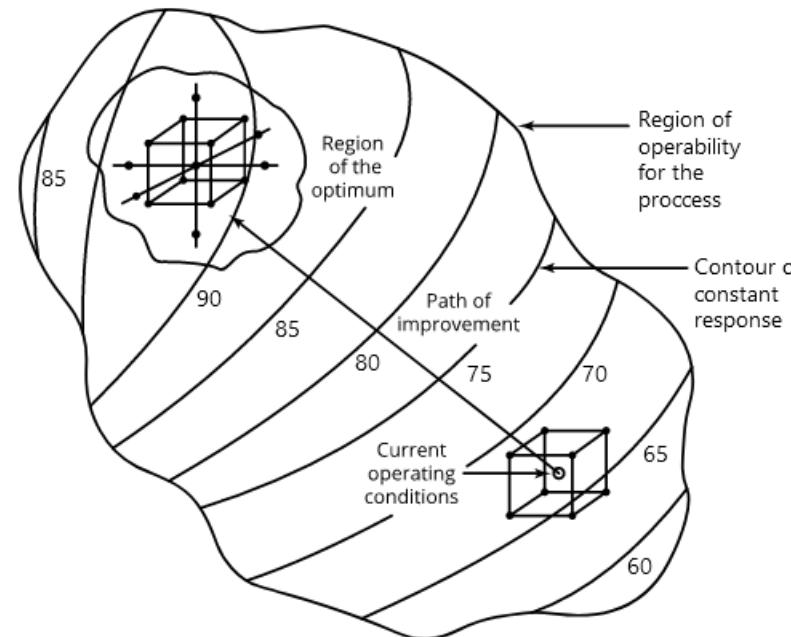


Why RSM?

- So far, the focus of the design of experiments was '**factor screening**' – which factors strongly affect the process, which factors are less important, how the factors interact ..
- After screening, we now shift our focus to **optimization** – which factor level combinations give us maximum (e.g. yield) or minimum (e.g. cost), or target result.
- *The objective of Response Surface Methods (RSM) is optimization, finding the best set of factor levels to achieve some goal.*



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Example

Suppose, yield (y) of a chemical process depends on temperature (x_1) and pressure (x_2). The chemical engineer would like to find out which levels of temperature and pressure give the maximum yield.

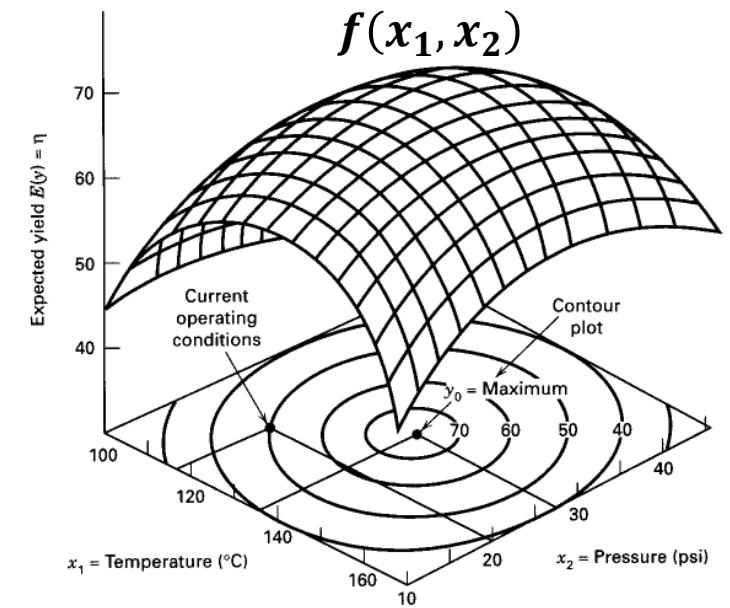
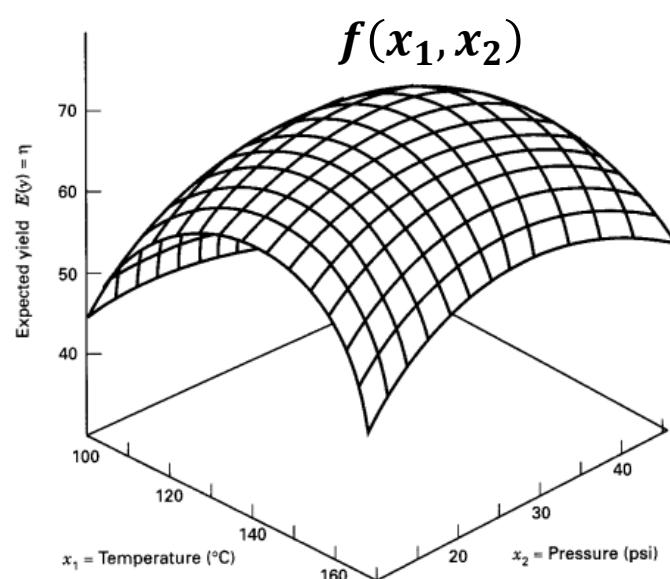
One may write,

$$y = f(x_1, x_2) + \epsilon$$

Where ' ϵ ' is the error/noise observed in response 'y'

The expected value of the response 'y' will be $E(y) = f(x_1, x_2)$

One could show this graphically,



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Sequential Process

Always Remember: 'RSM' is sequential procedure

- In most problems, *the exact relationship between the response variable and the independent variables is unknown*
- Therefore, the first step in RSM is *to find a suitable approximation* of the true functional relationship between response and independent variables.
- Typically, the approximations are in the *form of low-order polynomials* in some region of independent variables

For example, if response (y) is well modeled by linear function of independent variables ($x_1, x_2, x_3, \dots, x_k$), then we can write the approximate function as '**first order model**'

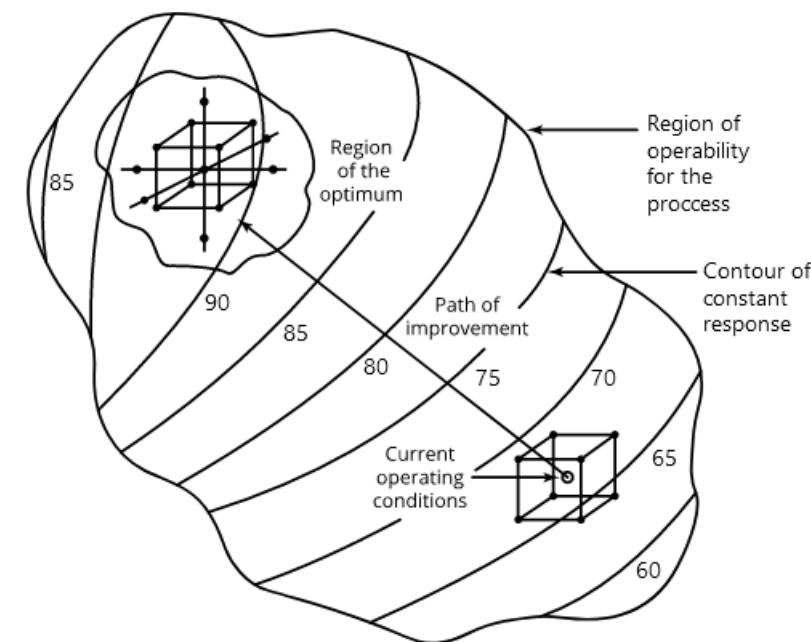
$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_k x_k + \epsilon$$

If there is curvature/non-linearity in the system, we must use polynomial of 2nd or higher degree,

For example, **second degree model** : $y = \beta_0 + \sum_{i=0}^k \beta_i x_i + \sum_{i=0}^k \beta_{ii} x_i^2 + \sum \sum \beta_{ij} x_i x_j + \epsilon$

