

Kaustubh Sridhar

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Education

- 2019 - Present **University of Pennsylvania,** *Philadelphia, PA.*
PhD Candidate, Electrical and Systems Engineering, *GPA: 3.86/4.*
Advised by [Prof. James Weimer](#), [Prof. Oleg Sokolsky](#) and [Prof. Insup Lee](#), [PRECISE Center](#).
- 2015 - 2019 **Indian Institute of Technology Bombay,** *Mumbai, India.*
Bachelor Of Technology (with Honors) In Aerospace Engineering, *GPA: 9.07/10.*
Minor in Systems and Control Engineering *Class Rank 2.*

Research Interests

Robust Deep Learning, Autonomous Vehicle Safety and Security, Cyber-Physical Systems, Deep RL.

Publications and Preprints

Robust Deep Learning

- 1 **Kaustubh Sridhar**, Oleg Sokolsky, Insup Lee, James Weimer, "[Improving Neural Network Robustness via Persistency of Excitation](#)", Submitted to the American Control Conference (ACC) 2022
- 2 Yiannis Kantaros, Taylor Carpenter, **Kaustubh Sridhar**, Yahan Yang, Insup Lee, James Weimer, "[Real-Time Detectors for Digital and Physical Adversarial Inputs to Perception Systems](#)", Proceedings of the ACM/IEEE 12th International Conference on Cyber-Physical Systems (ICCPs) 2021
- 3 Ramneet Kaur, **Kaustubh Sridhar**, Sangdon Park, Susmit Jha*, Anirban Roy*, Oleg Sokolsky, Insup Lee, "Using Temporal Equivariance for Conformal Out-Of-Distribution Detection in Cyber-Physical Systems: A Self-Supervised Learning Approach", Work in Progress. (* SRI)

Efficient Deep Reinforcement Learning

- 4 Souradeep Dutta, **Kaustubh Sridhar**, Osbert Bastani, James Weimer, Edgar Dobriban, Julia Parish-Morris, Insup Lee, "Reinforcement Learning with Expert Interventions via Option Templates", In preparation for the International Conference on Machine Learning (ICML) 2022

Safety and Security of Autonomous Vehicles (AVs) and other Cyber-Physical Systems (CPS)

- 5 **Kaustubh Sridhar**, Radoslav Ivanov, Marcio Juliato[†], Manoj Sastry[†], Vuk Lesi[†], Lily Yang[†], James Weimer, Oleg Sokolsky, Insup Lee, "[A Framework for Checkpointing and Recovery of Hierarchical Cyber-Physical Systems](#)", Preprint ([†] Intel Labs)

Earlier Work in Quadrotor Control

- 6 **Kaustubh Sridhar**, Srikant Sukumar, "[Finite-time, Event-triggered Tracking Control of Quadrotors](#)", Proceedings of the 5th CEAS Conference on Guidance, Navigation and Control (EuroGNC) 2019
- 7 Hemjyoti Das, **Kaustubh Sridhar**, Radhakant Padhi, "[Bio-inspired Landing of Quadrotor using Improved State Estimation](#)", Proceedings of the 5th IFAC Conference on Advances in Control and Optimization Of Dynamical Systems (ACODS) 2018

Work and Research Experience

- May - Aug 2021 **Systems Engineer Intern, [Argo AI](#),** *Dearborn, MI.*
Product Security and Sensor Functional Safety Team
- Ensured continuous coverage of AVs to adversarial actors and adversarial objects in the environment by bridging Systems-Theoretic Process Analysis (STPA) from SOTIF (Safety Of The Intended Functionality, ISO 21448) with TARA (Threat Analysis and Risk Assessment, ISO 21434) procedure.
- Identified potential attack paths in each autonomy subsystem's security architecture and created threat models for object detection and tracking algorithms.
- Programmed verification and validation scripts for the onboard authentication and encryption protocols.
- Aug 2019 - **PhD Researcher, [PRECISE Center](#),** *Philadelphia, PA.*
Present *Advised by [Prof. James Weimer](#), [Prof. Oleg Sokolsky](#), [Prof. Insup Lee](#).*

Collaborated with [Prof. Fanxin Kong](#), [Prof. Osbert Bastani](#), [Prof. Edgar Dobriban](#), and Dr. Marcio Juliato, Dr. Manoj Sastry, Dr. Vuk Lesi, Dr. Lily Yang [[Intel Labs](#)].

