

AMS 553.430 - Introduction to Statistics

Lectures by Dwijavanti P Athreya
Notes by Kaushik Srinivasan

Johns Hopkins University
Fall 2018

Lecture 0 (2018-08-30)	1	Lecture 10 (2018-10-03)	35
Lecture 1 (2018-08-30)	16	Lecture 11 (2018-10-10)	36
Lecture 2 (2018-09-05)	17	Lecture 12 (2018-10-15)	37
Lecture 3 (2018-09-10)	20	Lecture 13 (2018-10-17)	40
Lecture 4 (2018-09-12)	23	Lecture 14 (2018-10-22)	43
Lecture 5 (2018-09-17)	26	Lecture 15 (2018-10-24)	46
Lecture 6 (2018-09-19)	29	Lecture 16 (2018-10-29)	48
Lecture 7 (2018-09-24)	31	Lecture 17 (2018-10-31)	51
Lecture 8 (2018-09-26)	32	Lecture 18 (2018-11-05)	54
Lecture 9 (2018-10-01)	33	Lecture 19 (2018-11-07)	57

Introduction

Math 553.430 is one of the most important courses that is required/recommended for the engineering-based majors at Johns Hopkins University.

These notes are being live-Texed, through I edot for Typos and add diagrams requiring the *TikZ* package separately. I am using Texpad on Mac OS X.

I would like to thank Zev Chonoles from The University of Chicago and Max Wang from Harvard University for providing me with the inspiration to start live-Texing my notes. They also provided me the starting template for this, which can be found on their personal websites.

Please email any corrections or suggestions to ksriniv4@jhu.edu.

Lecture 0 (2018-08-30)

Introduction to Probability (553.420) Review

Part 1 - Counting

① Multiplication rule (Basic Counting Principle)

② Combinations/Permutations

- Sampling with or without replacement. \Rightarrow Inclusion-Exclusion Principle

$$\binom{n}{k} = \frac{n!}{k!(n-k)!} \quad {}^nP_k = \frac{n!}{(n-k)!}$$

③ Birthday Problem

④ Matching Problem (inclusion-exclusion principle)

$$- P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$- P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(A \cap C) - P(B \cap C) + P(A \cap B \cap C)$$

- etc...

⑤ n balls going into m boxes (all are distinguishable)

Example. n balls numbered $1, 2, \dots, n$. n boxes labelled $1, 2, \dots, n$. Distribute the balls into the boxes, one in each box. M_i = ball i is in box i

⑥ Multinomial Coefficients e.g. assign A, B, C, D, to different students \rightarrow anagram problem
- n distinct objects into r distinct groups

$$\frac{n!}{n_1!n_2!n_3! \dots n_r!} = \binom{n}{n_1, n_2, n_3, \dots, n_r}$$

⑦ Pairing Problem

$$2n \text{ people, paired up } \begin{cases} \text{ordered: } \binom{2n}{2, 2, \dots, 2} & \text{e.g. different courts for players} \\ \text{unordered: } \frac{\binom{2n}{2, 2, \dots, 2}}{n!} \end{cases}$$

⑧ Partition of integers $\rightarrow n$: sum of integer, r : number of partitions

$$\binom{n+r-1}{r-1} = \binom{n+r-1}{n}$$

Basics of Probability

Axioms

- ① $0 \leq P(A) \leq 1, \forall A$
- ② $P(\Omega) = 1 \rightarrow$ where Ω is the sample space
- ③ Countable additivity
 - if A_1, \dots, A_n are mutually exclusive, then

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = P(A_1) + P(A_2) + \dots = \sum_{i=1}^{\infty} P(A_i)$$

$$\Rightarrow P(A) = 1 - P(A^c)$$

$$P(A) = \frac{|A|}{|\Omega|}$$

Conditional Probability

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Law of Total Probability

$$P(A) = \sum_j P(A|B_j)P(B_j) = \sum P(A \cap B_j) \quad \underbrace{\bigcup_j B_j = \Omega}_{\text{partition of } \Omega}$$

Bayes Rule

$$P(B_i|A) = \frac{P(A|B_i)P(B_i)}{\sum_j P(A|B_j)P(B_j)} \quad \underbrace{\bigcup_j B_j = \Omega}_{\text{partition of } \Omega}$$

Independent events

If we have events A_1, A_2, \dots, A_n , then

$$P(A_1 \cap A_2 \cap A_3 \dots A_n) = P(A_1) \cdot P(A_2) \cdot P(A_3) \cdot \dots \cdot P(A_n)$$

Introduction to Discrete and Continuous Random Variables

Random Variable - a real valued function defined on the sample space of an experiment $X : \Omega \rightarrow \mathbb{R}, \forall \omega \in \Omega, X(\omega) \in \mathbb{R}$

Function	Discrete	Continuous
Probability Function	PMF: $P(X = x)$	PDF: $f_x(x)$
Probability Distribution	$\sum_x P(X = x) = 1$	$\int_x f_x(x)dx = 1$
Expectation	$E[X] = \sum_x xP(X = x)$	$E[X] = \int_x xf(x)dx$
Variance	$Var[X] = E[X^2] - (E[X])^2$	$Var[X] = E[X^2] - (E[X])^2$

Law of the Unconscious Statistician (LOTUS)

$$\text{1-dim} \quad E[g(x)] = \sum_x g(x)P(X = x) \quad \Bigg/ \quad E[g(x)] = \int_x g(x)f(x)dx$$

$$\text{2-dim} \quad E[g(X, Y)] = \sum_y \sum_x g(x, y)P(X = x, Y = y) \quad \Bigg/ \quad E[g(X, Y)] = \int_y \int_x g(x, y)f(x, y)dxdy$$

Discrete Distributions

- | | |
|--------------------------|--------------------------------|
| 1. Bernoulli(p) | 4. Geometric(p) |
| 2. Binomial(n, p) | 5. Negative Binomial(n, p) |
| 3. Poisson (λ) | 6. Hypergeometric(N, M, n) |

Bernoulli Distribution

X is a random variable with Bernoulli(p) distribution

$$X \sim \text{Bernoulli}(p)$$

$$P(X = x) = \begin{cases} p & x = 1 \\ 1 - p & x = 0 \end{cases}$$

Binomial Distribution

A sum of i.i.d. (identical, independent distribution) Bernoulli(p) R.V.

$$X \sim \text{Binomial}(n, p)$$

Support : $x \in \{0, 1, \dots, n\}$

n : sample size p : probability of success

$$P(X = k) = \binom{n}{k} p^k (1 - p)^{(n-k)}$$

$$E[X] = np \qquad \qquad \qquad Var(X) = np(1 - p)$$

- Approximation methods \Rightarrow

- if n is large, p very small and $np < 10$. \Rightarrow use Normal $(np, np(1-p))$
- $p \approx \frac{1}{2} \Rightarrow$ Use Poisson $(\lambda = np)$
- Mode:
 - if $(n+1)p$ integer, mode = $(n+1)p$ or $(n+1)p - 1$.
 - if $(n+1)p \notin \mathbb{Z}$ mode is $\lfloor (n+1)p \rfloor$
 - **Proof:** consider $\frac{P(X=x)}{P(X=x-1)}$ going below 1.

Poisson Distribution

$$\begin{aligned}
 X &\sim \text{Poisson}(\lambda) \\
 x &\in \{0, 1, \dots\} \\
 \lambda &: \text{parameter} \\
 P(X=x) &= \frac{e^{-\lambda} \lambda^x}{x!} \\
 E[X] &= \lambda & \text{Var}(X) &= \lambda
 \end{aligned}$$

- Approximations
 - if n is large \Rightarrow Normal (λ, λ)
- Sums of Poisson

Let $X \sim Po(\lambda)$ $Y \sim Po(\mu)$ \Rightarrow $X + Y \sim Po(\mu + \lambda)$

Negative Binomial

$$\begin{aligned}
 X &\sim NB(r, p) \\
 \text{Support : } x &= \{r, r+1, \dots\} \\
 r &= \text{the } r\text{th success} \\
 p &= \text{probability of success} \\
 P(X=k) &= \binom{k+r-1}{k} \cdot (1-p)^r \cdot p^k
 \end{aligned}$$

A sum of i.i.d Geometric(p) R.V.

■ a^{th} head before b^{th} tail

Example. A coin has probability p to land on a head, $q = 1 - p$ to land on a tail.

$P[5^{th} \text{ tail occurs before the } 10^{th} \text{ head}]?$

$$\left\{ \begin{array}{l} = P[5^{th} \text{ tail occurs before or on the } 14^{th} \text{ flip}] \\ = P[\text{Neg Binomial}(5, q) = 5, 6, 7, \dots, 14] \\ = \sum_{x=5}^{14} \binom{x-1}{4} q^5 p^{x-5} \end{array} \right. \quad (\text{or}) \quad \left\{ \begin{array}{l} = P[\text{at least } 5 \text{ tails in } 14 \text{ flips}] \\ = P[\text{binom}(14, q) = 5, 6, 7, \dots, 14] \\ = \sum_{x=5}^{14} \binom{14}{x} q^x p^{14-x} \end{array} \right.$$

Geometric Distribution

$$\begin{array}{l} X \sim \text{Geometric}(p) \\ \text{Support : } x \in \{1, 2, \dots\} \\ p : \text{probability of success} \\ P(X = r) = (1 - p)^{(r-1)} \cdot p \\ \text{prob for 1st success on } r\text{th trial} \\ E[X] = \frac{1}{p} \qquad \qquad \qquad \text{Var}(X) = \frac{1-p}{p^2} \end{array}$$

Example. ■ Coupon Question

Variation A: N different types of coupons $\rightarrow P(\text{get a specific type}) = \frac{1}{N}$

Question: $E[\text{draws to get } 10 \text{ different coupons}]?$

Answer:

$$X = X_1 + X_2 + \dots + X_{10} \qquad X_i = \# \text{ draws to get the } i\text{th distinct coupon type}$$

$$\boxed{X_i \sim \text{Geo}(p_i)} \qquad p_i : \text{prob to get a new coupon} \leftarrow \text{success, given that we have } i-1 \text{ types of coupons}$$

Hence, $E[X_1] = 1$

$$E[X_2] = \frac{1}{p_2} = \frac{1}{\frac{N-1}{N}} = \frac{N}{N-1}$$

$$E[X_3] = \frac{1}{p_3} = \frac{1}{\frac{N-2}{N}} = \frac{N}{N-2}$$

\vdots

$$E[X_{10}] = \frac{1}{p_{10}} = \frac{1}{\frac{N-9}{N}} = \frac{N}{N-9}$$

$$\text{So, } E[X] = E[X_1] + E[X_2] + \dots + E[X_{10}] = E\left[\sum_{i=1}^{10} X_i\right] = 1 + \frac{N}{N-1} + \frac{N}{N-2} + \dots + \frac{N}{N-9}$$

Variation B: Same setting, now you draw 10 times.

Question: $E[\# \text{ different types of coupons}]?$

Answer:

$$X = I_1 + I_2 + \dots + I_N$$

$$I_i \begin{cases} 1 & \text{if we have this type of coupon} \\ 0 & \text{o/w} \end{cases}$$

$$\begin{aligned}
E[I_i] &= P(\text{we draw coupon } i \text{ in } 10 \text{ draws}) \\
&= 1 - P(\text{we don't have coupon } i) \quad \text{we use binomial distribution where } 1 - P(N = 0) \\
&= 1 - \left(\frac{N-1}{N}\right)^{10}
\end{aligned}$$

$$E[X] = E\left[\sum_{i=1}^N I_i\right] = NE[I_i] = \boxed{N\left[1 - \left(\frac{N-1}{N}\right)^{10}\right]}$$

Hypergeometric Distribution

$$\begin{aligned}
X &\sim \text{Hyp}(N, M, n) \\
N &\in \{0, 1, 2, \dots\} \quad M \in \{0, 1, \dots, N\} \quad n \in \{0, 1, \dots, N\} \\
\text{Support : } k &\in \{\max(0, n + M - N), \min(n, M)\} \\
N &\text{ is the population size} \quad K \text{ is the no. of success states in the population} \\
n &\text{ is the no. of draws (i.e. quantity drawn in each trial)} \\
k &\text{ is the no. of observed successes} \\
P(X = k) &= \frac{\binom{M}{k} \binom{N-M}{n-k}}{\binom{N}{n}}
\end{aligned}$$

Continuous Distributions

Uniform Distribution

$$\begin{aligned}
X &\sim \text{Unif}(a, b) \\
f_X(x) &= \begin{cases} \frac{1}{b-a} & a \leq x \leq b \\ 0 & \text{o/w} \end{cases} \\
E[X] &= \frac{a+b}{2} \qquad \qquad \qquad \text{Var}(X) = \frac{(b-a)^2}{12}
\end{aligned}$$

Normal Distribution

$$\begin{aligned} X \sim N(\mu, \sigma^2) &\Rightarrow Z = \frac{X - \mu}{\sigma} \sim N(0, 1) \text{ with CDF } P(Z \leq z) = \Phi(z) \\ \Phi(-x) &= 1 - \Phi(x) \\ \text{Support: } x &\in (-\infty, \infty) \\ f_X(x) &= \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \\ E[X] &= \mu \qquad \qquad \qquad \text{Var}(X) = \sigma^2 \end{aligned}$$

- Sums and differences of Normal R.V.

$$\begin{array}{cc} X_1 \sim N(\mu, \sigma^2) & X_2 \sim N(\mu, \sigma^2) \\ Y_1 = X_1 + X_2 & Y_2 = X_1 - X_2 \\ \underbrace{Y_1 \sim N(2\mu, 2\sigma^2)}_{\text{has } \mu} & \underbrace{Y_2 \sim N(0, 2\sigma^2)}_{\text{doesn't have } \mu} \end{array}$$

- The sum and difference of Normal R.V. are Normal R.V.
- Any Linear Combination of Independent Normal R.V. is a Normal R.V.
- Dependence
 - $Y_2 = X_1 - X_2$ density does not depend on μ . But density of $X_1 + X_2$ does.
 - Key idea is used in Data Reduction

Exponential distribution

$$\begin{aligned} X &\sim \text{Exp}(\lambda) \\ \text{Support: } x &\in [0, \infty) \\ f_X(x) &= \lambda e^{-\lambda x} \\ E[X] &= \frac{1}{\lambda} \qquad \qquad \qquad \text{Var}(X) = \frac{1}{\lambda^2} \end{aligned}$$

Lack of memory property: $P(X \geq s + t | X \geq t) = P(X \geq s)$

- $M = \min \text{ of } \text{exp}(\lambda) \text{ and } \text{exp}(\mu) \Rightarrow M \sim \text{exp}(\lambda + \mu)$
- $M = \min \text{ of } X_1, X_2, \dots, X_n, \text{ where } X_i \sim_{\text{i.i.d.}} \text{exp}(\lambda) \Rightarrow \text{exp}(n\lambda)$

Gamma Distribution

$$X \sim \text{Gamma}(\alpha, \beta)$$

$$\text{Support: } x \in [0, \infty)$$

$$F_X(x) = \frac{\beta^\alpha}{\Gamma(\alpha)} x^{\alpha-1} e^{-\beta x}$$

$$E[X] = \frac{\alpha}{\beta}$$

$$\text{Var}(X) = \frac{\alpha}{\beta^2}$$

$$\textbf{Gamma Function: } \Gamma(z) = (z-1)! = \int_0^\infty x^{z-1} e^{-x} dx$$

$$\Gamma(n) = (n-1)!$$

$$\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}$$

- Sums of Gamma

$$- \underset{\text{ind}}{\text{Gamma}(s, \lambda)} + \text{Gamma}(s, \lambda) = \text{Gamma}(s+t, \lambda)$$

Beta Distribution

$$X \sim \text{Beta}(\alpha, \beta)$$

$$\text{Support: } x \in [0, 1]$$

$$f_X(x) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} x^{\alpha-1} (1-x)^{\beta-1}$$

$$E[X] = \frac{\alpha}{\alpha + \beta}$$

$$\text{Var}(X) = \frac{\alpha\beta}{(\alpha + \beta)^2(\alpha + \beta + 1)}$$

- Gamma to Beta

$$X \sim \text{Gamma}(\alpha_1, \beta) \quad Y \sim \text{Gamma}(\alpha_2, \beta)$$

$$\text{Then transformation } U = \frac{X}{X+Y} \sim \text{Beta}(\alpha_1, \alpha_2) \quad (\text{Use } X = UV, Y = V - UV)$$

