MA-111 Calculus II (D3 & D4)

Lecture 7

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February 7, 2022

Change of variables

Spherical change of variables

Cylindrical change of variables

Change of variables in \mathbb{R}^2

Let Ω be an open subset of \mathbb{R}^2 and $h:\Omega\to\mathbb{R}^2$ be an one-one transformation denoted by

$$h(u,v) := (h_1(u,v), h_2(u,v)), \quad \forall (u,v) \in \Omega.$$

We now want to make a general change of coordinates given by

$$x = h_1(u, v), \quad y = h_2(u, v).$$

What conditions do we need on h to be able to do a change of coordinates?

Can we compute the area of the image of a rectangle in the u-v plane?

Suppose we have a change in coordinates given by linear functions composed with translations (such functions are called affine linear functions):

$$x = au + bv + t_1$$
 and $y = cu + dv + t_2$.

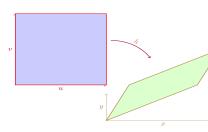
A linear change of coordinates

How does the area of the image of a rectangle under this map compare with the area of the original rectangle?

First, let us write down the affine map in a more compact notation:

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} + \begin{pmatrix} t_1 \\ t_2 \end{pmatrix}$$

Clearly, a rectangle $[1,0] \times [0,1]$ in the u-v plane is mapped to a parallelogram in the x-y plane. The sides of the parallelogram are given by $(a+t_1,c+t_2)$ and $(b+t_1,d+t_2)$.

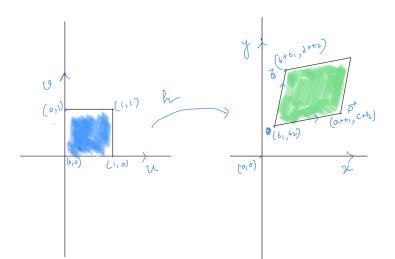


How does one compute the area of this parallelogram?

This is given by the absolute value of the cross product of the vectors,

$$(a, c, 0) \times (b, d, 0) = (ad - bc) \cdot \mathbf{k} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} \cdot \mathbf{k}.$$

The area element for a change of coordinates



The area element for a change of coordinates

Let us now suppose that we have a general (not linear any more) change of coordinates given by $x = h_1(u, v)$ and $y = h_2(u, v)$.

How does the area of a rectangle in the u-v plane change? In order to compute the change we need to know the partial derivatives exist.

Let us assume h is a one-one continuously differentiable function .

Noting

$$\Delta x = h_1(u+\Delta u, v+\Delta v) - h_1(u, v), \quad \Delta y = h_2(u+\Delta u, v+\Delta v) - h_2(u, v),$$
 and using Taylor's theorem for functions of two variables we see that

$$\Delta x \sim \frac{\partial h_1}{\partial u} \Delta u + \frac{\partial h_1}{\partial v} \Delta v$$

and

$$\Delta y \sim \frac{\partial h_2}{\partial u} \Delta u + \frac{\partial h_2}{\partial v} \Delta v.$$

Using our previous notation, we can write

$$\begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} = \begin{pmatrix} \frac{\partial h_1}{\partial u} & \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} & \frac{\partial h_2}{\partial v} \end{pmatrix} \begin{pmatrix} \Delta u \\ \Delta v \end{pmatrix}$$

The Jacobian

You may recognize the matrix

$$J(h) = \begin{pmatrix} \frac{\partial h_1}{\partial u} & \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} & \frac{\partial h_2}{\partial v} \end{pmatrix}$$

that appears in the preceding formula. The derivative matrix for the function $h = (h_1, h_2) : \mathbb{R}^2 \to \mathbb{R}^2$ is called the Jacobian.

In a neighborhood of the point (u_0, v_0) , the function h and the function J(h), behave very similarly (that is, they are the same upto the first order terms - use Taylor's theorem!). In fact, the derivative matrix is the *linear approximation* to the function h, at least in a neighborhood of a point, say (u_0, v_0) .

In particular, it is easy to see how the area of a small rectangle changes under h, since we have already done so in the case of a linear map. It simply changes by the (absolute value of) determinant of J!

