# CS 419M: Intro to ML

Overview Lecture: Overview of probability theory for  $$\operatorname{ML}$$ 

## A review of probability theory

• Sample space(S): A sample space is defined as a set of all possible outcomes of an experiment. (For now *discrete*.)

Example of an experiment: a coin pair toss;  $S = \{HH, HT, TH, TT\}$ .

- Probability Distribution p: A function  $p: S \to [0,1]$  s.t.  $\sum_{x \in S} p(x) = 1$ . E.g., p(HH) = 1/3, p(HT) = 1/3, p(TH) = 1/6, p(TT) = 1/6.
- Event (E): An event is any subset of the sample space. i.e.,  $E \subseteq S$ .

Often we describe events using "conditions." E.g., the event that the two coin tosses are the same,  $E_{\text{same}} = \{HH, TT\}$ .

Events can be combined using logical operations on these conditions: E.g., "the two coin tosses are the same **or** the second one is T":

$$E = \{HH, TT\} \cup \{HT, TT\} = \{HH, TT, HT\}.$$

## A review of probability theory

 Probability of an Event: The total weight assigned to all the elements in the event by a given probability distribution.

$$\Pr(E) = \sum_{x \in E} p(x)$$

- Note:
  - Pr(S) = 1 and  $Pr(\emptyset) = 0$
  - $\Pr(\overline{E}) = 1 \Pr(E)$ , where  $\overline{E} = S \setminus E$
  - $Pr(E_1 \cup E_2) = Pr(E_1) + Pr(E_2) Pr(E_1 \cap E_2)$
  - If  $E_1, E_2, \ldots, E_n$  are pairwise disjoint events, then

$$Pr(\bigcup_{i=1}^{n} E_i) = \sum_{i=1}^{n} Pr(E_i)$$

## A review of probability theory

• Conditional Probability: For events  $E_1$ ,  $E_2$  (s.t.  $Pr(E_2) > 0$ ), define

$$\Pr(E_1|E_2) = \frac{\Pr(E_1 \cap E_2)}{\Pr(E_2)}$$

• Bayes' Rule, named after Thomas Bayes (1701-1761):

$$Pr(A|B) = \frac{Pr(B|A) Pr(A)}{Pr(B)},$$

provided Pr(A), Pr(B) > 0.

#### **Exercise**

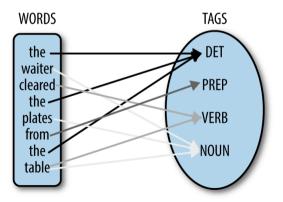
A lab test has a probability 0.95 of detecting a disease when applied to a person suffering from said disease, and a probability 0.10 of giving a false positive when applied to a non-sufferer. If 0.5% of the population are sufferers, what is the probability of a test being positive?

# **Example - Part of Speech**

POS tagging is a popular Natural Language Processing (NLP) problem

**Input**: A set of n-words

Output: Part-of-speech (POS) tag for each word



Assuming each word is independently drawn from a fixed vocabulary, find the probability that a sentence of length m contains a 'noun' given that it contains a 'verb'.

#### Solution:

- Probability that a word is of POS type 'k' is  $p_k$
- Let  $A_k$  be the event that the sentence contains POS type 'k'

$$\Pr(A_k) = 1 - (1 - p_k)^m$$
 where  $(1 - p_k)^m$  is that all  $m$  words are not of POS type 'k'.

$$\Pr(A_{noun} \mid A_{verb}) = \frac{\Pr(A_{noun} \cap A_{verb})}{\Pr(A_{verb})}$$

$$Pr(A_{j} \cap A_{k}) = 1 - Pr(\overline{A_{j} \cap A_{k}})$$

$$= 1 - Pr(\overline{A_{j}} \cup \overline{A_{k}})$$
(1)