Chi-Square

Chi-Square: χ_n^2 is Chi-square with degrees of Freedom n

$$\chi_n^2 = Z_1^2 + Z_2^2 + \cdots + Z_n^2 \quad \text{where } Z_i \sim \text{standard normal. } Z_i \sim \text{Gamma}\left(\frac{1}{2}, \frac{1}{2}\right)$$

$$\Rightarrow \chi_n^2 = n \text{ i.i.d. } Z_i \sim \text{Gamma}\left(\frac{1}{2}, \frac{1}{2}\right)$$

$$= \text{Gamma}\left(\frac{n}{2}, \frac{1}{2}\right)$$

CDF in General

- $F_x(t) = P(X \leq t)$

$$\begin{aligned} &= \sum_{x \leq t} P(X = x) && \text{discrete} \\ &= \int_{-\infty}^t f(x) dx && \text{continuous} \end{aligned}$$

- **Discrete:** "Left open, right closed" \Rightarrow if you flip the sign (from $<$ to \leq) in the left, you flip the sign of a (from a to a^-)

- $P(a < x \leq b) = F(b) - F(a)$
- $P(a \leq x \leq b) = F(b) - F(a^-)$
- $P(a < x < b) = F(b^-) - F(a)$
- $P(a \leq x < b) = F(b^-) - F(a^-)$

- **Continuous:** (because a point doesn't have a mass)

$$P(a \leq x \leq b) = \int_a^b f(x) dx = F(b) - F(a)$$

Integration by Recognition

$$1 = \int_{-\infty}^{\infty} \frac{e^{-\frac{x^2}{2\sigma^2}}}{\sigma\sqrt{2\pi}} dx \qquad \sigma\sqrt{2\pi} = \int_{-\infty}^{\infty} e^{-\frac{x^2}{2\sigma^2}} dx \qquad (\text{normal dist.})$$

Joint Distribution

Discrete	Continuous
$P_{X,Y}(x, y) = P(X = x, Y = y)$	$F_{X,Y}(x, y) = F_X(x)F_Y(y)$
Indep $\Rightarrow P_X(x)P_Y(y)$	$= \frac{\partial^2}{\partial x \partial y} F_{X,Y}(x, y)$

- **Marginal Density/PMF:**

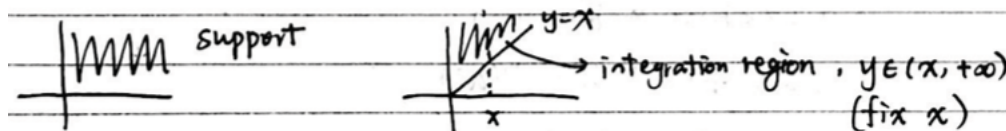
Continuous: $f_X(x) = \int_x f_{X,Y}(x, y) dy$ and $f_Y(y) = \int_y f_{X,Y}(x, y) dx$

** the bounds for y in the integration can depend on x , and vice versa*

Discrete: $P_X(x) = \sum_y P(X = x, Y = y)$ and $P_Y(y) = \sum_x P(X = x, Y = y)$

- Use joint pdf to compute probability

e.g. $P(X < Y) = \int_0^{\infty} \int_x^{\infty} f(x, y) dy dx$ assume $x > 0, y > 0$



- **Independence:** If X, Y are independent, then

Continuous: $f(x, y) = f_X(x)f_Y(y)$

Discrete: $P(X = x, Y = y) = P(X = x)P(Y = y)$

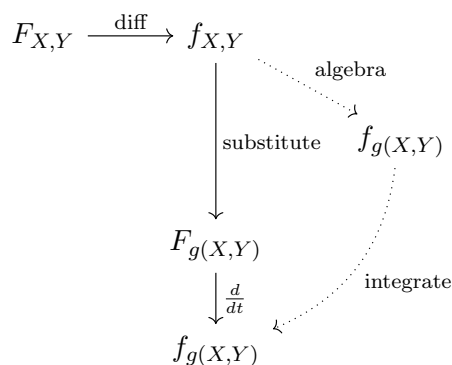
- **Convolution:** assume X, Y are independent

Discrete: $P_{X+Y}(a) = \sum_y P_X(a - y)P_Y(y) = \sum_x P_X(x)P_Y(a - x)$

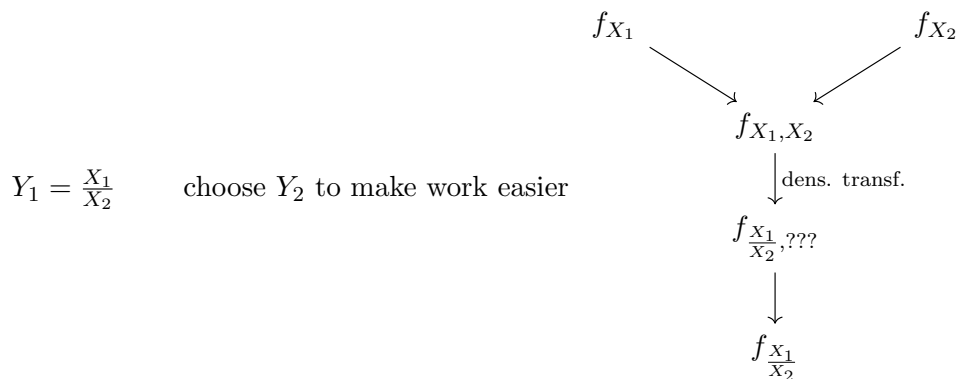
Continuous: $f_{X+Y}(a) = \int_y f_X(a - y)f_Y(y)dy = \int_y f_X(x)f_Y(a - x)dx$

MGF: we can use this $M_{X+Y}(t) = M_X(t)M_Y(t) \rightarrow$ then identify dist of $X+Y$ from mgf

- **Density Transformation:**



X_1 & X_2 are indep r.v. \Rightarrow want to find density of $\frac{X_1}{X_2}$



Density Transformation

For density transformation e.g. finding pdf of $U = X + Y$

- Convolution
- MGF
- Jacobian
- CDF Transformation

- Use CDF: Computer $P(Y \leq y) = P(g(x) = y)$

- **1-dim:** If Y is monotonically increasing or decreasing: $Y = g(x)$ $f_Y(y) = f_X(x(y)) \cdot |(x^{-1})'(y)|$

- **2-dim:** Joint Density:

$$(X, Y) \rightarrow (U, V) \quad U = h_1(X, Y) \quad V = h_2(X, Y)$$

$$f_{U,V}(u, v) = f_{X,Y}(x(u, v), y(u, v)) \cdot |J|$$

$$\text{where } J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \quad \text{determinant}$$

- if $Z = X + Y$ (2-dim \rightarrow 1-dim) use CDF. Compute $P(Z \leq z) = P(X + Y \leq z)$. Integrate $f(x, y)$ over this region.

Sterling's Formula

$$n! \approx \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n$$

This is only really useful when n is large, when factorials are represented as ratios.

Conditional distribution

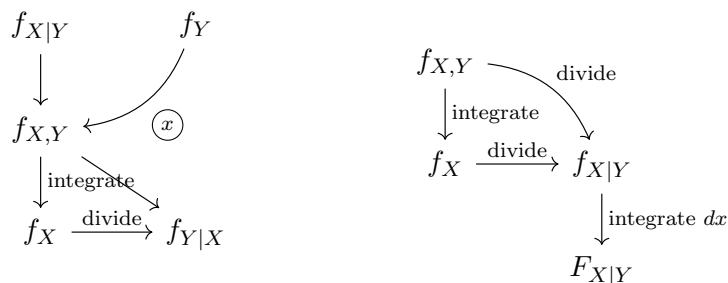
$$\text{Discrete} \quad P_{X|Y=y}(x|y) = \frac{P_{X,Y}(x, y)}{P_Y(y)} = \frac{P(X = x, Y = y)}{P(Y = y)}$$

$$\Rightarrow \sum_y P_{X,Y}(x, y) = \sum_y P_{X|Y=y}(x|y) \cdot P_Y(y)$$

$$\text{Continuous} \quad f_{X|Y=y}(x|y) = \frac{f_{X,Y}(x, y)}{f_Y(y)}$$

$$\Rightarrow f_X(x) = \int_y f(x, y) dy = \int_y f_{X|Y=y}(x|y) \cdot f_Y(y) dy$$

$$F_{X|Y}(x|y) = \int_{-\infty}^x f_{X|Y}(x|y) dx$$



Conditional Expectation

$$E[X|Y = y] = \sum_x xP(X = x|Y = y)$$

$$E[X|Y = y] = \int_x xf(x|y)dx$$

$E[X|Y]$: compute $E[X|Y = y]$ first, replace y with Y

• Properties:

- $E[aU + bV|Y = y] = aE[U|Y = y] + bE[V|Y = y]$ *LOTUS*
- If $g(Y) = X$ then $E[X|Y = y] = X$
- If X and Y are independent, then $E[X|Y = y] = E[X]$

Conditional Variance

$$\boxed{Var(X|Y) = E[(X - E[X|Y])^2]} \quad (\text{conditional variance})$$

$$\boxed{Var(X|Y) = E[X^2|Y] - (E[X|Y])^2} \quad (\text{unconditional variance})$$

Ordered Statistics

Consider X_1, X_2, \dots, X_n $X_{(j)}$ = j-th smallest

$$F_{\max(X_i)}(t) = P(\max X_i \leq t) = P(X_1 \leq t) \cdot P(X_2 \leq t) \cdots P(X_n \leq t)$$

$$= [F_X(t)]^n \quad \boxed{f_{\max X_i}(t) = nF(t)^{n-1}f_X(t)}$$

$$F_{\min(X_i)}(t) = 1 - P(\min x_i \geq t) = 1 - P(X_1 \geq t) \cdot P(X_2 \geq t) \cdots P(X_n \geq t)$$

$$= 1 - [1 - F_X(t)]^n \quad \boxed{f_{\min X_i}(t) = n[1 - F(t)]^{n-1}f_X(t)}$$

General: j -th order statistic

$$f_{x(j)}(t) = \binom{n}{j-1, 1, n-j} F_X(t)^{j-1} \cdot f_X(t) \cdot [1 - F_X(t)]^{n-j}$$

As Beta distribution: Let $U_1, U_2, \dots, U_N \sim i.i.d.$ Uniform(0, 1) and let $1 \leq j \leq N$
 $U_{(j)}$ = jth smallest in $U_{(1)}, U_{(2)}, \dots, U_{(N)}$ (ordered statistics). Then,

$$U_{(j)} \sim \text{Beta}(j, N - j + 1)$$

$$E[U_{(j)}] = \frac{j}{N + 1}$$

Expectation and Variance

Law of Total Expectation:

$$E[X] = E[E[X|Y]]$$

Law of Total Variance:

$$Var(X) = E[Var(X|Y)] + Var[E(X|Y)]$$

Expectation

① linearity of expectation

② How to compute

(a) LOTUS or definition (use density to integrate)

(b) MGF: $M^{(n)}(0) = E[X^n]$ or by recognition

(c) $E[X^2] = Var[X] + E[X]^2$

(d) Tail probability X is non-neg R.V. ($x > 0$) then $E[X] = \sum_{t=0}^{\infty} P(X \geq t)$ or $= \int_0^{\infty} P(X \geq t) dt$

Variance

① $Var(X_1 + X_2 + \cdots + X_n) = \sum_{i=1}^n Var(X_i) + \sum_{i \neq j} Cov(X_i, X_j)$

if X_i, X_j identical (not independent) $= nVar(X_i) + n(n-1)Cov(X_i, X_j)$ $i \neq j$

$Var(X+Y) = Var(X) + Var(Y) + 2Cov(X,Y)$

② **Covariance:**

$$Cov(X, Y) = E[XY] - E[X]E[Y]$$

$$Cov(X, c) = 0 \quad c \text{ is a constant}$$

$$Cov(X + Y, Z) = Cov(X, Z) + Cov(Y, Z)$$

$$Cov(cX, dZ) = cd \cdot Cov(X, Z)$$

$$Cov(aX + b, cY + d) = ac \cdot Cov(X, Y) \quad a, b, c, d \text{ are constants}$$

$$Cov(X, Y) = 0 \quad \text{If } X \perp Y \text{ (independent)}$$

③ **Correlation Coefficient:**

$$\rho(X, Y) = \frac{Cov(X, Y)}{\sqrt{Var(X)Var(Y)}} = \frac{Cov(X, Y)}{\sigma_x \sigma_y}$$

MGFs

Let X be a random variable. Then

$$M_X(t) = E[e^{tX}]$$

it can also be written as:

$$\begin{aligned} &= E\left[\sum_{j=0}^{\infty} \frac{(tX)^j}{j!}\right] \\ &= E\left[\sum_{j=0}^{\infty} \left(\frac{X^j}{j!} \cdot t^j\right)\right] \\ &\boxed{M_X^{(n)}(0) = E[X^n]} \end{aligned}$$

If X and Y are independent, then

$$\begin{aligned} M_{X+Y}(t) &= E[E^{(X+Y)t}] \\ &= E[e^{tX}]E[e^{tY}] \\ &= M_X(t)M_Y(t) \end{aligned}$$

Limit Theorems

Markov's Inequality

For any non-negative random variable X

$$P(X \geq a) \leq \frac{E(X)}{a} \quad (\text{for any } a > 0)$$

Proof. Let $X \geq 0$ a random variable and let $a > 0$. Define new random variable from X as Y_a

$$\begin{aligned} Y_a &= \begin{cases} 0 & \text{if } X < a \\ a & \text{if } X \geq a \end{cases} \\ 0 \leq Y_a \leq X &\implies \underbrace{E[Y_a]}_{a \cdot P(X \geq a)} \leq E[X] \\ E[Y_a] &= 0 \cdot P(Y_a < a) + a \cdot P(X \geq a) \\ E[Y_a] = a \cdot P(X \geq a) \leq E[X] &\implies \boxed{P(X \geq a) \leq \frac{E(X)}{a}} \end{aligned}$$

■

Chebyshev's Inequality

For any random variable Y with mean μ_y and variance σ_y^2

$$P(|Y - \mu_y| \geq c) \leq \frac{\sigma_y^2}{c^2} \quad (\text{for any } c > 0)$$

Proof.

$$P(|Y - \mu_y| \geq c) = P(\underbrace{|Y - \mu_y|^2}_{=X} \geq c^2)$$

$$P(|Y - \mu_y|^2 \geq c^2) \leq \frac{E[|Y - \mu_y|^2]}{c^2} = \frac{\sigma_y^2}{c^2}$$

■

This is the same as

$$- P(|Y - \mu_y| \geq k\sigma_y) \leq \frac{1}{k^2}$$

$$- P(|Y - \mu_y| \leq k\sigma_y) \geq \underbrace{1 - \frac{1}{k^2}}_{\text{very conservative}}$$

Central Limit Theorem

$$\sum_{i=1}^n X_i \sim \mathcal{N}(n\mu_n, n\sigma_x^2)$$

$$\frac{1}{n} \sum_{i=1}^n X_i \sim \mathcal{N}\left(\mu_n, \frac{\sigma_x^2}{n}\right)$$

Weak Law of Large Numbers

If X_1, X_2, \dots are *i.i.d.* with a mean μ

$$\text{then } \lim_{n \rightarrow \infty} P(|\bar{X}_n - \mu| \geq \epsilon) = 0$$

Strong Law of Large Numbers

$$X \xrightarrow{p} \mu_X \quad \text{as } n \rightarrow \infty$$

$$Pr\left(\lim_{n \rightarrow \infty} \bar{X}_n = \mu\right) = 1$$

Jensen's Inequality

If p_1, \dots, p_n are positive numbers and $\sum_{i=1}^n p_i = 1$, and f is a real continuous function that is convex, then

$$f\left(\sum_{i=1}^n p_i x_i\right) \leq \sum_{i=1}^n p_i f(x_i)$$

Conversely, if f is a concave function

$$f\left(\sum_{i=1}^n p_i x_i\right) \geq \sum_{i=1}^n p_i f(x_i)$$

Lecture 1 (2018-08-30)

Survey Sampling

We have a population of objects under study (people, animals, places, etc.). We will consider a single numerical measurement associated to object i : x_i

Example. $N = 5000$, x_i = height of person i , Population size = N . We denote population measurements $\{x_1, x_2, \dots, x_N\}$

Compute population quantities:

- population total $\tau = \sum_{i=1}^N x_i$
- population mean $\mu = \frac{\tau}{N} = \frac{\sum_{i=1}^N x_i}{N}$

Note: τ and μ are population parameters, their computation depends on all the population data.

Question. How to estimate τ and μ based on a sample of observation from this population?

Classical Answer: Choose a "random" sample of objects and associated measurements denoted $\{x_1, x_2, \dots, x_n\}$. *Note:* capital X_i denote random variables.

Whiter "Random"? Two types of ways to sample:

– without replacement

– with replacement

Claim 1. If X_i are drawn without replacement, then the distribution of X_1 and X_2 are identical. Is this true? **In fact, it is** \Rightarrow They are **NOT** independent but they are identically distributed.

$$P(\text{Ace in Pos 1}) = P(\text{Ace in Pos 2}) = \frac{4}{52}$$

Combinatorial Approach

"well-shuffled deck" \leftrightarrow all $52!$ rearrangements of the card are equally likely. How many rearrangements have ace at pos 1? $4 \cdot 51!$

$$P(A_1) = \frac{4 \cdot 51!}{52!} = \frac{4}{52} = P(A_2) = P(A_{19}) = P(A_{36})$$

Question. If X_1 and X_2 are identically distributed, then how do they differ between corresponding draws with replacement?