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- In real problems, it is unlikely that these polynomials will provide a reasonable approximation of the true functional relationship over the ENTIRE range of independent variables, but they work quite well for a relatively small region
- The coefficients in the RSM models (model parameters) are estimated using the least square method (least-square fitting)
- The response surface analysis is then performed on the fitted surface
- The model parameters can be obtained more effectively if proper experimental designs are used to collect the data (responses). *Designs for fitting the response surfaces are called response surface designs.*
- Often we start at a point that is far from optimum such as the existing operating conditions. If the region is linear, we use the first-order model.
- We then take the shortest and most efficient path towards the optimum
- As we near the optimum, there may be nonlinearities, so we can employ higher-order models



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Method of Steepest Ascent

- If we want to find maximum response, then we will be ‘climbing the hill’, if we want to minimize the response, we will be ‘descending into a valley’
- We then take the shortest and most efficient path towards the optimum
- ‘Method of steepest ascent’ is a procedure of moving sequentially along the path of steepest ascent, i.e., direction of the maximum increase in the response.
- If minimization is desired, we follow the ‘method steepest descent’

• If we use first order model,

$$\hat{y} = \hat{\beta}_0 + \sum_{i=1}^k \hat{\beta}_i x_i \quad \checkmark \quad y = \beta_0 + \beta_1 x_1 + \beta_2 x_2$$

Then, the contours of y will be a set of parallel lines

So the path of steepest ascent will be along a line perpendicular to the contours from center of the region

The actual step-size will be dependent on other practical considerations

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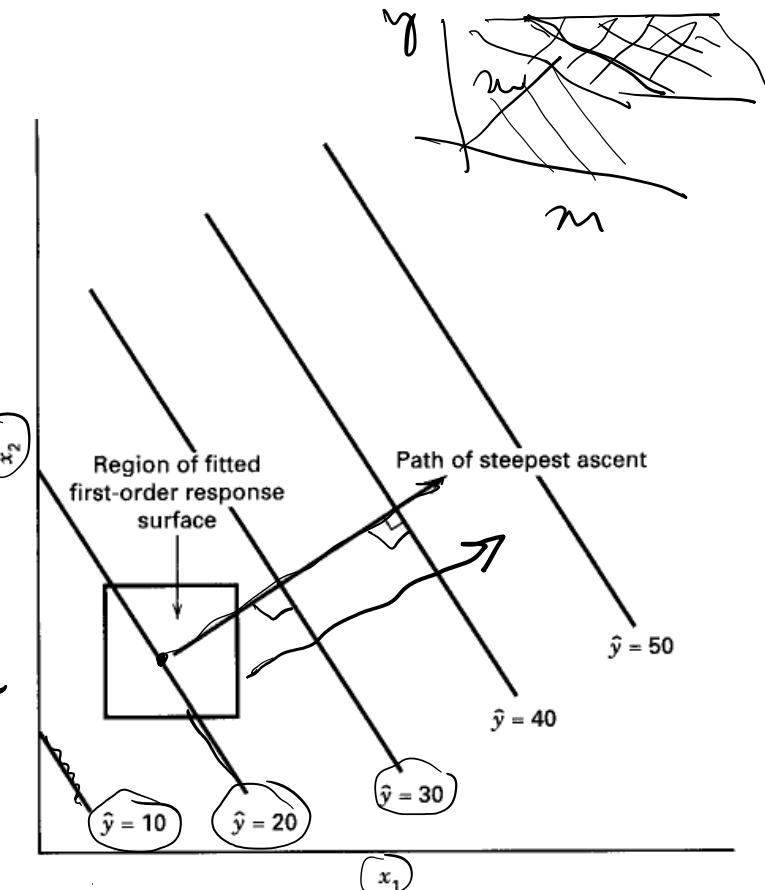


Figure 11-4 First-order response surface and path of steepest ascent.

Example

A chemical engineer is interested in determining the operating conditions that maximize the yield of a process. Two controllable variables influence process yield: reaction time and reaction temperature. The engineer is currently operating the process with a reaction time of 35 minutes and a temperature of 155°F, which result in yields of around 40 percent. Because it is unlikely that this region contains the optimum, she fits a first-order model and applies the method of steepest ascent.

Region of (30, 40) minutes of time, and (150, 160) F temperature was explored and responses were collected.

Note the experimental design is 2^2 factorial design augmented by five center points. 5 replications at the center point [35, 155] allow estimation of error as well as help us determine adequacy of linear (first-order) model

$$x_1 = \frac{\xi_1 - 35}{5} \quad \text{and} \quad x_2 = \frac{\xi_2 - 155}{5}$$

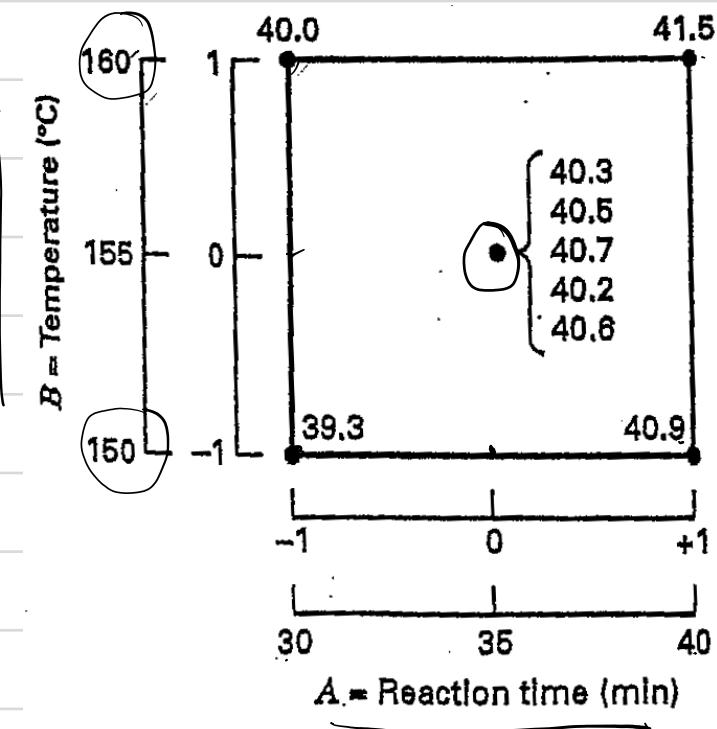
Time, Temp -----				
Natural Variables		Coded Variables		Response
ξ_1	ξ_2	x_1	x_2	y
30	150	-1	-1	39.3
30	160	-1	1	40.0
40	150	1	-1	40.9
40	160	1	1	41.5
35	155	0	0	40.3
35	155	0	0	40.5
35	155	0	0	40.7
35	155	0	0	40.2
35	155	0	0	40.6

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Can we find which terms are important?

What will be the first-order model?

Will a first-order model be appropriate?



Natural Variables		Coded Variables		Response
ξ_1	ξ_2	x_1	x_2	y
30	150	-1	-1	39.3
30	160	-1	1	40.0
40	150	1	-1	40.9
40	160	1	1	41.5
35	155	0	0	40.3
35	155	0	0	40.5
35	155	0	0	40.7
35	155	0	0	40.2
35	155	0	0	40.6

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ANOVA

- ANOVA

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2 + \epsilon$$

Can we reduce this to a 1-order model
 $+ (\beta_{11} x_1^2 + \beta_{22} x_2^2)$

SS_T, SS_{mean}

ANOVA TABLE

	DF	SS	MS	F ₀
Total	9			
x_1	1	2.4025	2.4025	55.87
x_2	1	0.4225	0.4225	9.83
$x_1 x_2$	1	0.0025	0.0025	0.06
mean	1	.	.	
ϵ	5-1	0.142	0.142	

and

1 ?

