MEASUREMENT OF PRESSURE

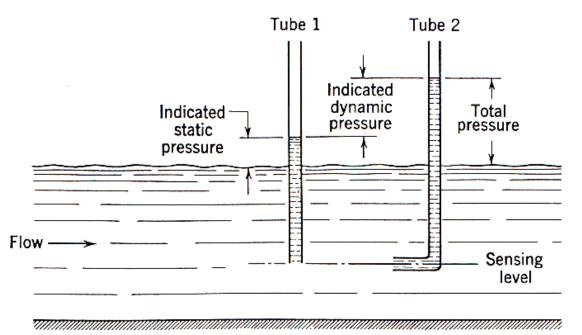
PRESSURE MEASUREMENT IN MOVING FLUIDS

STATIC PRESSURE: Pressure of fluid whether at rest or in motion, can be sensed by a probe that is at rest with respect to the fluid.

DYNAMIC PRESSURE: Pressure equivalent of the diverted kinetic energy of fluid (Continuum).

TOTAL PRESSURE: Sum of static and dynamic pressure sensed by a probe at rest with respect to system boundary when it locally stagnates the fluid isentropically.

TOTAL PRESSURE MEASUREMENT – fairly simple. For any shape body in flow there is a point where the fluid is brought to rest and pressure acting is the undisturbed flow pressure.

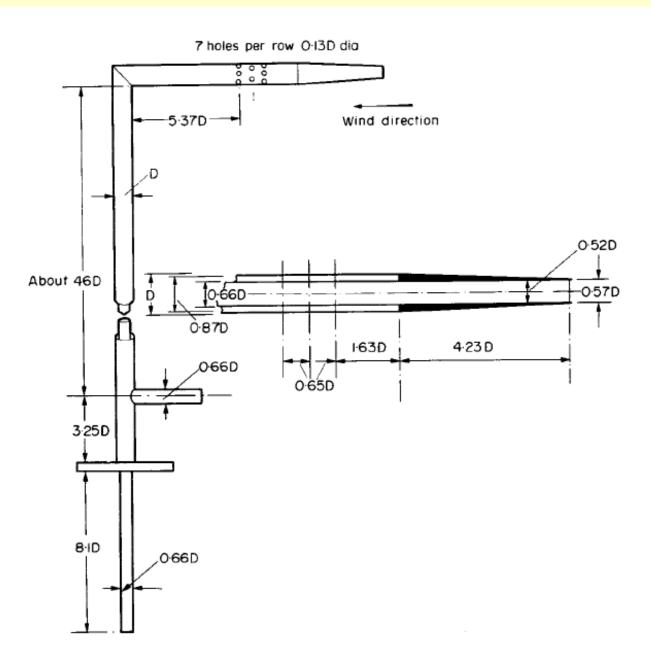


Principle of pitot tube: Bend a tube at right angle will give the total pressure.

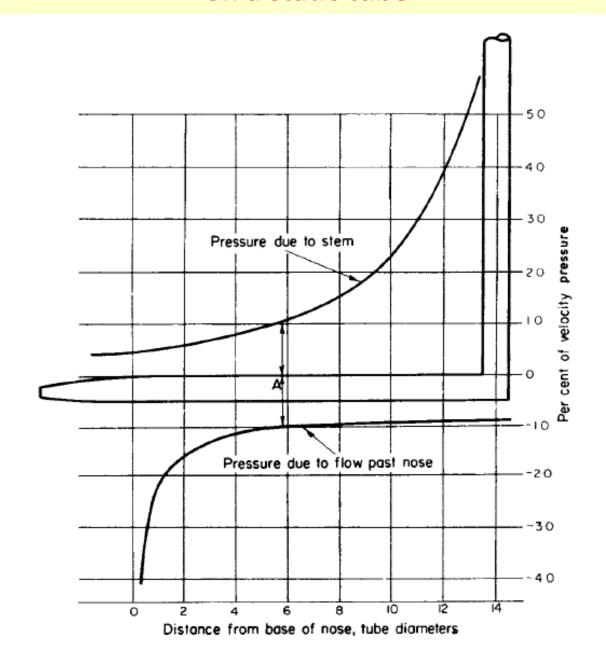
Static pressure measurement – slightly more difficult.

Both together – PITOT STATIC TUBE.

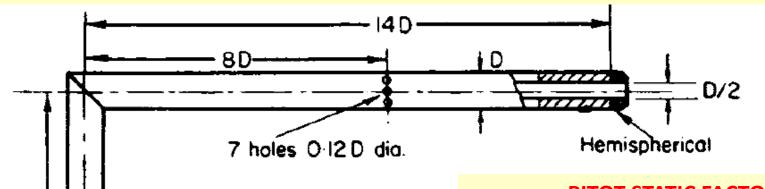
N.P.L. Standard (tapered nose) Pitot-Static Tube



