

LECTURE 12

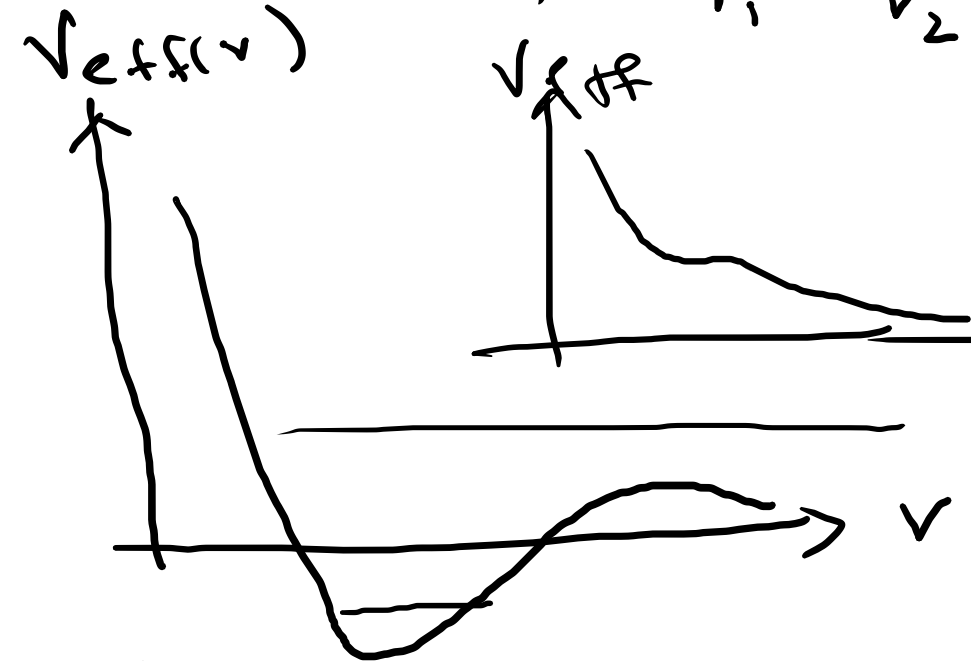
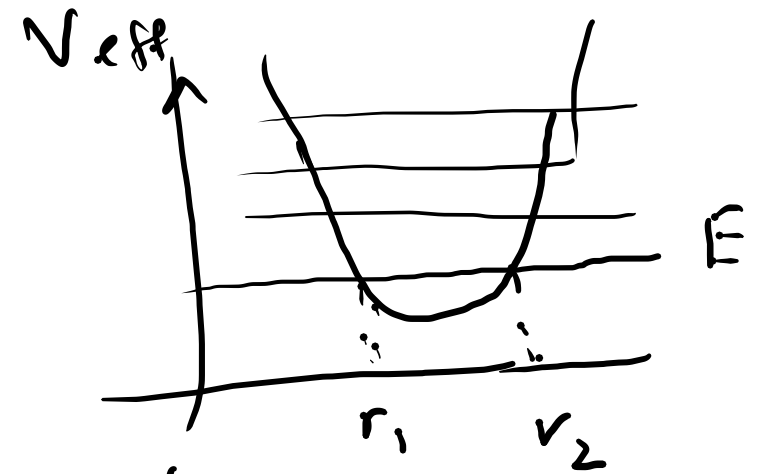
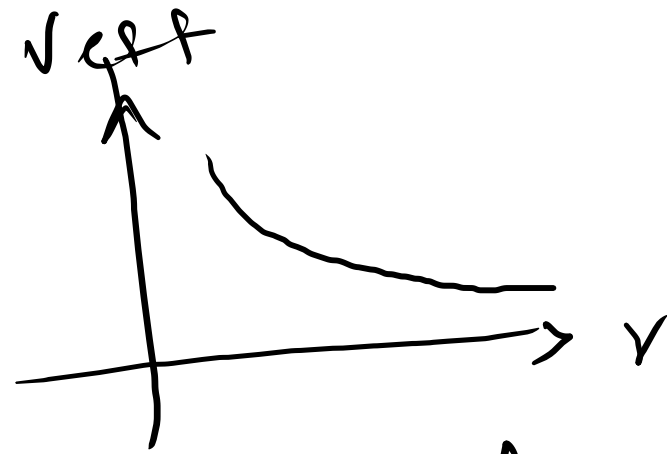
Type :- $\frac{dv}{dt} = g - F_{\text{drag}}$

