Non-parametric density estimation

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Slides credit: David Tax



Admin stuff

- Registrations on Brightspace: 800+
- Lab week 2 downloads: 309
- Questions asked on Thursday: 39

Lab questions on the exam!



Recap last week

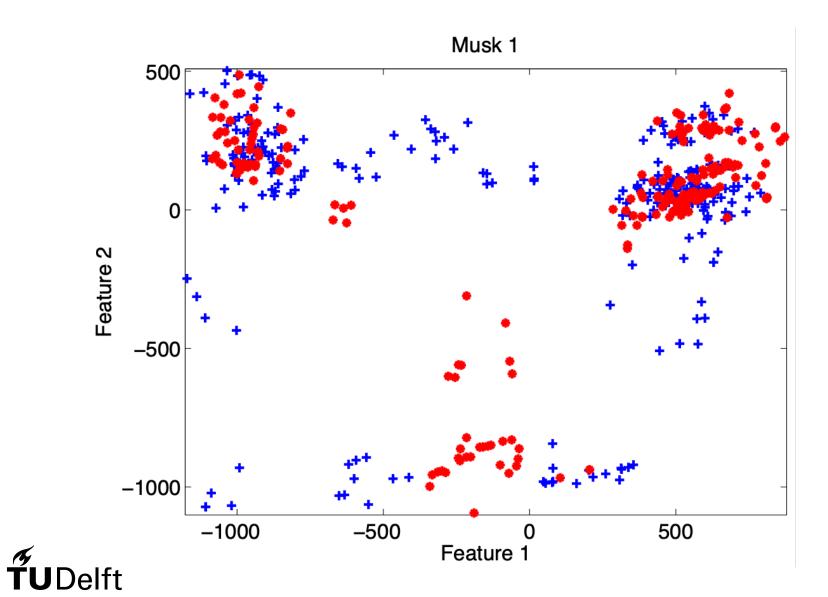
- Parametric density estimation
 - known distribution
 - estimate the parameters on training set
- Assume a single Gaussian distribution for each of the classes:

$$\hat{p}(x|y_i) = N(x|\mu_i, \Sigma_i)$$

$$N(x|\mu_i, \Sigma_i) = \frac{1}{(2\pi)^{p/2}|\Sigma_i|^{1/2}} \exp(\frac{1}{2}(x - \mu_i)^T \Sigma_i^{-1}(x - \mu_i))$$



But in real life...



Non-parametric density estimation

- Non-parametric
 - no knowledge on the distribution
 - manage the smoothness of the distribution
- Popular non-parametric algorithms are:
 - Parzen, k-Nearest Neighbors (today)
 - Naïve Bayes (Friday)



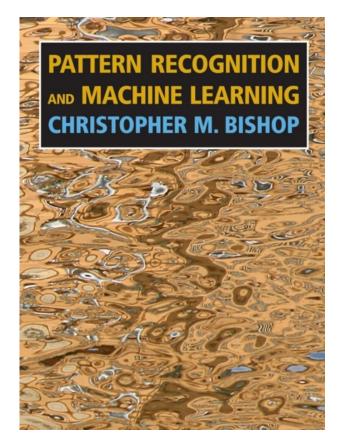
Literature

Chapter 2 section 2.5 from:

Bishop (2006). Pattern Recognition and Machine

Learning. Springer, UK.

Available online



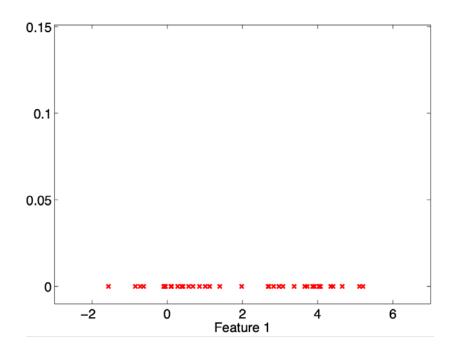


After practicing with the concepts of this lecture you should be able to:

- Explain the difference between parametric and non-parametric density estimation
- Explain Parzen density estimation and classification
- Explain k-nn density estimation and classification
- Explain the advantages and disadvantages of Parzen and k-nn
- Implement k-nn classifier in Python



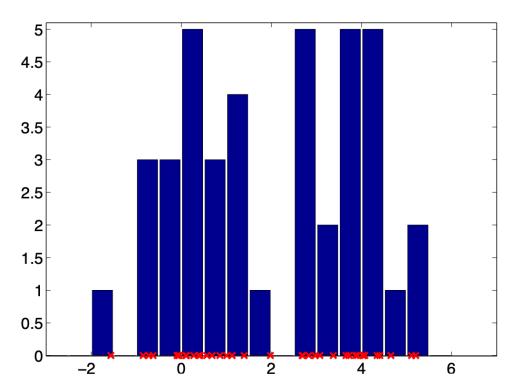
Histogram



- Example: we have one feature
- We have 40 examples: how to estimate the probability density?



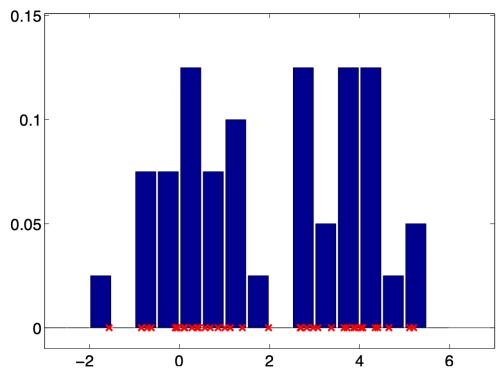
Histogram



- Split the feature in subregions: width h
- Count the number of objects in each region: k_N



Histogram method



Probability density estimate: fraction of points/volume

$$\hat{p}(x) = \frac{1}{h} \, \frac{k_N}{N}$$



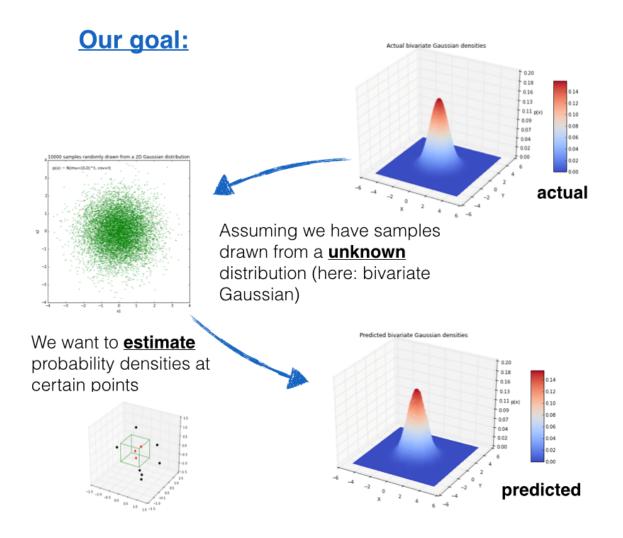
Histogram

- How many bins?
- For a reasonable precise approximation, h can't be too large
- For a stable estimate, h cannot be too small
- Depends on the number of training examples
- In practice, two very related methods are used:
 - Parzen density estimate
 - k-Nearest-neighbor density estimate