Balance of pressures due to stem and nose on a static tube



N.P.L. Standard Pitot static tube with hemispherical nose



40D

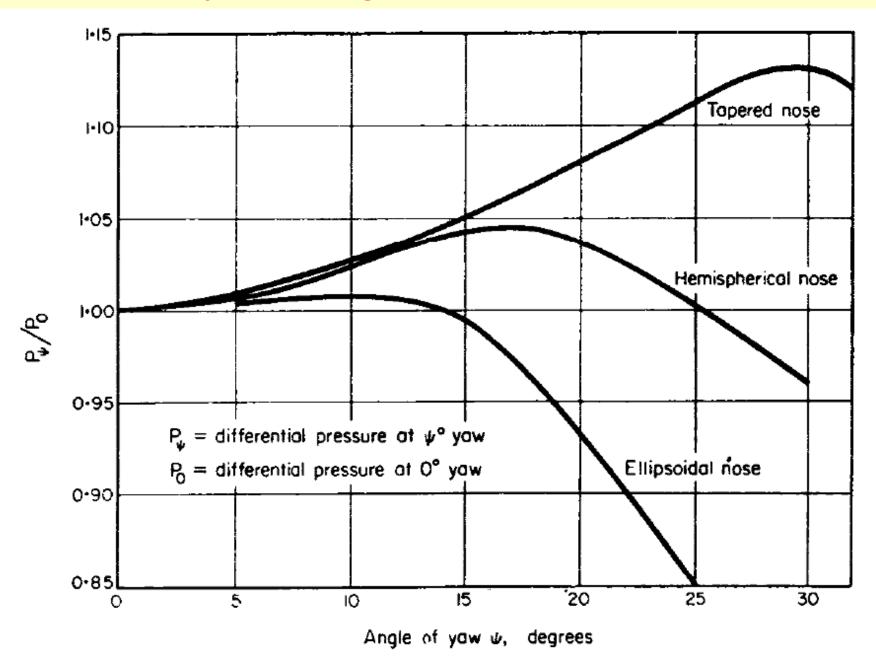
About

$$K = \frac{P_{total} - P_{static}}{\frac{1}{2}\rho V^2}$$

PITOT STATIC FACTORS (RE BASED ON TUBE DIAMETER)

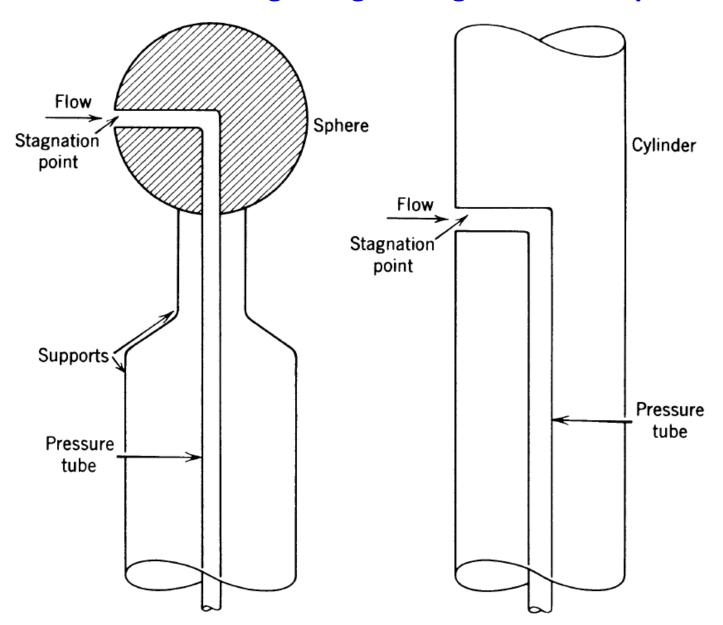
Tapered-nose tube (3.8 mm dia)		Hemispherical-nose tube (3.9 mm dia)	
Reynolds No. ^(a)	K	Reynolds No. ^(a)	K
330	1.020	335	1.055
655	0.989	670	1.006
985	0.995	1000	1.001
1310	0.992	1335	0.996
1 6 40	0.991	1670	0.992
1 9 70	0.992	2005	0.991
2295	0.995	2340	0.992
2625	0.998	2675	0.996
2950	0.999	3005	0.999
3280	1.000	3340	1.001