?

?

?

$$SS_{x_1} = 2 \left((39.65 - 40.425)^2 + (41.2 - 40.425)^2 \right)$$

$$SS_{x_2} = 2 \left((40.1 - 40.425)^2 + (40.75 - 40.425)^2 \right)$$

$$\underline{SS_{x_1 x_2}} = 2 \left((40.45 - 40.425)^2 + (40.9 - 40.425)^2 \right) \\ = 0.0025$$

$$\epsilon = (U_1 - \bar{U}_C)^2 + (U_2 - \bar{U}_C)^2 + \dots + (U_5 - \bar{U}_C)^2 \\ = (40.3 - 40.46)^2 + () + \dots + (40.6 - 40.46)^2$$

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$$\text{Find } \underline{\text{SS}_{\text{quad}}} = \frac{n_F n_C (\bar{y}_F - \bar{y}_C)^2}{n_F + n_C} = \frac{4 \times 5 (40.425 - 40.46)^2}{9}$$

Another check of the adequacy of the straight-line model is obtained by applying the check for pure quadratic curvature effect described in Section 6-6. Recall that this consists of comparing the average response at the four points in the factorial portion of the design, say $\bar{y}_F = 40.425$, with the average response at the design center, say $\bar{y}_C = 40.46$. If there is quadratic curvature in the true response function, then $\bar{y}_F - \bar{y}_C$ is a measure of this curvature. If β_{11} and β_{22} are the coefficients of the “pure quadratic” terms x_1^2 and x_2^2 , then $\bar{y}_F - \bar{y}_C$ is an estimate of $\beta_{11} + \beta_{22}$. In our example, an estimate of the pure quadratic term is

$$\begin{aligned}\hat{\beta}_{11} + \hat{\beta}_{22} &= \bar{y}_F - \bar{y}_C \\ &= 40.425 - 40.46 \\ &= -0.035\end{aligned}$$

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Method of Steepest Ascent

- 'Climbing the' $y = 40.44 + \overline{0.775}x_1 + \overline{0.325}x_2$

Table 11-3 Steepest Ascent Experiment for Example 11-1

Steps	Coded Variables		Natural Variables		Response y
	x_1	x_2	ξ_1	ξ_2	
Origin	(0)	(0)	35	155	40
Δ	1.00	0.42	5	2	
Origin + Δ	1.00	0.42	40	157	41.0
Origin + 2 Δ	2.00	0.84	45	159	42.9
Origin + 3 Δ	3.00	1.26	50	161	47.1
Origin + 4 Δ	4.00	1.68	55	163	49.7
Origin + 5 Δ	5.00	2.10	60	165	53.8
Origin + 6 Δ	6.00	2.52	65	167	59.9
Origin + 7 Δ	7.00	2.94	70	169	65.0
Origin + 8 Δ	8.00	3.36	75	171	70.4
Origin + 9 Δ	9.00	3.78	80	173	77.6
Origin + 10 Δ	10.00	4.20	85	175	80.3
Origin + 11 Δ	11.00	4.62	90	179	76.2
Origin + 12 Δ	12.00	5.04	95	181	75.1

New model needs to be employed around [85, 175]

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$$\beta = (X^T X)^{-1} X^T Y$$

$$0.42 = \frac{0.325}{0.775}$$

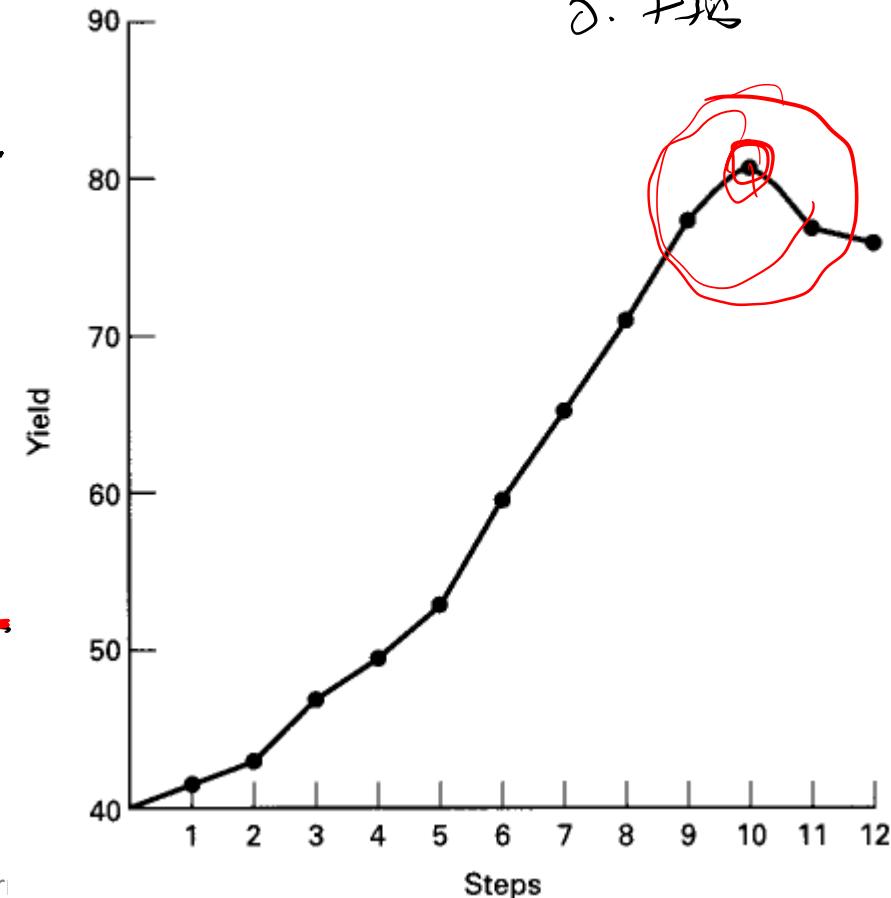


Table 11-4 Data for Second First-Order Model

Natural Variables		Coded Variables		Response
ξ_1	ξ_2	x_1	x_2	y
80	170	-1	-1	76.5
80	180	-1	1	77.0
90	170	1	-1	78.0
90	180	1	1	79.5
85	175	0	0	79.9
85	175	0	0	80.3
85	175	0	0	80.0
85	175	0	0	79.7
85	175	0	0	79.8

$$\hat{y} = 78.97 + 1.00x_1 + 0.50x_2$$

↗

$$\hat{y} = \beta_0 + \beta_1 x_1 + \beta_2 x_2$$

Table 11-5 Analysis of Variance for the Second First-Order Model

Source of Variation	Sum of Squares	Degrees of Freedom	Mean Square	F_0
Regression	5.00	2		
Residual (Interaction)	11.1200	6		
(Pure quadratic)	(0.2500)	1	0.2500	4.72
(Pure error)	(10.6580)	1	10.6580	201.09
Total	16.1200	8	0.0530	

What does the ANOVA table tell us?

Second-order terms are significant. There is a curvature in this region. First order model NOT good enough.

