

SC223 - Linear Algebra

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Lecture 20



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Direct sum of Subspaces

- **Definition:** (Direct Sum of Subspaces) In a VS V with subspaces U_1, \dots, U_n , $W = U_1 + \dots + U_n$ is said to be a **Direct Sum** if $\forall w \in W$, w is **uniquely** expressed as a sum of elements $w_i \in U_i, i = 1, \dots, n$.
- Direct sum notation: $W = U_1 \oplus U_2 \oplus \dots \oplus U_n$.
- **Proposition 8:** Let U_1, \dots, U_n be subspaces of V . Then $V = U_1 \oplus \dots \oplus U_n$ if and only if: (1) $V = U_1 + \dots + U_n$, and (2) The only decomposition of $\theta \in V$ is (θ, \dots, θ) .
- **Proposition 9:** Let V be a VS with subspaces U_1, U_2 . Then $V = U_1 \oplus U_2$ iff $V = U_1 + U_2$ and $U_1 \cap U_2 = \{\theta\}$.

Span and Linear Independence

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i.e., the set of all possible linear combinations of elements from U .

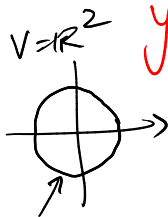
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- If $|U| = \infty \Rightarrow \text{span}(U) :=$ Set of all possible LC of all finite subsets of U .



$$y = \sum_{i=1}^{\infty} x_i$$

$$x_i \in \mathbb{R}$$

$$S_N = \sum_{i=1}^N x_i$$

$$\lim_{N \rightarrow \infty} S_N = y$$

$$\forall \epsilon > 0, \exists N_0 \in \mathbb{N} \text{ s.t. } \forall n \geq N_0$$

$$|S_n - y| < \epsilon$$

② $V = \mathcal{P}(\mathbb{R})$
 $U = \{1, x, x^2, x^3, x^4, \dots\}$

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- If $|U| = \infty$?
- Is $\text{span}(U)$ a subspace of V ?

Any $w_i \in \text{span}(U)$

$$w_1 = \sum_{i=1}^n a_i u_i, \quad u_i \in U.$$

$$w_2 = \sum_{i=1}^m b_i u_i, \quad u_i \in U$$

↑ Not necessarily the same

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- If $|U| = \infty$?
- Is $\text{span}(U)$ a subspace of V ?
- **Proposition 10:** Let $U \subseteq V$. Then $\text{span}(U)$ is a subspace of V .

- Let V be a VS, and let $W \subset V$. If $\text{span}(W) = V$, we say that W is a **spanning set** of V , or W **spans** V .

Ex: $V = \mathbb{R}^{n \times n}$

$$W = \left\{ \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & & & \\ \vdots & & & \\ 0 & \cdots & \cdots & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & & & 0 \\ \vdots & & & & \\ 0 & & & & 0 \end{bmatrix}, \dots \right.$$

$$\left. \dots, \begin{bmatrix} 0 & 0 & \cdots & 0 \\ \vdots & & & \\ 0 & \cdots & \cdots & 0 \\ & & & 1 \end{bmatrix} \right\}$$

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$$a_1 v_1 + \dots + a_n v_n = \theta \Rightarrow a_i = 0, i = 1, \dots, n$$

$$V = \{f: \mathbb{R} \rightarrow \mathbb{R}\}.$$

$$W = \{1, \sin t, \cos t\}.$$

$$1(t) = 1, \forall t \in \mathbb{R}.$$

$$a_1 \cdot 1 + a_2 \cdot \sin t + a_3 \cos t = 0, \forall t \in \mathbb{R}.$$

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- What if $|W| = \infty$.

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● Is it possible that $m > n$?

● If so, after n iterations, we will reach a contradiction:

$\text{span}(\{w_1, w_2, \dots, w_n\}) = V$

Basis of a Vector space

- **Definition:** (Hamel Basis) Let V be a finite dimensional vector space. An ordered set $\beta := \{v_1, \dots, v_n\}$ is said to be a **(Hamel) basis** of V if (1) $\text{span}(\beta) = V$, and (2) β is a set of linearly independent vectors.

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- Examples:

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- **Proposition 13:** Every FDVS has a basis.
- **Proposition 14:** Any set of basis vectors of a VS contains the same number of elements.
- **Dimension of a Vector Space:** Let V be a FDVS. For any set of basis vectors β of V , we define the dimension of V as $\dim(V) := |\beta|$.