Answer. Independence. We can have Random Variables that are identically distributed and not independent. Note if independent, $P(A_2|A_1) = P(A_2)$.

with replacement

$$P(A_1) = \frac{4}{52}, \quad P(A_2) = \frac{4}{52}$$
$$P(A_2|A_1) = \frac{4}{52}$$

without replacement

$$P(A_1) = \frac{4}{52}, \quad P(A_2) = \frac{4}{52}$$
$$P(A_2|A_1) = \frac{3}{51}$$

We can see from this that depending on sampling method, we gain or lose independence. In the finite population sampling method, we have $1, \dots, N$ objects we care about.

Loss of Independence when choosing sampling method is important.

Lecture 2 (2018-09-05)

Finite Population sampling – without replacement. Mean/expected value and variance of \bar{X}

Suppose our population is given by $\{x_1, \dots, x_N\} = \{1, 2, 2, 7, 8, 9\}$ where

$$N = 6, \quad x_1 = 1 \quad x_2 = 2 \quad x_3 = 2 \quad x_4 = 7 \quad x_5 = 8 \quad x_6 = 9$$

Could also describe it by counting.

Distinct Value	frequency
$\varphi_1 = 1$	$n_1 = 1$
$\varphi_2 = 2$	$n_2 = 2$
$\varphi_3 = 7$	$n_3 = 1$
$\varphi_4 = 8$	$n_4 = 1$
$\varphi_5 = 9$	$n_5 = 1$

Possible sample of size $n = 6$, where we sample without replacement

$$X_1 = 7 \quad X_2 = 2 \quad X_3 = 8 \quad X_4 = 9 \quad X_5 = 1 \quad X_6 = 2$$

Sample here is the same as population as $\bigcirc n=N$

Same thing with replacement

$$X_1 = 9 \quad X_2 = 9 \quad X_3 = 9 \quad X_4 = 9 \quad X_5 = 9 \quad X_6 = 9$$

Typically N is large and $n \ll N$

Recall population parameters

$$\mu = \frac{\sum_{i=1}^N X_i}{N} \quad \tau = N\mu = \sum_{i=1}^N X_i$$

Next, σ^2 (population variance)

$$\sigma^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \mu)^2 \quad (\sigma^2 \text{ is pop. variance})$$

Alternatively, we can also express σ^2 as

$$\begin{aligned} \sigma^2 &= \frac{\sum_{i=1}^N (x_i - \mu)^2}{N} = \frac{\sum_{i=1}^N (x_i^2 - 2\mu x_i + \mu^2)}{N} \\ &= \frac{\sum_{i=1}^N x_i^2}{N} - \frac{2\mu}{N} \underbrace{\sum_{i=1}^N x_i}_{\mu} + \frac{N\mu^2}{N} \\ &= \frac{\sum_{i=1}^N x_i^2}{N} - 2\mu^2 + \mu^2 \end{aligned}$$

$$= \underbrace{\left(\frac{1}{N} \sum_{i=1}^N x_i^2 \right)}_{\text{2nd moment}} - \mu^2 = \mu^{(2)} - \mu^2$$

Define: $\mu^{(k)} = \frac{1}{N} \sum_{i=1}^N x_i^k$

Sample Mean \bar{X} as an estimator

A function of the sample data for the population μ .

Note: If the sample is random (X_1, \dots, X_n are R.Vs), then \bar{X} is **random!**

Questions:

- ① How is \bar{X} distributed? - in theory, if we know ①, then we know the answers ② & ③ too.
- ② What is $E[\bar{X}]$?
- ③ What is $Var(\bar{X})$?

Let's address ②

Consider $E[\underbrace{X_1}_{\text{first draw}}]$

possible values for $X_1 = \{x_1, \dots, x_N\}$

$$P(X_1 = x_k) = \frac{1}{\binom{N}{1}} = \frac{1}{N}$$

e.x. $\{\underbrace{1}_{x_1}, \underbrace{2}_{x_2}, \underbrace{2}_{x_3}, \underbrace{7}_{x_4}, \underbrace{7}_{x_5}, \underbrace{9}_{x_6}\}$ gives every separate entry a unique ticket even if they are the same

$$E[X_1] = \frac{1}{N} \sum_{k=1}^N x_k = \mu = E[X_2] \quad (\text{b/c } X_1 \text{ \& } X_2 \text{ are identically dist.})$$

In sampling without replacement X_i & X_j are still identically distributed, but they are not independent.

In sampling with replacement, X_i & X_j are *i.i.d.*

Note that whether or not X_1, \dots, X_n are independent,

$$E\left[\sum_{i=1}^N X_i\right] = \sum_{i=1}^N E[X_i]$$

Note: The sample mean is equal to expected population mean regardless of sampling with or without replacement.

$$\begin{aligned} E[\bar{X}] &= E\left[\frac{1}{n} \sum_{i=1}^n X_i\right] = \frac{1}{n} \sum_{i=1}^n E[X_i] \\ &= \frac{n\mu}{n} = \mu \end{aligned}$$

Since $E[\bar{X}] = \mu$, we say \bar{X} is an unbiased estimator for μ . **BUT** $\underbrace{\bar{X}}_{\text{R.V.}} \neq \underbrace{\mu}_{\text{constant}}$

Let's address ③

Sampling with replacement.

Theorem. *Sampling from finite population with replacement*

$$\text{Var}(\bar{X}) = \frac{\sigma^2}{n}$$

Proof. Here X_1, \dots, X_n are *i.i.d.*. In general, X_i 's are R.V. and a_i 's are constants

$$\text{Var}\left(\sum_i a_i X_i\right) = \sum_i \sum_j a_i a_j \text{Cov}(X_i, X_j)$$

If X_1, \dots, X_N are independent, $\text{Cov}(X_i, X_j) = 0$! Hence

$$\begin{aligned} \text{Var}(\bar{X}) &= \text{Var}\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n^2} \text{Var}\left(\sum_{i=1}^n X_i\right) = \frac{1}{n^2} \sum_{i=1}^n \underbrace{\text{Var}(X_i)}_{\text{a constant}} \\ &\boxed{\text{Var}(\bar{X}) = \frac{\text{Var}(X_i)}{n} = \frac{\sigma^2}{n}} \end{aligned}$$

■

We need to compute $\text{Var}(X_i)$. Observe that $\text{Var}(X_i)$ are same for all: *Why?* because they are identical.

Also notice $\frac{\text{Var}(X_i)}{n}$ decreases with n .

Observe that for all finite n , $\text{Var}(\bar{X})$ is not 0 unless $\text{Var}(X_i) = 0$!

Note: $\text{Var}(X_i) = E[(X_i - E(X_i))^2] = E[(X_i - \mu)^2] = \frac{1}{N} \sum (x_i - \mu)^2 = \sigma^2$

So $\text{Var}(X_i) = 0$ **iff** all $X_i \equiv \mu$

Lemma. *\bar{X} is consistent for μ , i.e. $\forall \delta > 0$, the $P(|\bar{X} - \mu| > \delta) \rightarrow 0$ as $n \rightarrow \infty$*

For this Lemma, we need to Prove Chebyshev's Inequality, which is

$$P(|Z - E(Z)| > \delta) \leq \frac{\text{Var}(Z)}{\delta^2}$$

Use this identity!

$$\begin{aligned} E[\bar{X}] &= \mu, & \text{Var}(\bar{X}) &= \frac{\sigma^2}{n} \\ P(|\bar{X} - E(\bar{X})| > \delta) &\leq \frac{\text{Var}(\bar{X})}{\delta^2} = \frac{\sigma^2}{n\delta^2} \rightarrow 0 \quad \text{as } n \rightarrow \infty \end{aligned}$$

Lecture 3 (2018-09-10)

Sampling without replacement

$Var(\bar{X})$ = when sampling without replacement

Theorem. *Sampling from finite population without replacement*

$$Var(\bar{X}) = \frac{\sigma^2}{n} \underbrace{\left[\frac{N-n}{n-1} \right]}_{FPN} \quad (\text{finite population correction})$$

Points to Note - In sample without replacement,

- If $n = N$, $Var(\bar{X}) = 0$
- If $n = 1$, $Var(\bar{X}) = \frac{\sigma^2}{n} = \sigma^2$, same as with replacement
- Check: for $n > 1$, how does $\frac{N-n}{N-1}$ relate to 1? The $Var(\bar{X})$ is always less without replacement

Proof. Start

①

$$Var(\bar{X}) = Var\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n^2} \sum_i \sum_j Cov(X_i, X_j)$$

\left(\text{When sampling with replacement, } Cov(X_i, X_j) = 0 \text{ if } i \neq j \right)

In sampling without replacement, we cannot assert that $Cov(X_i, X_j) = 0$ and we'll compute it explicitly.

$$\text{Recall} \quad Cov(X_i, X_j) = E[X_i X_j] - \underbrace{E[X_i]E[X_j]}_{\mu^2}$$

$$\mu^2 \leftarrow \text{as identical but not independent} \quad = E[X_i X_j] - \mu^2$$

② To calculate $E[X_i X_j]$, let us list distinct values in population

Example. $\left\{ \underbrace{5}_{x_1}, \underbrace{5}_{x_2}, \underbrace{8}_{x_3}, \underbrace{11}_{x_4}, \underbrace{8}_{x_5}, \underbrace{17}_{x_6}, \underbrace{9}_{x_7} \right\}$ Let $n_l = \#$ of times ζ_l appears in population.

Distinct Value	frequency
$\zeta_1 = 5$	$n_1 = 2$
$\zeta_2 = 8$	$n_2 = 2$
$\zeta_3 = 11$	$n_3 = 1$
$\zeta_4 = 17$	$n_4 = 1$
$\zeta_5 = 9$	$n_5 = 1$

$$P[X_i = 5] = \frac{2}{7} = \frac{n_1}{N} \quad (\text{i draws identical})$$

$$\Rightarrow P[X_i = \zeta_l] = \frac{n_l}{N}$$

$$n_1 + n_2 + \dots + n_m = \sum_{j=1}^m n_j = N$$

$$E[X_i X_j] = \sum_{k=1}^m \sum_{l=1}^m \zeta_k \zeta_l \underbrace{P[X_i = \zeta_k, X_j = \zeta_l]}_?$$

$$P[X_i = \zeta_k, X_j = \zeta_l] = \underbrace{P[X_j = \zeta_l | X_i = \zeta_k]}_{\textcircled{3}} \cdot \underbrace{P[X_i = \zeta_k]}_{= \frac{n_k}{N}}$$

③ Cases for Conditional probability

$$P[X_j = \zeta_l | X_i = \zeta_k] \stackrel{\text{cases}}{=} \begin{cases} \frac{n_l}{N-1} & l \neq k \rightarrow \text{numbers are diff.} \\ \frac{n_l - 1}{N-1} & l = k \rightarrow \text{numbers are same} \end{cases}$$

④ So we have

$$E[X_i X_j] = \sum_{k=1}^m \sum_{l=1}^m \zeta_k \zeta_l P[X_i = \zeta_k, X_j = \zeta_l]$$

$$E[X_i X_j] = \sum_{k=1}^m \sum_{l=1}^m \zeta_k \zeta_l P[X_j = \zeta_l | X_i = \zeta_k] \cdot P[X_i = \zeta_k]$$

$$= \sum_k \zeta_k P[X_i = \zeta_k] \zeta_k \left(\sum_l \zeta_l P[X_j = \zeta_l | X_i = \zeta_k] \right)$$

$$= \sum_k \zeta_k P[X_i = \zeta_k] \zeta_k \left(\sum_{l \neq k} \zeta_l P[X_j = \zeta_l | X_i = \zeta_k] + \zeta_k P[X_j = \zeta_k | X_i = \zeta_k] \right)$$

$$= \sum_k \zeta_k P[X_i = \zeta_k] \zeta_k \underbrace{\left(\sum_{l \neq k} \zeta_l \frac{n_l}{N-1} + \zeta_k \frac{n_k - 1}{N-1} \right)}_{\textcircled{5}}$$

⑤ When $l \neq k$ and we want to remove all l terms

$$\begin{aligned} \sum_{l \neq k} \zeta_l \frac{n_l}{N-1} &= \frac{1}{N-1} \sum_{l \neq k} \zeta_l n_l \\ \left(\sum_l \zeta_l n_l = \tau = n\mu \right) &\quad \text{population total} \\ &= \frac{1}{N-1} (\tau - \zeta_k n_k) \end{aligned}$$

⑥ Now Back

$$\begin{aligned}
 E[X_i X_j] &= \sum_k \zeta_k \frac{n_k}{N} \left(\frac{1}{N-1} (\tau - \zeta_k n_k) + \zeta_k \frac{n_k - 1}{N-1} \right) \\
 &= \frac{1}{N(N-1)} \sum_k \zeta_k n_k [(\tau - \cancel{\zeta_k n_k}) + \cancel{\zeta_k n_k} - \zeta_k] \\
 &= \frac{1}{N(N-1)} \sum_k \zeta_k n_k [\tau - \zeta_k] \\
 &= \frac{1}{N(N-1)} \left(\sum_k \zeta_k n_k \tau - \sum_k \zeta_k^2 n_k \right) \\
 &= \frac{1}{N(N-1)} \left[\tau^2 - \sum_k \zeta_k^2 n_k \right]
 \end{aligned}$$

⑦ What is $\sum_k (\zeta_k)^2 \frac{n_k}{N}$? Second moment $E[X_i^2]$ $E[X_i^2] = \sigma^2 + \mu^2$

$$\begin{aligned}
 E[X_i^2] &= \sigma^2 + \mu^2 & \frac{\tau^2}{N} &= N\mu^2 \text{ as } \mu = \frac{\tau}{N} \\
 E[X_i X_j] &\Rightarrow \frac{1}{N-1} \left[N\mu^2 - (\sigma^2 + \mu^2) \right] \\
 &= \frac{1}{N-1} [(N-1)\mu^2 - \sigma^2] = \mu^2 - \frac{\sigma^2}{N-1}
 \end{aligned}$$

$$\begin{aligned}
 \text{So } \text{Cov}(X_i, X_j) &= \mu^2 - \frac{\sigma^2}{N-1} - \mu^2 \\
 &= -\frac{\sigma^2}{N-1}
 \end{aligned}
 \tag{Cov < 0}$$

$$\text{So } \text{Cov}(X_i, X_j) = \text{Var}(X_i) = \sigma^2$$

⑧ Putting it all together

$$\begin{aligned}
 \text{Var}(\bar{X}) &= \frac{1}{n^2} \left(\sum_{i \neq j} \text{Cov}(X_i, X_j) + \sum_{i=1}^n \text{Var}(X_i) \right) \\
 &= \frac{1}{n^2} \left(\sum_{i \neq j} -\frac{\sigma^2}{N-1} + n\sigma^2 \right) \\
 &= \frac{1}{n^2} \left(\frac{-n(n-1)\sigma^2}{N-1} + \frac{\sigma^2}{n} \right) \\
 &= \frac{\sigma^2}{n} \left(1 - \frac{n-1}{N-1} \right) \\
 &= \frac{\sigma^2}{n} \left(\frac{N-n}{N-1} \right)
 \end{aligned}$$



Lecture 4 (2018-09-12)

- Binary data- special case.
- Approximate distance of \bar{X} when n is large but $n \ll N$
- Estimating population Variance
- Bivariate data

Recall that population is dichotomous or binary then $x_i = \begin{cases} 1 \\ 0 \end{cases}$

Moreover if we consider $x_i = 1$ as a "success" and $x_i = 0$ as a "failure", then

$$\mu = \frac{\sum_{i=1}^N X_i}{N} = \frac{\# \text{ of successes in population}}{\text{population size}} = p \quad (\text{pop}^n \text{ proportion of success})$$

$$\text{Now, } \sigma^2 = \underbrace{\frac{\sum_{i=1}^N X_i}{N}}_{\mu} - \mu^2 = p - p^2 = p(1 - p) = pq$$

$$\mu \text{ as } 1 \Rightarrow 1^2 = 1$$

$$0 \Rightarrow 0^2 = 0$$

Recall that if $Y \sim \text{Bernoulli}(p)$, $Y_i = \begin{cases} 1 & \text{w/ prob } p \\ 0 & \text{w/ prob } 1 - p \end{cases}$

$$E[Y] = p$$

$$\text{Var}(Y) = p(1 - p)$$

Last few weeks involved an analysis of \bar{X} , $E(\bar{X})$, $\text{Var}(\bar{X})$. Could also ask: How is \bar{X} distributed if n is large.

Confidence Intervals - Sampling W.R.