Recap! $V(r) = -V_0 e^{-\lambda^2 r^2}$

$$V_{\text{eff}}(r) = \frac{L^2}{2mr^2} - V_0 e^{-\lambda^2 r^2}$$

$$\frac{dV_{\text{eff}}(r)}{dr} = 0$$

$$\Rightarrow L^2 = (2mV_0\lambda^2) \underbrace{r^4 e^{-\lambda^2 r^2}}_{g(r)}$$



Example: $V(r) = -\alpha/r$

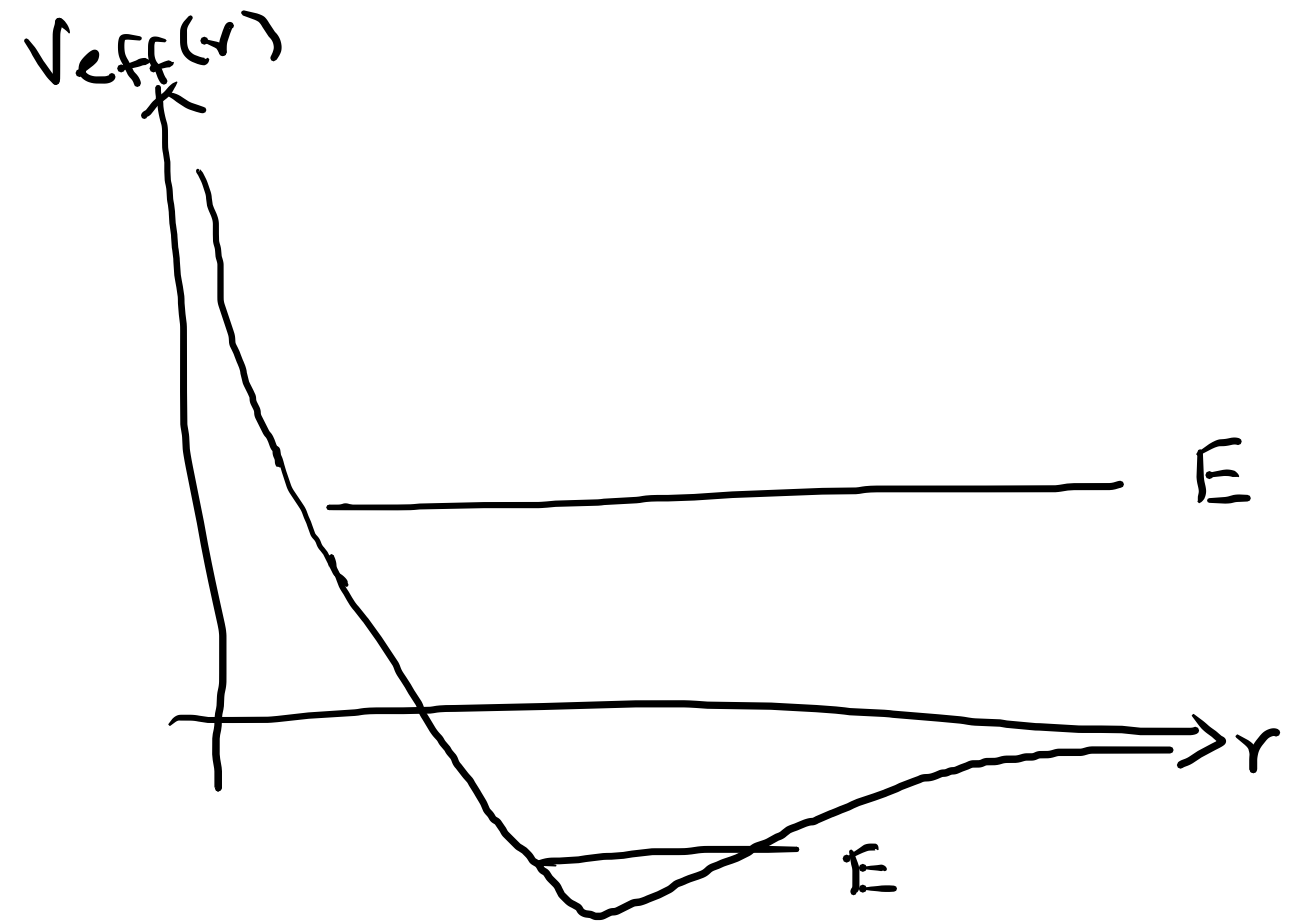
$$V_{\text{eff}}(r) = \frac{L^2}{2mr^2} + V(r)$$

