$$

- \Rightarrow i) Stable \rightarrow BIBO
- ii) Causal \rightarrow $\mathcal{D}\{x(n-n_0)\} = \frac{x(n-n_0)}{e}$
- iii) linear \rightarrow stability \rightarrow $\frac{x(n-n_0)}{e}$
- iv) TI/TV \rightarrow TI
- v) Memoryless \rightarrow

$$d) y(n) = \mathcal{D}\{x(n)\} = \underline{a \cdot x(n) + b}.$$

- i) Stability \rightarrow Stable if 'a' and 'b' are finite.
- ii) Causal \rightarrow Causal
- iii) linearity: stability
- iv) TI/TV \rightarrow TI
- v) Memoryless \rightarrow

(P)

③ Answer

$$\text{Let } x(n) = \delta(n) + 2 \cdot \delta(n+1) - \delta(n-3)$$

$$\text{and } h(n) = 2 \cdot \delta(n+1) + 2 \cdot \delta(n-1)$$

$$a) \underline{y_1(n)} = \underline{x(n)} * \underline{h(n)} = \sum_{k=-\infty}^{\infty} x(k) h(n-k)$$

We use properties of convolution sum

$$\therefore y_1(n) = [\underline{\delta(n)} + \underline{2 \delta(n+1)} - \underline{\delta(n-3)}]$$

$$* [\underline{2 \delta(n+1)} + \underline{2 \delta(n-1)}]$$

Using distributive property

~~Let~~

$$x(n) * [h_1(n) + h_2(n)] = x(n) * h_1(n) + x(n) * h_2(n)$$

$$\therefore y_1(n) = \{ \underline{\delta(n) * 2 \delta(n+1)} + \underline{2 \delta(n+1) * 2 \delta(n-1)} - \underline{\delta(n-3) * 2 \delta(n+1)} \} + \{ \underline{\delta(n) * 2 \delta(n-1)} + \underline{2 \delta(n+1) * 2 \delta(n-1)} - \underline{\delta(n-3) * 2 \delta(n-1)} \}$$

⑧

Using identity property of discrete-time impulse function,

$$x[n] * \delta[n] = x[n]$$

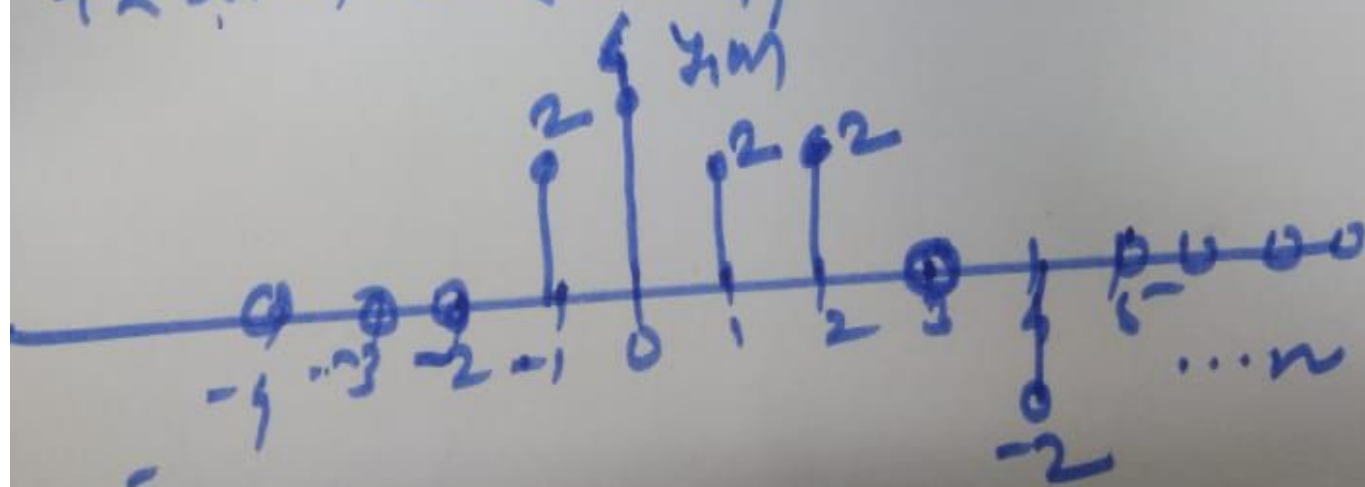
$$\therefore x[n-n_0] * \delta[n] = x[n-n_0]$$

$$x[n] * \delta[n-n_0] = x[n-n_0]$$

$$x[n] * \delta[n+n_0] = x[n+n_0]$$

$$\therefore y_1[n] = \underline{2 \delta[n+1]} + 4 \delta[n] + \underline{2 \delta[n-2]} + 2 \delta[n+1] + 4 \delta[n-2] - 2 \delta[n-4]$$

$$\therefore y_1[n] = 2 \delta[n+1] + 4 \delta[n] + 2 \delta[n-2] + 2 \delta[n+1] - 2 \delta[n-4]$$