We know that  $\Pr(A \cup B) = \Pr(A) + \Pr(B) - \Pr(A \cap B)$ . Now, we need  $\Pr(\overline{A_j} \cap \overline{A_k})$ . This refers to the event that neither tag k nor tag j are present. Thus,  $\Pr(\overline{A_j} \cap \overline{A_k}) = (1 - (p_j + p_k))^m$ . Using this in Equation 1, we get  $\Pr(A_i \cap A_k) = 1 - \Pr(\overline{A_i}) - \Pr(\overline{A_k}) + (1 - (p_i + p_k))^m$ 

$$egin{align} \mathsf{Pr}(A_j \cap A_k) &= 1 - \mathsf{Pr}(A_j) - \mathsf{Pr}(A_k) + (1 - (p_j + p_k))^m \ &= 1 - (1 - p_j)^m - (1 - p_k)^m + (1 - (p_j + p_k))^m \ \end{gathered}$$

#### Final answer:

$$Pr(A_{noun} \mid A_{verb}) = \frac{1 - (1 - p_{noun})^m - (1 - p_{verb})^m + (1 - p_{noun} - p_{verb})^m}{1 - (1 - p_{verb})^m}$$

#### Random Variable

• Random variable (X): A variable that takes values from S according to a probability distribution.

E.g., 
$$S = \{H, T\}$$
 and  $Pr(X = H) = 2/3$ ,  $Pr(X = T) = 1/3$ .

• Jointly distributed random variables: X, Y take values from sets  $S_1$ ,  $S_2$  respectively, according to a distribution over  $S_1 \times S_2$ . (Generalizes to more than 2 r.v.s.)

E.g., 
$$S_1 = S_2 = \{H, T\}$$
 and  $Pr((X, Y) = (H, H)) = 1/3$ ,  $Pr((X, Y) = (H, T)) = 1/3$ ,  $Pr((X, Y) = (T, T)) = 1/6$ ,  $Pr((X, Y) = (T, H)) = 1/6$ .

• Marginal Distribution: For  $x \in S_1$ ,  $\Pr(X = x) = \sum_{y \in S_2} \Pr((X, Y) = (x, y))$ . Similarly, marginal distribution of Y.

## Independence of Random Variables

- Abuse of Notation: Pr((X, Y) = (x, y)) abbreviated as p(x, y), Pr(X = x | Y = y) as p(x | y) etc.
- X, Y are said to be **independent**  $(X \perp Y)$  iff for all x, y, the events X = x and Y = y are independent. i.e., p(x, y) = p(x)p(y).
- X, Y are said to be **conditionally independent** given Z iff for all x, y, z (with p(z) > 0), p(x, y|z) = p(x|z)p(y|z).

# **Expectation**

If X is a random variable taking (say) real values (i.e.,  $S \subseteq \mathbb{R}$ ), we can define an "expected value" for X as:

$$E(X) = \sum_{x \in S} x \Pr(X = x)$$

Question: Suppose,  $f: S \to \mathbb{R}$  and Y is the random variable jointly distributed with X defined as Y = g(X). Then, what is E(Y)?

$$E(Y) = \sum_{x \in S} g(x) \Pr(X = x)$$

# **Properties of Expectation**

1. 
$$E[X + Y] = E[X] + E[Y]$$

2. 
$$E[(X-c)^2] \ge E[(X-\mu)^2]$$
  
where  $\mu = E[X]$   
for any constant c and any random variable X

Proof HW

3. E[cX] = cE[X]for any constant c and any random variable X Proof HW

4. If X, Y are independent, then E[XY] = E[X]E[Y]

Proof HW.

## **Variance**

The **variance** of a random variable X with  $E[X] = \mu$  is defined as:

$$Var[X] = E[(X - \mu)^2]$$

- $Var[X] = E[X^2] (E[X])^2$
- $Var[X + \beta] = Var[X]$  and  $Var[\alpha X] = \alpha^2 Var[X]$
- If  $X_1, \dots, X_n$  are pairwise independent, then  $Var[\sum_i X_i] = \sum_i Var[X_i]$  (Proof HW)
- If  $X_1, \dots, X_n$  are pairwise independent, each with variance  $\sigma^2$ , then,  $Var[\frac{1}{n}\sum_i X_i] = \sigma^2/n$

# Chebyshev's Inequality

If variance is small, the random variable has to be (somewhat) *concentrated* around its mean.