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Method of Steepest Ascent

we notice that the *path of steepest ascent is proportional to the signs and magnitudes of the regression coefficients* in the fitted first-order model

$$\hat{y} = \hat{\beta}_0 + \sum_{i=1}^k \hat{\beta}_i x_i \quad \checkmark \quad \checkmark$$


It is easy to give a general algorithm for determining the coordinates of a point on the path of steepest ascent. Assume that the point $x_1 = x_2 = \dots = x_k = 0$ is the base or origin point. Then

1. Choose a step size in one of the process variables, say Δx_j . Usually, we would select the variable we know the most about, or we would select the variable that has the largest absolute regression coefficient $|\hat{\beta}_j|$.
2. The step size in the other variables is

$$\Delta x_i = \frac{\hat{\beta}_i}{\hat{\beta}_j / \Delta x_j} \quad i = 1, 2, \dots, k; \quad i \neq j$$

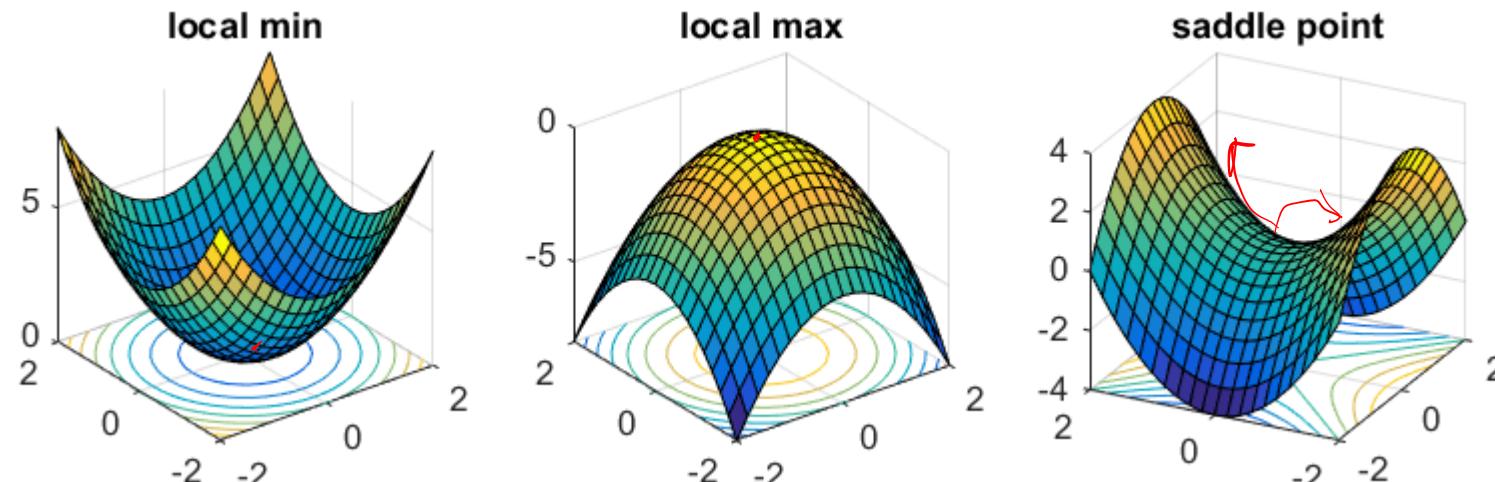
3. Convert the Δx_i from coded variables to the natural variables.

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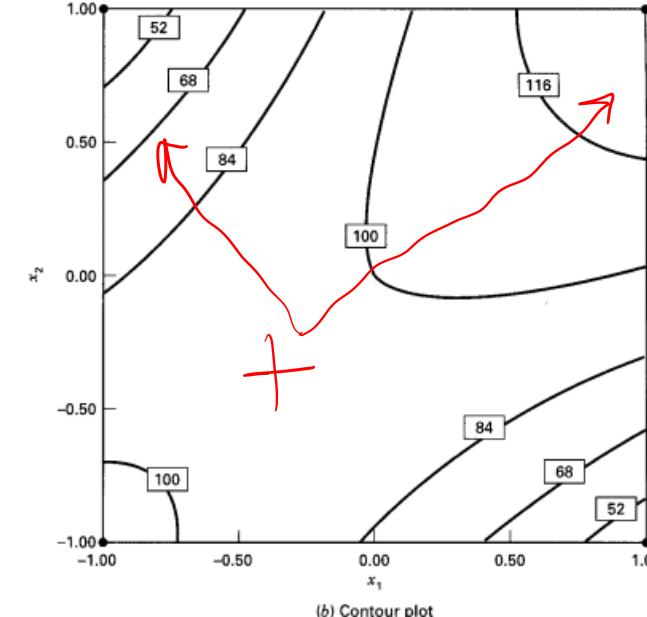
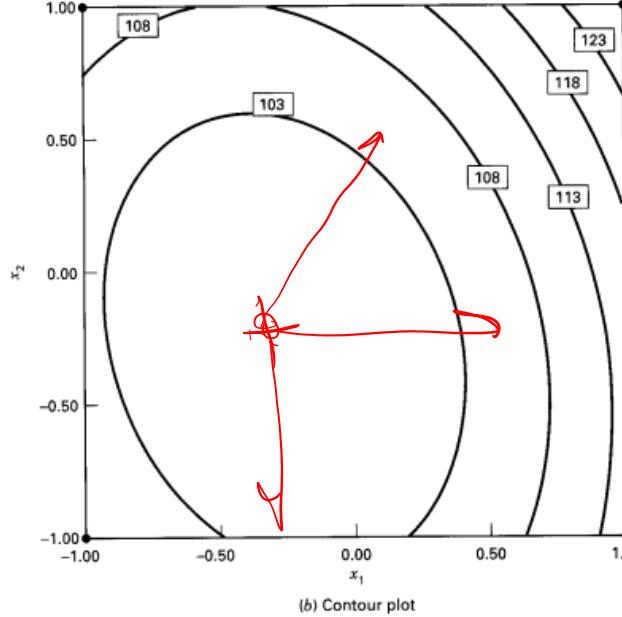
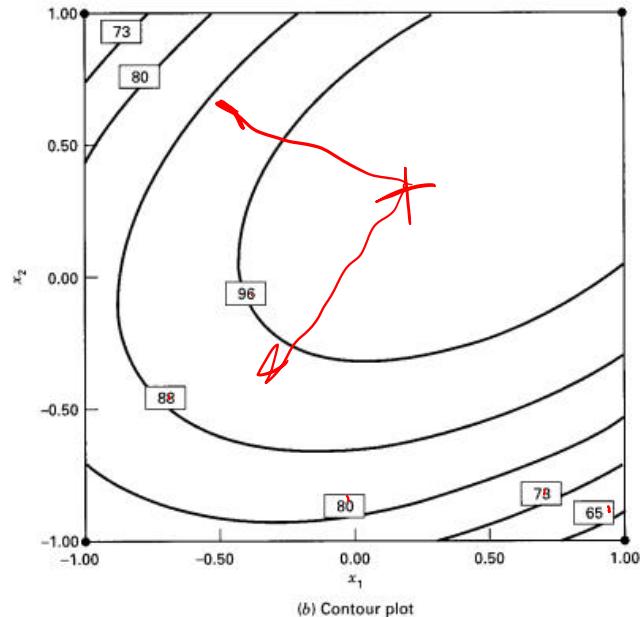
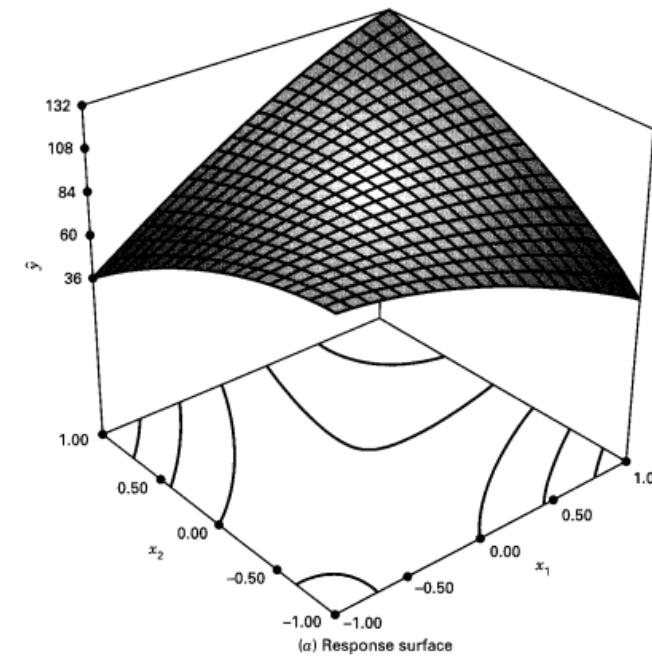
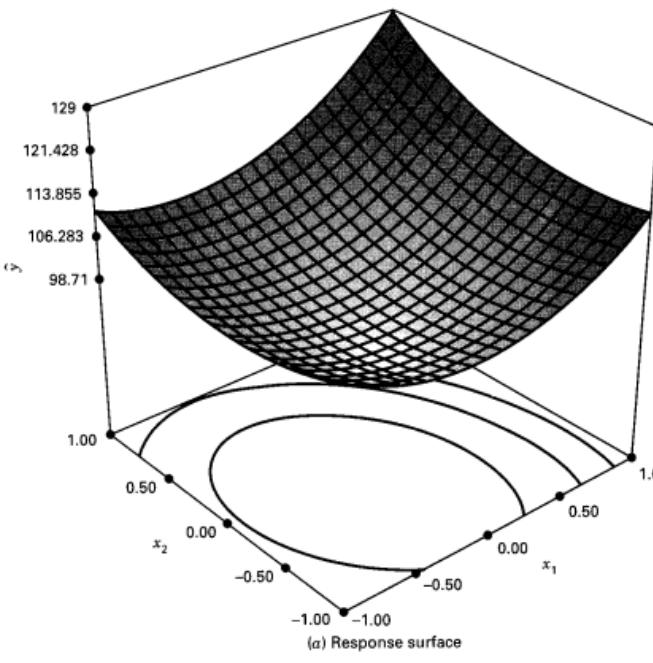
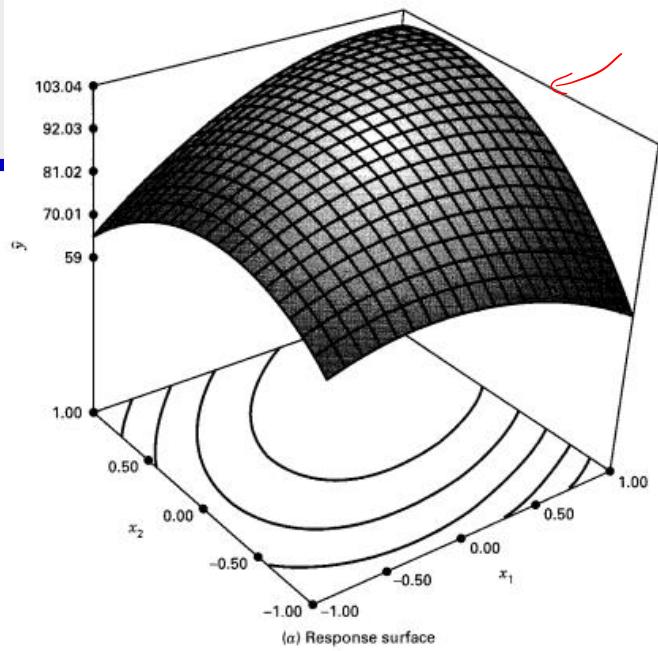
Analysis of Second-Order Response Surface