If sampling **with replacement**, where X_1, \dots, X_n denotes sample, we know X_i 's are *i.i.d.* Hence when n is large, by CLT \bar{X} has an approximately normal distribution.

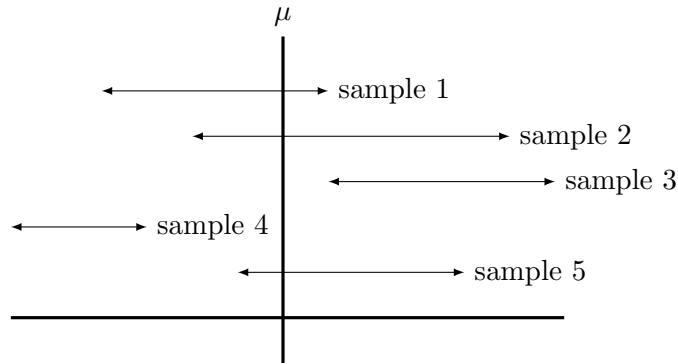
$$P\left(\frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \leq x\right) \rightarrow \Phi(x) \quad \text{as } n \rightarrow \infty$$

When sampling with replacement, we can use this to obtain confidence intervals for μ : Let $\alpha \in (0, 1)$ be given.

Let $Z_\alpha \in \mathbb{R}$ such that $P(Z > Z_\alpha) = \alpha$ where $Z \sim N(0, 1)$

By the Central Limit Theorem, for n large (sampling w/replacement)

$$\begin{aligned} &= P\left(-Z_{\alpha/2} \leq \frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \leq Z_{\alpha/2}\right) \\ &= P\left(\underbrace{\bar{X} - Z_{\alpha/2} \cdot \frac{\sigma}{\sqrt{n}}}_{\text{Random}} \leq \mu \leq \underbrace{\bar{X} + Z_{\alpha/2} \cdot \frac{\sigma}{\sqrt{n}}}_{\text{Random}}\right) \\ &\quad \text{Var}(\bar{X}) = 0 \quad \text{Never happens} \end{aligned}$$



In repeated sampling, approx $(1 - \alpha)$ of intervals contain μ , and (α) frac will not.

We say $\boxed{\bar{X} - Z_{\alpha/2} \cdot \frac{\sigma}{\sqrt{n}}}$ is $100(1 - \alpha)\%$ 2-sided confidence interval for μ

Problem: This interval involved σ which is unknown. Observe that if n is large, then $\frac{\bar{X} - \mu}{\sigma/\sqrt{n}}$ is still approx $N(0, 1)$ in distribution where (no population parameters)

$$\boxed{s^2 = \frac{1}{n-1} \sum (X_i - \bar{X})^2} \quad (\text{sample variance})$$

So we obtain

$$\boxed{\bar{X} \pm Z_{\frac{\alpha}{2}} \frac{s}{\sqrt{n}}} \quad \text{as a } 100(1 - \alpha) \text{ CI for } \mu$$

In the dichotomous case,

$$\bar{X} = \frac{\# \text{ of the succession sample}}{\text{sample size}} = \hat{p}$$

$$100(1 - \alpha)\% \text{ CI for } p : \hat{p} \pm Z_{\frac{\alpha}{2}} \sqrt{\frac{\hat{p}(1 - \hat{p})}{n}}$$

Confidence Intervals - Sampling W.o.R.

Recall now what happens when sampling **without replacement**

Here, X_1, X_2, \dots, X_n remain identically distributed, but not independent

We surmised, that if $n \ll N$, X_i & X_j have an "approximate independence"

Example 1. Let population consist of 1000 elements. In this case:

$$\left. \begin{array}{l} \text{blue} - \textcircled{1} - 200, \quad \text{red} - \textcircled{2} - 300, \quad \text{green} - \textcircled{1} - 500 \\ P(X_1 = \textcircled{3}) = \frac{1}{2} \\ P(X_2 = \textcircled{3} | X_1 = \textcircled{3}) = \frac{499}{999} \end{array} \right\} \text{not independent, but have approximate independence.}$$

In short, $n \ll N$, each successive draw does not alter probabilities that much, precisely b/c removal is only of a sample # of population elements.

So if $n \ll N$, then even in sampling W.O.R, X_i 's retain an approximate independence. Further if n is "large" and small relative to N , (note delicate point!) then \bar{X} will still have an approx Normal distribution.

$$\frac{\bar{X} - \mu}{\sqrt{\frac{\sigma^2}{n} \left(\frac{N-n}{N-1} \right)}} \sim N(0, 1)$$

Observe σ^2 is still unknown. We'd like to consider estimators for σ^2

Estimator for variance W.o.R

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2$$

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$$

Try to understand $E[\hat{\sigma}^2]$

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i^2 - 2X_i\bar{X} + \bar{X}^2)$$

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n X_i^2 - 2\bar{X}\bar{X} + \bar{X}^2 = \frac{1}{n} \sum_{i=1}^n X_i^2 - \bar{X}^2$$

$$E[\hat{\sigma}^2] = \underbrace{E\left[\frac{1}{n} \sum_{i=1}^n X_i^2\right]}_{\textcircled{1}} - \underbrace{E[\bar{X}^2]}_{\textcircled{2}} \quad \text{can get } E[\bar{X}^2] \text{ from } Var(\bar{X})$$

$$\textcircled{1} \quad E\left[\frac{1}{n} \sum_{i=1}^n X_i^2\right] = \frac{1}{n} \sum_{i=1}^n E[X_i^2] = \sigma^2 + \mu^2$$

$$\textcircled{2} \quad Var(\bar{X}) = E[\bar{X}^2] - (E[\bar{X}])^2$$

$$E[\bar{X}^2] = \underbrace{Var(\bar{X})}_{\text{computed}} + \mu^2$$

Combining, we get:

$$E[\hat{\sigma}^2] = \sigma^2 + \mu^2 - (Var(\bar{X}) + \mu^2)$$

$$E[\hat{\sigma}^2] = \sigma^2 - \left[\frac{\sigma^2}{n} \left(\frac{N-n}{N-1} \right) \right]$$

The estimator is biased, but

$$E[\hat{\sigma}^2] = \sigma^2 \underbrace{\left(1 - \frac{N-n}{(n)(N-1)} \right)}_{\text{constant, } c}$$

$$E[\hat{\sigma}^2] = C\sigma^2$$

and thus $\frac{\hat{\sigma}^2}{C}$ is an unbiased estimator.

Lecture 5 (2018-09-17)

- Approximation methods / Delta-methods
- Bivariate populations
- Ratio estimations

We calculated $E[\underbrace{\hat{\sigma}^2}_{C\sigma^2}]$ where $\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2$ and you can use our computations to generate an unbiased estimator for population variance σ^2 . Can also use this to calculate $E[s^2]$, where $s^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$

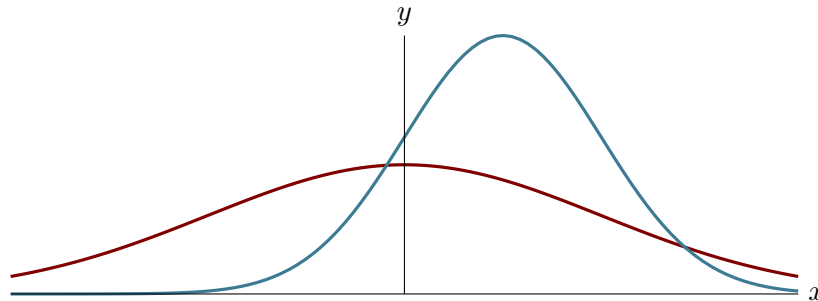
Bias-Variance Tradeoff

- ① Unbiased estimators are useful: if T is an unbiased estimator for θ then $E[T] = \theta$.
- ② However, if we wish to evaluate two estimators— one biased and other unbiased, we may not universally want to choose the unbiased one always, we need to consider variance.

Why? Suppose that T is an estimator for θ .

The Mean Squared Error (MSE):

$$MSE = E[(T - \theta)^2] \xrightarrow{\text{exercised}} \underbrace{Var(T)}_{\text{Variance}} + \underbrace{(E(T) - \theta)^2}_{\text{Bias}}$$



We can see from the above plots that the red graph has an estimator θ closer to μ , but has a higher variance. However, estimator B has an unbiased estimator, but has a smaller variance. Depends on sampling analysis.

Bivariate population sampling

Suppose we have a population of N objects. On each object we have a pair of measurements: (x_i, y_i)

Note: When sampling from this population if object i is in sample, then both measurements in pair (x_i, y_i) are retained. In particular (x_i, y_i) appears exactly once in the population, and sample w/o repl, then you cannot retrieve measurement i later.

Parameters

$$\sigma_Y^2 = \frac{1}{N} \sum_{i=1}^N (y_i - \mu_Y)^2 \quad \mu_X = \frac{1}{N} \sum_{i=1}^N X_i \quad \tau_X = N\mu_X$$

$$\mu_Y = \frac{1}{N} \sum_{i=1}^N Y_i \quad \tau_Y = N\mu_Y$$

$$\sigma_X^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \mu_X)^2$$

Covariance

$$\sigma_{XY}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \mu_X)(y_i - \mu_Y)$$

Suppose $\mu_X \neq 0$

Define $r = \frac{\mu_X}{\mu_Y}$

What is a reasonable estimator r ?

Could consider $R = \frac{\bar{X}}{\bar{Y}}$

Now Suppose that μ_X were known. Consider $\mu_X \cdot R = \frac{\mu_X}{\bar{Y}} \bar{Y}$.

Plausible estimator for μ_Y . But why? we already have \bar{Y} , an unbiased estimator for μ_Y . We will see that $\mu_X \cdot R$, the so called **ratio estimate**, is

① a biased estimate

② can contribute in reduction in variance relative to \bar{Y}

So we will need to understand $E[R]$, $Var(R)$ & approximations of $E[R]$ & $Var(R)$

Approximation Methods

Let X be a random variable with mean $= \mu_X$ and variance $= \sigma_X^2$. Let $Z = g(X)$, where $g : \mathbb{R} \rightarrow \mathbb{R}$, g a deterministic function of x .

Question: How to compute $E[Z]$?

Answer: If density of X is known, (call this f_X), then

$$E(Z) = \int_{\mathbb{R}} g(X) f_X(x) dx \quad \text{involves an integral}$$

Cumbersome even if f_X is known; closed form solution to integral exists; not possible to get exact value even if f_X known, but no closed form solution; not even possible to write integral if f_X unknown. If g is linear, then it is OK e.g. $E[g(X)] = E[aX + b] = a\mu_X + b$

Taylor Expansions

Taylor expansion of g about μ_X (Why? Think Chebyshev!)

$$g(x) \approx g(\mu_X) + g'(\mu_X)(x - \mu_X) + \frac{g''(x)(x - \mu_X)^2}{2!} + \dots + \text{higher order terms}$$

$$g(X) \approx g(\mu_X) + g'(\mu_X)(X - \mu_X) + \frac{g''(X)(X - \mu_X)^2}{2!}$$

$$E[Z] \approx E[g(\mu_X)] + E[g'(\mu_X)(X - \mu_X)] + E\left[\frac{g''(\mu_X)}{2!}(X - \mu_X)^2\right]$$

$$\approx g(\mu_X) + g'(\mu_X)E[(X - \mu_X)] + \frac{g''(\mu_X)}{2!}E[(X - \mu_X)^2]$$

$$E[Z] \approx g(\mu_X) + \frac{g''(\mu_X)}{2!}\sigma_X^2$$

But $R = \frac{\bar{Y}}{\bar{X}}$, a function of two variables!

Consider $g(x, y) : \mathbb{R}^2 \rightarrow \mathbb{R}$
Taylor expand g about (μ_x, μ_y)

① Linear Approximation

$$g(x, y) \approx g(\mu_x, \mu_y) + \frac{\partial g}{\partial x}(\mu_x, \mu_y) \cdot (x - \mu_x) + \frac{\partial g}{\partial y}(\mu_x, \mu_y) \cdot (y - \mu_y)$$

② Second order approximation

$$g(x, y) \approx g(\mu_x, \mu_y) + \frac{\partial g}{\partial x}(\mu_x, \mu_y) \cdot (x - \mu_x) + \frac{\partial g}{\partial y}(\mu_x, \mu_y) \cdot (y - \mu_y)$$

$$+ \frac{1}{2} \frac{\partial^2 g}{\partial x^2}(\mu_x, \mu_y) \cdot (x - \mu_x)^2 + \frac{1}{2} \frac{\partial^2 g}{\partial y^2}(\mu_x, \mu_y) \cdot (y - \mu_y)^2 + \frac{\partial g}{\partial x \partial y}(\mu_x, \mu_y) \cdot (x - \mu_x)(y - \mu_y)$$

Evaluating $E[g(X, Y)]$

$$E[g(X, Y)] \approx g(\mu_x, \mu_y) + \frac{\partial g}{\partial x}(\mu_x, \mu_y) \cdot E[(x - \mu_x)] + \frac{\partial g}{\partial y}(\mu_x, \mu_y) \cdot E[(y - \mu_y)]$$

$$+ \frac{1}{2} \frac{\partial^2 g}{\partial x^2}(\mu_x, \mu_y) \cdot E[(x - \mu_x)^2] + \frac{1}{2} \frac{\partial^2 g}{\partial y^2}(\mu_x, \mu_y) \cdot E[(y - \mu_y)^2] + \frac{\partial g}{\partial x \partial y}(\mu_x, \mu_y) \cdot E[(x - \mu_x)(y - \mu_y)]$$

When the dust settles,

$$E[g(X, Y)] \approx g(\mu_x, \mu_y) + \frac{1}{2} \frac{\partial^2 g}{\partial x^2}(\mu_x, \mu_y) \cdot \sigma_X^2 + \frac{1}{2} \frac{\partial^2 g}{\partial y^2}(\mu_x, \mu_y) \cdot \sigma_Y^2 + \frac{\partial g}{\partial x \partial y}(\mu_x, \mu_y) \cdot Cov(X, Y)$$

Lecture 6 (2018-09-19)

- Approximation methods, Δ -methods
- Ratio estimations
- Parametric Estimation

Let X be a r.v. mean μ_X and variance σ_X^2 . Let g be a deterministic function $g : \mathbb{R} \rightarrow \mathbb{R}$.
Let $Z = g(X)$ How to approximate $E[g(X)] = g(Z)$? We could do

$$E[Z] \approx g(\mu_X) + \frac{1}{2}g''(\mu_X) \cdot \text{Var}(X)$$

Whether or not this approximation is accurate depends on contribution to higher order terms.
If $Z = g(X, Y)$, then $E[Z]$ is

$$E[Z] \approx g(\mu_x, \mu_y) + \frac{1}{2} \frac{\partial^2 g}{\partial x^2}(\mu_x, \mu_y) \cdot \sigma_X^2 + \frac{1}{2} \frac{\partial^2 g}{\partial y^2}(\mu_x, \mu_y) \cdot \sigma_Y^2 + \frac{\partial g}{\partial x \partial y}(\mu_x, \mu_y) \cdot \sigma_{XY}$$

Goal: Understand $E[R]$, $\text{Var}(R)$ where $R = \frac{\bar{Y}}{\bar{X}}$ and we are sampling W.o.R from a finite bivariate population

Let's consider what happens when $g(X, Y) = \frac{Y}{X}$

$$\frac{\partial g}{\partial x} = \frac{-y}{x^2} \rightarrow \frac{\partial^2 g}{\partial x^2} = \frac{2y}{x^3} \quad \frac{\partial g}{\partial y} = \frac{1}{x} \rightarrow \frac{\partial^2 g}{\partial y^2} = 0 \quad \frac{\partial^2 g}{\partial x \partial y} = -\frac{1}{x^2}$$

Here we will look at $g(\bar{X}, \bar{Y}) = \frac{\bar{Y}}{\bar{X}}$ $E[\bar{X}] = \mu_x$ and $E[\bar{Y}] = \mu_y$

$$E[g(\bar{X}, \bar{Y})] = E\left[\frac{\bar{X}}{\bar{Y}}\right] \approx \frac{\mu_y}{\mu_x} + \frac{1}{2} \left(\frac{2\mu_y}{(\mu_x)^3} \right) \sigma_{\bar{X}}^2 + 0 - \frac{1}{\mu_x^2} \sigma_{\bar{X}\bar{Y}}$$

Do we think $\mu_x R$ is unbiased for μ_y **Answer:** No, it is not unbiased b/c look at approximation

What about variance?

