

UNIVERSITY OF CALIFORNIA, RIVERSIDE
Department of Electrical and Computer Engineering
WINTER 2025
EE 110B SIGNALS AND SYSTEMS
FINAL EXAM

You have 180 minutes to complete the exam. Answers must be fully justified. Good luck!

Question 1) Recall that a great mechanism to implement continuous-time filters is to convert signals into discrete-time domain, process them there, and then convert back to continuous-time. This only works if the signal is bandlimited and the sampling rate T is chosen appropriately. Also recall that if the desired filter is $H_c(j\Omega)$, the discrete-time implementation should use the filter

$$H_d(e^{j\omega}) = H_c(j\frac{\omega}{T})$$

for $-\pi \leq \omega \leq \pi$, and then repeat with a period of 2π on the ω axis. To figure out $h[n]$, we either apply inverse DTFT to $H_d(e^{j\omega})$, or perform a “thought experiment” of inputting $x_c(t) = \text{sinc}(\frac{\pi t}{T})$, tracking the resultant $y_c(t)$, and then using $h[n] = y_c(nT)$.

In class, we analyzed how a differentiator can be implemented using this technique. Now we will do the same for calculating the second derivative, i.e., implementing a system

$$y_c(t) = \frac{d^2 x_c(t)}{dt^2}$$

Assume that $X_c(j\Omega) = 0$ for $|\Omega| > \pi$ and take $T = 1$ for simplicity.

- a) Find $H_c(j\Omega)$ such that $Y_c(j\Omega) = H_c(j\Omega)X_c(j\Omega)$.
- b) Find the corresponding discrete-time filter $H_d(e^{j\omega})$.
- c) Find $h[n]$ either through $\text{DTFT}^{-1}\{H_d(e^{j\omega})\}$ or through the thought experiment. With either choice, pay special attention to $n = 0$.

Answer:

Question 2) This question will walk you through steps of showing

$$\sum_{k=0}^n k = \frac{n(n+1)}{2} .$$

using z-transforms. You may recall that the above formula was first derived by the famous mathematician Gauss in late 1700s when he was an elementary school student.

a) Letting

$$x[n] = u[n] \sum_{k=0}^n k ,$$

show that

$$x[n] = u[n] \star nu[n]$$

b) Using part a) and properties of the z-transform, compute $X(z)$. Do not forget to state the ROC.

c) Find an expression for $x[n]$ by inverting the z-transform using **long division**. If you did everything properly, the expression must be equivalent to $x[n] = \frac{n(n+1)}{2}u[n]$. In other words, $x[0] = 0$, $x[1] = 1$, $x[2] = 3$, $x[3] = 6$, $x[4] = 10, \dots$

Answer:

Question 3) Consider the filter

$$G(z) = \frac{z^{-1} - a}{1 - az^{-1}}$$

with ROC = $\{z : |z| > a\}$ for some real number $0 < a < 1$.

a) Find and sketch $g[n]$.

Hint: Write $\frac{z^{-1}-a}{1-az^{-1}} = \frac{z^{-1}}{1-az^{-1}} - a \cdot \frac{1}{1-az^{-1}}$, and use the delay property of the z-transform.

b) Show that this is an *all-pass* filter, i.e.,

$$|G(e^{j\omega})| = 1$$

for all ω .

c) Now consider the non-causal filter

$$h[n] = -2^n u[-n - 1] .$$

Find $H(z)$ and state the ROC. Argue why the DTFT $H(e^{j\omega})$ exists.

d) Let's say we want to be able to implement a filter with the magnitude response $|H(e^{j\omega})|$. To achieve that goal, there is no way to use $h[n]$ in its current form, because $h[n]$ is a left-sided infinite sequence and therefore wants to look ahead in the infinite future. The solution is to implement

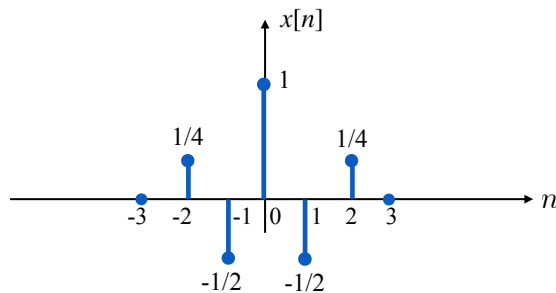
$$H(z)G(z)$$

instead. Since $|G(e^{j\omega})| = 1$, this modification will not change the magnitude response. Choose an a such that $H(z)G(z)$ becomes a causal and stable filter.