$$y = \beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_{ii} x_i^2 + \sum_{i < j} \beta_{ij} x_i x_j + \epsilon \quad \checkmark$$

- Suppose we want to find the levels of $x_1, x_2, x_3, \dots, x_k$ that optimize the predicted response
- If such an optimum point exists, then at that point, $\frac{\partial \hat{y}}{\partial x_1} = \frac{\partial \hat{y}}{\partial x_2} = \frac{\partial \hat{y}}{\partial x_3} = \dots = \frac{\partial \hat{y}}{\partial x_k} = 0$ ✓
- This point, say, $x_{1s}, x_{2s}, x_{3s}, \dots, x_{ks}$ is called a 'stationary point'
- Stationary point could represent a point of maximum response, or minimum response or saddle point.



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$$y = \beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_{ii} x_i^2 + \sum_{i < j} \beta_{ij} x_i x_j + \epsilon$$

$$\hat{y} = \hat{\beta}_0 + \sum \hat{\beta}_i x_i + \sum \hat{\beta}_{ii} x_i^2 + \sum \sum \hat{\beta}_{ij} x_i x_j$$

We may obtain a general mathematical solution for the location of the stationary point. Writing the second-order model in matrix notation, we have

$$\hat{y} = \hat{\beta}_0 + \mathbf{x}' \mathbf{b} + \mathbf{x}' \mathbf{B} \mathbf{x}$$

where

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_k \end{bmatrix}_{k \times 1}, \quad \mathbf{b} = \begin{bmatrix} \hat{\beta}_1 \\ \hat{\beta}_2 \\ \vdots \\ \hat{\beta}_k \end{bmatrix}_{k \times 1} \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} \hat{\beta}_{11}, \hat{\beta}_{12}/2, \dots, \hat{\beta}_{1k}/2 \\ \hat{\beta}_{21}, \dots, \hat{\beta}_{22}/2, \dots, \hat{\beta}_{2k}/2 \\ \vdots \\ \hat{\beta}_{kk} \end{bmatrix}_{K \times K} \quad \text{sym.}$$

That is, \mathbf{b} is a $(k \times 1)$ vector of the first-order regression coefficients and \mathbf{B} is a $(k \times k)$ symmetric matrix whose main diagonal elements are the *pure* quadratic coefficients ($\hat{\beta}_{ii}$) and whose off-diagonal elements are one-half the *mixed* quadratic coefficients ($\hat{\beta}_{ij}$, $i \neq j$). The derivative of \hat{y} with respect to the elements of the vector \mathbf{x} equated to $\mathbf{0}$ is

$$\frac{\partial \hat{y}}{\partial \mathbf{x}} = \mathbf{b} + 2\mathbf{B}\mathbf{x} = \mathbf{0} \quad (11-6)$$

The stationary point is the solution to Equation 11-6, or

$$\mathbf{x}_s = -\frac{1}{2} \mathbf{B}^{-1} \mathbf{b}$$

Furthermore, by substituting Equation 11-7 into Equation 11-5, we can find the predicted response at the stationary point as

y at x_s

$$\Rightarrow \hat{y}_s = \hat{\beta}_0 + \frac{1}{2} \mathbf{x}_s' \mathbf{b}$$

$$\mathbf{x}' = \mathbf{x}^T \quad (11-5)$$

$$\begin{aligned} \hat{y} &= \hat{\beta}_0 + \hat{\beta}_1 x_1 + \hat{\beta}_2 x_2 + \hat{\beta}_{12} x_1 x_2 + \hat{\beta}_{11} x_1^2 + \hat{\beta}_{22} x_2^2 \\ &= \hat{\beta}_0 + \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^T \begin{bmatrix} \hat{\beta}_1 \\ \hat{\beta}_2 \end{bmatrix} + \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^T \begin{bmatrix} \hat{\beta}_{11} & \hat{\beta}_{12}/2 \\ \hat{\beta}_{12}/2 & \hat{\beta}_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ &= \hat{\beta}_0 + [x_1 x_2] [\hat{\beta}_1 \hat{\beta}_2] + [x_1 x_2] \begin{bmatrix} \hat{\beta}_{11} & \hat{\beta}_{12}/2 \\ \hat{\beta}_{12}/2 & \hat{\beta}_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \end{aligned}$$