Let's return for a minute on general setting for approximations of moments of functions of random variables. Again $g(X, Y) = Z$

Let's write 1st order Taylor expansion for Z

$$Z \approx g(\mu_x, \mu_y) + \frac{\partial g}{\partial x}(\mu_x, \mu_y) \cdot (x - \mu_x) + \frac{\partial g}{\partial y}(\mu_x, \mu_y) \cdot (y - \mu_y)$$

So we find

$$\begin{aligned} Z &\approx a + b(X - \mu_X) + c(Y - \mu_Y) \\ \text{Var}(Z) &\approx b^2 \text{Var}(X) + c^2 \text{Var}(Y) + 2bc \text{Cov}(X, Y) \\ &\approx \underbrace{\left[\frac{\partial g}{\partial x} \right]^2}_{b} \sigma_X^2 + \underbrace{\left[\frac{\partial g}{\partial y} \right]^2}_{c} \sigma_Y^2 + 2 \underbrace{\left[\frac{\partial g}{\partial x} \right]}_b \underbrace{\left[\frac{\partial g}{\partial y} \right]}_c \sigma_{XY} \end{aligned}$$

We don't go further than linear as higher variance requires higher order moments e.g. $E[x^4] \leftarrow$ they don't matter.

$$Var(R) \approx \left[\frac{-\mu_y}{\mu_x^2} \right]^2 \sigma_{\bar{X}}^2 + \left[\frac{1}{\mu_x} \right]^2 \sigma_{\bar{Y}}^2 + 2 \left[\frac{-\mu_y}{\mu_x^2} \right] \left[\frac{1}{\mu_x} \right] \sigma_{\bar{X}\bar{Y}} \quad (\star)$$

Recall

$$\begin{aligned} \sigma_{\bar{X}}^2 &= \frac{\sigma_x}{n} \left[\frac{N-n}{N-1} \right] & \sigma_{\bar{Y}}^2 &= \frac{\sigma_y}{n} \left[\frac{N-n}{N-1} \right] \\ \sigma_{\bar{X}\bar{Y}} &= \textcircled{?} & \frac{\sigma_{xy}}{n} \left[\frac{N-n}{N-1} \right] \end{aligned}$$

Recall

$$\begin{aligned} \sigma_{XY} &= \frac{1}{N} \sum_{i=1}^N (x_i - \mu_x)(y_i - \mu_y) \\ \rho &= \frac{\sigma_{xy}}{\sigma_x \sigma_y} \Rightarrow \boxed{\sigma_{xy} = \rho \sigma_x \sigma_y} \end{aligned}$$

Now \star implies

$$\begin{aligned} Var(R) &\approx \frac{1}{n} \left[\frac{N-n}{N-1} \right] \left\{ \frac{\mu_y^2}{\mu_x^4} \sigma_x^2 + \frac{1}{\mu_x^2} \sigma_y^2 - \frac{2\mu_y}{\mu_x^3} \sigma_{xy} \right\} \\ &\approx \frac{1}{n\mu_x^2} \left[\frac{N-n}{N-1} \right] \left\{ \underbrace{\frac{\mu_y^2}{\mu_x^2}}_{r^2} \sigma_x^2 + \sigma_y^2 - 2 \underbrace{\frac{\mu_y}{\mu_x^3}}_r \underbrace{\sigma_{xy}}_{\rho \sigma_x \sigma_y} \right\} \\ Var(R) &\approx \frac{1}{n\mu_x^2} \left[\frac{N-n}{N-1} \right] (r^2 \sigma_x^2 + \sigma_y^2 - 2r\rho \sigma_x \sigma_y) \end{aligned}$$

Ratio Estimations

Ratio estimate for μ_Y is $\mu_X R \leftarrow$ useful if μ_X is known. We know from before that $E[\mu_X R] \neq \mu_Y$.

$$Var(\bar{Y}) = \frac{\sigma_y^2}{n} \left[\frac{N-n}{N-1} \right] \quad E[\bar{Y}] = \mu$$

Ratio is useful if bias is small and variance reduction is significant (relative to $Var(\bar{Y})$).

Recall

$$\begin{aligned} E(R) &= \frac{\mu_x}{\mu_y} + \frac{1}{2} \frac{\mu_y}{\mu_x^3} \cdot \frac{\sigma_y^2}{n} \left[\frac{N-n}{N-1} \right] - \frac{1}{\mu_x^2} \frac{\sigma_{xy}}{n} \left[\frac{N-n}{N-1} \right] \\ &\approx r + \frac{1}{n\mu_x^2} \left[\frac{N-n}{N-1} \right] (r\sigma_x^2 - \rho\sigma_x\sigma_y) \end{aligned}$$

Finally,

$$E[\mu_X R] \approx \mu_y + \frac{1}{\mu_y} \left(\frac{1}{n} \right) \left(\frac{N-n}{N-1} \right) (r\sigma_x^2 - \rho\sigma_x\sigma_y)$$

So is non-zero, but decaying in n .

Fact: For n large but small relative to N ($n \ll N$), R can be approx. using normal distribution.

Lecture 7 (2018-09-24)

- Properties of estimation
- Method of moments
- Maximum Likelihood
- Properties of estimators

Lecture 8 (2018-09-26)

Maximum Likelihood Estimation

Lecture 9 (2018-10-01)

- MLEs - normal, gamma, uniform
- Modes of convergence
- Slutsky's Theorem
- Asymptotic properties of MLEs

MLEs - Normal Distribution

Let $X_i, 1 \leq i \leq n$ be i.i.d. $\mathcal{N}(\mu, \sigma^2)$ The likelihood

$$\begin{aligned} f(x_1, \dots, x_n | \mu, \sigma^2) &= \prod_{i=1}^n f(x_i | \mu, \sigma^2) \\ &= \prod_{i=1}^n \left[\frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x_i - \mu)^2}{2\sigma^2}\right) \right] \\ &= \left(\frac{1}{\sigma\sqrt{2\pi}}\right)^n \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2\right) \\ \text{The log-likelihood:} \quad &= -n \log(\sigma\sqrt{2\pi}) - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \end{aligned}$$

Maximize this w.r.t. μ, σ . Here log-likelihood depends smoothly on parameters \rightarrow can consider critical points as 1st step in maximization.

$$\begin{aligned} \frac{\partial l}{\partial \mu} &= \frac{2}{2\sigma^2} \sum_{i=1}^n (x_i - \mu) = 0 \implies n\mu = \sum_{i=1}^n x_i \implies \boxed{\hat{\mu}_{\text{MLE}} = \bar{X}} \\ \frac{\partial l}{\partial \sigma} &= \frac{-n\sqrt{2\pi}}{\sigma\sqrt{2\pi}} - \frac{1}{\sigma^3} \sum_{i=1}^n (x_i - \mu)^2 = 0 \implies \frac{n}{\sigma} = \frac{1}{\sigma^3} \sum_{i=1}^n (x_i - \mu)^2 \implies \boxed{\hat{\sigma}_{\text{MLE}}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2} \end{aligned}$$

Need to make sure two partial derivatives vanish simultaneously

$$\begin{aligned} \mu &= \bar{X} \\ \sigma^2 &= \frac{1}{n} \sum_{i=1}^n (X_i - \mu)^2 \implies \boxed{\hat{\sigma}_{\text{MLE}} = \sqrt{\frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2}} \end{aligned}$$

Capital X_i 's because want a function of the random variables in our sample. $E[\bar{X}] = \mu$. So $\hat{\mu}$ MLE is unbiased. $\text{Var}(\hat{\mu}_{\text{MLE}}) = \frac{\sigma^2}{n}$

Question: Is $E[\hat{\sigma}_{\text{MLE}}] = \sigma$?

$$\text{Next, } \hat{\mu}_{\text{MLE}} = \bar{X} = \frac{1}{n} \sum_{i=1}^n X_i \sim \mathcal{N}\left(\mu, \frac{\sigma^2}{n}\right)$$

Support

Given a density function $f(x|\theta)$, we define the support of f to be

$$\text{supp } f = \{x : f(x|\theta) > 0\}$$

Suppose Θ is the space (in \mathbb{R}, \mathbb{R}^d) to which θ belongs:

If X_i 's are i.i.d.. Bernoulli(p), then $\Theta = (0, 1)$, $\text{supp } f = \{0, 1\}$
If X_i 's are i.i.d.. $N(\mu, \sigma^2)$, then $\Theta = \{(a, b) : a \in \mathbb{R}, b > 0\}$, $\text{supp } f = \mathbb{R}$

We say that the supp f is independent of θ if

$$\{x : f(x|\theta) > 0\} \text{ is the same set for all } \theta \in \Theta$$

MLEs - Uniform Distribution

Now let X_i be i.i.d. $\text{Unif}[0, \theta]$ $\theta > 0$ Here $\text{supp } f$ is not independent of θ .

$$\text{supp } f = \{x : f(x|\theta) > 0\} \quad f(x|\theta) \begin{cases} 0 & x < 0 \\ \frac{1}{\theta} & 0 \leq x \leq \theta \\ 0 & x > \theta \end{cases}$$

Joint Likelihood

$$f(x_1, x_2, \dots, x_n|\theta) = \underbrace{\frac{1}{\theta} \cdot \frac{1}{\theta} \cdots \frac{1}{\theta}}_{n \text{ times}} = \left(\frac{1}{\theta}\right)^n$$

with indicator $f(x_1, x_2, \dots, x_n|\theta) = \left(\frac{1}{\theta}\right)^n \left(I_{[0, \theta]}(x_1) \cdot I_{[0, \theta]}(x_2) \cdots I_{[0, \theta]}(x_n) \right)$

$$= \left(\frac{1}{\theta}\right)^n I_{\min(x_i) \geq 0, \max(x_i) \leq \theta}$$

Note: $\left(\frac{1}{\theta}\right)^n$ is decreasing in θ

- So want to choose θ as small as possible
- So note lower bound on θ in terms of x_i 's if likelihood is to remain positive.

$$\hat{\theta}_{\text{MLE}} = \max_{i \in \{1, \dots, n\}} (x_i)$$

Modes of Convergence

Let X be $\text{unif}[0, 1]$. Let $g_n(x) = nI_{[0, 1/n]}(x)$

Let $Y_n = g_n(X)$

If $X = 0$, $g_n(0) = n$ (grows unboundedly)

If $X = x \in (0, 1]$, $g_n(x)$ is eventually 0.

If $X > 0$, $g_n(X) \rightarrow 0$. $X = a > 0$. if n large enough so $\frac{1}{n} < a$, then $g_n(a) = 0$

For all ω except $\omega = 0$, $Y_n(\omega) \rightarrow 0 : P(\{\omega = 0\}) = 0$

So we have set A . $A = \{\omega : \omega > 0\}$ with $P(A) = 1$, such that $\forall \omega \in A$, $Y_n(\omega) \rightarrow 0$. So $Y_n \rightarrow 0$ with probability 1.

Lecture 10 (2018-10-03)

- Asymptotic properties of MLEs

Look at $\log f(x|\theta) \rightarrow$ Next, compute $\frac{\partial}{\partial \theta} \log f(x|\theta)$. Suppose $X_1, \dots, X_n \sim \text{i.i.d. } f(x|\theta)$

We are often concerned w/maximizing $\log f(x|\theta)$ as a function of θ .

Definition. Fisher Information: for a sample of size 1 from family $f(x|\theta)$. Denote $I(\theta)$, as follows

$$I(\theta) = \mathbb{E} \left[\underbrace{\left(\frac{\partial}{\partial \theta} \log f(X|\theta) \right)^2}_{\text{new r.v.} = y} \right]$$

For a sample i.i.d. of size n ,

$$\begin{aligned} \log f(x_1, x_2, \dots, x_n|\theta) &= \log \prod_{i=1}^n f(x_i|\theta) \\ &= \sum_{i=1}^n \log f(x_i|\theta) \end{aligned}$$

$$\text{So we find} \quad \frac{\partial}{\partial \theta} \left(\sum_i \log f(x_i|\theta) \right) = \sum_{i=1}^n \frac{\partial}{\partial \theta} \log f(x_i|\theta)$$

Note that

$$E \left[\left(\frac{\partial}{\partial \theta} \log f(X|\theta) \right)^2 \right] \rightarrow \text{look the same for all } j \text{ by identical distribution}$$

So if we could

Lecture 11 (2018-10-10)

- MLEs - consistency
- Asymptotic normality

Question: Are MLEs always unbiased?

Answer: No,

$$\begin{aligned}\text{Consider } X_i &\sim \text{i.i.d. } \mathcal{N}(\mu, \sigma^2) \\ \text{MLE for } \sigma^2, \quad \hat{\sigma}^2 &= \frac{1}{n} \sum (X_i - \bar{X})^2 \\ E[S^2] = \sigma^2 \quad \text{where } s^2 &= \frac{\sum (X_i - \bar{X})^2}{n-1} \\ s^2 &> \hat{\sigma}^2 \\ E[\hat{\sigma}^2] &< \hat{\sigma}^2 \\ E[\hat{\sigma}^2] = \frac{n-1}{n} \sigma^2 \quad \text{But } \mathbb{E}[\hat{\sigma}^2] &\xrightarrow{n \rightarrow \infty} \sigma^2\end{aligned}$$

So this estimator is asymptotically unbiased

$$\text{Bias}[\hat{\sigma}^2] = \left| \frac{n-1}{n} \sigma^2 - \sigma^2 \right| \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

We will see arguments for why

1. MLEs are consistent
2. Asymptotically normal & asymptotically unbiased
3. Have a variance related to Fisher Information

Lecture 12 (2018-10-15)

NEED TO FINISH ATLEAST 8 LECTURES FROM BEFORE

- Modes of convergence; Slutsky's Theorem
- Asymptotic normality of MLEs
- Sufficiency
- Efficiency

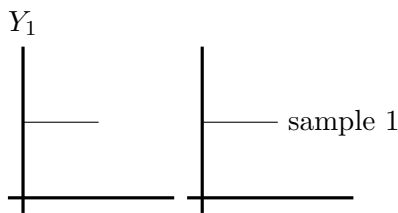
4 Typical Modes of Convergence

1. Convergence with probability 1
2. Convergence in probability
3. Convergence in L^P (expectation)
4. Convergence in distribution

$$Y_n = g_n(X) = n\mathbb{1}_{[0, \frac{1}{n})} \quad X \sim \text{unif}[0, 1]$$
$$Y_n \rightarrow y \quad \text{w.p. 1} \quad (\text{away from zero}) \quad \text{where } Y \equiv 0$$
$$g_n(X) = n^2\mathbb{1}_{[0, \frac{1}{n})}$$

1. Here $Y_n \rightarrow 0$ w.p. 1
2. $Y_n \rightarrow 0$ in probability
3. $E[|Y_n|] = n$ so $Y_n \rightarrow Y$ in Expectation or L^P for $p \geq 1$

Exercise: How can we construct a sequence Y_n s.t. $Y_n \rightarrow 0$ in probability but $Y_n \not\rightarrow 0$ w.p. 1?



For each $\omega \in (0, 1)$ the Y_n 's oscillate between 0 and 1, but the set of points at which Y_n is non-zero shrinks in probability.

Note: If $Y_n \rightarrow Y$ with probability 1, then $Y_n \rightarrow Y$ in probability, but converse is not necessarily true.

Theorem. *Slutsky's Theorem:*

- ① Suppose $X_n \rightarrow X$ in distribution ($X_n \xrightarrow{d} X$), $Y_n \rightarrow Y$ in probability. Then $X_n + Y_n \xrightarrow{d} X + Y$
- ② If $X_n \xrightarrow{d} X$ and $Y_n \rightarrow c$ in probability: $X_n Y_n \xrightarrow{d} cX$

Why all this fuss? Short answers: modes of convergence can be quite different!