Sensitivity Of Yaw Angle On Pitot-static Combination

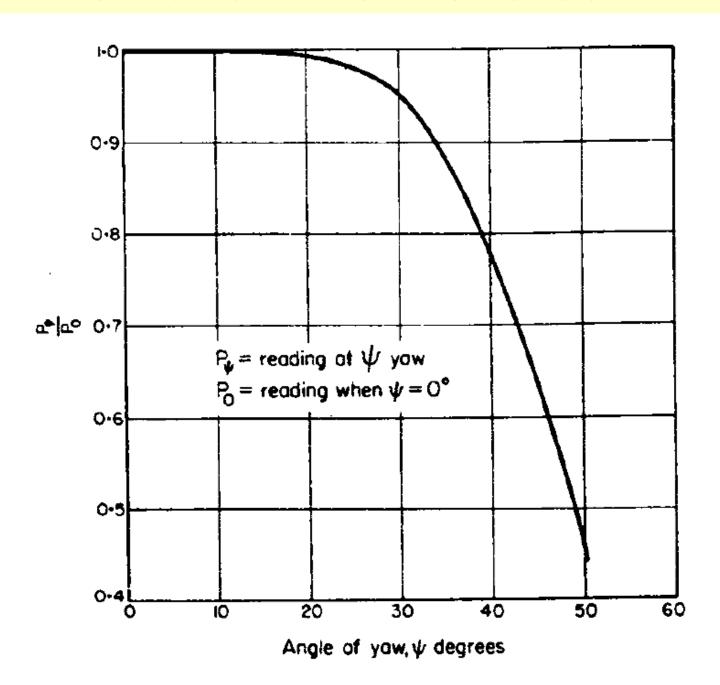


SIMPLE TOTAL PRESSURE PROBE – PITOT TUBES

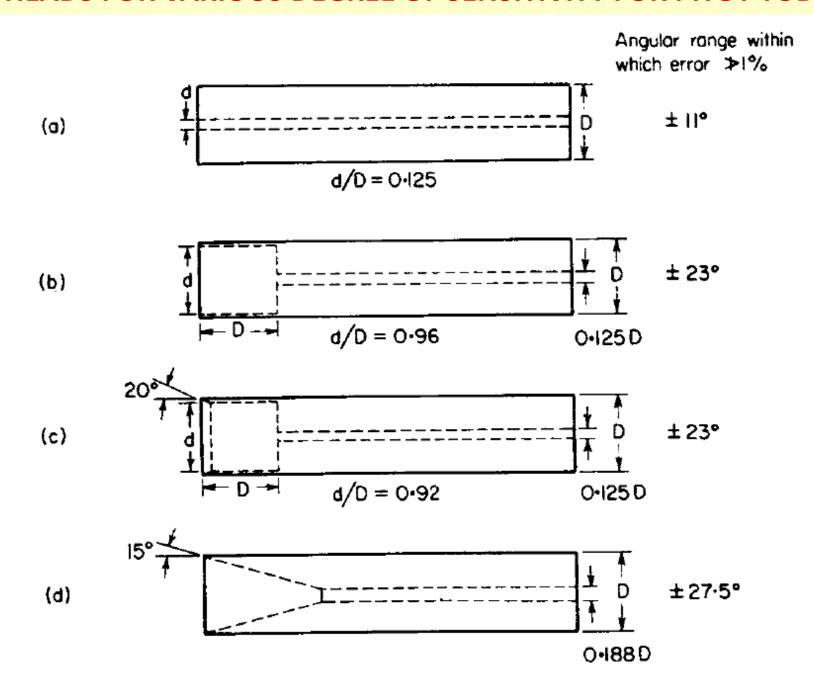
Principle of pitot tube: Bend a tube at right angle will give the total pressure



EFFECT OF MISALIGNMENT ON PITOT TUBES ONLY



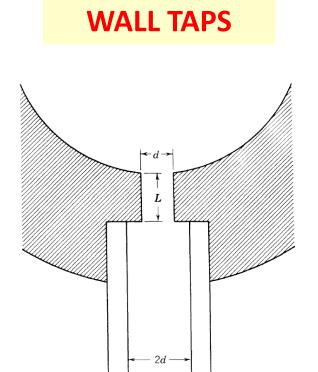
PITOT HEADS FOR VARIOUS DEGREE OF SENSITIVITY FOR PITOT TUBES

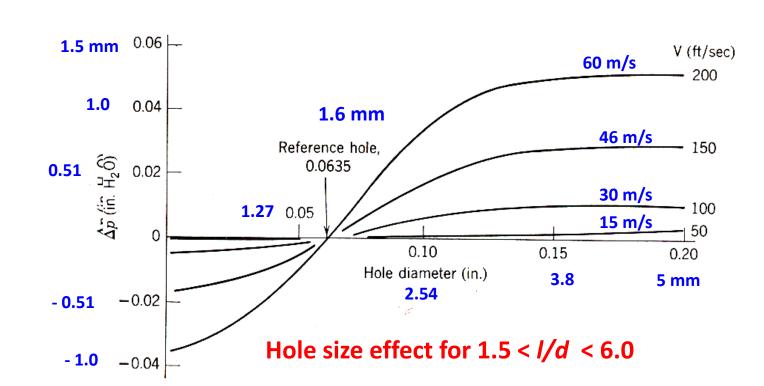


MEASUREMENT OF STATIC PRESSURE

- Wall taps Bernoulli used first extensively
- Small holes can be located on probes that streamline curvatures and other effects caused by the probe presence in the flowing fluid stream area self-compensating
- Small holes can be strategically located at critical points on *aerodynamic bodies* where static pressures naturally occur