(9)

$$(b) y_2(n) = x(n+2) * h(n)$$

\Rightarrow

$$y_2(n) = 1 - 2\delta(n-2) + 2\delta(n) + 2\delta(n+1) + 4\delta(n+2) + 2\delta(n+3) \quad \checkmark$$

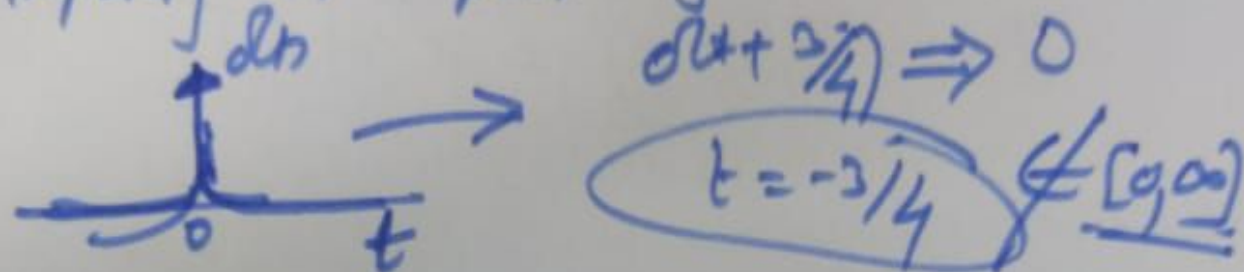
$$(c) y_3(n) = \underline{x(n)} * h(n+2)$$

$$\vdots$$

$$y_3(n) = y_2(n) \quad \checkmark$$

Problem 4) $I = \int_{-\infty}^{+\infty} \delta(t + 3/4) e^{-t} dt$

Property of impulse function??



$\therefore I = 0 \checkmark$

Problem 5) a) $y[n] = t^2 \cdot x[n-1]$ \checkmark

Linear \checkmark

TI or TV?? \Rightarrow TV

b) $y[n] = x^2[n-2]$

linear? \rightarrow nonlinear

TI/TV \rightarrow Time Invariant ①

Prob 6 Prove that the system
given by the following input-output
relationship is nonlinear

$$y(n) = D\{x(n)\} = x^*(n) \rightarrow \text{complex conjugate}$$

Proof: \rightarrow

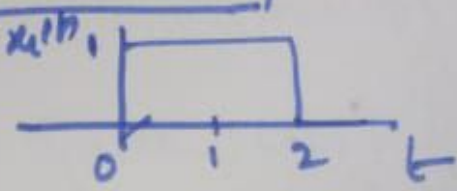
Additivity: \rightarrow satisfied.

Homogeneity \rightarrow Not satisfied
if scaling constant 'a'
is complex

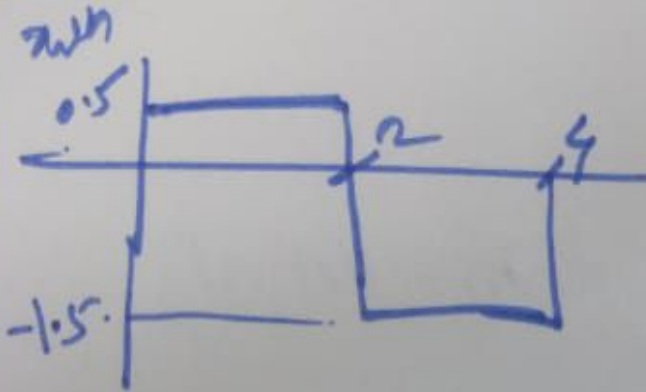
\therefore Given system $D\{x(n)\} = x^*(n) = \underline{\text{Nonlinear}}$

(2)