Answer:

Question 4)

Let $x[n]$ be as shown below.



a) Find the discrete-time Fourier transform (DTFT) of $x[n]$.

Hint: Write the sum

$$\sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

openly, and pair up suitable terms to simplify.

b) Sketch $|X(e^{j\omega})|$. What kind of signal is $x[n]$? Low-pass or high-pass?

Hint: You can have a rough idea when you evaluate $X(e^{j\omega})$ at $\omega = 0$, $\omega = \pm\frac{\pi}{2}$, and $\omega = \pm\pi$.

c) Calculate

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \left(\sin(\omega) - \sin(2\omega) \right)^2 d\omega$$

using the **differentiation property** of the DTFT, **Parseval's relation**, and your answer from part a.

Answer:

FORMULAS AND CONCEPTS YOU MIGHT FIND USEFUL

- **Sine waves and complex exponentials:**

$$\cos(\theta) = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

and

$$\sin(\theta) = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

- **Geometric series:** For any $\alpha \neq 1$ (complex or real),

$$\sum_{n=0}^N \alpha^n = \frac{1 - \alpha^{N+1}}{1 - \alpha}.$$

If $|\alpha| < 1$, then

$$\sum_{n=0}^{\infty} \alpha^n = \frac{1}{1 - \alpha}.$$

- **LTI properties:** An LTI system with impulse response $h[n]$ is

- **memoryless** if $h[n] = c\delta[n]$ for some constant c .
- **causal** if $h[n] = 0$ for all $n < 0$.
- **stable** if $\sum_{n=-\infty}^{\infty} |h[n]| < \infty$.
- **invertible** if there is $g[n]$ such that $g[n] * h[n] = \delta[n]$.

- **DTFS:** For a signal with period N , and $\omega_0 = \frac{2\pi}{N}$

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j\omega_0 kn}$$

where

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j\omega_0 kn}.$$

- **DTFT:** For any signal,

$$x[n] = \frac{1}{2\pi} \int_0^{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$

where

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}.$$

- **Properties of DTFT:**

- **Linearity:**

$$\begin{aligned} x[n] &\rightarrow X(e^{j\omega}) \\ y[n] &\rightarrow Y(e^{j\omega}) \end{aligned} \implies \alpha x[n] + \beta y[n] \rightarrow \alpha X(e^{j\omega}) + \beta Y(e^{j\omega})$$

- **Time reversal:**

$$x[n] \rightarrow X(e^{j\omega}) \implies x[-n] \rightarrow X(e^{-j\omega})$$

- **Time shifting:**

$$x[n] \rightarrow X(e^{j\omega}) \implies x[n - n_0] \rightarrow X(e^{j\omega}) e^{-j\omega n_0}$$

- **Frequency shifting:**

$$x[n] \rightarrow X(e^{j\omega}) \implies x[n] e^{j\omega_0 n} \rightarrow X(e^{j(\omega - \omega_0)})$$

- **Convolution:**

$$\begin{aligned} x[n] &\rightarrow X(e^{j\omega}) \\ y[n] &\rightarrow Y(e^{j\omega}) \end{aligned} \implies x[n] * y[n] \rightarrow X(e^{j\omega}) Y(e^{j\omega})$$

- **Multiplication:**

$$\begin{aligned} x[n] &\rightarrow X(e^{j\omega}) \\ y[n] &\rightarrow Y(e^{j\omega}) \end{aligned} \implies x[n] y[n] \rightarrow \frac{1}{2\pi} \left[X(e^{j\omega}) * Y(e^{j\omega}) \right]$$

- **Differentiation in frequency domain:**

$$x[n] \rightarrow X(e^{j\omega}) \implies nx[n] \rightarrow j \frac{dX(e^{j\omega})}{d\omega}$$

- **z-Transform:**

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}.$$

Region of convergence (ROC) is the set of z for which the above sum converges.