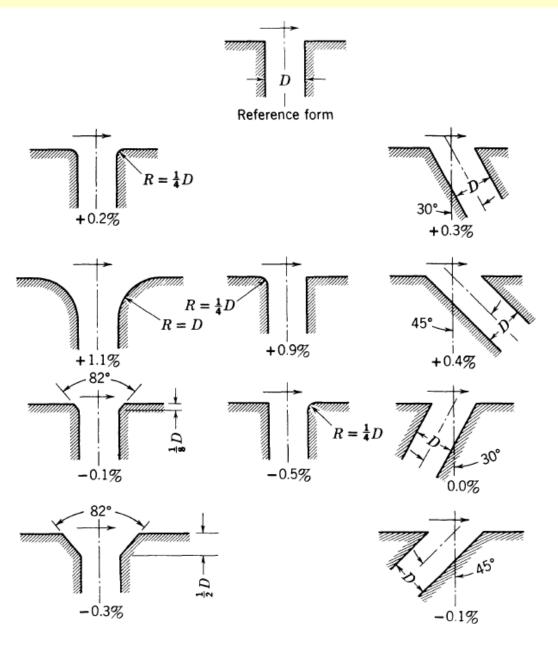
Ex: cylinder, sphere, wedge and cone



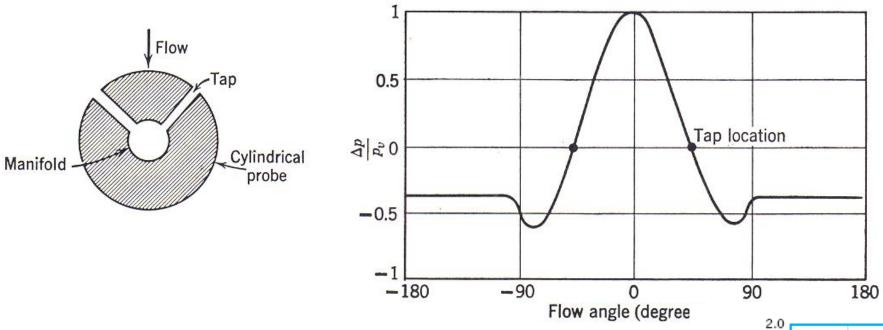


Effect of orifice edge form on static pressure measurement.

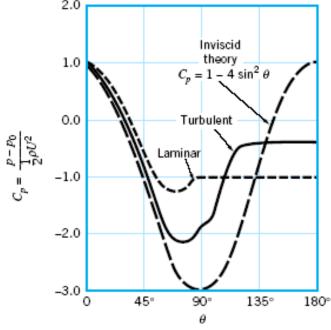
Variation in percentage of dynamic pressure



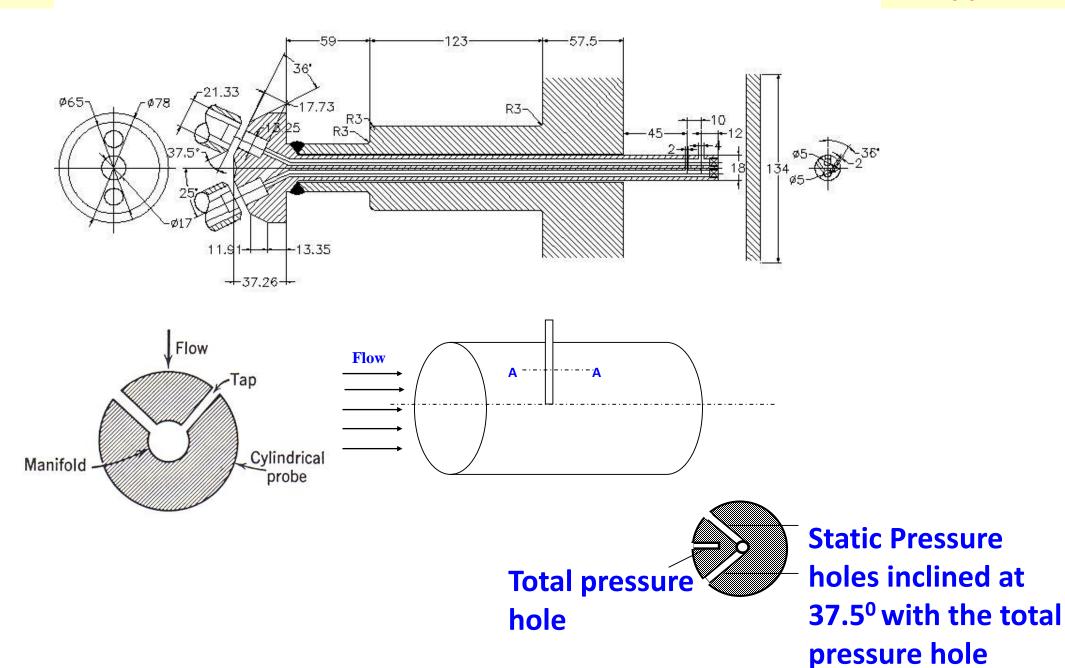
MANIFOLDED CYLINDRICAL PROBE WITH TWO TAPS



- If the flow direction changes pressure increase in one tap is just offset by decrease in other tap
- side holes located at angle of β = 36° so that they measure static pressure



Application Of Manifolded Cylindrical Probe With Two Taps For Steam Generator Application



$$Q_{meas} = AK \frac{U_{avg}}{U_{cl}} \sqrt{\frac{2\Delta P}{\rho}}$$

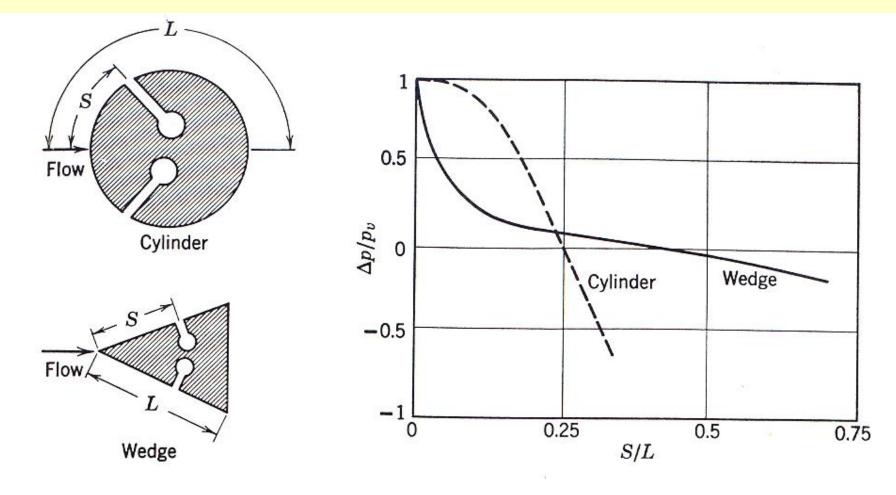
Probe No.	Calibration Constant K
1	0.9045
2	0.7966
3	0.8312
4	0.8071
5	0.8425
6	0.8506