Let's look at what happens to functions of random variables in particular:

Let $g : \mathbb{R} \rightarrow \mathbb{R}$ be smooth; and suppose $X_i \sim i.i.d. \quad f(x|\theta); \quad \mu = \mathbb{E}[X_i]; \quad Var(X_i) = \sigma^2 < \infty$

So \bar{X} is consistent for μ . Further, by CLT \Rightarrow

$$\frac{\bar{X} - \mu}{\frac{\sigma}{\sqrt{n}}} \underset{\text{approx}}{\sim} \mathcal{N}(0, 1)$$

$$\frac{\sqrt{n}}{\sigma}(\bar{X} - \mu) \rightarrow \mathcal{N}(0, 1)$$

How to understand approximatet/asymptotic behavior of $g(\bar{X})$? **Taylor expand** g about μ

$$g(x) \approx g(\mu) + g'(\mu)(x - \mu) + \frac{1}{2}g''(\mu)(x - \mu)^2$$

Taylor's theorem with remainder:

$$g(x) \approx g(\mu) + g'(\mu)(x - \mu) + \frac{g''(Z)}{2!}(x - \mu)^2$$

where Z is some point between x & μ

$$\Rightarrow g(\bar{X}) - g(\mu) = g'(\mu)(\bar{X} - \mu) + \frac{g''(Z)(\bar{X} - \mu)^2}{2!}$$

$$\sqrt{n}(g(\bar{X}) - g(\mu)) = \underbrace{\sqrt{n}g'(\mu)(\bar{X} - \mu)}_{\rightarrow \mathcal{N}(0, \text{some variance})} + \underbrace{\frac{\sqrt{n}g''(Z)(\bar{X} - \mu)^2}{2!}}_{\textcircled{?}}$$

$$\textcircled{?} = \sqrt{n} \underbrace{\frac{g''(Z)}{2!}}_{\substack{\text{suppose} \\ \text{we can bound} \\ \text{this piece}}} (\bar{X} - \mu)^2$$

$$\sqrt{n}(\bar{X} - \mu)^2 = \underbrace{\sqrt{n}(\bar{X} - \mu)}_{\substack{\text{converging} \\ \text{in distr} \\ \text{to normal}}} \underbrace{(\bar{X} - \mu)}_{0 \text{ in prob.}}$$

So Slutsky's Theorem $\Rightarrow \sqrt{n}(g(\bar{X}) - g(\mu)) \rightarrow \mathcal{N}(0, \text{some variance})$

Recall our properties of MLE's from last week:

- ① Consistency
- ② Fisher information as a variance
- ③ Asymptotic normality: $\sqrt{nI(\theta_0)}\left(\hat{\theta}_{\text{MLE}} - \theta_0\right) \xrightarrow{d} \mathcal{N}(0, 1)$

Let's look at $\ell(\theta) = \log\text{-likelihood}$

$$\text{MLE : } 0 = \ell'(\hat{\theta})$$

$$\ell'(\theta) - \ell'(\theta_0) \approx \ell''(\theta_0)(\theta - \theta_0)$$

We conclude that for $\theta = \hat{\theta}$

$$\begin{aligned}\ell'(\hat{\theta}) &\approx \ell'(\theta_0) + \ell''(\theta_0)(\hat{\theta} - \theta_0) \\ \Rightarrow 0 &= \ell'(\theta_0) + \boxed{\ell'(\theta_0)}(\hat{\theta} - \theta_0)\end{aligned}$$

So if $\ell''(\theta_0) \neq 0$, we find

$$\boxed{\hat{\theta} - \theta_0 \approx \frac{-\ell'(\theta_0)}{\ell''(\theta_0)}}$$

Now we can also write

$$\boxed{\sqrt{n}(\hat{\theta} - \theta_0) \approx -\frac{n^{-1/2}\ell'(\theta_0)}{n^{-1}\ell''(\theta_0)}}$$

$$\begin{aligned}\ell'(\theta) &= \sum_{i=1}^n \frac{\partial}{\partial \theta} \log f(X_i|\theta_0) \\ &= \sum_{i=1}^n \frac{\partial}{\partial \theta} \log \left(f(X_i|\theta_0) \right) \Big|_{\theta=\theta_0} \\ \mathbb{E}[n^{-1/2}\ell'(\theta_0)] &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbb{E} \left[\frac{\partial}{\partial \theta} \log \left(f(X_i|\theta_0) \right) \Big|_{\theta=\theta_0} \right] = 0 \quad (\text{by earlier result}) \\ \text{Var}(n^{-1/2}\ell'(\theta_0)) &= \frac{1}{n} \mathbb{E} \left[\left(\frac{\partial}{\partial \theta} \log \left(f(X_i|\theta_0) \right) \Big|_{\theta=\theta_0} \right)^2 \right]\end{aligned}$$

By independence of X_i 's and Zero 1st moment of $\frac{\partial}{\partial \theta} \log f(X_i|\theta) \Big|_{\theta=\theta_0}$

$$\boxed{= I(\theta_0)}$$

The denominator:

$$\frac{1}{n}\ell''(\theta_0) = \frac{1}{n} \sum_{i=1}^n \underbrace{\left[\frac{\partial^2}{(\partial \theta)^2} \log f(X_i|\theta) \right]}_{Z_i} \Big|_{\theta=\theta_0}$$

Lecture 13 (2018-10-17)

- Asymptotic normality of MLEs (8.5)
- Efficiency & Sufficiency (8.7)
- Bayesian Estimation (8.6)

Suppose X_i are i.i.d. $f(x|\theta)$ where f satisfies regularity conditions 1) smoothness 2) $\text{supp} f$ is independent of θ

Let $\hat{\theta}$ be MLE for θ suppose true value of θ is $\theta = \theta_0$. Then

$$\sqrt{nI(\theta_0)}(\hat{\theta} - \theta_0) \xrightarrow[d]{n \rightarrow \infty} \mathcal{N}(0, 1)$$

Note $\text{Var}(\hat{\theta})$ is asymptotically given by $\frac{1}{nI(\theta_0)}$

$$\sqrt{nI(\theta_0)}(\hat{\theta} - \theta_0) = \frac{\hat{\theta} - \theta_0}{1/nI(\theta_0)}$$

Recall: (where $\ell(\theta)$ is log likelihood)

$$\sqrt{n}(\hat{\theta} - \theta_0) \approx \frac{n^{-1/2}\ell'(\theta_0)}{n^{-1}\ell''(\theta_0)}$$

Recall: last time we showed

$$\text{Var}(n^{1/2}\ell'(\theta_0)) = I(\theta_0)$$

Also the denominator is

$$\frac{1}{n}\ell''(\theta_0) = \frac{1}{n} \sum_{i=1}^n \left[\frac{\partial^2}{(\partial\theta)^2} \log f(X_i|\theta) \right] \Big|_{\theta=\theta_0}$$

By LLN, this converges to

$$\mathbb{E} \left[\frac{\partial^2}{(\partial\theta)^2} \log f(X_i|\theta) \Big|_{\theta=\theta_0} \right] = +I(\theta_0)$$

So we've written

$$\sqrt{n}(\hat{\theta} - \theta_0) \approx \frac{W^{(n)}}{U^{(n)}}$$

We know that $U^{(n)} \rightarrow I(\theta_0)$ in probability But what is the numerator?

$$W^{(n)} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \underbrace{\left[\frac{\partial}{\partial\theta} \log f(X_i|\theta) \right] \Big|_{\theta=\theta_0}}_{Y_i}$$

Observe that Y_i 's are ii, $E[Y_i] = 0$; $\text{Var}(Y_i) = I(\theta_0)$ So by CLT applied to $\frac{1}{\sqrt{n}} \sum_{i=1}^n Y_i$, we find that

$$\frac{1}{\sqrt{nI(\theta_0)}} \sum Y_i \xrightarrow{d} \mathcal{N}(0, 1)$$

So Slutsky's theorem $\Rightarrow \sqrt{n}(\hat{\theta} - \theta_0) \xrightarrow{d} \mathcal{N}(0, ?)$ What is $(?)$

So we've written

$$[\sqrt{n}(\hat{\theta} - \theta_0)]\sqrt{I(\theta_0)} \approx \frac{W^{(n)}}{U^{(n)}} \quad (\sqrt{I(\theta_0)})$$

Notice that $\frac{\sqrt{I(\theta_0)}}{U^{(n)}} \rightarrow \frac{1}{\sqrt{I(\theta_0)}}$ in probability

Note that $\frac{W^n}{\sqrt{I(\theta_0)}} = \frac{1}{\sqrt{I(\theta_0)}} \sum Y_i \rightarrow \mathcal{N}(0, 1)$

So what did we do?

1. First, we did a Taylor expansion (1st order) of log likelihood
2. We used that to write

$$\sqrt{n}(\hat{\theta} - \theta_0) \approx -\frac{n^{-1/2}\ell'(\theta_0)}{n^{-1}\ell''(\theta_0)}$$

Note: $\sqrt{nI(\theta_0)}(\hat{\theta} - \theta_0) \approx \frac{\frac{1}{\sqrt{nI(\theta_0)}}\ell'(\theta_0)}{\boxed{\frac{-1}{I(\theta_0)} \cdot \frac{1}{n}\ell''(\theta_0)}}$

3. We used Central Limit Theorem to conclude that

$$\frac{1}{\sqrt{n}}\ell'(\theta_0) \rightarrow \mathcal{N}(0, I(\theta_0))$$

4. By LLN, boxed piece converges in probability to $1/\sqrt{I(\theta_0)}$
5. By Slutsky's Theorem, $\sqrt{nI(\theta_0)}(\hat{\theta} - \theta_0) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, 1)$

Next: Surprising!

Suppose that $X_i \sim f(X_i|\theta)$ satisfying regularity conditions and let $T = r(X_1, \dots, X_n)$ an estimator for θ . Suppose that T is unbiased for θ . (T is not necessarily MLE or MOM...) Then

$$\text{Var}(T) \geq \frac{1}{nI(\theta)}$$

This is a remarkable lower bound on the variance of an unbiased estimator! An unbiased estimator T ($T = T_n = r(X_1, \dots, X_n)$) Such that $\text{Var}(T_n) = \frac{1}{nI(\theta)}$ is said to be efficient

$$\text{if } \frac{\text{Var}(T_n)}{1/nI(\theta_0)} \xrightarrow[n \rightarrow \infty]{} 1, \quad \text{then } T_n \text{ is asymptotically efficient}$$

Relative Efficiency: If we have two unbiased estimators $\hat{\theta}_1$ and $\hat{\theta}_2$, their relative efficiency is the ratio $\frac{\text{Var}(\hat{\theta}_1)}{\text{Var}(\hat{\theta}_2)}$

The asymptotic relative efficiency is the limit of this ratio as $n \rightarrow \infty$:

$$\lim_{n \rightarrow \infty} \frac{Var(\hat{\theta}_1)}{Var(\hat{\theta}_2)}$$

So far we've shown

1. MLEs are consistent
2. MLEs are asymptotically unbiased
3. MLEs are asymptotically normal
4. MLEs are asymptotically efficient

Sufficiency

Let $X_i \sim f(x|\theta)$. Suppose $T = r(X_1, \dots, X_n)$ is a statistic (i.e. a function of X_1, \dots, X_n). We say T is sufficient for θ if the conditional distribution of X_1, \dots, X_n given T is independent of θ .

Theorem. (*Factorization*)

A statistic T is sufficient for a parameter θ **iff** $f(x_1, \dots, x_n|\theta) = g(T, \theta) \cdot h(x_1, \dots, x_n)$

Lecture 14 (2018-10-22)

Sufficiency: We say that a statistic T is sufficient for the parameter θ if the conditional distribution of the data X_1, X_2, \dots, X_n given T does not depend on θ .

Factorization Theorem: A statistic T is sufficient for a parameter θ **iff** the joint density can be factorized

$$f(x_1, \dots, x_n | \theta) = g(T, \theta) \cdot h(x_1, \dots, x_n)$$

Remark. Sufficient statistic need not be unique and many cases $h(x_1, \dots, x_n) = 1$

Example 1. Let X_i be i.i.d. Bernoulli(p). Suppose $n = 3$. Let $T = X_1 + X_2 + X_3$.

Claim: T is sufficient for p . Let's look at an example

$$P(X_1 = 1, X_2 = 0, X_3 = 1 | T = t) = \begin{cases} 0 & \text{if } t \neq 2 \\ \frac{1}{\binom{3}{2}} & \text{if } t = 2 \end{cases} \quad \{t = 2\} = \frac{P(X_1 = 1, X_2 = 0, X_3 = 1 | T = 2)}{P(T = 2)} = \frac{p^2 q}{\binom{3}{2} p^2 q}$$

Can also invoke Factorization:

$$\begin{aligned} p(x_1, \dots, x_n | \theta) &= \theta^{\sum x_i} \cdot (1 - \theta)^{n - \sum x_i} \\ &= \underbrace{\theta^T (1 - \theta)^{n - T}}_{g(T, \theta)} \cdot \underbrace{1}_{h(x_1, \dots, x_n)} \end{aligned}$$

Two Paradigms for Statistical Inference

- ① **Frequentist**: parameters are unknown non-random variables.

Goal: obtain estimate $T(X_1, \dots, X_n)$ for this parameter and try to extract useful properties — consistency, asymptotic distributions, unbiasedness, minimum variance, ... Might want CIs for θ based on asymptotic distribution of T .

- ② **Bayesian**: parameters are themselves random variables and these parameters have some probability distribution, $f_\lambda(\theta)$, this distribution might involve other parameters, called hyperparameters (often known).

This distribution models uncertainty in your belief about θ . It is called a *prior*.

Next we have X_i i.i.d. $f(x|\theta)$. This is our data, and $f(x_1, \dots, x_n|\theta)$ is our joined likelihood (common thread in both paradigms).

Goal: Use the observed data to recalculate conditional probabilities for θ given observed data i.e. to calculate a posterior distribution $f(\theta|x_1, \dots, x_n)$

Then we use posterior distribution to extract information about θ include estimates (for θ):

1. posterior mean
2. posterior median
3. posterior mode

Example 2. Suppose X_i i.i.d. Bernoulli(p).

Suppose p satisfies a discrete prior:

$$p = \begin{cases} \frac{1}{4} & \text{w.p. } \frac{1}{3} \\ \frac{1}{2} & \text{w.p. } \frac{1}{3} \\ \frac{3}{4} & \text{w.p. } \frac{1}{3} \end{cases}$$

An example of continuous, "non-informative" prior:

$$p \sim \text{Unif}(0, 1)$$

Given p , let $X_i \sim \text{i.i.d Bernoulli}(p)$ $X_1 = 1, X_2 = 1, X_3 = 1, X_4 = 1$

Let's calculate posterior distribution of p :

$$\begin{aligned} P(p = p_0 | X_1 = 1, X_2 = 1, X_3 = 1, X_4 = 1) &= \frac{P(p = p_0, X_1 = 1, X_2 = 1, X_3 = 1, X_4 = 1)}{\underbrace{P(X_1 = 1, X_2 = 1, X_3 = 1, X_4 = 1)}_{\text{function of the data} \rightarrow C(X_1, \dots, X_n)}} \\ &= \frac{P(X_1 = 1, X_2 = 1, X_3 = 1, X_4 = 1 | p = p_0) \cdot P(p = p_0)}{\sum_{\text{all } a} P(X_1 = 1, X_2 = 1, X_3 = 1, X_4 = 1 | p = a) \cdot P(p = a)} \end{aligned}$$

Now continue with the example

$$\begin{aligned} Pr(p = \frac{1}{4} | 1, 1, 1, 1) &= \frac{Pr(1, 1, 1, 1 | p = \frac{1}{4}) \cdot Pr(p = \frac{1}{4})}{Pr(1, 1, 1, 1)} \\ &= \frac{(1/4)^4 \cdot (1/3)}{(1/4)^4 \cdot (1/3) + (1/2)^4 \cdot (1/3) + (3/4)^4 \cdot (1/3)} = u_1 \end{aligned}$$

$$\begin{aligned} Pr(p = \frac{1}{2} | 1, 1, 1, 1) &= \frac{Pr(1, 1, 1, 1 | p = \frac{1}{2}) \cdot Pr(p = \frac{1}{2})}{Pr(1, 1, 1, 1)} \\ &= \frac{(1/2)^4 \cdot (1/3)}{(1/4)^4 \cdot (1/3) + (1/2)^4 \cdot (1/3) + (3/4)^4 \cdot (1/3)} = u_2 \end{aligned}$$

$$\begin{aligned} Pr(p = \frac{3}{4} | 1, 1, 1, 1) &= \frac{Pr(1, 1, 1, 1 | p = \frac{3}{4}) \cdot Pr(p = \frac{3}{4})}{Pr(1, 1, 1, 1)} \\ &= \frac{(3/4)^4 \cdot (1/3)}{(1/4)^4 \cdot (1/3) + (1/2)^4 \cdot (1/3) + (3/4)^4 \cdot (1/3)} = u_3 \end{aligned}$$

$$p_{\text{post}} \begin{cases} 1/4 & u_1 \\ 1/2 & u_2 \\ 3/4 & u_3 \end{cases}$$

$$\hat{p}_{\text{post}} = \frac{1}{4}u_1 + \frac{1}{2}u_2 + \frac{3}{4}u_3$$

Sometimes, we will find priors and posteriors and likelihoods such that prior and posterior belong to some family \mathcal{F} and the likelihood belongs to \mathcal{G} . Here, we say \mathcal{F} , \mathcal{G} are conjugate families of priors

Case when we have continuous distributions and want to obtain posterior densities:

$$\begin{aligned} f(\theta) &= \text{prior density} \\ f(x_1, \dots, x_n | \theta) &= \text{likelihood} \end{aligned}$$

$$f(\theta|x_1, \dots, x_n) = \frac{f(x_1, \dots, x_n|\theta) \cdot f(\theta)}{\underbrace{\int f(x_1, \dots, x_n|\theta) \cdot f(\theta) d\theta}_{\text{function of observed data} \rightarrow C(X_1, \dots, X_n)}}$$

The denominator is a function of observed data i.e. it is a *normalizing constant in the posterior density*. Often we don't have to calculate it explicitly! **Note** that the posterior density depends on the data. It is however a density for θ . So often, we will want to manipulate the posterior density into a recognizable form as a function of θ with moments that might depend on the data.

Lecture 15 (2018-10-24)

- Bayesian Estimation
- Sufficiency
- Likelihood Ratio Tests

We want to estimate a mean θ , for i.i.d. normal data. Suppose that the variance is known. We have a normal likelihood.

