Kaustubh Sridhar

Research Scientist @ Google Deepmind

Philadelphia, PA ♠ +1 267-290-7947 ⋈ ksridhar@alumni.upenn.edu n kaustubhsridhar.github.io

Education

Aug 2019 - University of Pennsylvania,

May 2025 PhD Candidate, Electrical and Systems Engineering,

ASSET and PRECISE Center

Thesis Title: Training Adaptive and Sample-Efficient Autonomous Agents

Thesis Committee: Prof Dinesh Jayaraman, Prof Insup Lee, Prof George Pappas, Prof Nikolai

Matni, Prof Dorsa Sadigh

Jul 2015 -Indian Institute of Technology Bombay,

May 2019 Bachelor Of Technology (with Honors) In Aerospace Engineering,

Minor in Systems and Control Engineering

Mumbai, India. GPA: 9.07/10.

Philadelphia, PA.

GPA: 3.94/4.

Class Rank 2.

Research Interests

I am interested in creating adaptive generalist agents that are parameter- and sample-efficient, for the digital and physical worlds. Towards this goal, I have worked on generative models, incontext learning, deep reinforcement and imitation learning, and robust deep learning. My recent work on a retrieval-augmented generalist agent (REGENT) and adding in-context adaptability to pre-trained VLAs (RICL) directly aims for this goal.

Selected Publications and Preprints

[Preprint 2025A] RICL: Adding In-Context Adaptability to Pre-Trained Vision-Language-Action Models

Kaustubh Sridhar, Souradeep Dutta, Dinesh Jayaraman, Insup Lee

→ Conference on Robot Learning (CoRL) 2025.

[2024B] REGENT: A Retrieval-Augmented Generalist Agent That Can Act In-Context In New Environments

Kaustubh Sridhar, Souradeep Dutta, Dinesh Jayaraman, Insup Lee

- ▶ International Conference on Learning Representations (ICLR) 2025,
- **→ Oral presentation** at ICLR 2025, top 1.8% of 11672 submissions,
- ➤ NeurIPS 2024 workshops on Adaptive Foundation Models and Open World Agents.

[2023B] Memory-Consistent Neural Networks for Imitation Learning

Kaustubh Sridhar, Souradeep Dutta, Dinesh Jayaraman, James Weimer, Insup Lee

➡ International Conference on Learning Representations (ICLR) 2024 (Acceptance rate: 31%).

[2023A] Guaranteed Conformance of Neurosymbolic (World) Models to Natural Constraints

Kaustubh Sridhar, Souradeep Dutta, James Weimer, Insup Lee

- **► ICLR 2023** workshop on Neurosymbolic Generative Models,
- ➤ Conference on Learning For Dynamics and Control (L4DC) 2023.

[2022D] Exploring with Sticky Mittens: Reinforcement Learning with Expert Interventions via Option **Templates**

S. Dutta*, K. Sridhar*, O. Bastani, E. Dobriban, J. Weimer, I. Lee, J. Parish-Morris

► Conference on Robot Learning (**CoRL**) **2022** (Acceptance rate: 39%).

[Preprint 2022C] Predict-and-Critic: Accelerated End-to-End Predictive Control for Cloud Computing through

Reinforcement Learning

Kaustubh Sridhar, Vikramank Singh[†], Murali Narayanaswamy[†], Abishek Sankararaman[†]

■ Under review (†Amazon AWS AI Labs).

[2022B] CODiT: Conformal Out-of-distribution Detection in Time-series Data

Ramneet Kaur, Kaustubh Sridhar, Sangdon Park, Susmit Jha[†], Anirban Roy[†], Oleg Sokolsky, Insup Lee (†SRI International)

- **► ICML 2022** workshop on Principles of Distribution Shift,
- ▶ International Conference on Cyber-Physical Systems (ICCPS) 2023 (Acceptance: 25.6%),
- **Best paper award nomination** at ICCPS 2023.

[2022A] Improving Neural Network Robustness via Persistency of Excitation Kaustubh Sridhar, Oleg Sokolsky, Insup Lee, James Weimer

→ American Control Conference (ACC) 2022.

[2021B] Real-Time Detectors for Digital and Physical Adversarial Inputs to Perception Systems
Yiannis Kantaros, Taylor Carpenter, **Kaustubh Sridhar**, Yahan Yang, Insup Lee, James Weimer
International Conference on Cyber-Physical Systems (**ICCPS**) 2021 (Acceptance rate: 26%).

[2021A] Real-Time Data-Predictive Attack-Recovery for Complex Cyber-Physical Systems
Lin Zhang, Kaustubh Sridhar, Mengyu Liu, Pengyuan Lu, F. Kong, Oleg Sokolsky, Insup Lee

➡ IEEE Real-Time and Embedded Technology and Applications Symposium (RTAS).

[2019] Finite-time, Event-triggered Tracking Control of Quadrotors

Kaustubh Sridhar, Srikant Sukumar

→ Conference on Guidance, Navigation and Control (EuroGNC) 2019.

Work Experience

May 2025 - Google Deepmind, Research Scientist,

Toronto, Canada

Present Supervised by Dr. Tim Rocktäschel | Previously supervised by Dr. Volodymyr Mnih

Building general agents and open-ended world models.

Aug 2019 - May University of Pennsylvania, PhD Candidate,

Philadelphia, PA.

2025 Advised by Prof Insup Lee.

Closely collaborated with Prof Dinesh Jayaraman, Prof Oleg Sokolsky.