If X is a random variable with mean  $\mu$  and variance  $\sigma^2$ , then  $\forall \alpha > 0$ 

$$Pr[|X - \mu| \ge \alpha] \le \frac{\sigma^2}{\alpha^2}$$

If  $X_i$  are pairwise independent, identically distributed random variables with mean  $\mu$  and variance  $\sigma^2$ , then  $\Pr[|\left(\frac{1}{n}\sum_i X_i\right) - \mu| \geq \alpha] \to 0$  as  $n \to \infty$ . **Law of Large Numbers**: Sample mean  $\frac{1}{n}\sum_i X_i$  (for say, i.i.d. samples) converges to the expected value  $\mu$  as n grows.

# Recall: Expectation, Variance

If X is a random variable, taking (say) real values (i.e.,  $S \subseteq \mathbb{R}$ ), with probability distribution  $p: S \to [0,1]$ , then **expected value** of X is:

$$E[X] = \sum_{x \in S} p(x) \cdot x$$

The **variance** of a random variable X with  $E[X] = \mu$  is

$$Var[X] = E[(X - \mu)^2] = E[X^2] - \mu^2$$

## **Covariance**

For random variables X and Y, **covariance** is defined as:

$$Cov[X, Y] = E[(X - E(X))(Y - E(Y))] = E[XY] - E[X]E[Y]$$

If X and Y are independent then their covariance is 0, since in that case

$$E[XY] = E[X]E[Y]$$

**Note:** However, covariance being 0 does not necessarily imply that the variables are independent.

### **Covariance**

## **Properties:**

- 1. Cov[X, X] = Var[X]
- 2. Cov[X + Z, Y] = Cov[X, Y] + Cov[Z, Y]
- 3.  $Cov[\sum_i X_i, Y] = \sum_i Cov[X_i, Y]$

# Some Important Distributions

Notation: We write  $X \sim \mathcal{D}$  if the random variable X takes its values according to some distribution  $\mathcal{D}: S \to [0,1]$ : i.e.,  $\Pr[X=x] = \mathcal{D}(x)$ .

**Bernoulli Random Variable**: Takes values from  $S = \{0, 1\}$ .

A single **parameter**  $q \in [0,1]$  fully specifies a Bernoulli random variable, where Pr[X=1] = q (and Pr[X=0] = 1-q).

**Notation:** Denoted as Bern(q).

If  $X \sim \text{Bern}(q)$  then

- $E[X] = (1-q) \times 0 + q \times 1 = q$
- $Var[X] = q q^2 = q(1 q)$

Quintessential example: X = 1 iff a coin toss yields H, where q is the coin's probability of coming up H.

#### **Binomial Random Variable**

Quintessential example: number of H out of n tosses of a coin with Pr[H] = q.

Sample space,  $S = \{0, \dots, n\}$ .

**Notation:** Distribution denoted as B(n, q). Note: **2 parameters**, n and q.

Formally, if  $Y = \sum_{i=1}^n X_i$ , where  $X_i \sim \mathrm{Bern}(q)$  are i.i.d., then  $Y \sim \mathrm{B}(n,q)$ .

If  $Y \sim B(n, q)$  then

- $\Pr(Y = k) = \binom{n}{k} q^k (1 q)^{n-k}$
- E[Y] = nq (by linearity of expectation, applied to  $Y = \sum_{i=1}^{n} X_i$ )
- Var[Y] = nq(1-q) (Why?)

# **Coming Up**

#### Continuous Random Variables

- Distribution function
  - Probability Density Function
  - Cumulative Distribution Function
  - Conditioning, Independence for Continuous Random Variables
  - Expectation (and other statistics) for Continuous Random Variables
  - Important Example: Normal Distribution
- Central Limit Theorem

## **Continuous Distributions**

Suppose a random variable X is uniformly distributed in the range S = [0,1], and Y is uniformly distributed in  $[0,\frac{1}{2}]$ . But note that for all  $a \in [0,1]$ , Pr(X = a) = Pr(Y = a) = 0! So, how do we formally define these distributions?

**Mass vs. Density:** When S is discrete, weights were assigned to individual items in S so that they summed up to 1. When S is continuous, we shall assign density to all points in S so that S still "weighs" 1.