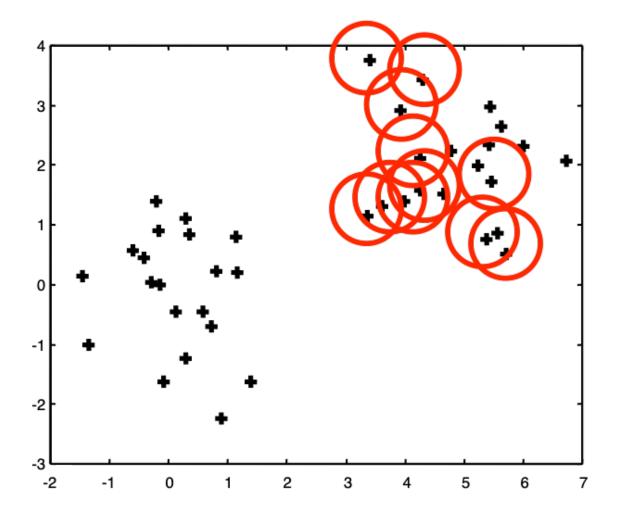




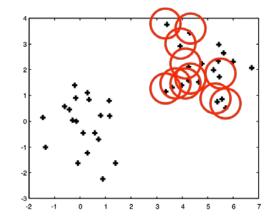
Non-parametric density estimation



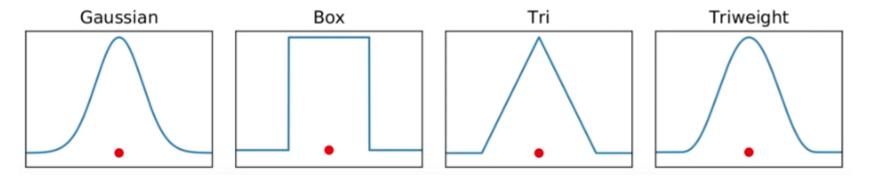








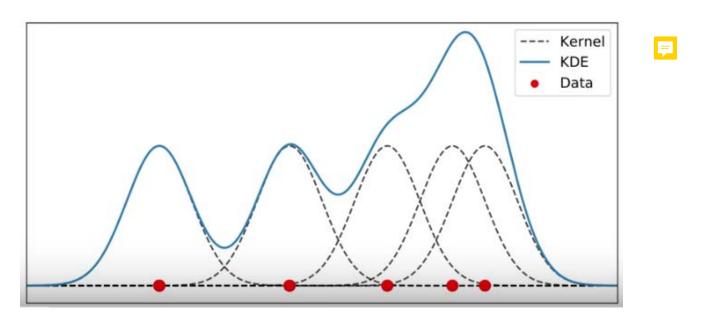
- Procedure:
 - Define cell shape (kernel) eg. Gaussian



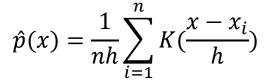
- Fix size of cell (h)
- Add contributions of cells



On every datapoint x_i place a kernel function K.



Parzen density estimate is:

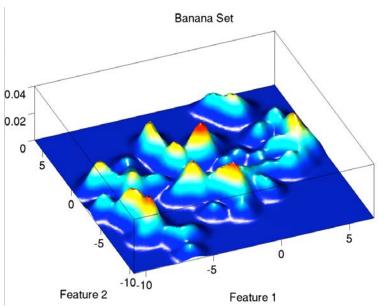


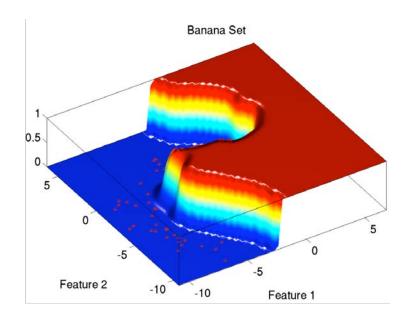


Parzen classifier

Using Normal density

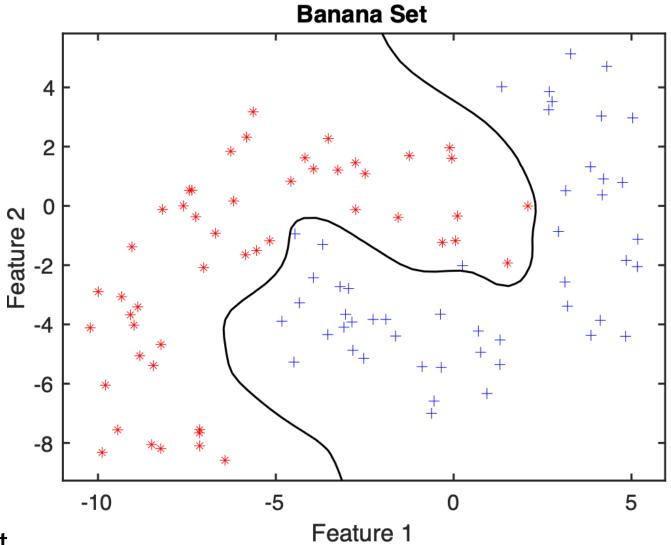
$$\hat{p}(x|y_i) = \frac{1}{n_i} \sum_{j=1}^{n_i} N(x|x_j^{(i)}, hI)$$