We know that, at stationary point

$$\frac{\partial \hat{y}}{\partial x_j} = 0 \quad \text{at } x = x_s$$

$$x_s = -\frac{1}{2} \mathbf{B}^{-1} \mathbf{b}$$

y_s

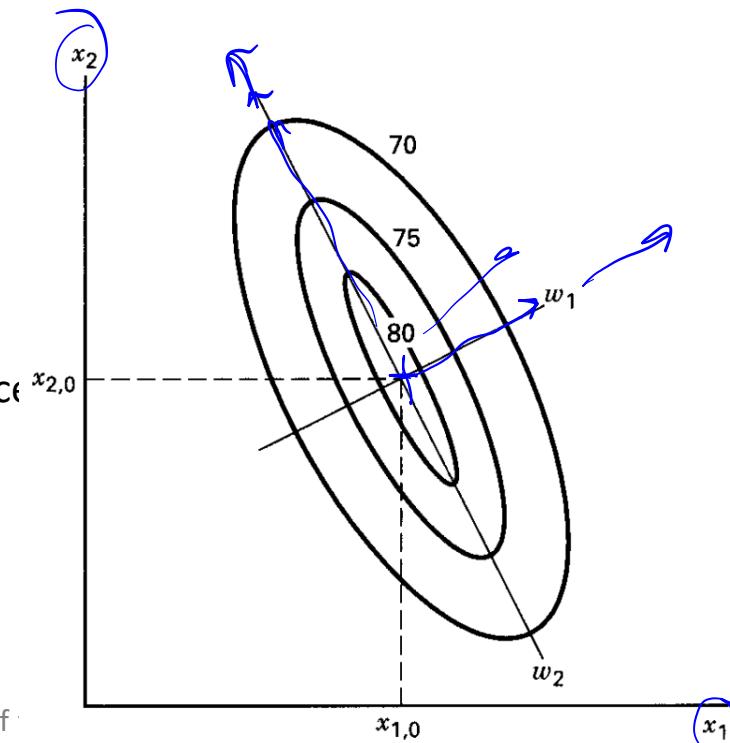
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Characterizing the Response Surface

- Once we find the stationary point (x_s), we would like to characterize the response surface near it – to find out whether that point is maximum, minimum or a saddle
- How can we do that? – by finding the relative sensitivity of the response to $x_1, x_2, x_3, \dots, x_k$
- This can be done by examining the contour plot – easy if there are only 2/3 independent variables
- What to do when there are more variables? -> “Canonical Analysis”

Canonical Analysis

- To characterize the region near x_s ,
 - We shift our origin to x_s , and
 - Rotate our axes until they are parallel to the principal axes of the fitted response surface



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Canonical Form

- After the transformation, we can show that the original equation of the surface

$$y = \beta_0 + \sum_{i=1}^k \beta_i x_i + \sum_{i=1}^k \beta_{ii} x_i^2 + \sum_{i < j} \beta_{ij} x_i x_j = \hat{\beta}_0 + \mathbf{x}' \mathbf{b} + \mathbf{x}' \mathbf{B} \mathbf{x}$$

$m \rightarrow w_1$
 $n \rightarrow w_2$

takes the form of

$$\hat{y} = \hat{y}_s + \lambda_1 w_1^2 + \lambda_2 w_2^2 + \dots + \lambda_k w_k^2$$

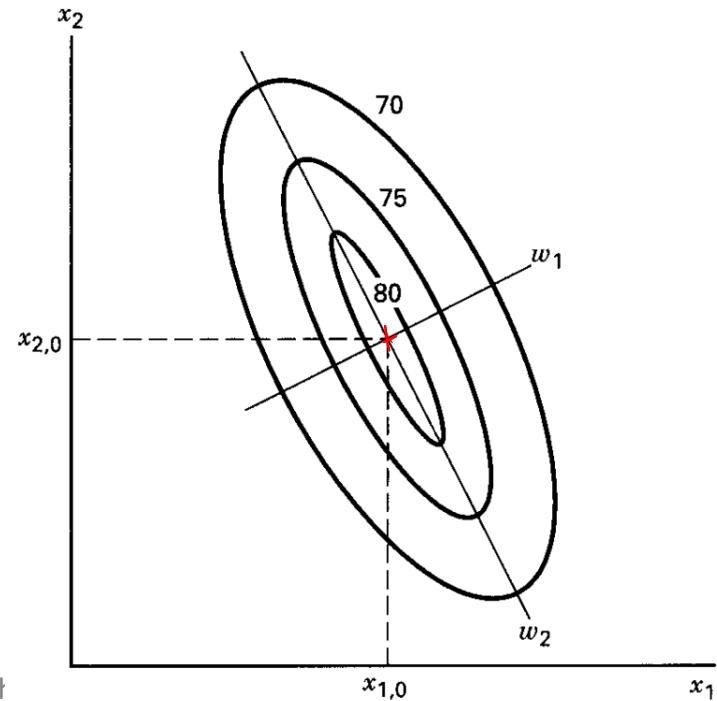
- Here, w_i are the new (transformed) independent variables, and λ_i are the constants
- This is called '**Canonical Form**' of the model.
- λ_i are the eigen values of matrix \mathbf{B}

$$\underline{\mathbf{B}} = \begin{bmatrix} \hat{\beta}_{11}, \hat{\beta}_{12}/2, \dots, \hat{\beta}_{1k}/2 \\ \hat{\beta}_{21}, \dots, \hat{\beta}_{2k}/2 \\ \vdots \\ \text{sym.} & \hat{\beta}_{kk} \end{bmatrix}_{k \times k}$$

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Canonical Form

The nature of the response surface can be determined from the stationary point and the *signs* and *magnitudes* of the $\{\lambda_i\}$. First, suppose that the stationary point is within the region of exploration for fitting the second-order model. If the $\{\lambda_i\}$ are all positive, \mathbf{x}_s is a point of minimum response; if the $\{\lambda_i\}$ are all negative, \mathbf{x}_s is a point of maximum response; and if the $\{\lambda_i\}$ have different signs, \mathbf{x}_s is a saddle point. Furthermore, the surface is steepest in the w_i direction for which $|\lambda_i|$ is the greatest. For example, Figure 11-9 depicts a system for which \mathbf{x}_s is a maximum (λ_1 and λ_2 are negative) with $|\lambda_1| > |\lambda_2|$.



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Example

We will continue the analysis of the chemical process in Example 11-1. A second-order model in the variables x_1 and x_2 cannot be fit using the design in Table 11-4. The experimenter decides to augment this design with enough points to fit a second-order model.¹ She obtains four observations at $(x_1 = 0, x_2 = \pm 1.414)$ and $(x_1 = \pm 1.414, x_2 = 0)$. The complete experiment is shown in Table 11-6 (page 442), and the design is displayed in Figure 11-10 (on the next page). This design is called a **central composite design** (or a CCD)

$$x_1 = \frac{\xi_1 - 85}{5} \quad x_2 = \frac{\xi_2 - 175}{5}$$

Time, Temp				y ₁ (yield)	Responses		
Natural Variables		Coded Variables			y ₂ (viscosity)	y ₃ (molecular weight)	
ξ_1	ξ_2	x_1	x_2				
80	170	-1	-1	76.5	62	2940	
80	180	-1	1	77.0	60	3470	
90	170	1	-1	78.0	66	3680	
90	180	1	1	79.5	59	3890	
85	175	0	0	79.9	72	3480	
85	175	0	0	80.3	69	3200	
85	175	0	0	80.0	68	3410	
85	175	0	0	79.7	70	3290	
85	175	0	0	79.8	71	3500	
92.07	175	1.414	0	78.4	68	3360	
77.93	175	-1.414	0	75.6	71	3020	
85	182.07	0	1.414	78.5	58	3630	
85	167.93	0	-1.414	77.0	57	3150	

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Final Equation in Terms of Coded Factors:

$$\text{yield} = +79.94 + 0.99 * A + 0.52 * B - 1.38 * A^2 - 1.00 * B^2 + 0.25 * A * B$$

Final Equation in Terms of Actual Factors:

$$\text{yield} = -1430.52285 + 7.80749 * \text{time} + 13.27053 * \text{temp} - 0.055050 * \text{time}^2 - 0.040050 * \text{temp}^2 + 0.010000 * \text{time} * \text{temp}$$

Response: yield

ANOVA for Response Surface Quadratic Model

Analysis of variance table [Partial sum of squares]

Source	Sum of Squares	DF	Mean Square	F Value
Model	28.25	5	5.65	79.85
A	7.92	1	7.92	111.93
B	2.12	1	2.12	30.01
A^2	13.18	1	13.18	186.22
B^2	6.97	1	6.97	98.56
AB	0.25	1	0.25	3.53
Residual	0.50	7	0.071	
Lack of Fit	0.28	3	0.094	1.78
Pure Error	0.21	4	0.053	
Cor Total	28.74	12		

How do we find the stationary point?