$$= \frac{L^2}{2mr^2} - \alpha/r$$

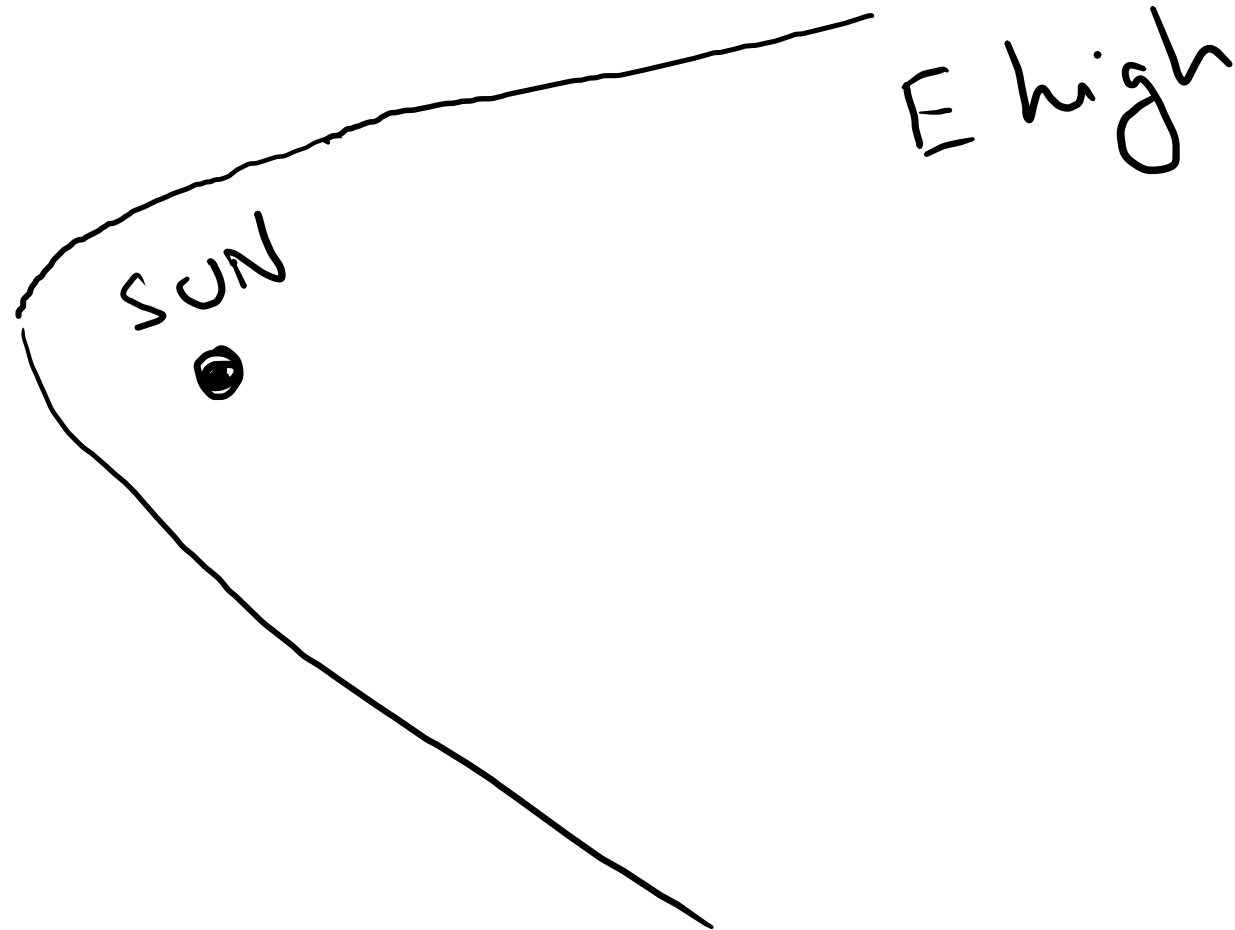
$$\frac{dV_{\text{eff}}}{dr} = -\frac{L^2}{mr^3} + \frac{\alpha}{r^2} = 0$$

$$\Rightarrow r = \frac{L^2}{m\alpha} = r_*$$

$$V_{\text{eff}}(r_*) = \frac{L^2}{2mr_*^2} - \frac{\alpha}{r_*} = -\frac{m\alpha^2}{2L^2} < 0$$