For rectangular channel, n = 12

$$\frac{u_{avg}}{u_c} = \frac{n}{(n+1)} = 0.89$$

$$\frac{U_{avg}}{U_{cl}} = \frac{n}{n+1}$$

WEDGE PROBE



- Wedge probe has less rapid change in tap pressure in the region of the pressure taps than does the cylinder
- Fragile knife edge of the wedge makes it a less robust instrument than the cylinder for many applications

HISTORICAL NOTE ON PITOT TUBE

- Henri Pitot (1695-1771) Arman in France
- Astronomer and Mathematician
- 1732 measured velocity between two piers of a bridge over the Seine River in Paris
- Measured the variation of the velocity with the depth of the river
- Velocity was thought to increase with depth Misconception
- Pitot measured and reported that velocity decreases with the increase of the depth
- Pitot used this tube before present form of Bernoulli's equation was introduced in 1738
- People got all wrong results because of not measuring static pressure
- Prof. John Airey (Mech. Engg) University of Michigan performed series of experiments 1913
- 1915 Prof. Herschel and Dr. Buckingham International standards





$$\frac{u}{u_{max}} = \frac{u}{u_c} = \left(1 - \frac{r}{R}\right)^{\frac{1}{n}} = \left(\frac{y}{R}\right)^{\frac{1}{n}}$$

$$\frac{u_{avg}}{u_c} = \frac{\int u \, dA}{Au_c} = \left(1 - \frac{r}{R}\right)^{\frac{1}{n}} = \left(\frac{y}{R}\right)^{\frac{1}{n}}$$

$$\int u \, dA = 2\pi \int_0^R u \, r \, dr = 2\pi \int_R^0 u \, (R - y) \, (-dy)$$

$$r = R - y$$
$$dr = -dy$$

$$\int u dA = 2\pi \int_0^R u (R - y) dy$$

$$\int u dA = 2\pi \int_0^R u (R - y) dy$$

$$\int u dA = 2\pi u_c \int_0^R \left(\frac{y}{R}\right)^{\frac{1}{n}} (R - y) dy$$

$$\int u dA = 2\pi u_c \left(\frac{1}{R}\right)^{\frac{1}{n}} \int_0^R y^{\frac{1}{n}} (R - y) dy$$

$$\int u \, dA = 2\pi u_c \left(\frac{1}{R}\right)^{\frac{1}{n}} \int_0^R y^{\frac{1}{n}} (R - y) \, dy$$

$$\int u \, dA = 2\pi u_c \left(\frac{1}{R}\right)^{\frac{1}{n}} \int_0^R y^{\frac{1}{n}} \left(Ry^{\frac{1}{n}} - yy^{\frac{1}{n}}\right) \, dy$$

$$\int u \, dA = 2\pi u_c \left(\frac{1}{R}\right)^{\frac{1}{n}} \int_0^R y^{\frac{1}{n}} \left(Ry^{\frac{1}{n}} - yy^{\frac{1}{n}}\right) dy$$

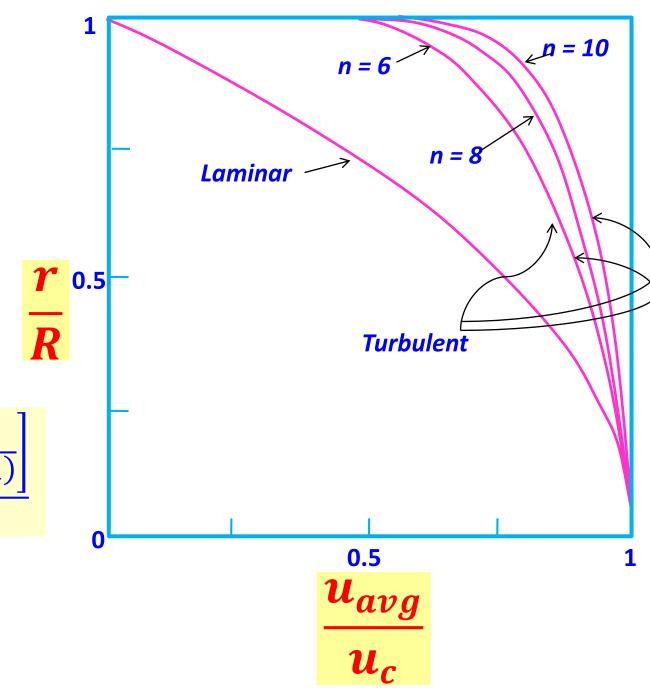
$$\int u \, dA = \frac{2\pi u_c}{R^{\frac{1}{n}}} \left[\frac{Ry^{\frac{n+1}{n}}}{\frac{n+1}{n}} - \frac{y^{\frac{n+1}{n}+1}}{\frac{n+1}{n}+1}\right]^{\frac{n}{n}}$$

$$\int u \, dA = \frac{2\pi u_c}{R^{\frac{1}{n}}} \left[\frac{Ry^{\frac{n+1}{n}}}{\frac{n+1}{n}} - \frac{y^{\frac{n+1}{n}+1}}{\frac{n+1}{n}+1} \right]_0^{\frac{n}{n}}$$