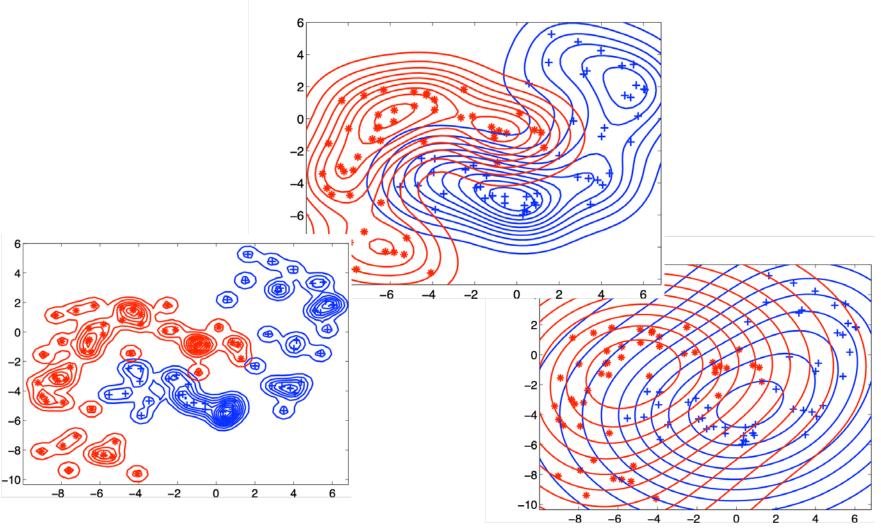


Parzen classifier





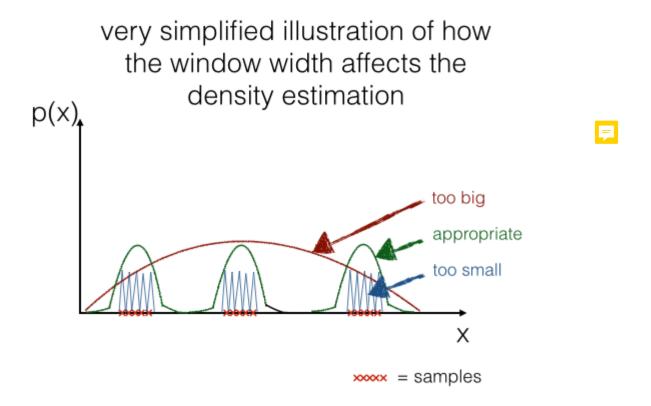
Parzen width parameter





Parzen width parameter

The choice of h is important





Optimization of h

Use a heuristic

$$h = \sigma \left(\frac{4}{p+2}\right) n^{\frac{-1}{p+4}}$$

$$\sigma^2 = \frac{1}{p} \sum_{i=1}^p s_{ii}$$

Optimize the likelihood

$$\prod_{i=1}^n \hat{p}(x_i)$$

 Use the average k-nearest neighbor distance (k=10 is suggested)



Question

Given a set of five data points:

$$x_1 = 2, x_2 = 2.5, x_3 = 3, x_4 = 1, x_5 = 6,$$

find Parzen probability density function (pdf) estimates at x = 3,

using the Gaussian function with $\sigma = 1$ as window function.