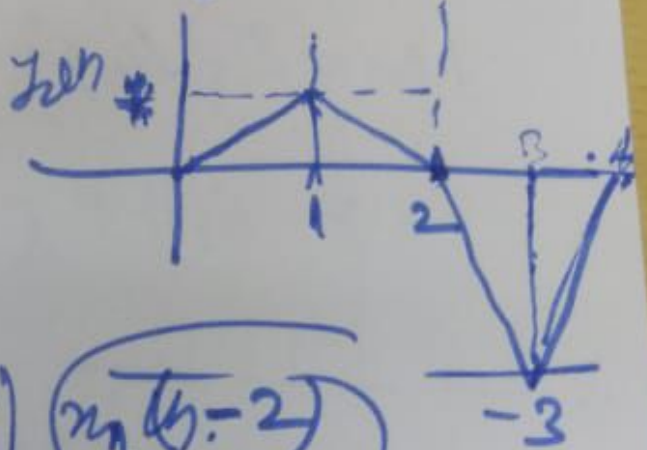
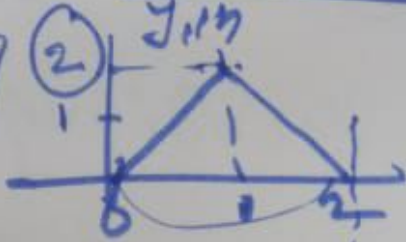
Problem 1



→ LTI



Tutorial 05



$$x_2(t) = \left(\frac{1}{2}\right) x_1(t) - \left(\frac{3}{2}\right) x_1(t-2)$$

$$\hookrightarrow y_2(t) = \left(\frac{1}{2}\right) y_1(t) - \left(\frac{3}{2}\right) y_1(t-2)$$

Problem 2

a) Ideal delay system

$$H(\omega) y(n) = D\{x(n)\} = x(n-n_0)$$

$$\therefore h(n] = \delta[n-n_0]$$

c) For mixed delay
 $h(n) = \delta[n-n_0] - \delta[n-n_1]$

(13)

① Linear Interpolation system

$$y(n) = \mathcal{D}\{x(n)\} = x(n) + \frac{1}{2} \{x(n+1) - x(n+1)\}$$

$$\therefore h(n) = \mathcal{D}\{\delta(n)\}$$

$$= \delta(n) + \frac{1}{2} \{ \delta(n+1) - \delta(n+1) \}$$

System 3 (consider an input signal $x(n]$ and an unit impulse response sequence $h(n]$ given by

$$x(k) = \left(\frac{1}{2}\right)^{k-2} \cdot u_{k-2}$$

$$x(n) = \left(\frac{1}{2}\right)^{n-2} \cdot u_{n-2}$$

$$h(n) = u_{n+2} \rightarrow h(n) = u_{n+2}$$

Determine and plot $y(n) = x(n) * h(n)$

$$\text{Ans.} \rightarrow y(n) = x(n) * h(n)$$

$$= \sum_{k=-\infty}^{+\infty} \underbrace{x(k)}_{(k)} \cdot h(n-k)$$

(4)

$$\therefore y_{in} = \sum_{k=-\infty}^{+\infty} \underbrace{\left[\left(\frac{1}{2}\right)^{k-2} u_{k-2} \right]}_{\text{new}} \cdot u_{n-k+2}$$

$$u_{k-2} = \begin{cases} 1 & k-2 \geq 0 \\ 0 & k-2 < 0 \end{cases}$$

$$u_{n-k+2} = \begin{cases} 1 & n-k+2 \geq 0 \\ 0 & n-k+2 < 0 \end{cases}$$

$k \leq n+2$

$$\therefore y_{in} = \sum_{k=-\infty}^n \cancel{(1)} + \sum_{k=2}^{n+2} \cancel{(1)} + \sum_{k=n+2}^{\infty} \cancel{(1)}$$

$\text{max } k = n+2 \rightarrow \frac{n-2}{2}$

$$y_{in} = \sum_{k=2}^{n+2} \left(\frac{1}{2}\right)^{k-2} \cdot u_{k-2} \cdot u_{n-k+2}$$

Let $m = k-2$

$$\textcircled{15} = \sum_{m=0}^n \left(\frac{1}{2}\right)^m \xrightarrow{\text{GP}} = \frac{1 - \left(\frac{1}{2}\right)^{n+1}}{1 - \frac{1}{2}}$$

$$y_{n+1} = 2 \left[1 - \left(\frac{1}{2} \right)^{n+1} \right]$$

um
??
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