A **probability density function** (pdf) of a continuous random variable is  $f: S \to \mathbb{R}_+$  such that for all  $D \subseteq S$ ,  $Pr(X \in D) = \int_D f(x) dx$ .

E.g., Above, 
$$f_X(a)=1$$
 for all  $a\in[0,1]$ , but  $f_Y(a)=\begin{cases} 2 & \text{if } a\leq \frac{1}{2}\\ 0 & \text{otherwise} \end{cases}$ 

#### **Cumulative Distribution Function**

Suppose X is a continuous random variable which takes values from the sample space  $\mathbb{R}$ , and has a pdf f. Its **cdf** is defined as  $F : \mathbb{R} \to [0,1]$ :

$$F(a) = Pr(X \le a) = \int_{-\infty}^{a} f(x) dx$$

**Note**: pdf for continuous distribution can be obtained by differentiating the cdf of that random variable:

$$f(a) = \frac{dF(x)}{dx}|_{x=a}$$

## **Joint Distributions**

A jointly distributed pair of continuous random variables X, Y has a joint distribution function  $f : \mathbb{R}^2 \to \mathbb{R}_+$  s.t. for all  $D \subseteq \mathbb{R}^2$ ,

$$\Pr((X,Y) \in D) = \int \int_D f(x,y) dxdy.$$

If f(x, y) is a joint pdf, then

$$F(a,b) = Pr(X \le a, Y \le b) = \int_{-\infty}^{b} \int_{-\infty}^{a} f(x,y) dxdy$$
$$f(a,b) = \frac{\partial^{2} F(x,y)}{\partial x \partial y}|_{a,b}$$

## Independence

Suppose X, Y are two continuous random variables with a joint pdf f.

**Marginal Distribution**: From f can define marginal distribution density functions  $f_X$  and  $f_Y$ :  $f_X(a) = \int_{-\infty}^{\infty} f(a,y) dy$  and  $f_Y(a) = \int_{-\infty}^{\infty} f(x,a) dx$ 

**Independence:** X, Y are said to be independent iff for all x, y,

$$f(x,y)=f_X(x)f_Y(y)$$

where  $f_X$ ,  $f_Y$  are the marginal density functions.

# **Conditional Density**

Suppose X and Y are two jointly distributed continuous random variables, with a density function f. Then we can define the conditional probability density of X given Y = y as:

$$f_X(x|Y=y) = \frac{f(x,y)}{f_Y(y)} = \frac{f(x,y)}{\int_{-\infty}^{\infty} f(x,y)dx}$$

If X, Y are independent, then for all x, y (with non-zero marginals),  $f_X(x|Y=y)=f_X(x)$  and  $f_Y(y|X=x)=f_Y(y)$ .

# Example

Let X and Y be independent continuous random variables with same marginal density functions

$$f(x) = \begin{cases} e^{-x} & \text{if } x > 0; \\ 0 & \text{otherwise.} \end{cases}$$

Define the random variable  $Z = \frac{X}{Y}$ . Find the density function for Z.

## Solution

$$F_{Z}(a) = 0$$

$$F_{Z}(a) = \Pr(Z \le a) = \Pr(X \le aY)$$

$$= \int_{0}^{\infty} \int_{0}^{ya} f(x, y) dx dy = \int_{0}^{\infty} \int_{0}^{ya} e^{-x} e^{-y} dx dy$$

$$= \int_{0}^{\infty} e^{-y} (1 - e^{-ya}) dy$$

$$= 1 - \frac{1}{a+1} = \frac{a}{a+1}$$
if  $a > 0$ 

The pdf is obtained by differentiating the cdf. For a > 0:

$$f_Z(a) = \frac{dF_Z(z)}{dz}|_a = \frac{d}{dz}(1 - \frac{1}{z+1})|_a = \frac{1}{(a+1)^2}.$$

# **Expectation**

Expectation is equivalent to probability density weighted integral of possible values.