Theorem (Change of Variables Formula)

- ▶ Let D be a closed and bounded subset of \mathbb{R}^2 such that ∂D has content zero. Let $f: D \to \mathbb{R}$ be continuous.
- Suppose Ω is an open subset of \mathbb{R}^2 and $h: \Omega \to \mathbb{R}^2$ is a one-one differentiable function such that $h:=(h_1,h_2)$, where h_1 and h_2 have continuous partial derivatives in Ω and $\det(J(h)(u,v)) \neq 0$ for all $(u,v) \in \Omega$.
- Let $D^* \subset \Omega$ be such that $h(D^*) = D$.

Then D^* is a closed and bounded subset of Ω , and ∂D^* is of content zero. Moreover, $f \circ h : D^* \to \mathbb{R}$ is continuous, and

$$\int \int_{D} f(x,y) \, dxdy = \int \int_{D^*} (f \circ h)(u,v) |\det(J(h)(u,v))| \, dudv.$$

Notation

Often we write x=x(u,v) and y=y(u,v). In this case we use the notation $\frac{\partial(x,y)}{\partial(u,v)}=\det\begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix}$, for the Jacobian determinant.

Let D be a region in the xy plane and D^* a region in the uv plane such that $\phi(D^*)=D$. Then

$$\int \int_{D} f(x,y) dx dy = \int \int_{D^{*}} f(x(u,v),y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv.$$

Remark: Note what we get in the familiar case of polar coordinates: We have $x = r \cos \theta$, $y = r \sin \theta$ and

$$\frac{\partial(x,y)}{\partial(r,\theta)} = \det\begin{pmatrix}\cos\theta & -r\sin\theta\\\sin\theta & r\cos\theta\end{pmatrix} = r,$$

which is what we obtained previously.

How to choose the change of variables

- ▶ Aim: Find h such that a rectangle D^* in u v plane is getting mapped to the given area D in the xy plane. If D^* is not a rectangle, at least try to have it in the form of the elementary region Type 1 or Type 2.
- ▶ Presumably, the boundary D^* in u v plane should go to the boundary of D in x y plane.
- ▶ The non-vanishing Jacobian determinant of h assures that the properties of D^* is preserved under the transformation and D has similar properties as of D^* .
- ▶ In some cases, *h* can be chosen in a way such that the expression of the integrand becomes simpler after the change of variables.

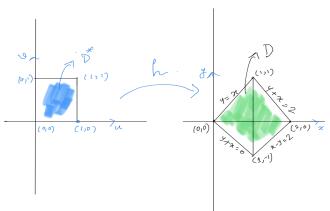
Example Evaluate the integral

$$\iint_D (x^2 - y^2) dx dy$$

where D is the square with vertices at (0,0), (1,-1), (1,1) and (2,0).

Solution: Note D is the region in x-y plane bounded by lines y=x, y+x=0, x-y=2 and y+x=2. Put

$$x = u + v$$
, $y = u - v$,



Then the rectangle

Further,

 $D^* = \{(u, v) \in \mathbb{R}^2 \mid 0 < u < 1, \ 0 < v < 1\}$

$$D^*$$

$$D^* =$$

 $\frac{\partial(x,y)}{\partial(u,v)} = \det\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = -2.$

 $\int \int_{\Omega} (x^2 - y^2) dxdy = \int \int_{\Omega^*} (4uv) \times 2 dudv$

 $=8\left(\int_{0}^{1}udu\right)\left(\int_{0}^{1}vdv\right)=2.$

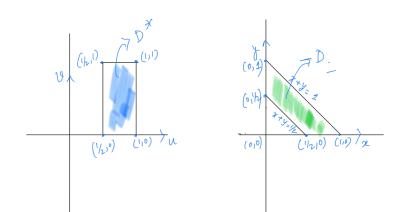
in the
$$uv$$
-plane gets mapped to D , in the xy -plane.

Example

Let D be the region in the first quadrant of the xy-plane bounded by the lines $x+y=\frac{1}{2}$ and x+y=1. Find $\iint_D dA$ by transforming it to $\iint_{D^*} du dv$, where $u=x+y, v=\frac{y}{x+y}$.