Solution

$$\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x_1 - x)^2}{2}\right)$$

$$= \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(2-3)^2}{2}\right) = 0.2420$$

$$\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x_2-x)^2}{2}\right)$$

$$= \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(2.5-3)^2}{2}\right) = 0.3521$$



Solution

$$\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x_3 - x)^2}{2}\right) = 0.3989$$

$$\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x_4 - x)^2}{2}\right) = 0.0540$$

$$\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x_5 - x)^2}{2}\right) = 0.0044$$

SO

$$p(x = 3) = (0.2420 + 0.3521 + 0.3989$$

$$+0.0540 + 0.0044)/5 = 0.2103$$



Parzen summary

 Estimates probability densities using kernel function

Kernel funtion of fixed shape and size

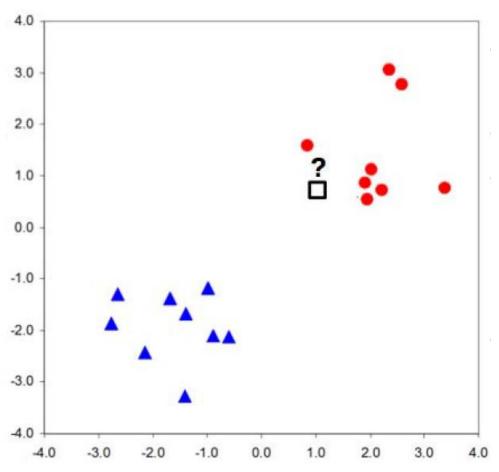
The choice of window shape and size is important



K-nearest Neighbours



K-nearest neighbour intuition

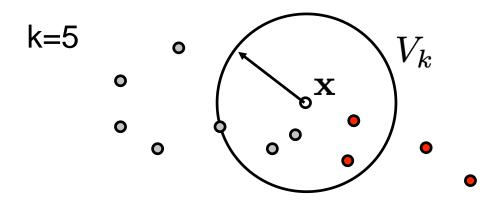


- Set of points (x_1, x_2)
 - Two classes
- Is the box red or blue?
- How did you do it?
- Nearby points are red
 - Use as a bias for a learning algorithm



K nearest neighbor

- Use the intuition to classify a new point x:
 - Locate the cell on the new point x
 - Do **not** fix the volume of the cell: grow the cell until it covers k objects: find the k-th neighbors
 - predict the class y of new point x





K-nn density estimation

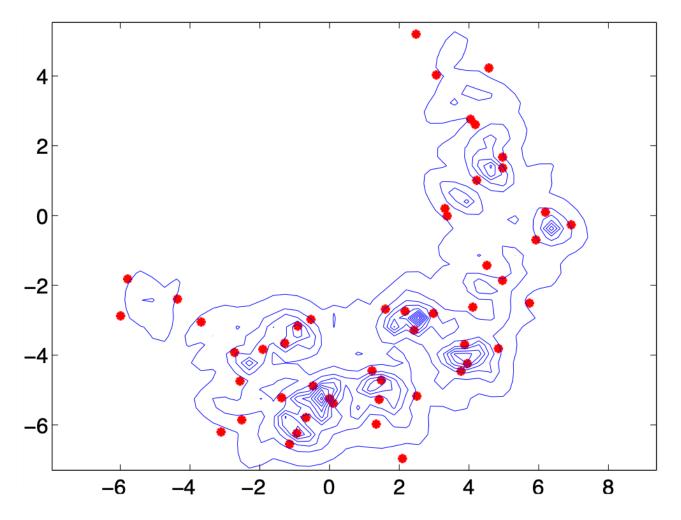
- k = 5
- $k_1 = 3$
- $k_2 = 2$

$$\hat{p}(x|y_i) = \frac{k_i}{n_i V_k}$$

- Where V_k is the volume of the sphere centered at x with radius r, being the distance to the k-th nearest neighbor
- Class priors: $\hat{p}(y_i) = \frac{n_i}{n}$
- Bayes: $\hat{p}(x|y_i)\hat{p}(y_i) > \hat{p}(x|y_i)\hat{p}(y_i) \to k_i > k_j$