$$\int u \, dA = \frac{2\pi u_c}{R^{\frac{1}{n}}} \left[\frac{RR^{\frac{n+1}{n}}}{\frac{n+1}{n}} - \frac{R^{\frac{n+1}{n}+1}}{\frac{2n+1}{n}} \right]_0^R = \frac{2\pi u_c}{R^{\frac{1}{n}}} \left[\frac{R^{\frac{2n+1}{n}}}{\frac{n+1}{n}} - \frac{R^{\frac{2n+1}{n}}}{\frac{2n+1}{n}} \right]_0^R$$

$$\int u \, dA = \frac{2\pi u_c R^{\frac{2n+1}{n}}}{R^{\frac{1}{n}}} \left[\frac{1}{\frac{n+1}{n}} - \frac{1}{\frac{2n+1}{n}} \right] = 2\pi u_c R^2 \left[\frac{\frac{2n+1}{n} - \frac{n+1}{n}}{\frac{n+1}{n} + \frac{2n+1}{n}} \right]$$

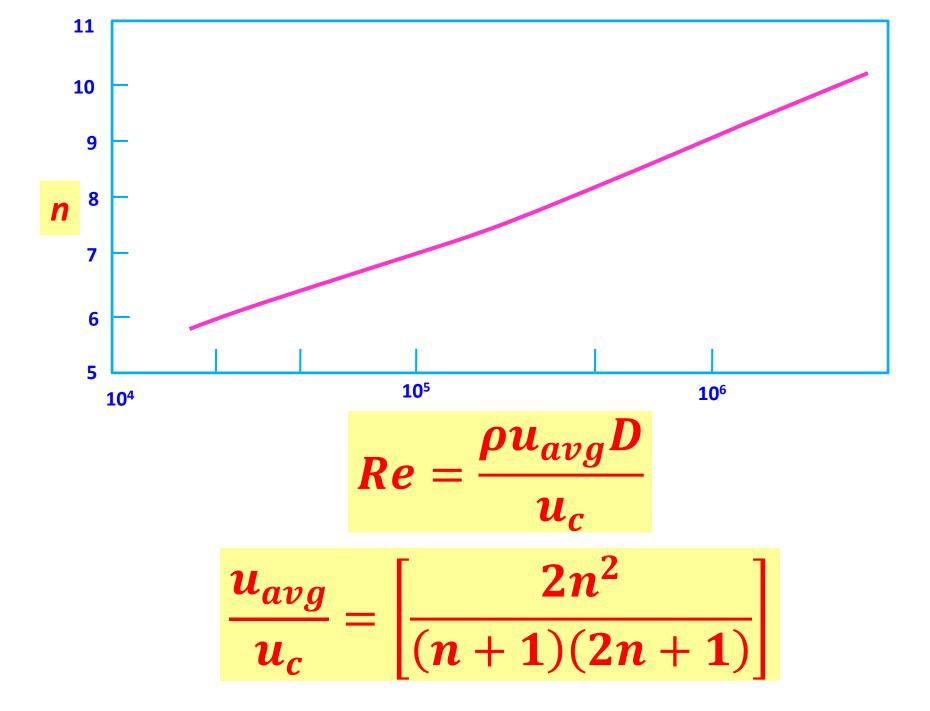
$$\int u \, dA = 2\pi u_c R^2 \left[\frac{\frac{2n+1-n-1}{n}}{\frac{n+1}{n}\frac{2n+1}{n}} \right] = 2\pi u_c R^2 \left[\frac{\frac{n}{n}}{\frac{n+1}{n}\frac{2n+1}{n}} \right] = \pi u_c R^2 \left[\frac{2n^2}{(n+1)(2n+1)} \right]$$



$$\int u dA = \pi u_c R^2 \left[\frac{2n^2}{(n+1)(2n+1)} \right]$$

$$\frac{u_{avg}}{u_c} = \frac{\int u \, dA}{Au_c} = \frac{\pi u_c R^2 \left[\frac{2n^2}{(n+1)(2n+1)} \right]}{\pi R^2 u_c}$$

$$\frac{u_{avg}}{u_c} = \left[\frac{2n^2}{(n+1)(2n+1)}\right]$$



RESTRICTIONS ON THE USE OF THE BERNOULLI EQUATION

Compressibility effects

$$\int \frac{dp}{\rho} + \frac{1}{2}V^2 + gz = C$$

$$\rho = \frac{p}{RT}$$

For inviscid and isothermal flows

$$RT\int \frac{dp}{p} + \frac{1}{2}V^2 + gz = C$$

$$RT \ln p_1 + \frac{V_1^2}{2} + gz_1 = RT \ln p_2 + \frac{V_2^2}{2} + gz_2$$

$$RT \ln\left(\frac{p_1}{p_2}\right) + \frac{V_1^2}{2} + z_1 g = \frac{V_2^2}{2} + gz_2$$