Solution: Put

$$x=u(1-v), \ y=uv.$$



Further,

Hence,

 $\frac{\partial(x,y)}{\partial(u,v)} = \det\begin{pmatrix} 1-v & -u \\ v & u \end{pmatrix} = u \neq 0.$

 $Area(D) = \int \int_{D} dA = \int \int_{D_{*}^{*}} |u| du dv$

 $= \left(\int_{\frac{1}{2}}^1 \frac{u^2}{2} du\right) \left(\int_0^1 dv\right) = \frac{3}{4}.$

The change of variables formula in three variables

In three variables, we once again have a formula for a change of variables. The formula has the same form as in the two variable case:

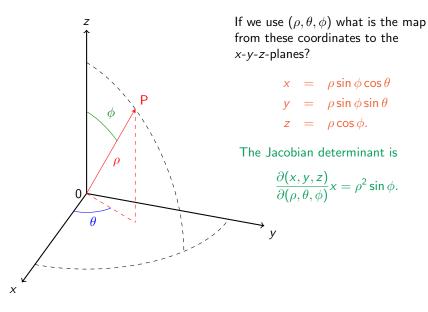
$$\iiint_{P} f(x,y,z) dx dy dz = \iiint_{P^{*}} g(u,v,w) \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| du dv dw,$$

where $h(P^*) = P$. If the change in coordinates is given by $h = (h_1, h_2, h_3)$, the function g is defined as $g = f(h_1, h_2, h_3)$. The expression

$$\frac{\partial(x,y,z)}{\partial(u,v,w)} = \det \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{pmatrix}$$

is just the Jacobian determinant for a function of three variables.

Spherical Coordinates



Example

Example: It should be much easier computing the volume of the unit sphere now. Let $W = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 \leq 1\}$.

Then $W^* = \{(\rho, \theta, \phi) \in \mathbb{R}^3 \mid 0 \le \rho \le 1, 0 \le \theta \le 2\pi, 0 \le \phi \le \pi\}.$ Then,

$$\iiint_{W} dxdydz = \iiint_{W^{*}} \rho^{2} \sin \phi \ d\rho d\theta d\phi$$
$$= \int_{0}^{\pi} \int_{0}^{2\pi} \int_{0}^{1} \rho^{2} \sin \phi \ d\rho d\theta d\phi$$
$$= \frac{2\pi}{3} \int_{0}^{\pi} \sin \phi \ d\phi = \frac{4\pi}{3}$$

Cylindrical coordinates in formulae

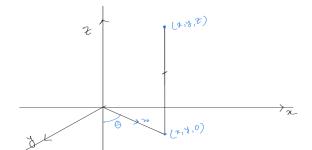
We can also consider a generalization of the polar coordinates. In this case, we use the change of transformation from (r, θ, z) coordinates to $P = (x, y, z) \in \mathbb{R}^3$ given by

$$x = r \cos \theta$$
, $y = r \sin \theta$ and $z = z$.

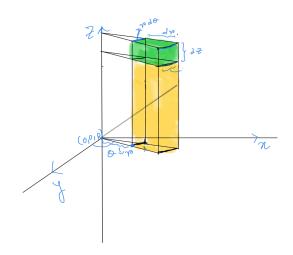
Here $r \geq 0$ and $0 \leq \theta \leq 2\pi$ and the (r, θ, z) are

It is very easy to see that

$$\left|\frac{\partial(x,y,z)}{\partial(r,\theta,z)}\right|=r.$$



The good thing about our convention is that θ means the same thing in both the cylindrical and spherical coordinate systems as well as in the (two-dimensional) polar coordinate system, and r means the same thing in both the cylindrical and (two-dimensional) polar coordinate systems.



Example

Evaluate $\int \int \int_W z^2(x^2 + y^2) dx dy dz$, where W is the cylindrical region determined by $x^2 + y^2 \le 1$ and $-1 \le z \le 1$.

Solution. The region W is described in cylindrical coordinates as W^*

$$W^* = \{ (r, \theta, z) \mid 0 \le r \le 1, \quad 0 \le \theta \le 2\pi, \quad -1 \le z \le 1 \}.$$

$$\int \int \int_{W} z^{2}(x^{2} + y^{2}) \frac{dxdydz}{dx} = \int_{z=-1}^{1} \int_{\theta=0}^{2\pi} \int_{r=0}^{1} z^{2} r^{2} r \frac{drd\theta dz}{dz}$$
$$= \int_{-1}^{1} \frac{2\pi}{4} z^{2} dz = \frac{\pi}{3}.$$