

# First order instrument

|   |   |
|---|---|
| $\tau \frac{dq_o}{dt} + q_o = K q_i$  | $\frac{\rho CpV}{h A_s} \frac{dx}{dt} + x = \frac{\beta V}{A_c} T_f$ - Thermometer  |
| Step response<br>$\frac{q_o(t)}{q_{is}} = K \left( 1 - e^{-\frac{t}{\tau}} \right)$   | Ramp response<br>$q_o(t) = K q_{is} \left( -\tau + t + \tau e^{-\frac{t}{\tau}} \right)$  |
| Frequency response<br>$\left  \frac{q_o}{K q_i} \right  = \frac{1}{\sqrt{1 + \tau^2 \omega^2}}$<br>$\phi = \tan^{-1}(-\tau \omega)$ | Impulse function<br>$q_o(t) = \frac{KA}{T} \left( 1 - e^{-\frac{t}{\tau}} \right)$ for $t < T$<br>$q_o = \frac{KA \left( 1 - e^{-\frac{T}{\tau}} \right)}{T e^{-\frac{T}{\tau}}} e^{-\frac{t}{\tau}}$ for $t > T$ |

Fourier Coefficients for Functions Having Arbitrary Period  $T = 2\pi/\omega$

$$y(t) = A_0 + \sum_{n=1}^{\infty} (A_n \cos n\omega t + B_n \sin n\omega t); A_0 = \frac{1}{T} \int_{-T/2}^{T/2} y(t) dt; A_n = \frac{2}{T} \int_{-T/2}^{T/2} y(t) \cos n\omega t dt;$$

$$B_n = \frac{2}{T} \int_{-T/2}^{T/2} y(t) \sin n\omega t dt$$

If function is even,  $y(t) = \sum_{n=1}^{\infty} A_n \cos n\omega t = \sum_{n=1}^{\infty} A_n \cos \frac{2\pi n t}{T}$

If function is odd,  $y(t) = \sum_{n=1}^{\infty} B_n \sin n\omega t = \sum_{n=1}^{\infty} B_n \sin \frac{2\pi n t}{T}$

|   | $f(t)$                         | $\mathcal{L}(f)$              |    | $f(t)$                 | $\mathcal{L}(f)$                    |
|---|--------------------------------|-------------------------------|----|------------------------|-------------------------------------|
| 1 | 1                              | $1/s$                         | 7  | $\cos \omega t$        | $\frac{s}{s^2 + \omega^2}$          |
| 2 | $t$                            | $1/s^2$                       | 8  | $\sin \omega t$        | $\frac{\omega}{s^2 + \omega^2}$     |
| 3 | $t^2$                          | $2!/s^3$                      | 9  | $\cosh at$             | $\frac{s}{s^2 - a^2}$               |
| 4 | $t^n$<br>( $n = 0, 1, \dots$ ) | $\frac{n!}{s^{n+1}}$          | 10 | $\sinh at$             | $\frac{a}{s^2 - a^2}$               |
| 5 | $t^a$<br>( $a$ positive)       | $\frac{\Gamma(a+1)}{s^{a+1}}$ | 11 | $e^{at} \cos \omega t$ | $\frac{s-a}{(s-a)^2 + \omega^2}$    |
| 6 | $e^{at}$                       | $\frac{1}{s-a}$               | 12 | $e^{at} \sin \omega t$ | $\frac{\omega}{(s-a)^2 + \omega^2}$ |

## Second order instrument

|   |  |
|---|--|
| $\frac{1}{\omega_n^2} \frac{d^2x}{dt^2} + \frac{2\xi}{\omega_n} \frac{dx}{dt} + x = KF(t)$ $\frac{1}{\omega_n^2} \frac{d^2V_o}{dt^2} + \frac{2\xi}{\omega_n} \frac{dV_o}{dt} + V_o = KV(t)$   | $\xi = \frac{C}{2\sqrt{mK_s}}; \omega_n = \sqrt{\frac{K_s}{m}}; K = \frac{1}{K_s}$ <p>Sping mass damper</p> $\xi = \frac{R}{2} \sqrt{\frac{C}{L}} \quad \omega_n = \frac{1}{\sqrt{LC}} \quad K = 1$  |
| <p>Step response</p> $\frac{q_o(t)}{Kq_{is}} = 1 - \frac{e^{-\xi\omega_n t}}{\sqrt{1-\xi^2}} \sin\left(\omega_d t + \tan^{-1}\left(\frac{\sqrt{1-\xi^2}}{\xi}\right)\right) \text{ for underdamped system}$ $\frac{q_o(t)}{Kq_{is}} = 1 - e^{-\omega_n t} (1 + \omega_n t) \text{ for critically damped system}$ $\frac{q_o(s)}{Kq_{is}} = 1 + \frac{1}{2\sqrt{(\xi^2-1)}(\xi + \sqrt{(\xi^2-1)})} e^{-(\xi + \sqrt{(\xi^2-1)})\omega_n t} - \frac{1}{2\sqrt{(\xi^2-1)}(\xi - \sqrt{(\xi^2-1)})} e^{-(\xi - \sqrt{(\xi^2-1)})\omega_n t} \text{ for overdamped system}$ |  |
| <p>Frequency response</p> $\left  \frac{q_o}{Kq_i} \right  = \frac{1}{\sqrt{\left[ \left(1 - \frac{\omega^2}{\omega_n^2}\right)^2 + \left(\frac{2\xi\omega}{\omega_n}\right)^2 \right]}} = \frac{1}{\sqrt{\left(1 - \frac{\omega^2}{\omega_n^2}\right)^2 + \left(\frac{2\xi\omega}{\omega_n}\right)^2}}$  | $\theta = \tan^{-1} \left[ \frac{-2\xi \frac{\omega}{\omega_n}}{1 - \frac{\omega^2}{\omega_n^2}} \right] = \tan^{-1} \left[ \frac{-2\xi}{\frac{\omega_n}{\omega} - \frac{\omega}{\omega_n}} \right]$ |

|                   | $f(t)$ | $e(t)$        |                         |
|-------------------|--------|---------------|-------------------------|
|                   | $v$    | $i$           |                         |
| $M \frac{dv}{dt}$ | $M$    | $L$           | $L \frac{di}{dt}$       |
| $Bv$              | $B$    | $R$           | $iR$                    |
| $K \int v dt$     | $K$    | $\frac{1}{C}$ | $\frac{1}{C} \int i dt$ |

|                   | $f(t)$ | $i(t)$        |                         |
|-------------------|--------|---------------|-------------------------|
|                   | $v$    | $e$           |                         |
| $M \frac{dv}{dt}$ | $M$    | $C$           | $C \frac{de}{dt}$       |
| $Bv$              | $B$    | $\frac{1}{R}$ | $\frac{e}{R}$           |
| $K \int v dt$     | $K$    | $\frac{1}{L}$ | $\frac{1}{L} \int e dt$ |