- **Properties of the z-Transform:**

- If $X(z) = \frac{(z-z_0)(z-z_1)\cdots(z-z_M)}{(z-p_0)(z-p_1)\cdots(z-p_K)}$, then z_m are *zeros* and p_k are *poles*. In addition, there are $K-M$ zeros at ∞ if $K > M$, $M-K$ poles at ∞ if $M > K$.
- The ROC can only take one of three possible forms:
 - * $|z| < a$ when $x[n]$ is left-sided,
 - * $a < |z| < b$ when $x[n]$ is two-sided,
 - * $b < |z|$ when $x[n]$ is right-sided.

In addition, the ROC cannot contain any poles.

- An LTI system that has a transfer function $H(z)$ with ROC \mathcal{R} is
 - * **causal** if \mathcal{R} is of the form $b < |z|$ and $H(z)$ has no pole at $z = \infty$.
 - * **stable** if \mathcal{R} contains the unit circle $|z| = 1$.
- The DTFT exists (converges) if the ROC contains $|z| = 1$.
- **Linearity:** If $x[n] \rightarrow X(z)$ with ROC \mathcal{R}_1 and $y[n] \rightarrow Y(z)$ with ROC \mathcal{R}_2 , then

$$\alpha x[n] + \beta y[n] \rightarrow \alpha X(z) + \beta Y(z)$$

with an ROC containing $\mathcal{R}_1 \cap \mathcal{R}_2$. There might be a zero-pole cancellation resulting in a larger ROC.

- **Time reversal:** If $x[n] \rightarrow X(z)$ with ROC \mathcal{R} , then

$$x[-n] \rightarrow X(z^{-1})$$

with $\text{ROC} = \mathcal{R}^{-1} \triangleq \{z : z^{-1} \in \mathcal{R}\}$

- **Time shifting:** If $x[n] \rightarrow X(z)$ with ROC \mathcal{R} , then

$$x[n - n_0] \rightarrow X(z) z^{-n_0}$$

with $\text{ROC} = \mathcal{R}$ (possibly excluding $z = 0$ or $z = \infty$).

- **Frequency shifting:** If $x[n] \rightarrow X(z)$ with ROC \mathcal{R} , then

$$x[n] z_0^n \rightarrow X(z/z_0)$$

with $\text{ROC} = |z_0| \mathcal{R} \triangleq \{z : z/z_0 \in \mathcal{R}\}$.

- **Convolution:** If $x[n] \rightarrow X(z)$ with ROC \mathcal{R}_1 and $y[n] \rightarrow Y(z)$ with ROC \mathcal{R}_2 , then

$$x[n] * y[n] \rightarrow X(z) Y(z)$$

with an ROC containing $\mathcal{R}_1 \cap \mathcal{R}_2$. There might be a zero-pole cancellation resulting in a larger ROC.

- **Differentiation in z-domain:** If $x[n] \rightarrow X(z)$ with ROC \mathcal{R} , then

$$nx[n] \rightarrow -z \frac{dX(z)}{dz}$$

with $\text{ROC} = \mathcal{R}$ (possibly excluding $z = 0$ or $z = \infty$).

• **Some known signal/z-Transform pairs:**

- If $x[n] = a^n u[n]$, then

$$X(z) = \frac{1}{1 - az^{-1}}$$

with ROC = $\{z : |z| > a\}$.

- If $x[n] = -a^n u[-n - 1]$, then

$$X(z) = \frac{1}{1 - az^{-1}}$$

with ROC = $\{z : |z| < a\}$.

- If $x[n] = na^n u[n]$, then

$$X(z) = \frac{az^{-1}}{(1 - az^{-1})^2}$$

with ROC = $\{z : |z| > a\}$.

- If $x[n] = -na^n u[-n - 1]$, then

$$X(z) = \frac{az^{-1}}{(1 - az^{-1})^2}$$

with ROC = $\{z : |z| < a\}$.

- If $x[n] = \delta[n - n_0]$, then

$$X(z) = z^{-n_0}$$

with ROC = $\{z : |z| > 0\}$ if $n_0 > 0$. If $n_0 < 0$, then ROC is the entire complex plane with the exception of ∞ .