K-nn density estimate





K-nn classification algorithm

Given:

- training examples $\{x_i, y_i\}$
 - x_i attribute-value representation of examples
 - *y_i* class label: {male, female}, digit {0,1, ... 9} etc.
- testing point x that we want to classify

Algorithm:

- compute distance $D(x, x_i)$ to every training example x_i
- select k closest instances $x_{i1} \dots x_{ik}$ and their labels $y_{i1} \dots y_{ik}$
- output the class y^* which is most frequent in $y_{i1} \dots y_{ik}$ (majority vote)



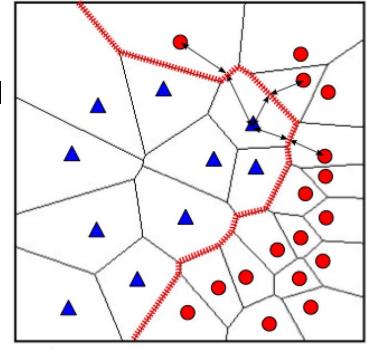
Decision boundary 1-nn

F

- Voronoi tessellation
 - partitions space into regions

boundary: points at same distance from two different training examples

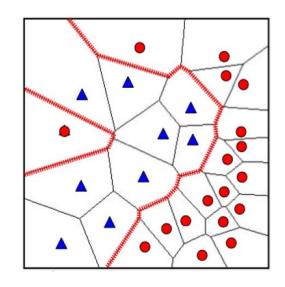
- Classification boundary
 - non-linear, reflects classes well
 - impressive for simple method





Nearest neighbout outliers

- Algorithm is sensitive to outliers
 - single mislabeled example
 dramatically changes boundary

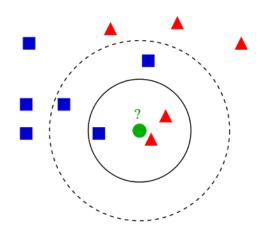


Idea:

- use more than one nearest neighbor to make decision
- count class labels in k most similar training examples
- many "triangles" will outweigh single "circle" outlier



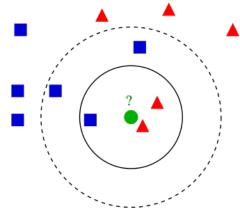
What is the influence of k?



- What is the largest/smallest value of k that you can choose?
 - What will be the classification error then?



What is the influence of k?

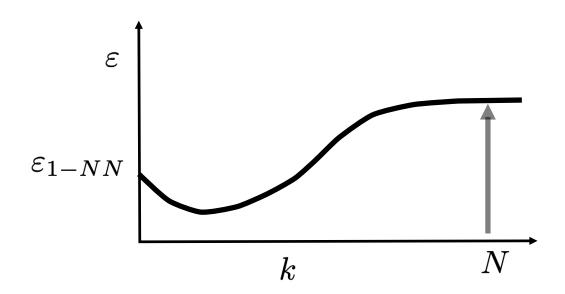


- Value of k has strong effect on k-nn performance
 - Large value → everything classified as the most probable class
 - Small value → highly variable, unstable decision boundaries
 - Small changes to training set→ large changes to classification
 - affects "smoothness" of the boundary



Choosing the value of k

- Selecting the value of k
 - set aside a portion of the training data (validation set)
 - vary k
 - Pick k that gives best generalization performance

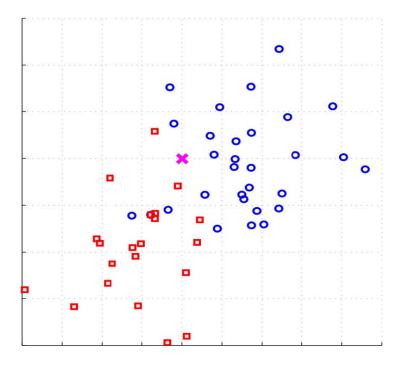




Question

 According to a k-NN classifier, to which class (red box or blue circle) does the new point X belong?