- **Robust Deep Learning**

- Leveraged Persistency of Excitation from adaptive control to provably improve the adversarial robustness of state-of-the-art standard and adversarially trained deep neural networks on MNIST, CIFAR10, and CIFAR 100 datasets against projected gradient descent attack and autoattack. (Paper 1)
- Invented state-of-the-art real-time detectors for both digital and physical adversarial images based on label-invariant, feature smoothing transformations and KL divergence. (Paper 2)
- Devised out-of-distribution detectors for anomalous weather and motion events in AV video streams with temporally equivariant non-conformity measures. (Paper 3, In Progress)

- **Efficient Deep Reinforcement Learning**

- Pioneered order-of-magnitude speed improvements in long-horizon deep RL tasks like craft and robotic block stacking with option templates, shortcuts that use expert-designed controllers to execute a potential option to understand the benefits of learning said option's policy. (Paper 4, In Progress)

- **Safety and Security of Autonomous Vehicles and other Cyber-Physical Systems**

- Designed a framework for sensor-anomaly resilient control of AVs via checkpointing and roll-forward recovery of states; proved attack-time recovery unlike an EKF on simulated ground robots. (Paper 5)
- Proposed MPC (Model-Predictive Control) based real-time recovery of nonlinear CPS facing sensor or actuator attacks within a dynamically estimated safety deadline computed with reachability techniques and aided by Taylor model flowpipe approximations. (Under Review)

May - Aug 2018 **Summer Research Fellow**, [Cyber-Physical Systems Lab](#), Duke University, Durham NC.

Advised by [Prof. Miroslav Pajic](#), [Self-Driving Platform for Intrusion Detection testing](#)

- Created lane-keeping and cruise control algorithms for a 1/10th scale, Nvidia TK1 powered self-driving robot and proposed a novel intrusion detection system to tackle camera misinformation attacks.

2018 **Undergraduate Research Assistant**, Indian Institute of Technology Bombay, India.

Advised by [Prof. Srikant Sukumar](#), [Real-time Quadrotor Control](#)

- Formulated a novel finite-time, event-triggered control strategy for quadrotor attitude and position tracking with resource-constrained embedded hardware and validated via numerical simulations. (Paper 6)

Awards

2019 **The Dean's Fellowship** (University of Pennsylvania)

2019 **The Howard Bradwell Fellowship** (University of Pennsylvania)

2018 **SN Bose Scholarship** (Govt. of India and the Indo-U.S. Science and Technology Forum)

2015 **KVPY Fellowship** (Govt. of India)

Technical skills

Languages Python, C, C++

Robotics OpenCV, ROS, Gazebo, MATLAB

Machine Learning Pytorch, Tensorflow, CUDA, Gym, Sklearn, Pandas

Relevant Coursework

Graduate Principles of Deep Learning, Machine Learning, Convex Optimization, Data-driven IoT/Edge Computing, Linear Systems Theory, Elements of Probability, Computer Aided Verification

Undergraduate Data Structures and Algorithms, Linear and Nonlinear Control Theory, Adaptive Control, Optimal Control, State Estimation, Modelling and Simulation, Navigation and Guidance

Positions of Responsibility

Jan - May 2021 **Teaching Assistant**, *CIT 595: Computer Systems Programming*, University of Pennsylvania

- Responsible for lectures on C/C++ and weekly recitations to class of 80 students.

2018 - 2019 **Head**, *Department Academic Mentorship Program*, IIT Bombay

- Led a team of 22 senior mentors to counsel 89 sophomores, 29 under-performing students.