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We may obtain a general mathematical solution for the location of the stationary point. Writing the second-order model in matrix notation, we have

$$\hat{y} = \hat{\beta}_0 + \mathbf{x}'\mathbf{b} + \mathbf{x}'\mathbf{B}\mathbf{x} \quad (11-5)$$

where

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_k \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} \hat{\beta}_1 \\ \hat{\beta}_2 \\ \vdots \\ \hat{\beta}_k \end{bmatrix} \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} \hat{\beta}_{11}, \hat{\beta}_{12}/2, \dots, \hat{\beta}_{1k}/2 \\ \hat{\beta}_{21}, \dots, \hat{\beta}_{2k}/2 \\ \vdots \\ \hat{\beta}_{kk} \end{bmatrix} \quad \text{sym.}$$

That is, \mathbf{b} is a $(k \times 1)$ vector of the first-order regression coefficients and \mathbf{B} is a $(k \times k)$ symmetric matrix whose main diagonal elements are the *pure* quadratic coefficients ($\hat{\beta}_{ii}$) and whose off-diagonal elements are one-half the *mixed* quadratic coefficients ($\hat{\beta}_{ij}$, $i \neq j$). The derivative of \hat{y} with respect to the elements of the vector \mathbf{x} equated to $\mathbf{0}$ is

$$\frac{\partial \hat{y}}{\partial \mathbf{x}} = \mathbf{b} + 2\mathbf{B}\mathbf{x} = \mathbf{0} \quad (11-6)$$

The stationary point is the solution to Equation 11-6, or

$$\mathbf{x}_s = -\frac{1}{2}\mathbf{B}^{-1}\mathbf{b} \quad (11-7)$$

Furthermore, by substituting Equation 11-7 into Equation 11-5, we can find the predicted response at the stationary point as

$$\hat{y}_s = \hat{\beta}_0 + \frac{1}{2}\mathbf{x}_s'\mathbf{b} \quad (11-8)$$

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Final Equation in Terms of Coded Factors:

$$\begin{aligned} \text{yield} = & \\ & +79.94 \\ & +0.99 * A \\ & +0.52 * B \\ & -1.38 * A^2 \\ & -1.00 * B^2 \\ & +0.25 * A * B \end{aligned}$$

Final Equation in Terms of Actual Factors:

$$\begin{aligned} \text{yield} = & \\ & -1430.52285 \\ & +7.80749 * \text{time} \\ & +13.27053 * \text{temp} \\ & -0.055050 * \text{time}^2 \\ & -0.040050 * \text{temp}^2 \\ & +0.010000 * \text{time} * \text{temp} \end{aligned}$$

$$\mathbf{b} = \begin{bmatrix} 0.995 \\ 0.515 \end{bmatrix} \quad \mathbf{B} = \begin{bmatrix} -1.376 & 0.1250 \\ 0.1250 & -1.001 \end{bmatrix}$$

and from Equation 11-7 the stationary point is

$$\begin{aligned} \mathbf{x}_s &= -\frac{1}{2}\mathbf{B}^{-1}\mathbf{b} \\ &= -\frac{1}{2} \begin{bmatrix} -0.7345 & -0.0917 \\ -0.0917 & -1.0096 \end{bmatrix} \begin{bmatrix} 0.995 \\ 0.515 \end{bmatrix} = \begin{bmatrix} 0.389 \\ 0.306 \end{bmatrix} \end{aligned}$$

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for eigen vector $\bar{\pi}_2$

$$\begin{aligned}\mathbf{B} \bar{\pi}_2 &= \lambda \bar{\pi}_2 \\ \Rightarrow [\mathbf{B} - \lambda \mathbf{I}] \bar{\pi}_2 &= 0\end{aligned}$$

$$\Rightarrow \boxed{|\mathbf{B} - \lambda \mathbf{I}| = 0} \rightarrow \text{gives us } n \text{ eigenvalues}$$

Find Eigen values and Eigen vectors of B

$\mathbf{B} = []_{K \times K}$ if this is a transformation

$$\mathbf{B} \bar{\pi} = \bar{\pi}$$

$$[]_{K \times K} []_{K \times 1} = []_{K \times 1}$$

eigen vectors are those who do NOT change dir under B

$$\mathbf{B} \bar{\pi} = \lambda \bar{\pi}$$

$$\mathbf{b} = \begin{bmatrix} 0.995 \\ 0.515 \end{bmatrix}$$

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and from Equation 11-7 the stationary point is

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$$= -\frac{1}{2} \begin{bmatrix} -0.7345 & -0.0917 \\ -0.0917 & -1.0096 \end{bmatrix} \begin{bmatrix} 0.995 \\ 0.515 \end{bmatrix} = \begin{bmatrix} 0.389 \\ 0.306 \end{bmatrix}$$

$$|\mathbf{B} - \lambda\mathbf{I}| = 0$$

$$\begin{vmatrix} -1.376 - \lambda & 0.1250 \\ 0.1250 & -1.001 - \lambda \end{vmatrix} = 0$$

which reduces to

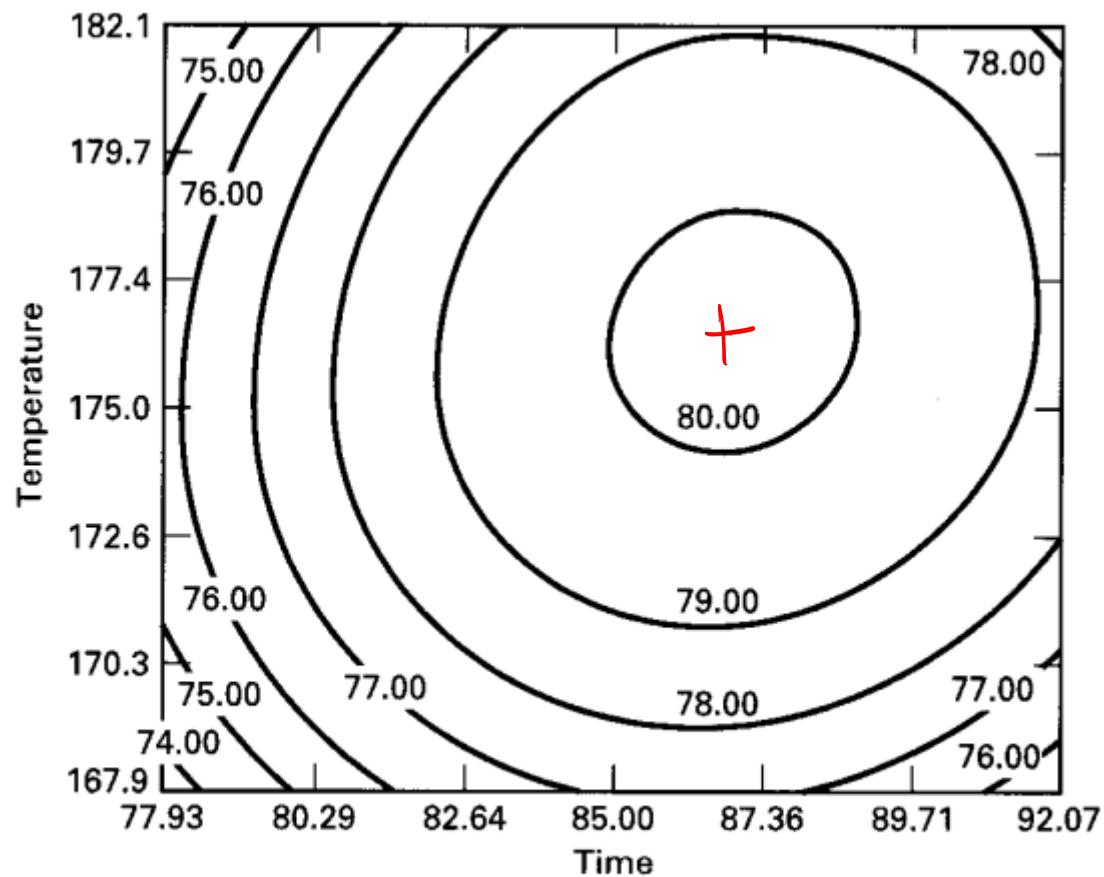
$$\lambda^2 + 2.3788\lambda + 1.3639 = 0$$