- 1. If k=5?
- 2. If k=2?





K-nn resolving ties

- Resolving ties:
 - equal number of positive/negative neighbours
 - use odd k (doesn't solve multi-class)
 - breaking ties:
 - random: flip the coin to decide positive/negative
 - prior: pick class with greater prior
 - nearest: use 1-nn classifier to decide



Distance measures

- The key component of the kNN algorithm
 - defines which examples are similar and which aren't
 - can have strong effect on performance
- Euclidean (numeric attributes):

$$D(x, x') = \sqrt{\sum_{d} |x_{d} - x'_{d}|^{2}}$$

- symmetric, spherical, treats all dimensions equal
- sensitive to extreme differences in single attribute



Distance measures

- Hamming (categorical attributes):
 - number of attributes where x, x' differ

$$D(x, x') = \sum_{d} 1_{x_d \neq x'_d}$$

- Other
 - Kullback-Leibler (KL) divergence (for histograms)
 - Custom distance measures (BM25 for text)



Distance measures

Minkowski distance (p-norm):

$$D(x,x') = \sqrt[p]{\sum_{d} |x_d - x'_d|^p}$$

- -p=2: Euclidean
- -p=1: Manhattan
- -p=0: Hamming
- $-p = \infty$: $max_d | x_d x'_d |$



Question

- Given a labeled two-dimensional data set:
 - Blue label: (1,4); (2,2); (3,3); (3,4);
 - Red label: (3,7); (5,7); (5,6); (6,5);
- Predict the label of a new point (4, 5) using 3-nn classifier with Manhattan distance.



K-nn missing values

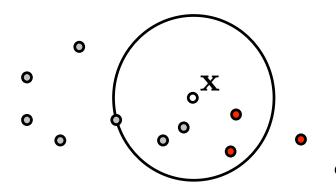
- Missing values
 - have to "fill in", otherwise can't compute distance
 - keyconcern: should affect distances as little as possible
 - reasonable choice: average value across entire dataset



Why is k-nn slow?

Find nearest neighbors of the new point X

What you see:

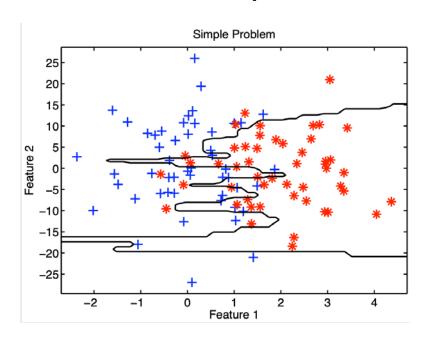


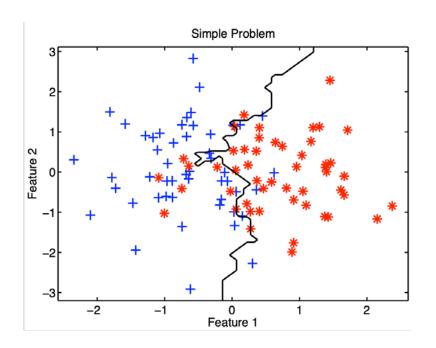
- What algorithm sees:
 - Training set
 {(1, 9), (2, 3), (4, 1), (3, 7), (5, 4), (6, 8), (7, 2), (8, 8), (7, 9), (9, 6)}
 - Testing instance:(7, 4)
 - Nearest neighbors?
 compare one-by-one to each training instance



Sometimes strange results

• How is this possible?





Scale your features!



K-nn pros and cons

- Simple and flexible classifiers
- often a very good classification performance
- it is simple to adapt the complexity of the classifier

- relatively large training sets are needed
- the complete training set has to be stored
- distances to all training objects have to be computed
- the features have to be scaled sensibly
- the value for k has to be optimized



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Lab

- Starts at 13:45
- I will be at the lab today from 15:00