- Post-trained a VLA to add in-context adaptability to boost its performance on new robotic tasks with unseen objects, motions, and scenes [2025A, videos].
- Pretrained a generalist agent that can generalize to unseen robotics and game-playing environments via retrieval-augmentation & in-context learning [2024B, videos].
- Strengthened imitation learning with any neural network diffusion models, transformers, or MLPs, via a novel semi-parametric model class called the MCNN [2023B, videos].
- Created a tool for guaranteed conformance of generative models to constraints [2023A, gifs].
- Boosted deep hierarchical RL sample-efficiency by two-orders-of-magnitude [2022D, videos].
- Enhanced adversarial robustness of NN's with guarantees [2022A].
- Developed out-of-distribution detectors with guarantees [2022B] that run in real-time [2021B].
- May Aug 2023 Amazon Web Services (AWS) Al Labs, Applied Scientist Intern, Santa Clara, CA. Hosts: Dr. Abishek Sankararaman, Dr. Vikram Nathan, Dr. Murali Narayanaswamy
 - Improved generalization in offline RL by incorporating transformer model based forecasts in conservative Q learning; applied to cloud resource allocation problems.
- May Aug 2022 **Amazon Web Services (AWS) AI Labs**, *Applied Scientist Intern*, Santa Clara, CA. Hosts: Dr. Abishek Sankararaman, Dr. Murali Narayanaswamy
 - Accelerated datacenter resource allocation by combining model-free RL with mixed integer linear programs [Preprint 2022C].
- May Aug 2021 Argo Al (Ford & VW's Self-Driving Partner), Systems Research Intern, Dearborn, Ml. Product Security and Sensor Functional Safety Team
 - o Built threat models for object detection and segmentation models on autonomous vehicles.
- May Jul 2018 **Duke University**, *Undergraduate Summer Research Fellow*, Advised by Prof Miroslav Pajic, Cyber-Physical Systems Lab
 - Developed a self-driving platform for intrusion detection testing [videos].
- Jan Dec 2018 Indian Institute of Technology Bombay, Undergraduate Research Assistant, India. Advised by Prof Srikant Sukumar,
 - Bachelor's thesis on real-time quadrotor control [2019].

Awards

- 2025 Oral Presentation (top 1.8% of 11672 submissions) for REGENT [2024B] at ICLR 2025
- 2023 Best Paper Award Nomination for CODiT [2022B] at ICCPS 2023
- 2022 **Top Reviewer (top 10%)**, NeurIPS 2022

- 2022 Outstanding Reviewer (top 10%), ICML 2022
- 2023 NSF Travel Grant, International Conference on Cyber-Physical Systems (ICCPS) 2023
- 2022 Student Travel Grant, American Control Conference 2022
- 2019 The Dean's Fellowship, University of Pennsylvania
- 2019 The Howard Bradwell Fellowship, University of Pennsylvania
- 2018 SN Bose Scholarship, Govt. of India and the Indo-U.S. Science and Technology Forum
- 2015 KVPY Fellowship, Govt. of India

Selected Talks

- Apr 2025 Oral Talk at ICLR 2025 on REGENT, our generalist embodied agent [recording+Q&A].
- 2024-2025 Training Adaptive and Sample-Efficient Generalist Embodied Agents.
 - [Apr 2025] NTU Singapore
 - [Nov 2024] Google Deepmind
 - [Nov 2024] Apple MLR
 - 2023 Learning Better Policies and Dynamics Models with Memory-Consistent and Memory-Constrained Neural Networks.
 - University of Pennsylvania (GRASP Lab) [video]
 - University of Pennsylvania (Perception Action Learning Group)
 - 2023 Guaranteed Conformance of Neurosymbolic Generative (Dynamics) Models to Physics and Medical Constraints
 - Johns Hopkins University (CISS Session on Learning for Optimization and Control)
 - Amazon Science (Deep Earth Reading Group)
 - University of Pennsylvania (Formal Methods and Machine Learning Reading Group)

Press Coverage

2023 Making Better Decisions with AI, Penn Engineering Today (USA).

Service and Mentorship

2022 - Present Reviewer

ICLR 2025, 2024, ICML 2025, 2024, 2023, 2022, NeurIPS 2024, 2023, 2022, L4DC 2023, ICCPS 2025, 2022, RSS 2025

- 2020 2021 Organizer, Reading Group in Robust Deep Learning, University of Pennsylvania
- 2018 2019 **Team Lead**, *Department Academic Mentorship Program*, IIT Bombay Led a team of 22 senior mentors to counsel 89 sophomores, 29 under-performing students.

Technical skills

Languages Python, C, C++

Machine Learning Pytorch, OpenAl Gym, Tensorflow, JAX, CUDA, Sklearn, Pandas

Robotics Mujoco, Bullet, CARLA, ROS, Gazebo

Kev Coursework

Graduate Deep Learning, Reinforcement Learning, Convex Optimization, Probability, Computer Aided Verification Undergraduate Data Structures and Algorithms, Linear and Nonlinear Control Theory, Adaptive and Optimal Control

Other Projects

Apr - May 2023 "Fixing Reward Hacking with Large Language Models."

• Created a framework for an RL agent in Deepmind Al Safety environments to leverage GPT4 to detect reward hacking, fix its own reward function, and adapt quickly to the new reward.

Teaching

Spring 22, Fall 24 **Teaching Assistant**, CIS 541: Embedded Software for Life-Critical Systems, UPenn

Spring 2021 **Teaching Assistant**, CIT 595: Computer Systems Programming, University of Pennsylvania