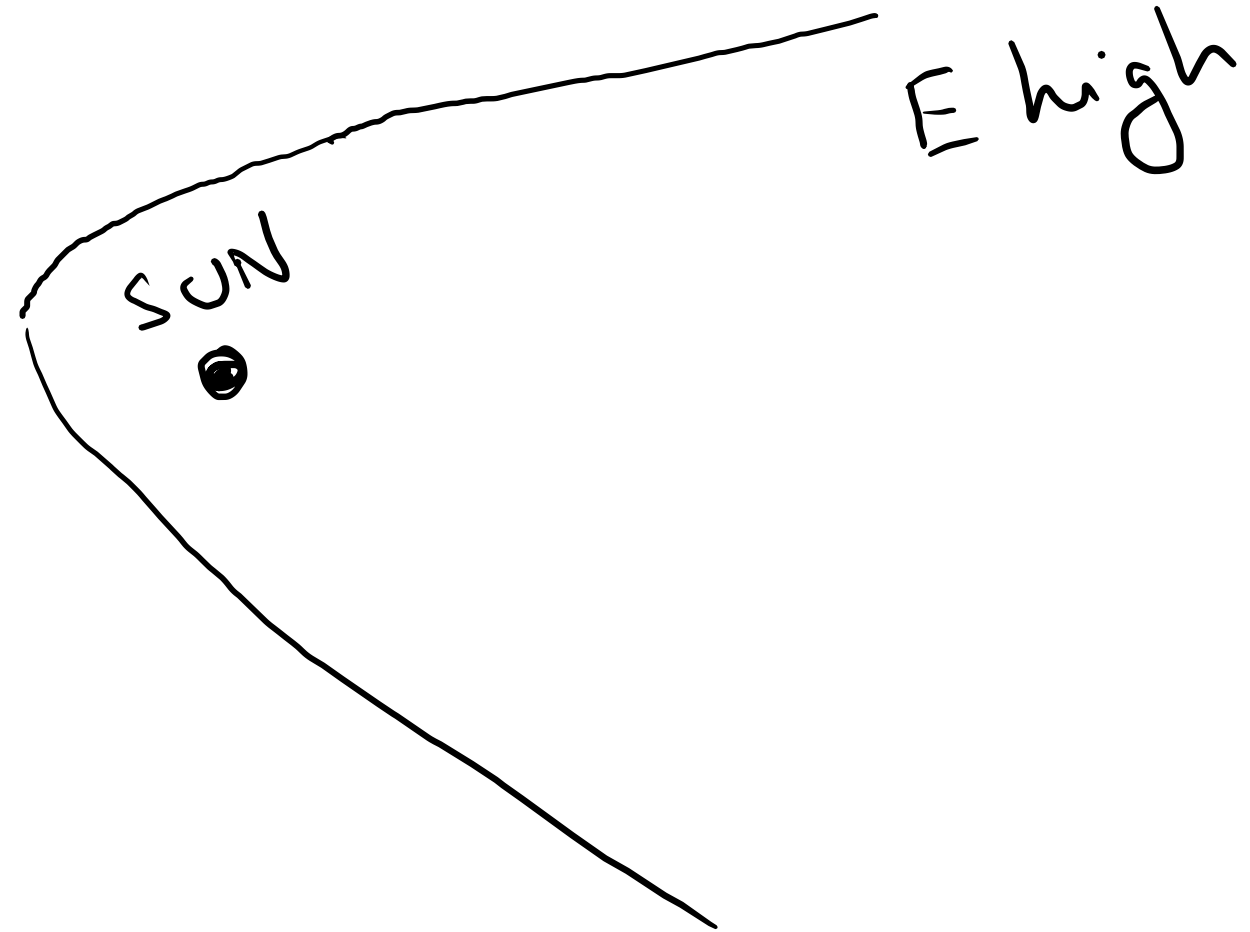


Physical situation (Roughly)



Ref! - Gregory
Classical mechanics.