Consider a normal prior distribution for θ . Need to specify a prior mean & a prior variance.

Suppose we have a prior mean of θ_0 and a prior variance of σ_{pr}^2 . Let's write all expressions in terms of precision $\xi = 1/\sigma^2$

$$\text{Prior: } f(\theta) = \frac{(\xi_{\text{prior}})^{\frac{1}{2}}}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}\xi_{\text{prior}}(\theta - \theta_0)^2\right)$$

Likelihood: Suppose that θ , mean, is unknown but σ^2 , variance, is known; $\sigma^2 = \sigma_0^2 \longleftrightarrow \xi_0 = 1/\sigma_0^2$

$$f(x|\theta, \xi_0) = \left(\frac{\xi_0}{2\pi}\right)^{\frac{1}{2}} \exp\left(-\frac{1}{2}\xi_{\text{prior}}(x - \theta_0)^2\right)$$

Note that ξ_{pr} is a measure of our uncertainty about θ

Question: Once we calculate the posterior distribution, we updated our "belief" about θ . In this new "belief" — i.e. this new posterior distribution, do we have more precision or less?

Let $X_1, \dots, X_n \sim \text{i.i.d. } f(x|\theta, \xi_0)$. Calculate $f(\theta|x_1, \dots, x_n)$.

$$f(\theta|x_1, \dots, x_n) = \frac{f(x_1, \dots, x_n|\theta, \xi_0) \cdot f(\theta)}{\underbrace{\int_{\theta} f(x_1, \dots, x_n|\theta, \xi_0) \cdot f(\theta) d\theta}_{C(x_1, \dots, x_n)\text{-normalizing constant}}}$$

θ has been integrated out

$$\text{Likelihood: } f(x_1, \dots, x_n|\theta, \xi_0) = \left(\frac{\xi_0}{2\pi}\right)^{\frac{n}{2}} \exp\left(-\frac{\xi_0}{2} \sum_{i=1}^n (x_i - \theta)^2\right)$$

$$\text{Product: } f(x_1, \dots, x_n|\theta, \xi_0) \cdot f(\theta) = \underbrace{\left(\frac{\xi_0}{2\pi}\right)^{\frac{n}{2}} \left(\frac{\xi_{\text{pr}}}{2\pi}\right)^{\frac{1}{2}}}_C \exp\left(-\underbrace{\left[\frac{\xi_{\text{pr}}}{2}(\theta - \theta_0)^2 + \frac{\xi_0}{2} \sum_{i=1}^n (x_i - \theta)^2\right]}_{Q(\theta)}\right)$$

So the posterior is of the form $C \exp(-Q(\theta))$ where Q is a quadratic - hence, normal!

$Q(\theta)$ will depend on $\theta, \underbrace{\theta_0, \{x_1, \dots, x_n\}}_{\text{known!}}$

Objective: Force, through rough sheer of algebra, $Q(\theta)$ into the form. **Why?** Because the form of the product tells us the posterior density belongs to normal family - we now want to figure out mean and precision. We are going to force just by algebra, where each terms are calculable.

$$\left[\frac{\xi_{\text{post}}}{2} (\theta - \theta_{\text{post}})^2 \right]$$

We have

$$\begin{aligned} &= \frac{\xi_{\text{pr}}}{2} (\theta - \theta_0)^2 + \frac{\xi_0}{2} \sum_i (X_i - \theta)^2 \quad \text{in the exponent} \\ &= \frac{\xi_{\text{pr}}}{2} (\theta^2 - 2\theta\theta_0 + \theta_0^2) + \frac{\xi_0}{2} \sum_i (x_i^2 - 2x_i\theta + \theta^2) \\ &= \underbrace{\left[\frac{\xi_{\text{pr}} + n\xi_0}{2} \right]}_a \theta^2 - \underbrace{(\theta_0\xi_{\text{pr}} + n\bar{X}\xi_0)}_b \theta + \underbrace{\left[\frac{\theta_0^2\xi_{\text{pr}}}{2} + \frac{\xi_0 \sum_i x_i}{2} \right]}_c \approx a\theta^2 + b\theta + c \end{aligned}$$

How do we work with this?

$$\begin{aligned} a\theta^2 + b\theta + c &= a \left(\theta^2 - \frac{b}{a}\theta + \frac{c}{a} \right) \\ &= a \left(\theta - \frac{2b}{2a}\theta + \left(\frac{b}{2a} \right)^2 + \frac{c}{a} - \left(\frac{b}{2a} \right)^2 \right) \leftrightarrow \boxed{\exp \left(-a \left(\theta - \frac{b}{2a} \right)^2 \right)} + \text{STUFF} \end{aligned}$$

So we get Normal with mean μ and precision ξ : $C \exp(-Q(\theta))$

$$a = \frac{\xi_{\text{pr}} + n\xi_0}{2}$$

So posterior precision:

1. $\xi_{\text{pr}} + n\xi_0 > \xi_{\text{pr}}$
2. As $n \rightarrow \infty$, ξ_{pr} matters less

$$\begin{aligned} \text{Posterior mean:} \quad \frac{b}{2a} &= \frac{\theta_0\xi_{\text{pr}} + n\bar{x}\xi_0}{\xi_{\text{pr}} + n\xi_0} = \theta_{\text{post}} = \frac{\theta_0\xi_{\text{pr}}}{\xi_{\text{pr}} + n\xi_0} + \frac{n\bar{x}\xi_0}{\xi_{\text{pr}} + n\xi_0} \\ f_{\text{post}} &\sim \mathcal{N}\left(\frac{b}{2a}, 2a\right) \quad \text{where its } \mathcal{N}(\text{mean, precision}) \quad \theta_{\text{post}} \xrightarrow{\text{as } n \rightarrow \infty} \bar{X}! \end{aligned}$$

Sufficiency in this Context

if T is sufficient for θ ,

$$f(x_1, \dots, x_n | \theta) = g(T, \theta) h(x_1, \dots, x_n)$$

So the posterior distribution is

$$\frac{f(x_1, \dots, x_n | \theta) \cdot f(\theta)}{\int_{\theta} f(x_1, \dots, x_n | \theta) f(\theta) d\theta} = \frac{g(T, \theta) h(x_1, \dots, x_n) f(\theta)}{\int_{\theta} g(T, \theta) h(x_1, \dots, x_n) f(\theta) d\theta} = \frac{g(T, \theta) \overbrace{h(x_1, \dots, x_n)}^{\text{as } n \rightarrow \infty} f(\theta)}{\overbrace{h(x_1, \dots, x_n)} \int_{\theta} g(T, \theta) f(\theta) d\theta}$$

Posterior density depends on data ONLY through sufficient statistic

Lecture 16 (2018-10-29)

Hypothesis Testing

A hypothesis is a conjecture about a population parameter. Recall that in parametric inference we often consider X_i i.i.d. $f(X|\theta)$, where θ is the parameter and $\theta \in \Theta = \text{parameter space}$

- Example.**
1. $X_i \sim \text{Bernoulli}(p)$ $p \in (0, 1)$
 2. $X_i \sim \mathcal{N}(\mu, \sigma^2)$, $\theta = (\mu, \sigma^2)$, $\Theta = \mathbb{R}_x(0, \infty)$
 3. $X_i \sim \text{Unif}[0, \infty]$ and $\theta > 0$ so $\Theta = \mathbb{R}^+$

Hypothesis typically take the form (in the frequentist interpretation)

$$\theta = \theta_0$$
$$\text{or } \theta \in \bigcirc_0 \subset \Theta$$

We say that a hypothesis H is simple if it fully determines the distribution $f(x|\theta)$

Example. $H: \theta = 4$ in uniform case, then $f(x|\theta) = \frac{1}{4}I_{(0,4)}(x)$
 $H: \theta > 3$ NOT SIMPLE

Any non simple hypothesis is called composite. Typically we want to evaluate a pair of competing conjecture.

We let these be denoted by H_0 , the so called *NULL*, and H_1 , the so called *ALTERNATE*.

In the frequentist framework, parameters are not random. Consider an especially simple starting point:

$$\bigcirc = \bigcirc_0 \cup \bigcirc_a$$
$$H_0 : \theta \in \bigcirc_0 \quad \text{is simple}$$
$$H_a : \theta \in \bigcirc_a \quad \text{is simple}$$

Questions: Is the data we observe more likely under H_0 or under H_a

That is, what is the likelihood under H_0 and what is the likelihood under H_a and how do they compare?

$$H_0 : \theta = \theta_0$$
$$H_a : \theta = \theta_a$$

$$\textbf{Likelihood Ratio (LR)} : \frac{f(x_1, \dots, x_n | \theta_0)}{f(x_1, \dots, x_n | \theta_a)}$$

If LR is large, suggests observed data more likely under H_0 so LR gives us a decision rule - $T(X_1, \dots, X_n)$ - where T is binary either *reject* H_0 or *fail to reject* H_0 .

Decision Rule may be in correct for a given string of data you might fail to reject H_0 when H_a is true or reject H_0 when H_0 is true

Types of Error

- ① **Type I Error:** Reject H_0 when H_0 is true
- ② **Type II Error:** Fail to reject H_0 when H_0 is false

It can be challenging to simultaneously control both.

$$\alpha = P(\text{Type I Error})$$

$$\beta = P(\text{Type II Error})$$

Instead, we will set a tolerance for the probability of Type I Error, α , called the significance level of the test, and we will look for the decision rule that satisfies this tolerance and also minimizes the probability of Type II Error.

Note: Decision rule to always accept H_0 has no Type I Error, but might have high probability of Type II Error.

There are many possible decision rules $T(X_1, \dots, X_n)$. How to both control Type I error and Type II error? \rightarrow look at likelihood

Supposed we say $P(\text{Type I Error}) \leq \alpha$. This will help us determine a rejection region: a set of values of data for which H_0 is rejected.

$$\text{Let } d(X_1, \dots, X_n) = \begin{cases} 0 & \text{if we do not reject } H_0 \\ 1 & \text{if we reject } H_0 \end{cases}$$

$$\text{LRT: } \frac{f(X_1, \dots, X_n | \theta_0)}{f(X_1, \dots, X_n | \theta_n)} = g(X_1, \dots, X_n; \theta_0, \theta_n)$$

We want to reject H_0 for observed data in which

$$\frac{f(X_1, \dots, X_n | \theta_0)}{f(X_1, \dots, X_n | \theta_n)} \text{ is small}$$

i.e. we want to choose a constant c s.t.

$$P\left(\frac{f(X_1, \dots, X_n | \theta_0)}{f(X_1, \dots, X_n | \theta_n)} \leq c \mid H_0\right) \leq \alpha$$

Observe that the LRT depends on data and the specific non-random values $\theta_0 + \theta_a$. But to determine the critical value c , we only need to know the distribution of the data under H_0 .

Example. X_i i.i.d. Bernoulli(p)

$$\left. \begin{array}{l} H_0 : \theta = p = p_0 \\ H_a : \theta = p = p_a \end{array} \right\} p_0 > p_a$$

$$\text{LRT } \frac{p_0^{\sum X_i} (1 - p_0)^{\sum (1 - X_i)}}{p_a^{\sum X_i} (1 - p_a)^{\sum (1 - X_i)}} \quad \text{where } n = \text{sample size}$$

Rejecting for small values of LRT i.e. when $LRT = c$. is equivalent to rejecting when $\ln(LRT) = \ln(c) = d$

$$\begin{aligned} \text{Taking logs we get} \quad & \ln \left(p_0^{\sum X_i} (1 - p_0)^{\sum (1 - X_i)} \right) - \ln \left(p_a^{\sum X_i} (1 - p_a)^{\sum (1 - X_i)} \right) \\ &= (\ln p_0 - \ln p_a) \sum_i X_i + [\ln(1 - p_0) - \ln(1 - p_a)] \left(\sum_i (1 - X_i) \right) \end{aligned}$$

Want this to be bounded from above in order to determine a critical region or rejection region

We expect to reject H_0 for small values on $\sum X_i$

$$\begin{aligned} \ln \left(\frac{p_0}{p_a} \right) \sum_i X_i + \ln \left(\frac{1 - p_0}{1 - p_a} \right) \sum_i (1 - X_i) &\leq d \\ \sum_i X_i \left[\ln \left(\frac{p_0}{p_a} \right) - \ln \left(\frac{1 - p_0}{1 - p_a} \right) \right] &\leq d - n \ln \left(\frac{1 - p_0}{1 - p_a} \right) \end{aligned}$$

So we reject if

$$\begin{aligned} \sum_i X_i &\leq \underbrace{d - n \ln \left(\frac{1 - p_0}{1 - p_a} \right)}_D \\ \text{We want} \quad & P \left(\sum_i X_i \leq D | H_0 \right) \leq \alpha \end{aligned}$$

Suppose $\alpha = 0.05$. Note that under H_0 $\sum_i X_i \sim \text{Bin}(n, p_0)$. So can determine D such that $P(\sum X_i \leq D) \leq 0.05$

Now suppose that we have determined C for our rejection region observe that probability of **Type II Error** is given by

$$P(LRT > C | H_a)$$

Power

$$\text{Power} = 1 - P(\text{Type II Error})$$

Lecture 17 (2018-10-31)

- Neyman Pearson
- Uniformly most powerful tests
- GLRTs

Neyman-Pearson Lemma

Theorem. (*The Neyman-Pearson*)

Let H_0, H_1 be simple, let $\bigcirc H_0 \cup \bigcirc H_a = \bigcirc H$. Suppose LRT rejects H_0 when $LR \leq C$ and that this test procedure has significance level α . Consider any other test with significance less than or equal to α . The power of this test is less than or equal to power of LRT.

Proof. Since H_0, H_a (or H_1) are both simple, let $f_0(x), F_1(x)$ denote the respective densities under null and alternative. Any decision rule is of the form

$$d(x) = \begin{cases} 0 & \text{if } H_0 \text{ accepted} \\ 1 & \text{if } H_0 \text{ rejected} \end{cases}$$

$$\text{Note that } \mathbb{E}[d(\underline{X})] = P(d(\underline{X}) = 1)$$

$$\text{Note that significance level: } P(d(\underline{X}) = 1 | H_0) = \mathbb{E}[d(\underline{X})]$$

$$\textbf{Power: } 1 - \beta = 1 - P(\text{Type II Error}) = P(d(\underline{X}) = 1 | H_1) = E_1(d(\underline{X}))$$

Now, let's consider the particular decision rule given by LRT

$$\textbf{Reject } H_0 \text{ if } \frac{f_0(\underline{X})}{f_1(\underline{X})} < c \quad c \text{ is chosen so that } P(\text{Type II Error}) = \alpha$$

$$E_0[d(\underline{X})] = \alpha \quad \text{where } d(\underline{X}) \text{ is the LRT decision rule.}$$

Let d^* be any other decision rule with at most α as Type I error: $\mathbb{E}_0[d^*(X)] \leq \alpha$

It suffices to show:

$$\underbrace{\mathbb{E}_1[d^*(\underline{X})]}_{\text{power of } d^*} = \underbrace{\mathbb{E}_1[d(\underline{X})]}_{\text{power of LRT}}$$

■

Key Inequality

$$d^*(\underline{x})[cf_1(\underline{x}) - f_0(\underline{x})] \leq \underbrace{d(\underline{x})}_{\text{LRT}}[cf_1(\underline{x}) - f_0(\underline{x})]$$

We reject LRT, i.e. $d(\underline{x}) = 1$, when

$$\begin{aligned} f_0(\underline{x}) &< cf_1(\underline{x}) \\ cf_1(\underline{x}) - f_0(\underline{x}) &> 0 \end{aligned}$$

So if \underline{x} is such that $d(\underline{x}) = 1$, then

$$cf_1(\underline{x}) - f_0(\underline{x}) > 0$$

$$\text{and} \quad d^*(\underline{x})[cf_1(\underline{x}) - f_0(\underline{x})] \leq cf_1(\underline{x}) - f_0(\underline{x})$$

If \underline{x} is such that $d(\underline{x}) = 0$, then $d(\underline{x})[cf_1(\underline{x}) - f_0(\underline{x})] = 0$.