Isentropic flow - reversible adiabatic process with no friction or heat transfer

$$\frac{p}{\rho^{\gamma}} = C \Rightarrow \rho = p^{\frac{1}{\gamma}} C^{-\frac{1}{\gamma}}$$

$$\int \frac{dp}{\rho} + \frac{1}{2}V^2 + gz = C$$

$$\int_{p_{1}}^{p_{2}} \frac{dp}{p^{\frac{1}{\gamma}} C^{-\frac{1}{\gamma}}} = C^{\frac{1}{\gamma}} \int_{p_{1}}^{p_{2}} p^{-\frac{1}{\gamma}} dp = C^{\frac{1}{\gamma}} \left(\frac{\gamma}{\gamma - 1}\right) \left(\frac{\gamma - 1}{p_{2}^{\gamma}} - p_{1}^{\frac{\gamma - 1}{\gamma}}\right) = \left(\frac{\gamma}{\gamma - 1}\right) \left(\frac{\gamma - 1}{p_{2}^{\gamma}} - p_{1}^{\frac{1}{\gamma}} - p_{1}^{\frac{\gamma - 1}{\gamma}} - p_{1}^{\frac{\gamma - 1}{\gamma}}\right) = \left(\frac{\gamma}{\gamma - 1}\right) \left(\frac{\gamma - 1}{p_{2}^{\gamma}} - p_{1}^{\frac{\gamma - 1}{\gamma}} - p_{1}^{\frac{\gamma - 1}{\gamma}}\right)$$

$$\int_{p_1}^{p_2} \frac{dp}{p^{\frac{1}{\gamma}}C^{-\frac{1}{\gamma}}} = \left(\frac{\gamma}{\gamma - 1}\right) \left(\frac{p_2}{\rho_2} - \frac{p_1}{\rho_1}\right)$$

$$\left(\frac{\gamma}{\gamma - 1}\right) \frac{p_1}{\rho_1} + \frac{V_1^2}{2} + gz_1 = \left(\frac{\gamma}{\gamma - 1}\right) \frac{p_2}{\rho_2} + \frac{V_2^2}{2} + gz_2$$

Assuming $z_1 = z_2$ and $V_2 = 0$

$$\left(\frac{\gamma}{\gamma - 1}\right) \frac{p_1}{\rho_1} + \frac{V_1^2}{2} + gz_1 = \left(\frac{\gamma}{\gamma - 1}\right) \frac{p_2}{\rho_2} + \frac{V_2^2}{2} + gz_2$$

Assuming $z_1 = z_2$ and $V_2 = 0$

$$\rho_1 = \frac{p_1}{RT_1}; \rho_2 = \frac{p_2}{RT_2}$$

$$\left(\frac{\gamma}{\gamma-1}\right)RT_1 + \frac{M_1^2(\gamma RT_1)}{2} = \left(\frac{\gamma}{\gamma-1}\right)RT_2$$

$$\left(\frac{1}{\gamma - 1}\right)T_1 + \frac{M_1^2}{2}T_1 = \left(\frac{1}{\gamma - 1}\right)T_2 \Rightarrow T_2 = T_1\left(1 + \frac{\gamma - 1}{2}M_1^2\right)$$

$$\frac{T_2}{T_1} = \left(1 + \frac{\gamma - 1}{2} M_1^2\right)$$

$$\frac{p}{\rho} = RT \Rightarrow \frac{p_1}{p_2} \left(\frac{\rho_2}{\rho_1}\right) = \frac{T_1}{T_2}$$

$$\frac{p}{\rho^{\gamma}} = C \Rightarrow \rho = \left(\frac{p}{C}\right)^{\frac{1}{\gamma}}$$

$$\frac{p_1}{p_2} \left(\frac{p_2}{p_1}\right)^{\frac{1}{\gamma}} = \frac{T_1}{T_2}$$

$$\left(\frac{p_1}{p_2}\right)^{1-\frac{1}{\gamma}} = \frac{T_1}{T_2} \Longrightarrow \left(\frac{p_1}{p_2}\right)^{\frac{\gamma-1}{\gamma}} = \frac{T_1}{T_2} \Longrightarrow \frac{p_1}{p_2} = \left(\frac{T_1}{T_2}\right)^{\frac{\gamma}{\gamma-1}}$$

$$\frac{p_2}{p_1} = \left(\frac{T_2}{T_1}\right)^{\frac{\gamma}{\gamma-1}} = \left(1 + \frac{\gamma - 1}{2}M_1^2\right)^{\frac{\gamma}{\gamma-1}}$$

$$\frac{T_2}{T_1} = \left(1 + \frac{\gamma - 1}{2} M_1^2\right)$$

$$\frac{p_2}{p_1} - 1 = \left(1 + \frac{\gamma - 1}{2}M_1^2\right)^{\frac{\gamma}{\gamma - 1}} - 1$$

$$\frac{p_2 - p_1}{p_1} = \left[\left(1 + \frac{\gamma - 1}{2} M a_1^2 \right)^{\frac{\gamma}{\gamma - 1}} - 1 \right]$$

$$\frac{p_2 - p_1}{p_1} = \left[\left(1 + \frac{\gamma - 1}{2} M_1^2 \right)^{\frac{\gamma}{\gamma - 1}} - 1 \right]$$

$$\frac{p_2 - p_1}{p_1} = \frac{\gamma M_1^2}{2} \left(1 + \frac{1}{4} M_1^2 + \frac{2 - \gamma}{24} M_1^4 + \dots \right)$$