$$E[X] = \int_{-\infty}^{\infty} x f(x) dx$$

Note: Expectation of a function of a random variable is

$$E[g(X)] = \int_{-\infty}^{\infty} g(x)f(x)dx$$

Variance, Covariance are defined as before in terms of expectation

# Normal (Gaussian) Distribution

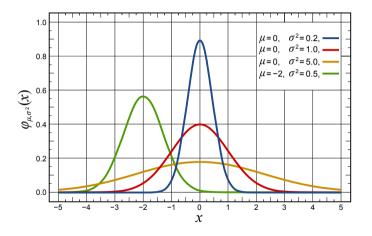
• It is a popular continuous distribution

$$\mathcal{N}(x|\mu,\sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right)$$

- $\mu$  is the mean and  $\sigma^2$  is the variance
- Exercise: Verify the mean and variance. For e.g.

$$E[X] = \int_{-\infty}^{\infty} x \frac{1}{\sqrt{2\pi\sigma}} \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right) dx \stackrel{?}{=} \mu$$

## 1-D Gaussian distribution



# Normal (Gaussian) Distribution

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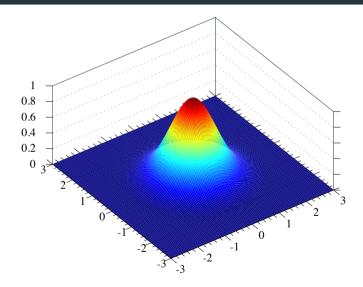
$$E[X] = \int_{-\infty}^{\infty} x \frac{1}{\sqrt{2\pi\sigma}} \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right) dx \stackrel{?}{=} \mu$$

Multivariate Gaussian (d-dim)

$$f(x|\mu, \Sigma) = (2\pi)^{-d/2} |\Sigma|^{-1/2} \exp\left\{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right\}$$

ullet x is now a vector,  $\mu$  is the mean vector and  $\Sigma$  is the co-variance matrix

# 2-D Gaussian distribution



# **Properties of Normal Distribution**

- All marginals of a Gaussian are again Gaussian
- Any conditional of a Gaussian is Gaussian
- The product of two Gaussians is again Gaussian
- Even the sum of two independent Gaussian r.v.'s is a Gaussian

**Note:** Many of the standard distributions belong to the family of **exponential distributions** 

- Bernoulli, binomial/multinomial, Poisson, Normal (Gaussian), Beta/Dirichlet
   ...
- Share many important properties e.g. They have a conjugate prior. (We will briefly discuss this within the next 2 weeks)

## **Central Limit Theorem**

Suppose  $E[X] = \mu$  and  $X_1, X_2, \ldots$  are independent r.v.s distributed as X

Define  $S^{(m)} = \frac{1}{m} \sum_{i=1}^{m} X_i$  (average of m independent copies of X)

Law of large numbers: for very large m,  $S^{(m)}$  is sharply concentrated around  $\mu$ 

But for moderately large m,  $S^{(m)}$  is a little "fuzzy" around  $\mu$ . What does this distribution look like?

Depends on the distribution of X. In particular,  $S^{(1)}$  is identical to X.

But as m increases, it very quickly starts looking like a Gaussian distribution, no matter what the actual distribution of X is!<sup>1</sup>

 $<sup>^{1}</sup>$ Actually, the rate of convergence depends on  $E[|X - \mu|^{3}]$ .

# **Central Limit Theorem: More Formally**

Suppose  $X_1, X_2, \ldots$  are i.i.d random variables, each with mean  $\mu$  and variance  $\sigma^2$ . Let  $S^{(m)} = \frac{1}{m} \sum_{i=1}^m X_i$ .

Note 
$$E[S^{(m)}] = \mu$$
 and  $Var[S^{(m)}] = \sigma^2/m$ 

To observe the shape of the distribution without letting it becoming sharper as m grows, we shall scale it to make variance a constant: Let  $Z^{(m)} = \sqrt{m}(S^{(m)} - \mu)$ , so that  $E[Z^{(m)}] = 0$  and  $Var[Z^{(m)}] = \sigma^2$ .

**Central Limit Theorem**: As  $m \to \infty$ , the distribution of  $Z^{(m)} \to \mathcal{N}(0, \sigma^2)$ .

**Rule of Thumb**: For m > 30, we may take  $Z^{(m)} \sim \mathcal{N}(0, \sigma^2)$ . i.e.,  $S^{(m)} \sim \mathcal{N}(\mu, \sigma^2/m)$ .