Physical situation (Roughly)



Get exact eqn. for the orbit for $V(r) = -\alpha/r$.

EOM can be written in the form,

$$\frac{L^2}{m^2 r^4} \left[\left(\frac{dr}{d\theta} \right)^2 + r^2 \right] = \frac{2(E - V)}{m}$$

Convenient to change variable, $u = \frac{1}{r}$

$$\frac{dr}{d\theta} = \frac{dr}{du} \frac{du}{d\theta} = -\frac{1}{u^2} \left(\frac{du}{d\theta} \right)$$

$$\frac{L^2}{m^2} u^4 \left[\frac{1}{u^4} \left(\frac{du}{d\theta} \right)^2 + \frac{1}{u^2} \right] = \frac{2(E - V)}{m}$$

$$\Rightarrow \left(\frac{du}{d\theta} \right)^2 + u^2 = \frac{2m(E - V)}{L^2}$$

$$\left(\frac{du}{d\theta}\right)^2 + u^2 = \frac{2m(E-V)}{L^2}$$

$$\Rightarrow \left(\frac{du}{d\theta}\right)^2 = -u^2 + \frac{2m\hat{E}}{L^2} + \frac{2m\alpha}{L^2} u$$

$$\begin{aligned} \Rightarrow \left(\frac{du}{d\theta}\right)^2 &= -\left(u^2 - 2\frac{m\alpha}{L^2} u + \frac{m^2\alpha^2}{L^4} - \frac{m^2\alpha^2}{L^4}\right) + \frac{2m\hat{E}}{L^2} \\ &= -\underbrace{\left(u - \frac{m\alpha}{L^2}\right)^2}_Z + B^2 \end{aligned}$$

$$\frac{dz}{d\theta} = \sqrt{B^2 - z^2}$$

$$\Rightarrow \int \frac{dz}{\sqrt{B^2 - z^2}} = \int d\theta = \theta - \theta_0.$$

$$\Rightarrow \cos^{-1}(z/B) = \theta - \theta_0$$

Can set $\theta_0 = 0$.

$$z = B \cos(\theta)$$

$$\epsilon = \left(1 + \frac{2EL^2}{m\alpha^2}\right)^{1/2}$$

$$\epsilon = 0$$

Substituting,

$$\frac{1}{r} = \frac{m\alpha}{L^2} + \frac{m\alpha}{L^2} \left(1 + \frac{2EL^2}{m\alpha^2}\right)^{1/2} \cos \theta$$

$$\Rightarrow 1 + \frac{2EL^2}{m\alpha^2} = 0$$

$$\Rightarrow E = -\frac{m\alpha^2}{2L^2}$$

$$\Rightarrow \frac{1}{r} = \frac{m\alpha}{L^2} (1 + \epsilon \cos \theta)$$

$$\cos \theta = -1/\epsilon$$

$$\Rightarrow \cos^{-1}(z/B) = \theta - \theta_0$$

Can set $\theta_0 = 0$.

$$z = B \cos(\theta)$$

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$$\Rightarrow 1 + \frac{2EL^2}{m\alpha^2} = 0$$

$$\Rightarrow E = -\frac{m\alpha^2}{2L^2}$$

$$\Rightarrow \frac{1}{r} = \frac{m\alpha}{L^2} (1 + \epsilon \cos \theta)$$

$$\cos \theta = -1/\epsilon$$

Case I :- $\epsilon > 1$

$$r_{\min} = \frac{L^2}{m\alpha(1+\epsilon)}$$

Since, there will be a value of θ such that $\cos\theta = -1/\epsilon$

$$r_{\max} = \infty.$$

$$\frac{1}{2} m \frac{d}{dt} (\dot{r}^2 + r^2 \dot{\theta}^2) = \frac{d}{dt} \int dr f(r).$$

$$\Rightarrow \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - \int dr f(r) = \underline{\underline{E}}.$$

Had used: $\dot{r} f(r) = \frac{d}{dt} \int dr f(r)$ |

$$F(x) = \int_a^x dt f(t)$$

$$F'(x) = f(x).$$

$$\frac{d}{dt} \int_{r+\Delta r}^r f(r)$$

$$(r + \Delta r) - r$$

$$f(r) \frac{dr}{dt} = r f(r)$$