But also since $d(\underline{x}) = 0$, $cf_1(\underline{x}) - f_0(\underline{x}) \leq 0$

Thus we now consider two options - either $d^*(\underline{x}) = 0$, in which case:

$$d^*(\underline{x})[cf_1(\underline{x}) - f_0(\underline{x})] = 0 \quad \text{which leads to } 0 = 0$$

If $d(\underline{x}) = 0$ & $d^*(\underline{x}) = 1$, we have

$$\underbrace{d^*(\underline{x})}_1 \underbrace{[cf_1(\underline{x}) - f_0(\underline{x})]}_{\text{non-positive}} \leq 0 = \overbrace{d(\underline{x})}^0 [cf_1(\underline{x}) - f_0(\underline{x})]$$

so we find $cd^*(\underline{x})f_1(\underline{x}) - d^*(\underline{x})f_0(\underline{x}) \leq cd(\underline{x})f_1(\underline{x}) - d(\underline{x})f_0(\underline{x})$

Let's note that, integrating over possible values x_1, \dots, x_n in the vector $\underline{x} = (x_1, \dots, x_n)$

$$c\mathbb{E}_1(d^*(X)) - \mathbb{E}_0(d^*(X)) \leq c\mathbb{E}_1(d(X)) - \mathbb{E}_0(d(X))$$

so note that $\underbrace{\mathbb{E}_0(d^*(X)) - \mathbb{E}_0(d(X))}_{\text{-ve if } d^* \text{ has small TI error than } d} \geq c \left(\mathbb{E}_1(d^*(X)) - \mathbb{E}_1(d(X)) \right)$

In which case

$$\begin{aligned} \mathbb{E}_1(d^*(X)) - \mathbb{E}_1(d(X)) &< 0 \\ \mathbb{E}_1(d^*(X)) &< \mathbb{E}_1(d(X)) \end{aligned}$$

Most powerful test

Example 1. X_i i.i.d. $\mathcal{N}(\mu, \sigma^2)$, suppose σ^2 is known

Consider $H_0: \mu = \mu_0$

$H_a: \mu = \mu_a$

Folk wisdom: use \bar{X} as T.S.

$$LRT = \frac{f_0(\underline{X})}{f_1(\underline{X})} = \frac{\left(\frac{1}{\sigma\sqrt{2\pi}} \right)^n \exp \left\{ -\frac{\sum_i (x_i - \mu_0)^2}{2\sigma^2} \right\}}{\left(\frac{1}{\sigma\sqrt{2\pi}} \right)^n \exp \left\{ -\frac{\sum_i (x_i - \mu_a)^2}{2\sigma^2} \right\}}$$

take logs :

$$\frac{-\sum_i (x_i - \mu_0)^2}{2\sigma^2} + \frac{\sum_i (x_i - \mu_a)^2}{2\sigma^2} \leq d$$

Reject if

$$\begin{aligned} 2\bar{X}n\mu_0 - n\mu_0^2 - 2\bar{X}n\mu_a + \mu_a^2 &\leq d' \\ = 2n\bar{X}(\mu_0 - \mu_a) + n(\mu_a^2 - \mu_0^2) &\leq d' \end{aligned}$$

Reject H_0 if

$$\bar{X}(\mu_0 - \mu_a) \leq \frac{d' - n(\mu_a^2 - \mu_0^2)}{2n}$$

Since $\mu_a > \mu_0$, we find reject H_0 if

$$\bar{X} \geq \frac{d' - n(\mu_a^2 - \mu_0^2)}{2n(\mu_0 - \mu_a)} \quad (\star)$$

i.e. we reject H_0 if \bar{X} is sufficiently large. \star looks complicated like it depends on μ_0, μ_a , etc.

$$P(\text{Reject } H_0 | H_0) = \alpha$$

$$P(\bar{X} > \star | H_0) = \alpha$$

we know from previous lectures that $\bar{X} \sim N(\mu_0, \sigma^2/n)$

$$\begin{aligned} &= P\left(\frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} > \frac{\star - \mu_0}{\sigma/\sqrt{n}} \middle| H_0\right) = \alpha \\ &= P\left(Z > \frac{\star - \mu_0}{\sigma/\sqrt{n}}\right) = \alpha \end{aligned}$$

So

$$\star = Z_\alpha \frac{\sigma}{\sqrt{n}} + \mu_0$$

So we reject if $\bar{X} > Z_\alpha \frac{\sigma}{\sqrt{n}} + \mu_0$ and we note that this rejection region is not dependent on explicit value of μ_a , as long as $\mu_a > \mu_0$

So note that the exact same test (reject H_0 if $\bar{X} > Z_\alpha \frac{\sigma}{\sqrt{n}} + \mu_0$) is most powerful for $H_0 : \mu = \mu_0$ vs $H_a : \mu = \mu_a$ for any choice of $\mu_a > \mu_0$.

So this is a uniformly most powerful test (UMP) for

$$\begin{aligned} &H_0 : \mu = \mu_0 \text{ (simple } H_a) \\ &\text{vs } H_0 : \mu > \mu_0 \text{ (comp. } H_a) \end{aligned}$$

Lecture 18 (2018-11-05)

- Hypothesis tests/Confidence Intervals.
- Bayesian HTs.
- GLRTs and Wilks Theorem.
- Distributions based on normal.
- Midterm II next Wednesday

Confidence Intervals

Last time we considered $X_i \sim \text{i.i.d. } \mathcal{N}(\mu, \sigma^2)$, σ^2 known

$$H_0 : \mu = \mu_0 \quad H_a : \mu > \mu_0$$

We found that if we considered

$$\frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} \quad \text{as our test statistic with rejection region}$$
$$T > Z_\alpha, \quad \underbrace{\text{i.e. reject } H_0 \text{ if } \bar{X} > Z_\alpha \frac{\sigma}{\sqrt{n}} + \mu_0}_{\text{test procedure is uniformly most powerful}}$$

Now, what if we had instead considered a two sided test?

$$H_0 : \mu = \mu_0 \quad H_a : \mu \neq \mu_0$$

Here might consider rejecting H_0 if $|\bar{X} - \mu_0|$ is sufficiently large. i.e.

$$\frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} \sim \mathcal{N}(0, 1) \text{ under } H_0$$
$$\text{So reject if } \frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} < -Z_{\alpha/2} \quad \text{or} \quad \frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} > Z_{\alpha/2}$$

So we reject if

$$\bar{X} < -Z_{\alpha/2} \frac{\sigma}{\sqrt{n}} + \mu_0$$
$$\bar{X} > Z_{\alpha/2} \frac{\sigma}{\sqrt{n}} + \mu_0$$

So we accept H_0 if

$$-Z_{\alpha/2} \frac{\sigma}{\sqrt{n}} + \mu_0 < \bar{X} < Z_{\alpha/2} \frac{\sigma}{\sqrt{n}} + \mu_0$$

Suppose we want a random interval that contains the population parameter μ (whatever its value) with probability $1 - \alpha$ i.e. suppose we have some population parameter (in this case μ) whose value we'd like to estimate.

A $(100)(1 - \alpha)$ % C.I. for μ is a random interval containing μ with specified probability $1 - \alpha$

Note that a CI for μ @ level α looks like

$$\left(\bar{X} - Z_{\alpha/2} \frac{\sigma}{\sqrt{n}}, \bar{X} + Z_{\alpha/2} \frac{\sigma}{\sqrt{n}} \right)$$

and we can say we accept $H_0 : \mu = \mu_0$ when $100(1 - \alpha)\%$ CI given by $\left(\bar{X} - Z_{\alpha/2} \frac{\sigma}{\sqrt{n}}, \bar{X} + Z_{\alpha/2} \frac{\sigma}{\sqrt{n}} \right)$ contains μ_0

That is, we have a duality between CIs and HTs.

Theorem. Suppose for every $\theta_0 \in \Theta$, \exists a level α test of $H_0 : \theta = \theta_0$. Suppose $A(\theta_0) = \{\underline{X} : \text{decision rule is to accept } H_0\}$. Then let $C(X) = \{\theta \in \Theta : X \in A(\theta)\}$. Then $C(X)$ is a $100(1 - \alpha)\%$ confidence region for θ .

Conversely,

Theorem. Suppose that $C(X)$ is a $100(1 - \alpha)\%$ confidence region for θ . i.e.

$$P(\theta_0 \in C(X) | \theta = \theta_0) = 1 - \alpha$$

for every θ_0 . Then if we define

$$A(\theta_0) = \{\underline{X} : \theta_0 \in C(X)\}$$

this is an acceptance region for a level α test of $H_0 : \theta = \theta_0$

Bayesian Hypotheses Tests

Consider X_i 's i.i.d. $f(x|\theta)$, suppose we now have a probability distribution over hypotheses: let H_0 and H_1 be two simple null and alternative hypotheses (respectively) and let $\pi_0 = P(H_0)$ and $\pi_1 = P(H_1)$. So in the Bayesian framework, we observe a vector of data and then update π_0 and π_1

$$\begin{aligned} \text{Compute } P(H_1 | X_1, \dots, X_n) &= \frac{P(X_1, \dots, X_n | H_1) \pi_1}{P(X_1, \dots, X_n | H_0) \pi_0 + P(X_1, \dots, X_n | H_1) \pi_1} \\ P(H_0 | X_1, \dots, X_n) &= \frac{P(X_1, \dots, X_n | H_0) \pi_0}{P(X_1, \dots, X_n | H_0) \pi_0 + P(X_1, \dots, X_n | H_1) \pi_1} \\ \text{Decision Rule: } P(H_0 | X_1, \dots, X_n) &> P(H_1 | X_1, \dots, X_n) \end{aligned}$$

Observe that

$$\frac{P(H_0 | X_1, \dots, X_n)}{P(H_1 | X_1, \dots, X_n)} = \frac{P(X_1, \dots, X_n | H_0) \pi_0}{P(X_1, \dots, X_n | H_1) \pi_1}$$

Accept H_0 if \star is greater than some constant.

So we are still comparing likelihoods, i.e. computing a L.R.

Detour now into Rice, Ch 6

Distributions derived from the normal distribution.

Suppose $\underline{X} \in \mathbb{R}^d$ has a multivariate normal distribution, so \underline{X} has density

$$f_{\underline{X}}(\underline{t}) = C \exp \left(-\frac{1}{2}(\underline{t} - \underline{\mu})^T \Sigma^{-1}(\underline{t} - \underline{\mu}) \right) \quad \text{where} \quad \underline{t} = \begin{bmatrix} t_1 \\ \vdots \\ t_d \end{bmatrix} \quad \underline{\mu} = \begin{bmatrix} \mathbb{E}[X_1] \\ \vdots \\ \mathbb{E}[X_d] \end{bmatrix} \quad \Sigma_{ij} = \text{cov}(X_i, X_j)$$

Facts (lemmas):

- ① If $\underline{X} \sim$ jointly normal and $\sigma_{ij} = 0$, then X_i, X_j are independent.
- ② If \underline{X} is normal and $O \in \theta(dxd)$, so $O^T O = I$ the OX is normal (invariance of normality under rotation).
- ③ If X_1, \dots, X_d are separately normal and independent, then $\underline{X} = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$ is jointly normal and Σ is diagonal.
- ④ if $\underline{X} = (X_1, \dots, X_n)$ where X_i 's are i.i.d. normal then \bar{X} and s^2 are independent.

Chi-squared

If Z_1, \dots, Z_n are i.i.d. $\mathcal{N}(0, 1)$, then

$$\sum_{i=1}^n Z_i^2 \sim \chi^2 \quad n \text{ degrees of freedom}$$

Degrees of Freedom in a χ^2 correspond to number of independent squared normals in the sum.

Finally, if X_1, \dots, X_n is i.i.d. $\mathcal{N}(0, 1)$, then

$$(n-1)s^2 = (n-1) \left[\frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2 \right] = \sum_{i=1}^n (X_i - \bar{X})^2 \sim \chi_{n-1}^2$$

Lecture 19 (2018-11-07)

Lemma. In this case \bar{X} is independent of $(X_1 - \bar{X}, X_2 - \bar{X}, \dots, X_n - \bar{X})$

Lemma. If X_i s are i.i.d $\mathcal{N}(\mu, \sigma^2)$ then \bar{X} and s^2 are independent (follows immediately from earlier lemma).

Lemma. If $X_i \sim \text{i.i.d } \mathcal{N}(\mu, \sigma^2)$ then $\frac{(n-1)s^2}{\sigma^2} \sim \chi^2$ ($n-1$ degrees of freedom)

So if $X_1, \dots, X_n \sim \text{i.i.d. } \mathcal{N}(\mu, \sigma^2)$

$$\text{We know } \frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \sim \mathcal{N}(0, 1)$$

$$\text{We also know } \frac{s^2(n-1)}{\sigma^2} \sim \chi^2(n-1 \text{ df})$$

$$\frac{s^2(n-1)}{\sigma^2} \text{ is independent of } \frac{\bar{X} - \mu}{\sigma/\sqrt{n}}$$

So we find

$$\begin{aligned} \frac{\frac{\bar{X} - \mu}{\sigma/\sqrt{n}}}{\sqrt{\frac{s^2(n-1)}{\sigma^2}}} &\sim t(n-1 \text{ df}) \\ &= \frac{\bar{X} - \mu}{s/\sigma} = \boxed{\frac{\bar{X} - \mu}{s/\sqrt{n}} \sim t(n-1 \text{ df})} \end{aligned}$$

So we want to understand hypotheses about μ e.g.

$$\begin{aligned} H_0 : \mu &= \mu_0, \quad \sigma^2 \text{ unknown (composite null)} \\ \text{vs } H_1 : \mu &\neq \mu_0, \quad \sigma^2 \text{ unknown (composite alternative)} \end{aligned}$$

But to build a framework for testing such hypotheses, we will consider generalized likelihood ratio test. Suppose we would like to test:

$$H_0 : \theta \in \Theta_0$$

$$H_a : \theta \in \Theta_a$$

$$\text{Suppose } \Theta = \Theta_0 \cup \Theta_a$$

Consider $l = \text{likelihood: } l(X_1, \dots, X_n | \theta)$. Define:

$$\Lambda^* = \frac{\max_{\theta \in \Theta_0} l(X_1, \dots, X_n | \theta)}{\max_{\theta \in \Theta} l(X_1, \dots, X_n | \theta)}$$

Λ^* is called the generalized ratio and the test procedure in which we reject H_0 if $\Lambda^* \leq c$ is called GLRT or generalized likelihood ratio test.

In our class, Θ_0 , and Θ_a will generally be "nice" subsets of Euclidean space, whose dimension is well defined and straight forward to calculate.

Example 1.

$$\begin{aligned}\Theta &= \{(\mu, \sigma^2) : \mu \in \mathbb{R}, \sigma^2 > 0\} \\ \dim \Theta &= 2, \text{ if } \Theta_0 = \{\theta : \mu = \mu_0, \sigma^2 = \sigma_0^2\} \\ \text{Note } \dim \Theta_0 &= 0\end{aligned}$$

Suppose we consider $\mu > \mu_0, \sigma^2 = \sigma_0^2$

$$\text{Then if } \Theta_0 = \{\theta : \mu > \mu_0, \sigma^2 = \sigma_0^2\}, \quad \dim \Theta_0 = 1$$

$$\text{If } \Theta_0 = \{\theta : \mu > \mu_0, \sigma^2 > \sigma_0^2\}, \quad \dim \Theta_0 = 2$$

Theorem. Under Certain regularity conditions, $-2 \log \Lambda^*$ has $n \rightarrow \infty$, an asymptotic distribution given by $\chi^2(\dim \Theta - \dim \Theta_0)$

Example 2. Let $X_1, \dots, X_n \sim \text{i.i.d. } \mathcal{N}(\mu, \sigma^2)$. Consider

$$H_0 : \mu = \mu_0$$

$$H_a : \mu \leq \mu_0$$

Suppose σ^2 is known (all this happens when null is true)

$$\begin{aligned}\Theta &= \{\mu \in \mathbb{R}\}, \quad \dim \Theta = 1 \text{ and } \dim \Theta_0 = 0 \\ \Lambda^* &= \frac{\max_{\theta \in \Theta_0} l(X_1, \dots, X_n | \theta)}{\max_{\theta \in \Theta} l(X_1, \dots, X_n | \theta)} \\ \Lambda^* &= \frac{f(x_1, \dots, x_n | \mu_0, \sigma^2)}{\max_{\mu} f(x_1, \dots, x_n | \mu, \sigma^2)} \\ &\vdots \\ \log \Lambda^* &= \frac{-1}{2\sigma^2} \sum (X_i - \mu_0)^2 + \frac{1}{2\sigma^2} \sum (X_i - \bar{X})^2 \\ &\vdots \\ &= \frac{2\mu_0}{2\sigma^2} n\bar{X} - \frac{n\mu_0^2}{2\sigma^2} - \frac{n\bar{X}^2}{2\sigma^2} \\ &= \frac{-n}{2\sigma^2} (\bar{X}^2 - 2\mu\bar{X} + \mu_0^2) \\ &= \frac{-n}{2\sigma^2} (\bar{X} - \mu_0)^2 \\ &= \frac{-1}{2} \underbrace{\left(\frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} \right)^2}_{\sim \mathcal{N}(0,1) \text{ under } H_0}\end{aligned}$$

Hence Wilks theorem

$$-2 \log \Lambda^* = \left(\frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} \right)^2 \sim \chi_{1df}^2$$

Wilks under regularity conditions $-2 \log \Lambda^*$ converges in distribution under H_0 to $\chi^2(\dim \Theta - \dim \Theta_0)$