For incompressible flow

$$p_1 + \frac{\rho V_1^2}{2} + \rho \ gz_1 = p_2 + \frac{\rho V_2^2}{2} + \rho \ gz_2$$
 Assuming $z_1 = z_2$ and $v_2 = 0$

$$p_{1} + \frac{\rho V_{1}^{2}}{2} = p_{2} \Rightarrow p_{2} - p_{1} = \frac{\rho V_{1}^{2}}{2} \Rightarrow p_{2} - p_{1} = \frac{\rho M_{1}^{2} (\gamma R T_{1})}{2} \Rightarrow \frac{p_{2} - p_{1}}{p_{1}} = \frac{\rho M_{1}^{2} (\gamma R T_{1})}{2p_{1}}$$

$$\frac{p_2 - p_1}{p_1} = \frac{\gamma M_1^2}{2}$$

$$(a+x)^{n} = a^{n} + na^{n-1}x + \frac{n(n-1)}{2!}a^{n-2}x^{2} + \frac{n(n-1)(n-2)}{3!}a^{n-3}x^{3} + \dots$$
$$(1+x)^{n} = 1 + nx + \frac{n(n-1)}{2!}x^{2} + \frac{n(n-1)(n-2)}{3!}x^{3} + \dots$$

$$n = \frac{\gamma}{\gamma - 1} \quad x = \frac{\gamma - 1}{2} M_1^2$$

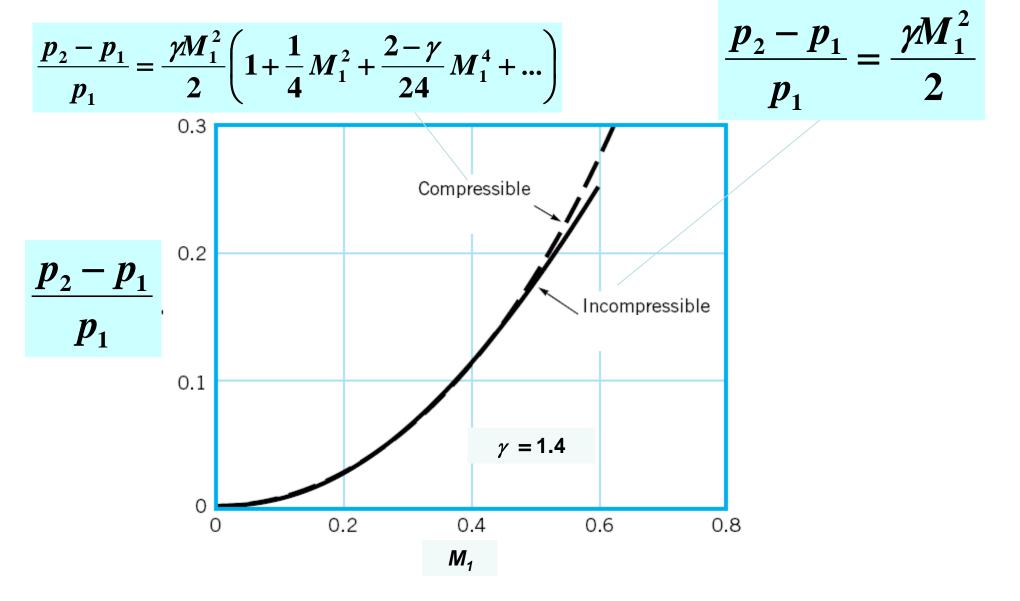
$$nx = \frac{\gamma}{\gamma - 1} \times \frac{\gamma - 1}{2} M_1^2 = \frac{\gamma}{2} M_1^2$$
 $nx = \frac{\gamma}{2} M_1^2$

$$\frac{n(n-1)}{2!}x^{2} = \frac{1}{2}\left(\frac{\gamma}{\gamma-1}\right)\left(\frac{\gamma}{\gamma-1}-1\right)\left(\frac{(\gamma-1)^{2}}{4}M_{1}^{4}\right) = \frac{1}{2}\left(\frac{\gamma}{\gamma-1}\right)\left(\frac{1}{\gamma-1}\right)\left(\frac{(\gamma-1)^{2}}{4}M_{1}^{4}\right) \qquad \frac{n(n-1)}{2!}x^{2} = \frac{\gamma M_{1}^{4}}{8}$$

$$\frac{n(n-1)(n-2)}{3!}x^{3} = \frac{1}{6}\left(\frac{\gamma}{\gamma-1}\right)\left(\frac{\gamma}{\gamma-1}-1\right)\left(\frac{\gamma}{\gamma-1}-2\right)\frac{(\gamma-1)^{3}}{8}M_{1}^{6} = \frac{1}{6}\left(\frac{\gamma}{\gamma-1}\right)\left(\frac{1}{\gamma-1}\right)\left(\frac{2-\gamma}{\gamma-1}\right)\frac{(\gamma-1)^{3}}{8}M_{1}^{6}$$

$$\frac{n(n-1)(n-2)}{3!}x^3 = \frac{\gamma(2-\gamma)}{48}M_1^6$$

$$\left(1+\frac{\gamma-1}{2}M_{1}^{2}\right)^{\frac{\gamma}{\gamma-1}}=1+\frac{\gamma}{2}M_{1}^{2}+\frac{\gamma M_{1}^{4}}{8}+\frac{\gamma(2-\gamma)}{48}M_{1}^{6}+...=1+\frac{\gamma}{2}M_{1}^{2}\left(\frac{M_{1}^{2}}{4}+\frac{(2-\gamma)}{24}M_{1}^{4}+...\right)$$



Upto M = 0.3, the comparison between the compressible and incompressible equations agree within \pm 2%