The roots of this quadratic equation are $\lambda_1 = -0.9641$ and $\lambda_2 = -1.4147$. Thus, the canonical form of the fitted model is

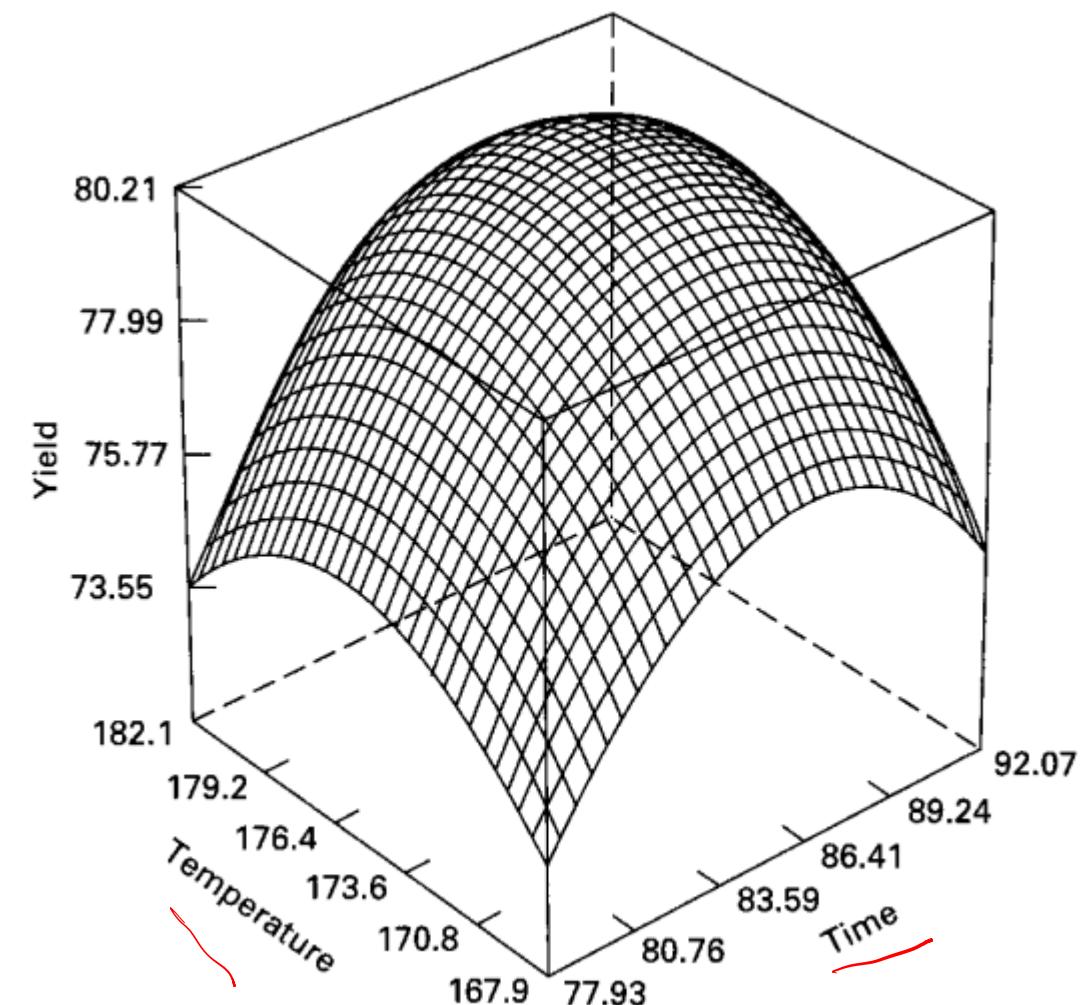
$$\hat{y} = 80.21 - 0.9641w_1^2 - 1.4147w_2^2$$

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- Example: Contour Plot



(a) The contour plot



(b) The response surface plot

The stationary point we found was $x_{1,s} = 0.389$ and $x_{2,s} = 0.306$

In terms of original time and temperature units, $\xi_1 = 86.95 \approx 87$ minutes of reaction time and $\xi_2 = 176.53 \approx 176.5^\circ\text{F}$.

What would you do if for some reason (e.g. cost) we cannot operate at this point?

- We can back away slightly from this optimum point and see if any other point in vicinity can work
- Where to go?

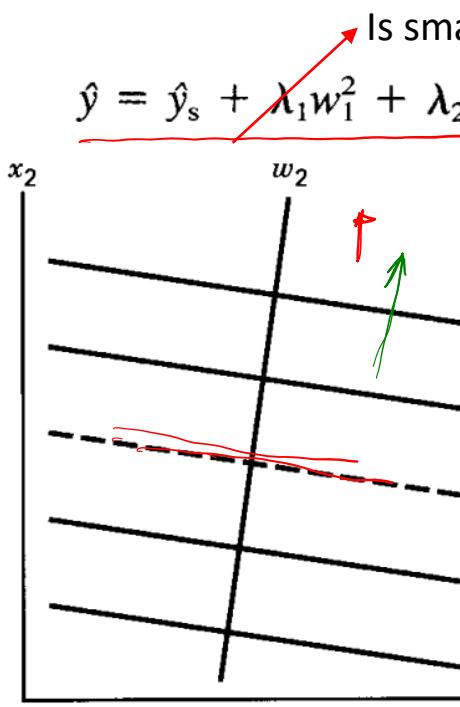
$$\hat{y} = 80.21 - 0.9641w_1^2 - 1.4147w_2^2$$

at π_s
 $w_1 = w_2 = 0$

You would move first in dir where $|D|$ is smallest

Ridge Systems

- Consider 2nd order model with canonical form $\hat{y} = \hat{y}_s + \lambda_1 w_1^2 + \lambda_2 w_2^2 + \dots + \lambda_k w_k^2$ ✓✓
- Suppose the stationary point (x_s) is in the region of experimentation, and some λ_i are small, i.e., $\lambda_i \approx 0$
- Then, the response variable y is very insensitive to variables with small λ



- Because of small λ_1 , the optimum can be taken anywhere along the line of $y = 70$
- This type of response surface is called 'stationary ridge system'

Figure 11-12 A contour plot of a stationary ridge system.

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