Philadelphia, PA # +1 267-290-7947

Philadelphia, PA.

GPA: 3.94/4.

Mumbai, India.

GPA: 9.07/10.

Class Rank 2.

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Kaustubh Sridhar

Education

2019 - Present University of Pennsylvania,

PhD Candidate, Electrical and Systems Engineering,

ASSET and PRECISE Center

Thesis Committee: Prof Dinesh Jayaraman, Prof Insup Lee, Prof George Pappas, Prof Nikolai

Matni, Prof Dorsa Sadigh

2015 - 2019 Indian Institute of Technology Bombay,

Bachelor Of Technology (with Honors) In Aerospace Engineering,

Minor in Systems and Control Engineering

Research Interests

I am interested in creating adaptive generalist agents that are parameter- and sample-efficient, for the digital and physical worlds. Towards this goal, I have worked on generative models, in-context learning, deep reinforcement and imitation learning, and robust deep learning. My recent work on a retrieval-augmented generalist agent directly aims for this goal.

Selected Publications and Preprints

[Preprint 2024B] REGENT: A Retrieval-Augmented Generalist Agent That Can Act In-Context In New Environments Kaustubh Sridhar, Souradeep Dutta, Dinesh Jayaraman, Insup Lee

- ▶ Under review at the International Conference on Learning Representations (ICLR) 2025
- ➡ NeurIPS 2024 workshops on Adaptive Foundation Models and Open World Agents.
- [Preprint 2024A] A Retrieval-Enhanced Mixed-Modal Foundation Model for Ophthalmology

Kaustubh Sridhar, Aditya Rangamani, Kuk Jang, Insup Lee

▶ In Preparation.

[2023B] Memory-Consistent Neural Networks for Imitation Learning

Kaustubh Sridhar, Souradeep Dutta, Dinesh Jayaraman, James Weimer, Insup Lee

▶ International Conference on Learning Representations (ICLR) 2024 (Acceptance rate: 31%).

[2023A] Guaranteed Conformance of Neurosymbolic (World) Models to Natural Constraints

Kaustubh Sridhar, Souradeep Dutta, James Weimer, Insup Lee

- **► ICLR 2023** workshop on Neurosymbolic Generative Models,
- ➡ Conference on Learning For Dynamics and Control (L4DC) 2023.
- [2022D] Exploring with Sticky Mittens: Reinforcement Learning with Expert Interventions via Option **Templates**
 - S. Dutta*, K. Sridhar*, O. Bastani, E. Dobriban, J. Weimer, I. Lee, J. Parish-Morris
 - **►** Conference on Robot Learning (**CoRL**) **2022** (Acceptance rate: 39%).
- [Preprint 2022C] Predict-and-Critic: Accelerated End-to-End Predictive Control for Cloud Computing through Reinforcement Learning

Kaustubh Sridhar, Vikramank Singh[†], Murali Narayanaswamy[†], Abishek Sankararaman[†] ■ Under review (†Amazon AWS AI Labs).

[2022B] CODiT: Conformal Out-of-distribution Detection in Time-series Data

Ramneet Kaur, Kaustubh Sridhar, Sangdon Park, Susmit Jha[†], Anirban Roy[†], Oleg Sokolsky, Insup Lee (†SRI International)

- **► ICML 2022** workshop on Principles of Distribution Shift,
- **▶** International Conference on Cyber-Physical Systems (ICCPS) 2023 (Acceptance: 25.6%).
- **⇒** Best paper award nomination at ICCPS 2023.
- [2022A] Improving Neural Network Robustness via Persistency of Excitation

Kaustubh Sridhar, Oleg Sokolsky, Insup Lee, James Weimer

→ American Control Conference (ACC) 2022.

- [2021B] Real-Time Detectors for Digital and Physical Adversarial Inputs to Perception Systems Yiannis Kantaros, Taylor Carpenter, **Kaustubh Sridhar**, Yahan Yang, Insup Lee, James Weimer **▶** International Conference on Cyber-Physical Systems (ICCPS) 2021 (Acceptance rate: 26%).
- [2021A] Real-Time Data-Predictive Attack-Recovery for Complex Cyber-Physical Systems Lin Zhang, Kaustubh Sridhar, Mengyu Liu, Pengyuan Lu, F. Kong, Oleg Sokolsky, Insup Lee **■** IEEE Real-Time and Embedded Technology and Applications Symposium (RTAS).
 - [2019] Finite-time, Event-triggered Tracking Control of Quadrotors

Kaustubh Sridhar, Srikant Sukumar

➡ Conference on Guidance, Navigation and Control (EuroGNC) 2019.

Experience

Aug 2019 - University of Pennsylvania, PhD Candidate,

Philadelphia, PA.

Present Advised by Prof Insup Lee.

Closely collaboratored with Prof Dinesh Jayaraman, Prof James Weimer, Prof Oleg Sokolsky.