• **Continuous time Fourier Transform (CTFT):** For any signal $x(t)$,

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\Omega) e^{j\Omega t} d\Omega$$

where

$$X(j\Omega) = \int_{-\infty}^{\infty} x(t) e^{-j\Omega t} dt.$$

• **Properties of CTFT:**

- **Linearity:**

$$\begin{aligned} x(t) \rightarrow X(j\Omega) \\ y(t) \rightarrow Y(j\Omega) \end{aligned} \implies \alpha x(t) + \beta y(t) \rightarrow \alpha X(j\Omega) + \beta Y(j\Omega)$$

- **Time reversal:**

$$x(t) \rightarrow X(j\Omega) \implies x(-t) \rightarrow X(-j\Omega)$$

- **Time shifting:**

$$x(t) \rightarrow X(j\Omega) \implies x(t - t_0) \rightarrow X(j\Omega) e^{-j\Omega t_0}$$

- **Frequency shifting:**

$$x(t) \rightarrow X(j\Omega) \implies x(t) e^{j\Omega_0 t} \rightarrow X(j(\Omega - \Omega_0))$$

- **Convolution:**

$$\begin{aligned} x(t) \rightarrow X(j\Omega) \\ y(t) \rightarrow Y(j\Omega) \end{aligned} \implies x(t) * y(t) \rightarrow X(j\Omega) Y(j\Omega)$$

- **Multiplication:**

$$\begin{aligned} x(t) \rightarrow X(j\Omega) \\ y(t) \rightarrow Y(j\Omega) \end{aligned} \implies x(t)y(t) \rightarrow \frac{1}{2\pi} [X(j\Omega) * Y(j\Omega)]$$

- **Differentiation in time domain:**

$$x(t) \rightarrow X(j\Omega) \implies \frac{dx(t)}{dt} \rightarrow j\Omega X(j\Omega)$$

- **Differentiation in frequency domain:**

$$x(t) \rightarrow X(j\Omega) \implies -jtx(t) \rightarrow \frac{dX(j\Omega)}{d\Omega}$$

• **Some known signal-CTFT pairs:**

- If $x(t) = \delta(t - t_0)$, then

$$X(j\Omega) = e^{-j\Omega t_0}.$$

- If $x(t) = e^{j\Omega_0 t}$, then

$$X(j\Omega) = 2\pi \delta(\Omega - \Omega_0).$$

- If $x(t) = \frac{\sin(At)}{t}$, then

$$X(j\Omega) = \begin{cases} \pi & -A \leq \Omega \leq A \\ 0 & \text{otherwise} \end{cases}$$

- If $x(t) = \begin{cases} 1/2 & -B \leq t \leq B \\ 0 & \text{otherwise} \end{cases}$, then

$$X(j\Omega) = \frac{\sin(B\Omega)}{\Omega}.$$

• **Sampling and reconstruction:** If $x_d[n] = x_c(nT)$, x_d is said to be the sampled version of the continuous-time signal x_c . The sampling period is T , and the sampling frequency is $\Omega_s = \frac{2\pi}{T}$.

- Defining the intermediate signal $x_s(t)$ as

$$x_s(t) = x_c(t) \left(\sum_{k=-\infty}^{\infty} \delta(t - kT) \right),$$

we have the relation

$$X_s(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s)).$$

- The relation between $X_s(j\Omega)$ and $X_d(e^{j\omega})$ is

$$X_d(e^{j\omega}) = X_s \left(j \left(\frac{\omega}{T} \right) \right)$$

or

$$X_s(j\Omega) = X_d(e^{j\Omega T}).$$

- Therefore,

$$X_d(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c \left(j \left(\frac{\omega - k2\pi}{T} \right) \right).$$

- These imply that in order for us to reconstruct $x_c(t)$ perfectly, we need

$$\Omega_s = \frac{2\pi}{T} \geq 2\Omega_M$$

where Ω_M is the bandwidth, i.e., maximum frequency where $X_c(j\Omega) \neq 0$.

- Reconstruction is accomplished by eliminating the replicas of $X_c(j\Omega)$ from $X_s(j\Omega)$. Ideally, this is done by a filter

$$H(j\Omega) = \begin{cases} T & -\frac{\pi}{T} \leq \Omega \leq \frac{\pi}{T} \\ 0 & \text{otherwise} \end{cases}$$

which, in the time domain becomes $h(t) = \frac{\sin(\frac{\pi}{T}t)}{\frac{\pi}{T}t}$.