- Developed a generalist agent, without large models and vast datasets, that can generalize to new environments via retrieval-augmentation & in-context learning [Preprint 2024B, videos].
- Building a foundation model for ophthalmology trained on a synthetic mixed-modal dataset created from uni-modal vision-language datasets with retrieval [Preprint 2024A].
- Strengthened imitation learning with any neural network diffusion models, transformers, or MLPs, via a novel semi-parametric model class called the MCNN [2023B, videos].
- Created a tool for guaranteed conformance of generative models to constraints [2023A, gifs].
- Boosted deep hierarchical RL sample-efficiency by two-orders-of-magnitude [2022D, videos].
- Enhanced adversarial robustness of NN's with guarantees [2022A].
- Developed out-of-distribution detectors with guarantees [2022B] that run in real-time [2021B].
- May Aug 2023 Amazon Web Services (AWS) AI Labs, Applied Scientist Intern, Santa Clara, CA. Hosts: Dr. Abishek Sankararaman, Dr. Vikram Nathan, Dr. Murali Narayanaswamy
 - Improved generalization in offline RL by incorporating transformer model based forecasts in conservative Q learning; applied to cloud resource allocation problems.
- May Aug 2022 Amazon Web Services (AWS) Al Labs, Applied Scientist Intern, Santa Clara, CA. Hosts: Dr. Abishek Sankararaman, Dr. Murali Narayanaswamy
 - Accelerated datacenter resource allocation by combining model-free RL with mixed integer linear programs [Preprint 2022C].
- May Aug 2021 Argo Al (Ford & VW's Self-Driving Partner), Systems Research Intern, Dearborn, MI. Product Security and Sensor Functional Safety Team
 - Built threat models for object detection and segmentation algorithms on autonomous vehicles.
- May Jul 2018 **Duke University**, *Undergraduate Summer Research Fellow*, Durham, NC. Advised by Prof Miroslav Pajic, Cyber-Physical Systems Lab • Developed a self-driving platform for intrusion detection testing [videos].
- Jan Dec 2018 Indian Institute of Technology Bombay, Undergraduate Research Assistant, India. Advised by Prof Srikant Sukumar,
 - Bachelor's thesis on real-time quadrotor control [2019].

Awards

- 2023 Best Paper Award Nomination for CODiT [2022B] at ICCPS 2023
- 2022 **Top Reviewer (top 10%)**, NeurIPS 2022
- 2022 Outstanding Reviewer (top 10%), ICML 2022
- 2023 NSF Travel Grant, International Conference on Cyber-Physical Systems (ICCPS) 2023
- 2022 Student Travel Grant, American Control Conference 2022
- 2019 The Dean's Fellowship, University of Pennsylvania
- 2019 The Howard Bradwell Fellowship, University of Pennsylvania
- 2018 SN Bose Scholarship, Govt. of India and the Indo-U.S. Science and Technology Forum
- 2015 KVPY Fellowship, Govt. of India

Invited Talks

- 2024 Training Adaptive and Sample-Efficient Generalist Agents.
 - Google Deepmind (Upcoming)
 - Apple MLR
- 2023 Learning Better Policies and Dynamics Models with Memory-Consistent and Memory-**Constrained Neural Networks.**
 - University of Pennsylvania (GRASP Lab) [video]
- 2023 Memory-Consistent Neural Networks Boost Your Diffusion Policies, Behavior Transformers, and Behavior Cloning Agents.
 - University of Pennsylvania (Perception Action Learning Group)
- 2023 Guaranteed Conformance of Neurosymbolic Generative (Dynamics) Models to Physics and Medical Constraints
 - Johns Hopkins University (CISS Session on Learning for Optimization and Control)
 - Amazon Science (Deep Earth Reading Group)
 - University of Pennsylvania (Formal Methods and Machine Learning Reading Group)

Press Coverage

2023 Making Better Decisions with Al, Penn Engineering Today (USA).

Service and Mentorship

2022 - Present Reviewer

ICLR 2025, 2024, ICML 2024, 2023, 2022, NeurIPS 2024, 2023, 2022, L4DC 2023, ICCPS 2022

- 2020 2021 Organizer, Reading Group in Robust Deep Learning, University of Pennsylvania
- 2018 2019 Team Lead, Department Academic Mentorship Program, IIT Bombay Led a team of 22 senior mentors to counsel 89 sophomores, 29 under-performing students.

Technical skills

Languages Python, C, C++

Machine Learning Pytorch, OpenAl Gym, Tensorflow, JAX, CUDA, Sklearn, Pandas

Robotics Mujoco, Bullet, CARLA, ROS, Gazebo

Key Coursework

Graduate Deep Learning, Reinforcement Learning, Convex Optimization, Probability, Computer Aided Verification Undergraduate Data Structures and Algorithms, Linear and Nonlinear Control Theory, Adaptive and Optimal Control

Other Projects

- Apr May 2023 "Fixing Reward Hacking with Large Language Models."
 - Created a framework for an RL agent in Deepmind AI Safety environments to leverage GPT4 to detect reward hacking, fix its own reward function, and adapt quickly to the new reward.

Teaching

Spring 22, Fall 24 Teaching Assistant, CIS 541: Embedded Software for Life-Critical Systems, UPenn

Spring 2021 **Teaching Assistant**, CIT 595: Computer Systems Programming, University of Pennsylvania